

MAE 598 - DESIGN OPTIMIZATION

PROJECT -2 DESIGN OPTIMIZATION OF BRAKE DISC GEOMETRY

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ABSTRACT

The aim of this project is to solve the brake disc assemble for the different conditions like Stress ,Modal and Thermal and doing the optimization using these values. The optimization is carried out to find the best suitable dimensions. The optimization objective is to minimize the stress, temperature and maximize the first natural frequency of the disc. These goals are accomplished using optimization algorithm and the results are correlated with the values obtained from ANSYS. The system optimization is performed using Kriging method and by using the load cases.

ACKNOWLEDGEMENT

I primarily would like thank Dr.Yi Ren for his time in teaching and giving me the right resources to understand this class in the better way. The High computing laboratory from Arizona State University was of major assistance in carrying out the simulation.

Introduction

Brake design analysis is going to be done ANSYS Design of Experiment (DOE) and Optimization tools which will allow you to better validate and understand your engineering model and further refine your design for specific properties

the brake design problem has the following objectives:

- Design a brake disc for emergency braking conditions with minimal volume
- Minimize the maximum stress in the brake disc
- Maximize the first natural frequency of the brake disc
- Minimize the maximum temperature in the brake disc

The three subsystems are as follows:

- **Structural Analysis:** The brake disc has to sustain the pressure from the hydraulically actuated brake pads during sudden braking conditions. Stresses are induced due to friction between the brake pads and the disc. The disc also experiences centrifugal body forces due to its rotation. Resultant stresses generated due these forces can lead to material failure. Therefore, it is of prime importance to make sure that the stresses in the disc are minimized.
- **Modal Analysis:** Free modal analysis is performed to ensure that the disc's first natural frequency is higher than the engine firing frequency. This guarantees that the disc does not experience failure due to resonance.
- **Thermal Analysis:** Braking in a vehicle takes place due to friction between the brake pads and the rotor disc. This leads to heat flux generation in the disc which consequently results in increase in its temperature and thermal stresses. Emergency braking conditions induce high temperatures that damage the contact surfaces. It is therefore essential to minimize the temperature to prevent disc wear and tear.

Significance of Analysis :

Structural Analysis

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Modal Analysis

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Glossary of terms used :

- V: Volume (mm³)
- α : Regression coefficients for volume
- S: Stress (MPa)
- β : Regression coefficients for stress
- F: First natural frequency (Hz)
- γ : Regression coefficients for frequency
- T: Temperature (°C)
- δ : Regression coefficients for temperature
- P1: Inner disc radius (mm)
- P2: Outer disc radius (mm)
- P3: Disc thickness (mm)
- d: Braking distance (m)
- t_e : Braking time (s)
- u: Initial vehicle velocity (kmph)
- m: Vehicle mass (kg) ν : Coefficient of friction

- w: Disc rotational velocity (rad/s)
- Ravg: Average of P1 and P2 (mm)
- KE: Vehicle kinetic energy (J)
- Fb: Total braking force on the disc (N)
- P: Pressure acting on the disc due to one brake pad (Pa)
- Ap: Brake pad area (mm²)
- Asp: Brake pad swept area (mm²)
- q: Heat flux (W/m²)
- Tamb: Ambient temperature (oC)

Mathematical Model :

- The brake disc inner radius (P1), outer radius (P2) and thickness (P3) are the design variables in this optimization study. Initially, structural, modal, and thermal analyses are performed in ANSYS. For the assumed geometric constraints, Design of Experiment (DOE) points are generated. Mathematical model is then generated by performing a 2nd order regression analysis on these DOE points to obtain the volume, stress, frequency, and temperature quadratic functions. The objective function is designed as follows:

$$\text{Min } V = \sum_{n=1}^{n=3} \alpha_n x_n + \sum_{n=4}^{n=6} \alpha_n x_n^2 + \alpha_7; (R_{\text{volume}}^2 = 0.98)$$

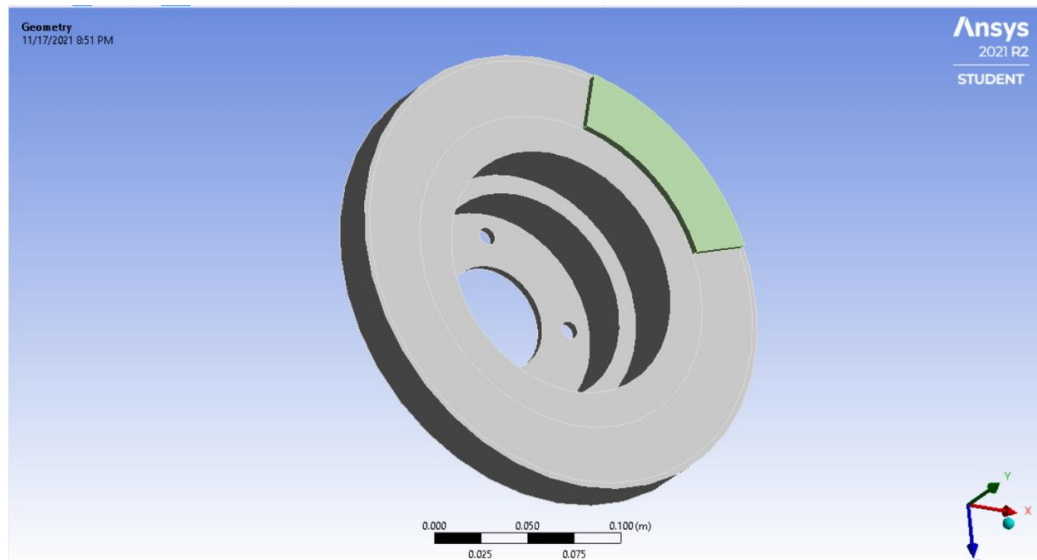
Geometric Constraints for these Analysis

I have given the following constraint for my model in order to have the desired data during the optimization formulation using the response surface.

