

Mike #6 Differences

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February 2022

This document shows the most important differences between the ETH Mike backend branches for Mike #6 and the "normal" branch for the other mike versions (with older electronics version).

1. **TF_MotorCurrentInput.vi** & **TF_MotorCurrentOutput.vi** Adjust "Motor Peak Current" and "ESCON Input Range" to 10A. In case you change the maximum current in the escon setup, you need to take the new value according to the setup.
2. **min_jerk_params.vi** Adjust the output range to 10 and -10, also according to the escon setup.