

Mike #6 Differences

Jannis

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This document shows the most important differences between the ETH Mike backend branches for Mike #6 and the "normal" branch for the other mike versions (with older electronics version).

1. **TF_MotorCurrentInput.vi** & **TF_MotorCurrentOutput.vi** Adjust "Motor Peak Current" to 10A. In case you change the maximum current in the escon setup, you need to take the new value according to the setup.
2. **min_jerk_params.vi** Adjust the output range to 10 and -10, also according to the escon setup.