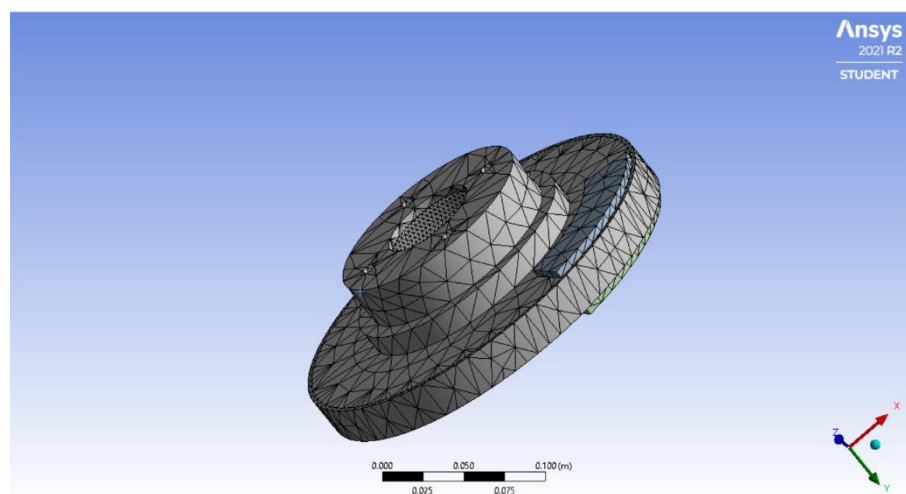
$$\begin{aligned} g1 &: -P1 \leq -60 \\ g2 &: P1 \leq 87 \\ g3 &: -P2 \leq -124 \\ g4 &: P2 \leq 153 \\ g5 &: -P3 \leq -10 \\ g6 &: P3 \leq 30 \end{aligned}$$

Finite Element Model

FE Model The brake disc geometry is prepared in ANSYS Design Modeler as shown in Figure .The initial values for P1, P2 and P3 are 75 mm, 125 mm and 25 mm respectively.



The CAD geometry is meshed tetrahedral quadratic elements as shown in Figure. The reason for the choosing this shape is that the node which are unrealistic won't be considered which removes complexity.



The brake disc is made of gray cast iron and the part are made of Structured Steel.

The assumptions made for performing the FEM analysis are as follows:

- Natural convection takes place due to the ambient air.
- The disc brake considered is of the solid type.
- Heat flux on the disc brake acts on both sides of the disc.

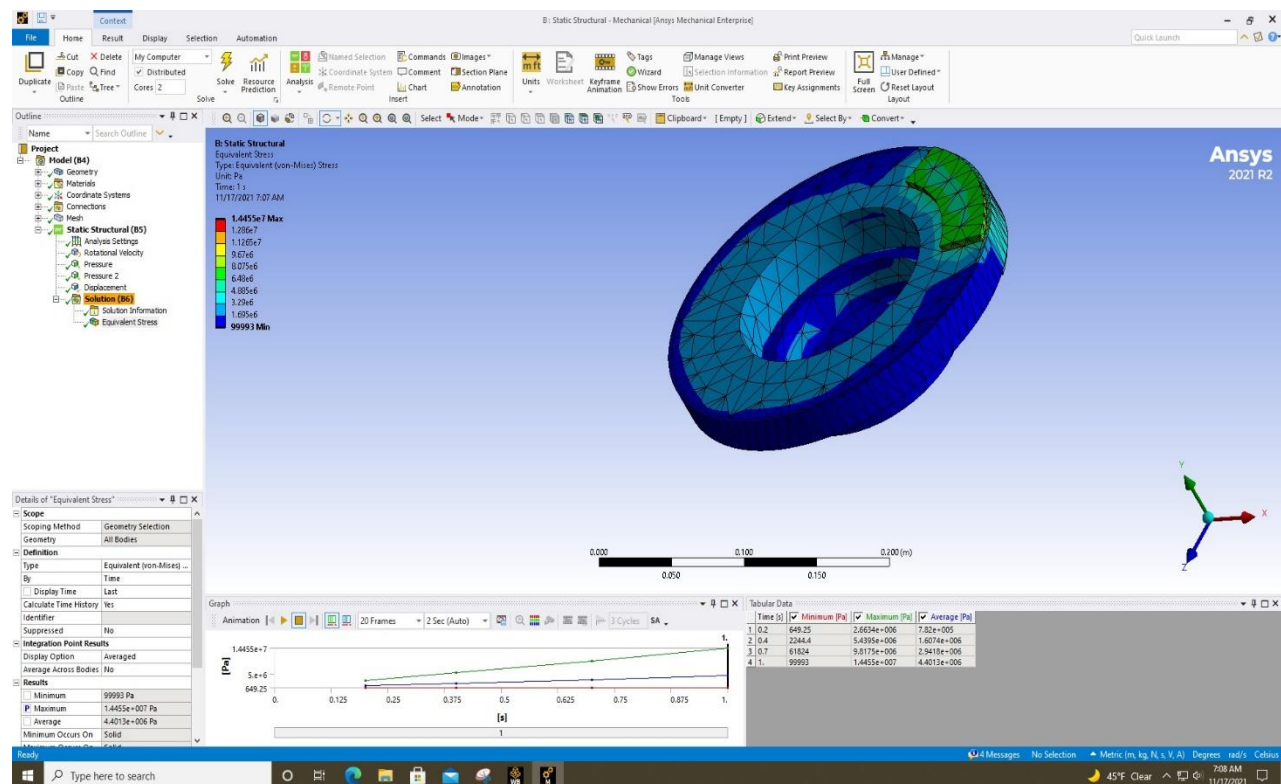
Structural Analysis:

Considering the emergency braking distance of 0 m with stopping time of 5 seconds for a vehicle with initial velocity of 100 km/hr, the braking pressure required is calculated. This pressure will act as one of the boundary conditions for the simulation.

Using this, the pressure on each pad is calculated by considering the coefficient of friction. Here, $d = 10\text{m}$; $t_e = 5\text{s}$; $u = 90\text{kmph}$; $m = 1500\text{kg}$; $\nu = 0.22$; $A_p = 3552\text{mm}^2$.

Stress distribution of the Structural Analysis

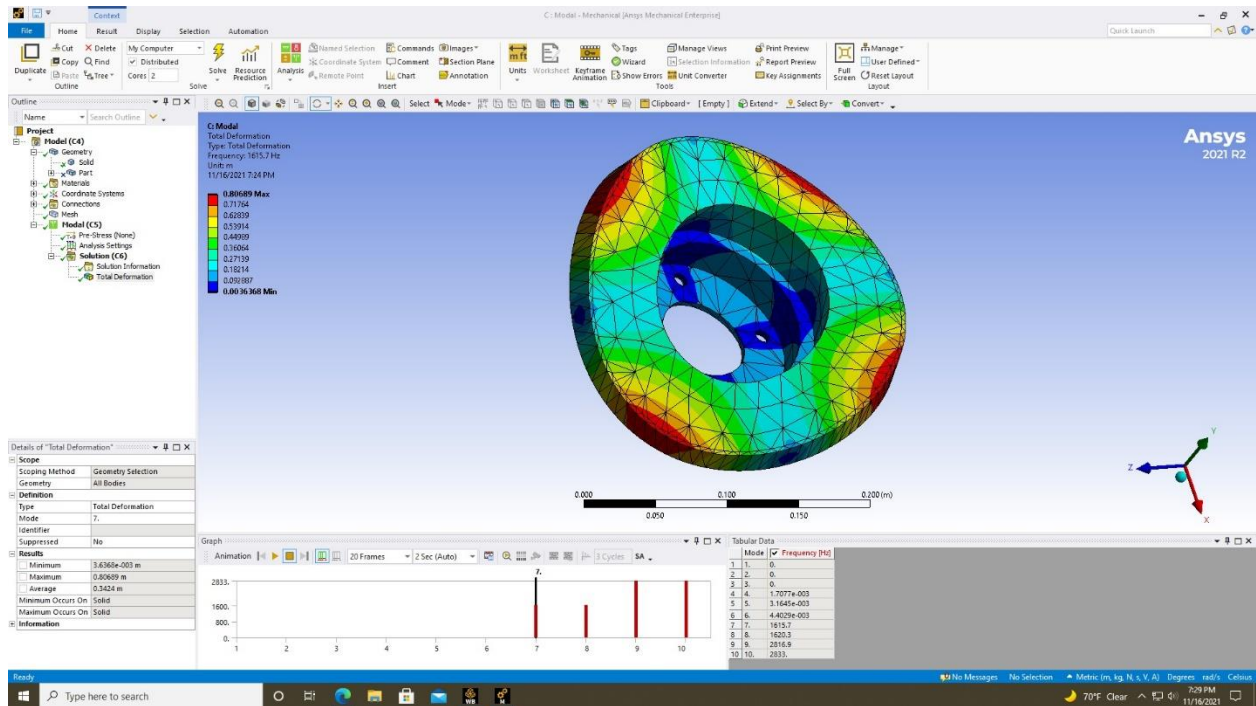
Calculating the disc angular velocity (ω), $\omega = u/R_{avg} = 250\text{rad/s}$.



The max stress obtained is $1.4455\text{e}+007$.

Modal Analysis:

Modal Analysis Modal analysis is performed on the brake disc to determine its free natural frequency. The brake caliper pad geometry is suppressed while performing this analysis because the natural frequency of the brake disc is to be determined. The following figure shows the first natural frequency and its mode shape. The frequency obtained is 1614 Hz

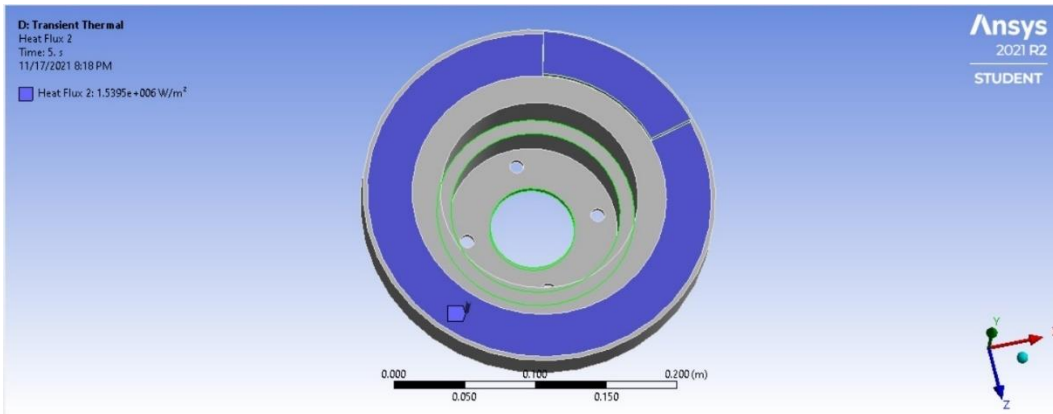


Modal Plot for the defined input parameter

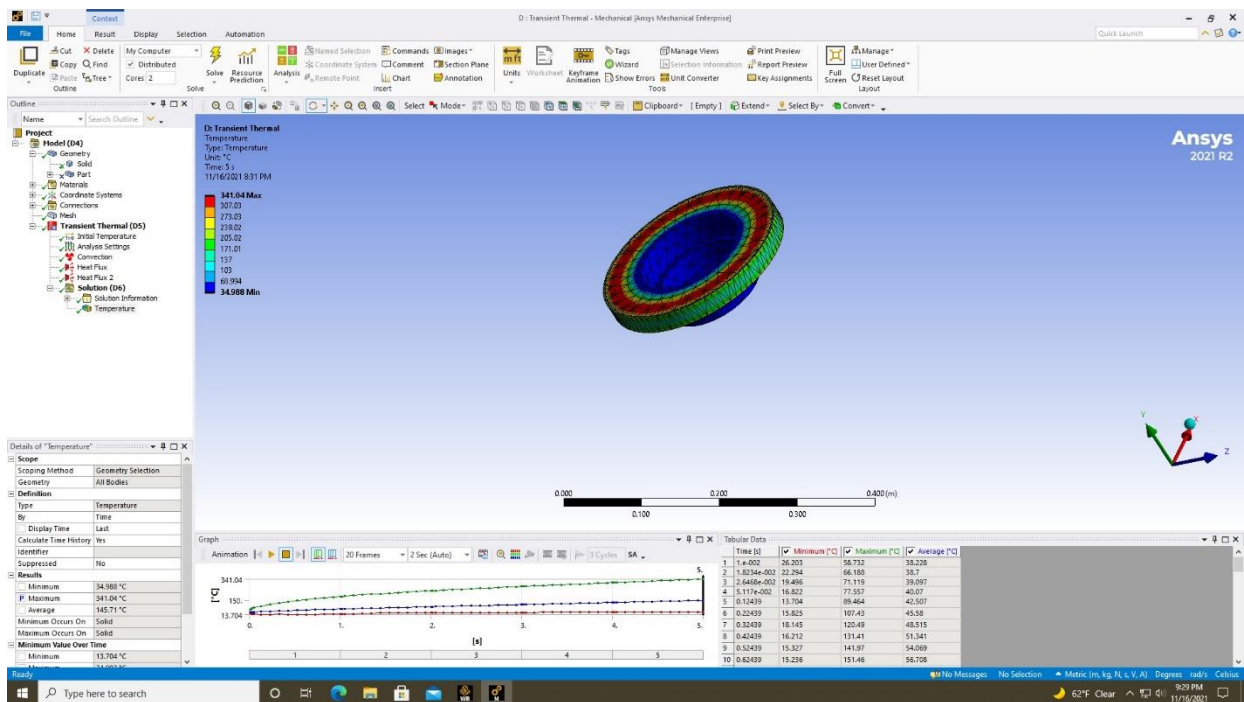
Thermal Analysis

Transient thermal analysis is performed on the disc to observe the maximum temperature rise after the braking operation. The brake caliper pad geometry is suppressed while performing this analysis.. It is assumed that 70% of the braking power is in the front axle of a four-wheeler vehicle. The total heat flux is also multiplied by 0.5 to get the flux generated by a single pad on the disc brake. Here, $t_e = 5s$; $A_{sp} = 0.021m^2$; $T_{amb} = 35 \text{ deg C}$.

The Heat flux is obtained as ,

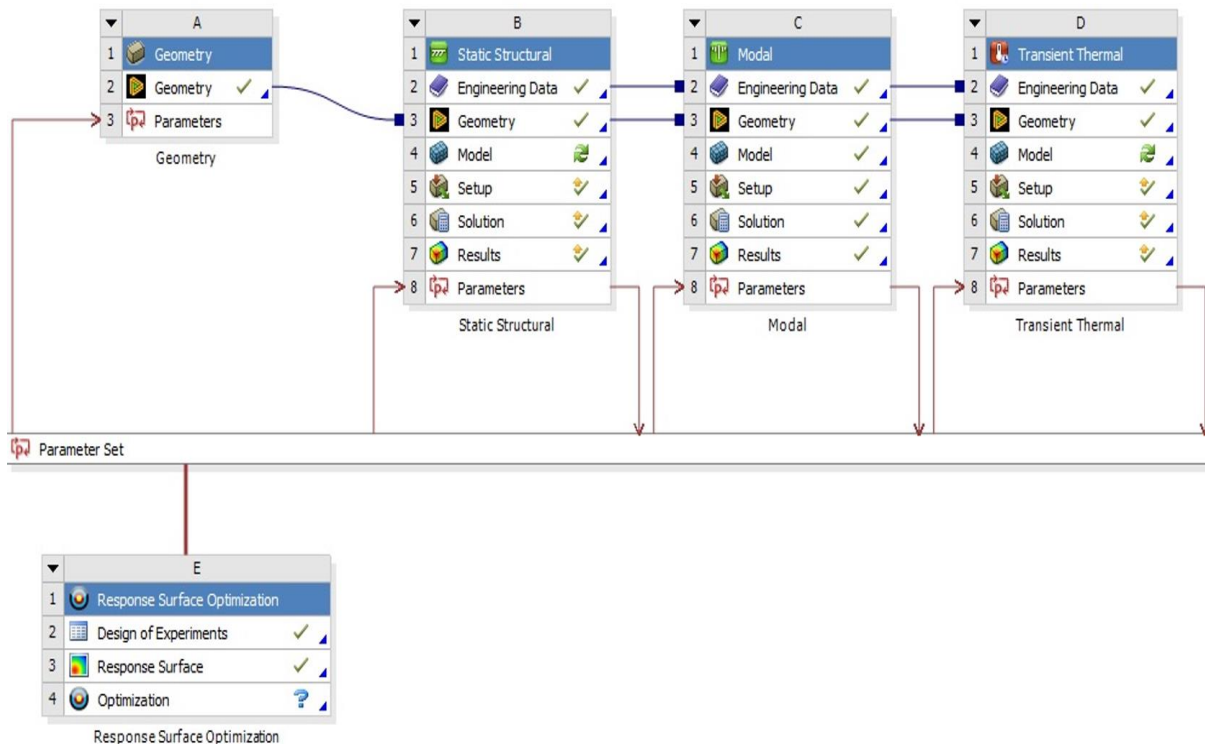


The temperature plot obtained . As observed, the maximum temperature of 341 deg C is obtained for initial conditions on the design variables.



Full Brake Model:

The model of the brake is analyzed in stages and the model is fed into next stages with the existing geometry and meshing conditions in the setup.



Design of Experiments:

It allows for multiple input factors to be manipulated, determining their effect on a desired output (response). By manipulating multiple inputs at the same time, DOE can identify important interactions that may be missed when experimenting with one factor at a time. All possible combinations can be investigated (full factorial) or only a portion of the possible combinations (fractional factorial).

A strategically planned and executed experiment may provide a great deal of information about the effect on a response variable due to one or more factors. Many experiments involve holding certain factors constant and altering the levels of another variable. This "one factor at a time" (OFAT) approach to process knowledge is, however, inefficient when compared with changing factor levels simultaneously.

Many of the current statistical approaches to designed experiments originate from the work of R. A. Fisher in the early part of the 20th century. Fisher demonstrated how taking the time to seriously consider the design and execution of an experiment before trying it helped avoid frequently

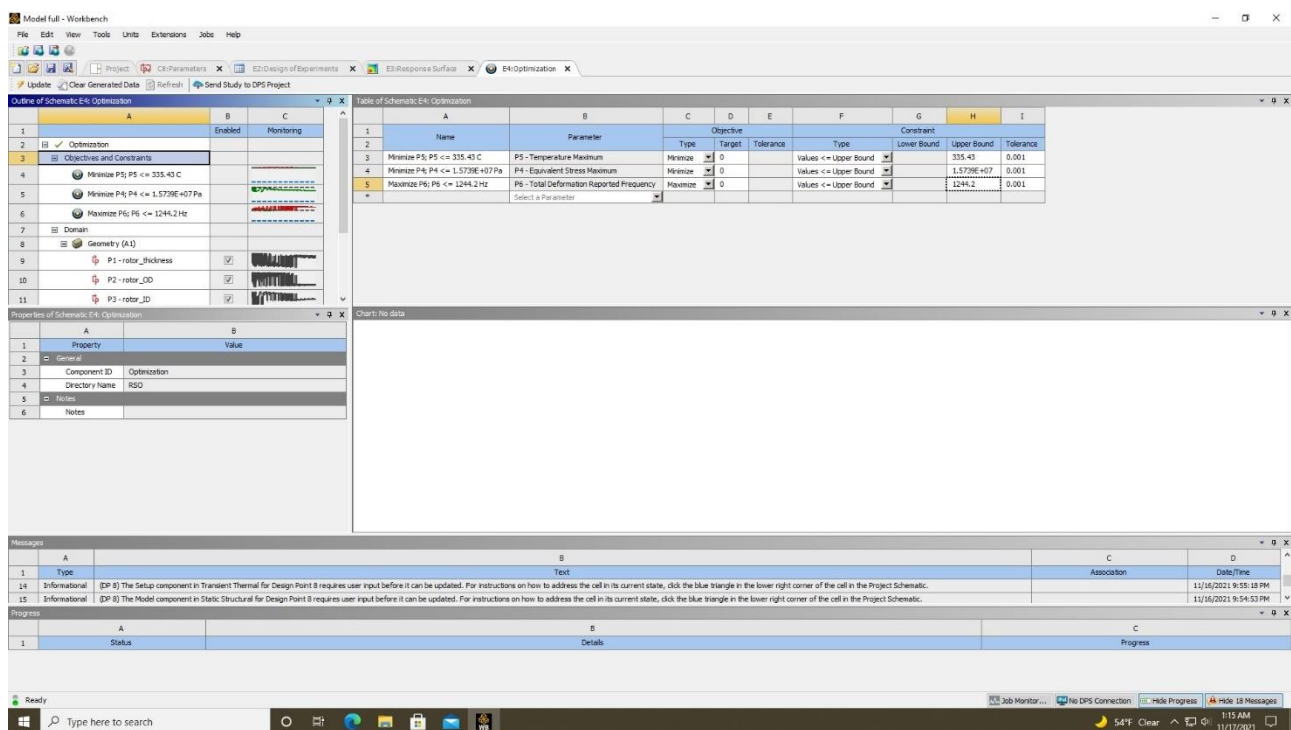
encountered problems in analysis. Key concepts in creating a designed experiment include blocking, randomization, and replication.

Blocking: When randomizing a factor is impossible or too costly, blocking lets you restrict randomization by carrying out all of the trials with one setting of the factor and then all the trials with the other setting.

Randomization: Refers to the order in which the trials of an experiment are performed. A randomized sequence helps eliminate effects of unknown or uncontrolled variables.

Replication: Repetition of a complete experimental treatment, including the setup.

The upper and lower bound limits for each of the following analysis is given and the DOE points are generated.



Outline of Schematic: E4: Optimization

Item	Name	Enabled	Monitoring
1	Optimization	Enabled	Monitoring
2	Objectives and Constraints		
3	Minimize P5: P5 <= 335.43 C		
4	Minimize P4: P4 <= 1.5779E+07 Pa		
5	Maximize P6: P6 <= 1244.2 Hz		
6	Domain		
7	Geometry (A1)		
8	P1 - rotor_thickness		
9	P2 - rotor_ID		
10	P3 - rotor_ID		

Table of Schematic: E4: Optimization

Item	Name	Parameter	Objective	Target	Tolerance	Constraint	Lower Bound	Upper Bound	Tolerance
1									
2	Minimize P5: P5 <= 335.43 C	P5 - Temperature Maximum	Minimize	0		Values <= Upper Bound	335.43		0.001
3	Minimize P4: P4 <= 1.5779E+07 Pa	P4 - Equivalent Stress Maximum	Minimize	0		Values <= Upper Bound	1.5779E+07		0.001
4	Maximize P6: P6 <= 1244.2 Hz	P6 - Total Deformation Reported Frequency	Maximize	0		Values <= Upper Bound	1244.2		0.001

Properties of Schematic: E4: Optimization

Item	Property	Value
1	General	
2	Component ID	Optimization
3	Directory Name	RO
4	Notes	
5	Notes	

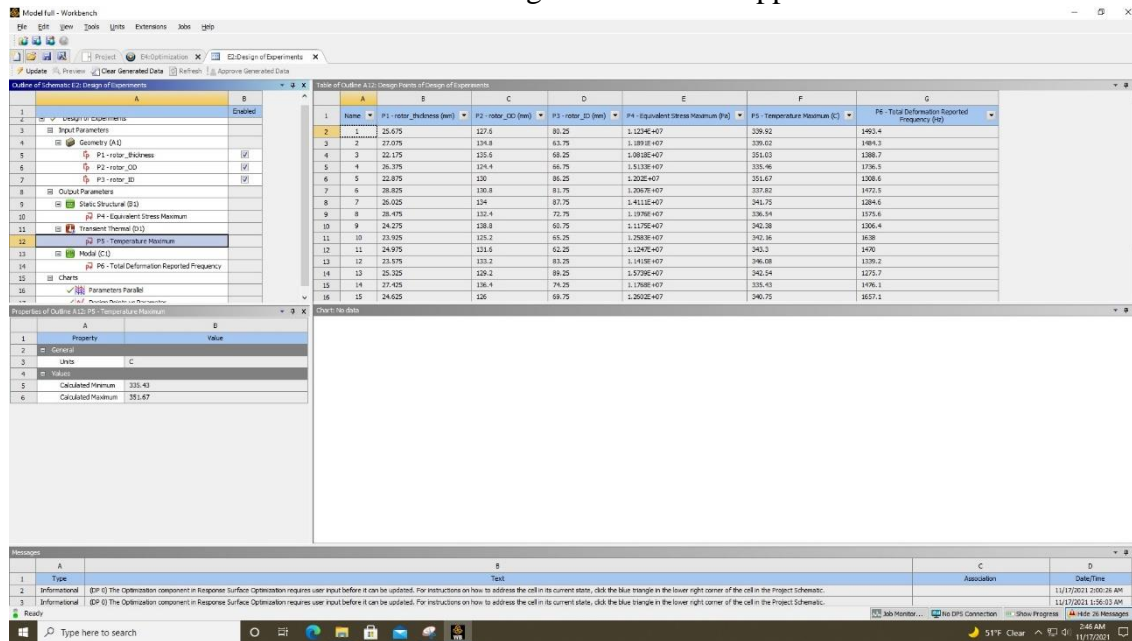
Messages

Item	Type	Text	Association	Date/Time
14	Informational	[DP B] The Setup component in Transient Thermal for Design Point B requires user input before it can be updated. For instructions on how to address the cell in its current state, click the blue triangle in the lower right corner of the cell in the Project Schematic.		11/16/2021 9:55:18 PM
15	Informational	[DP B] The Model component in Static Structural for Design Point B requires user input before it can be updated. For instructions on how to address the cell in its current state, click the blue triangle in the lower right corner of the cell in the Project Schematic.		11/16/2021 9:54:53 PM

Progress

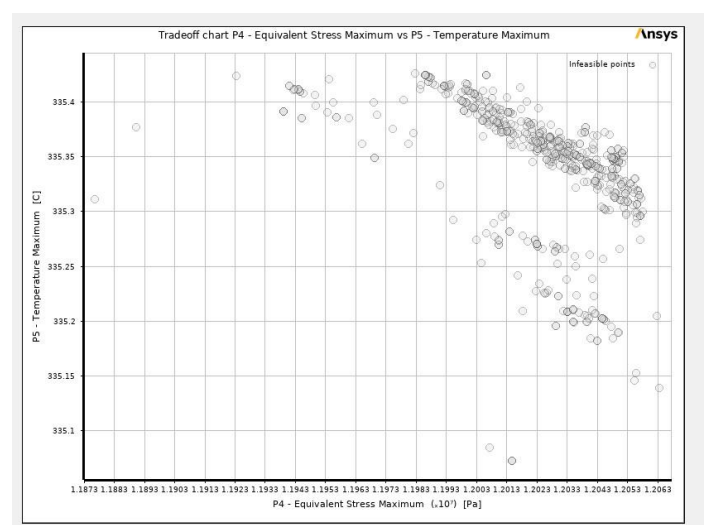
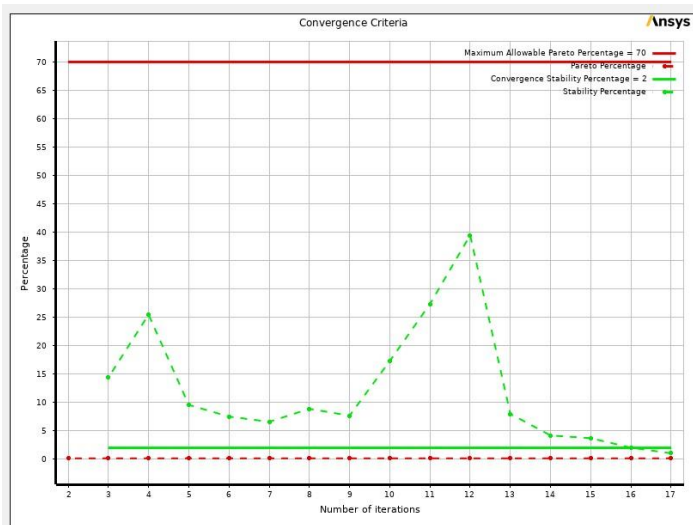
Item	Status	Details	Progress
1			

DOE results after the simulation for the given lower and upper bound values.

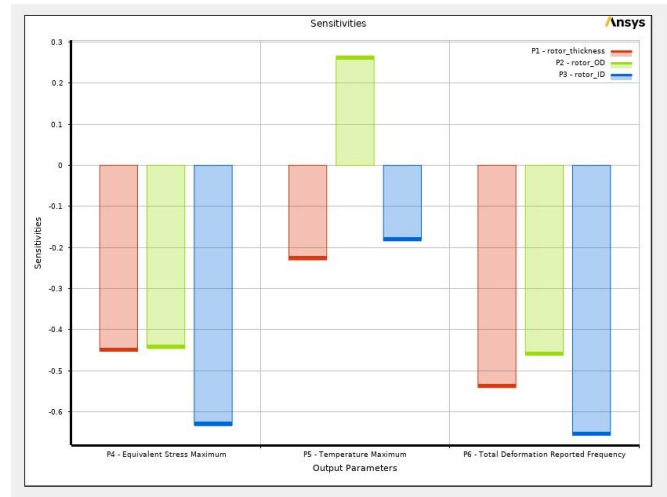
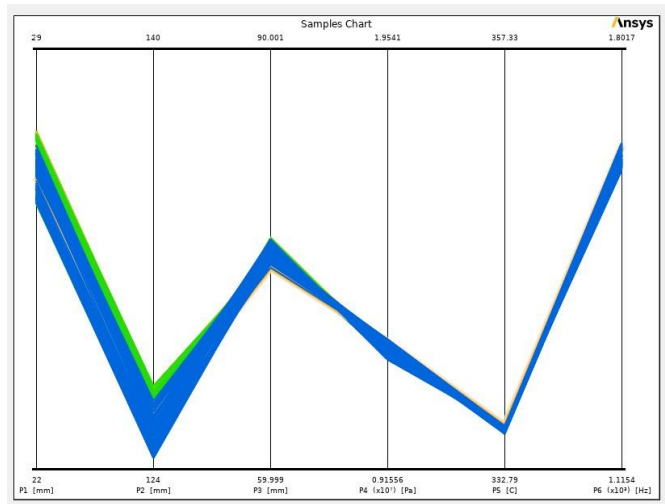


Response Surface:

After DOE, a response surface is generated for all the input and output values using the least squares methodology. The data points are fitted with a standard 2nd order model. The plots are generated for the convergence, Trade Off & Sensitivity.



The response surface enables us to track the change of the objective with respect to variable. When many variables exist, sensitivity analysis allows us to reduce the computational cost of the optimization.



Response Surface Optimization Study :

Single objective vs. Multi-objective

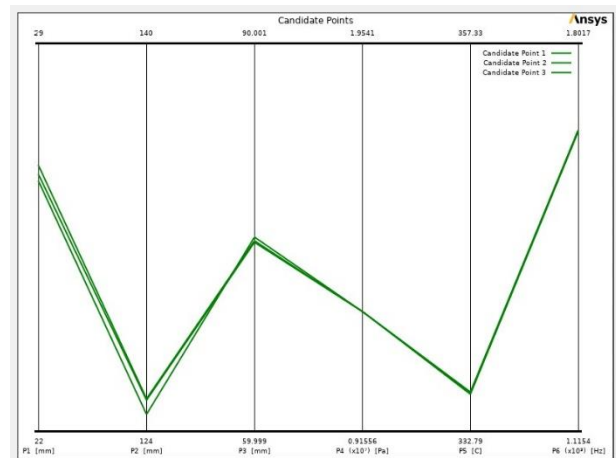
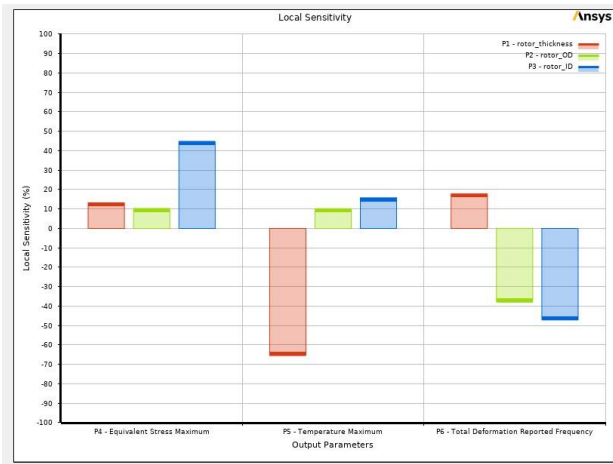
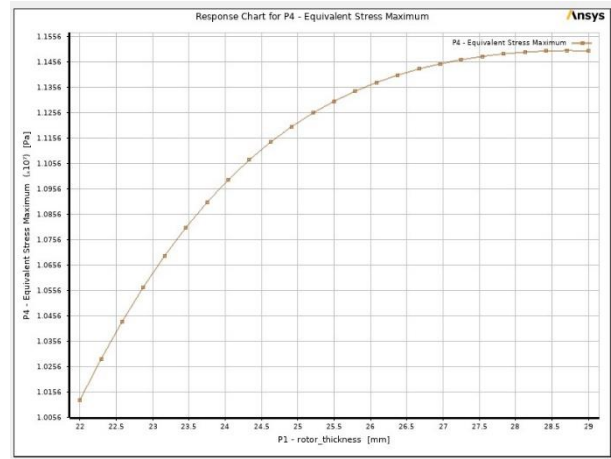
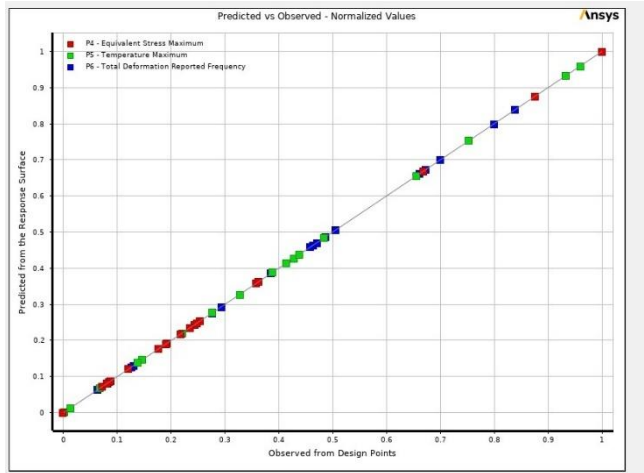
There is rarely a design case where we only want to optimize a single response. In the running example, a set of objectives are listed.

ANSYS provides a list of optimization algorithms:

- **Screening:** Randomly sampling the space and pick out the good ones. Use this as an initial trial to make sure everything is setup correctly, e.g., does your simulation give reasonable results?
- **Multiobjective Genetic Algorithm (MOGA):** Simultaneously find Pareto-optimal designs. Use this when you have multiple objectives. This is not the only choice for this situation though, see discussion above.
- **Nonlinear Programming by Quadratic Lagrangian (NLPQL):** Fast local search. Use this when (1) there is only one objective (but you can set other objectives as constraints), (2) the simulation does not take too long (in minutes), (3) the number of variables is small (less than 10).
- **Mixed-Integer Sequential Quadratic Programming (MISQP):** Similar to NLPQL, but allows integer variables. Note that the addition of integer variables will often significantly increase the computation time.
- **Adaptive Single-Objective Optimization (ASO):** This method uses Optimal Space Filling for DOE, Kriging as a response surface, and MISQP for finding local optimal solutions from the response surface. Use this when the evaluation of objective/constraints are expensive and you have limited budget/time for optimization.

- **Adaptive Multi-Objective Optimization (AMO):** Similar to ASO, this one uses Kriging and MOGA.

Rather than generating the plots of Response Surface , The response surface optimization method is used here. The models are solved for the existing conditions with Kriging Method and the responses from the same are recorded .



Figures depicting Convergence , Response Chart , Local Sensitivity & Candidate points for the optimization...

CONCLUSION

The critical factors can be determined by this analysis of Stress , Modal & Thermal. The purpose of Design of Experiments and the sensitivity analysis is to find a relationship between the input and the output parameter. The basic idea of kriging is to predict the value of a function at a given point by computing a weighted average of the known values of the function about the point. The method is mathematically closely related to regression analysis

References

- 1 Prof Yi Ren's Tutorial on the Design and Analysis in ANSYS in GitHub.
- 2 Project report by A. Durgude, A. Vipradas, S. Kishore, and S. Nimse.