

1. Another Approximation for Set Cover

Given a set of ground elements $U := \{e_1, \dots, e_n\}$, there is a collection $\mathcal{S} := \{S_1, \dots, S_m\}$ of subsets defined over U . The set cover problem seeks a minimum number of subsets from \mathcal{S} such that they cover all elements in the ground set.

In the lecture, we have seen that a greedy algorithm can achieve $O(\log n)$ -approximation and this is the best possible unless $P=NP$. Now, let us consider another greedy algorithm (Algorithm 1). We define the *frequency* of an element to be the number of sets that contain that element. Let f be the largest frequency among all elements.

Algorithm 1 Greedy Algorithm for Set Cover

- 1: $\mathcal{T} \leftarrow \emptyset$.
- 2: **while** there is an element not covered by \mathcal{T} **do**
- 3: Pick an arbitrary uncovered element e .
- 4: Add all sets containing e to \mathcal{T} .
- 5: **end while**
- 6: **return** \mathcal{T} .

$$U = \{e_1, e_2\} \quad \mathcal{S} = \{S_1, S_2, S_3\}$$

$$S_1 = \{e_1\} \quad S_2 = \{e_2\} \quad S_3 = \{e_1, e_2\}$$

$$f = 2 \quad \frac{2}{1} = f$$

$$\mathcal{T} = \{S_1, S_3\}$$

Q1. (5 marks) Prove that the approximation ratio of Algorithm 1 is at least f . Namely, construct a set cover instance such that if we run Algorithm 1 on that instance, the ratio between the output and the instance's optimal solution is exactly f .

Q2. (10 marks) Prove that Algorithm 1 is f -approximate.

Q3. (10 marks) Now, let us consider the following LP rounding algorithm for the set cover problem. For each set S , we have a variable x_S : $x_S = 1$ indicates that we select set S ; otherwise, we do not select the set S . Then, we have the following LP formulation (SC-LP). The second constraint ensures that for each element, one of the set includes the element is selected.

$$\min \sum_{S \in \mathcal{S}} x_S \quad (\text{SC-LP})$$

s.t.

$$\sum_{S: e \in S} x_S \geq 1 \quad \forall e \in U \quad (1)$$

$$x_S \geq 0, \quad \forall S \in \mathcal{S} \quad (2)$$

Now, we solve (SC-LP) above and obtain the optimal fractional solution $(x_S^*)_{S \in \mathcal{S}}$. Consider the following simple rounding algorithm:

$$\mathcal{T} := \{S \mid x_S^* \geq \frac{1}{f}\}.$$

Show that \mathcal{T} is a f -approximate solution.

$$\frac{1}{f} = 0.3 \quad x_{S_1}^* = 0.2 \quad x_{S_2}^* = 0.5 \quad \dots \quad x_{S_t}^* = 0.8$$

2. Another LP Rounding for Vertex Cover

Given an undirected graph $G := (V, E)$ and find a min-size subset of vertices $S \subseteq V$ such that every edge is incident to at least one vertex in S .

In the lecture, we have seen that the weighted version of the problem admits a 2-approximate algorithm via a simple LP rounding. For each vertex i , we have a variable x_i indicating whether we pick i or not; see (VC-LP).

min

$$\sum_{i \in V} x_i$$

(VC-LP)

s.t.

$$x_i + x_j \geq 1$$

$$\forall (i, j) \in E \quad (3)$$

$$x_i \geq 0,$$

$$\forall i \in V \quad (4)$$

Let $(x_i^*)_{i \in V}$ be the optimal fractional solution to (VC-LP). Now, we slightly change the parameter used in the lecture; recall that we used $\theta = 2$ in the lecture.

$$S = \left\{ i \in V \mid x_i^* \geq \frac{1}{\theta} \right\}, \quad \theta \geq 2.$$

Q1. (6 marks) Prove that the new rounding algorithm is a θ -approximate algorithm, and explain why θ must be some value larger than 2.

Q2. (9 marks) Show that the *integrality gap* of (VC-LP) is at least $2 - \epsilon$ for any $\epsilon > 0$. Namely, construct a vertex cover instance such that the ratio between the optimal solution to that instance and a fractional solution to (VC-LP) is $2 - \epsilon$.

$$|S| = \sum_{i \in S} 1 \leq \sum_{i \in S} \theta \cdot x_i^* \leq \sum_{i \in V} \theta \cdot x_i^* = \theta \cdot \sum_{i \in V} x_i^* \leq \theta \cdot \text{OPT}$$

$$\theta = \frac{3}{2} < 2 \quad S = \left\{ i \in V \mid x_i^* > \frac{2}{3} \right\} \quad x_i^* = \frac{1}{2} x_j^* \quad (i, j)$$

Q2: complete graph with n vertices

$$\leq \binom{n-1}{2}$$

OPT (integral): $\frac{n-1}{2}$

fraction: $\frac{n}{2}$

$$\frac{\frac{n-1}{2}}{\frac{n}{2}} = 2 - \frac{2}{n} \rightarrow 2 \quad n \rightarrow \infty$$

2

$$\epsilon > 0 \quad n = \frac{2}{\epsilon} \rightarrow 2 - \epsilon$$

3. Core and Shapley Value

Consider the following cooperative game:

$$v(C) = \begin{cases} 2, & \text{if } C = \{1\} \\ 3, & \text{if } C = \{2\} \\ 4, & \text{if } C = \{3\} \\ 6, & \text{if } C = \{1, 2\} \\ 8, & \text{if } C = \{1, 3\} \\ 5, & \text{if } C = \{2, 3\} \\ 16, & \text{if } C = \{1, 2, 3\} \end{cases}$$

$$v(C) \leq v(C') \text{ for } \forall C \subseteq C'$$

Q1. (4 marks) Is the game monotonic? Is the game superadditive?

Q2. (12 marks) Derive the Shapley value and show the steps.

Q3. (4 marks) Suppose the Shapley value is ϕ . Is $(\{1, 2, 3\}, \phi)$ in the core?

1 2 3
1 3 2
2 1 3
2 3 1
3 1 2
3 2 1

4. Boolean Games

In Boolean games, there are n players $N = \{1, \dots, n\}$ and a set of boolean variables Φ . Each player i has a subset Φ_i indicating the set of variables whose values are under player i 's control. No two players control one common variable and each variable in Φ is controlled by one player, i.e., (Φ_1, \dots, Φ_n) is a partition of Φ . Each player will choose a value (0 or 1) for each variable under her control. After each player makes her choices, each variable in Φ will have a value and ξ denotes a value profile of Φ where each entry of ξ specifies the value of each variable.

Each player i also has a goal θ_i which is a boolean formula over Φ . Player i gets utility 1 if θ_i is True under ξ and gets 0 otherwise. Note that a player's goal formula may include variables controlled by other players, and thus what utility a player can obtain depends not just on the choices she herself makes.

Definition 1. Given a value profile ξ , if there exist a coalition $S \subseteq N$ and a value profile $\xi' \neq \xi$ such that

1. $\xi = \xi'$ on those variables controlled by $i \in N \setminus S$, meaning that the values for those variables not controlled by players in S are the same in both ξ and ξ' ;
2. When deviating from ξ to ξ' , each player $i \in S$'s utility will change from 0 to 1, meaning that each player in the coalition S strictly prefers ξ' to ξ ,

then we say the coalition S **strictly prefers** ξ' to ξ .

Definition 2. A value profile ξ is in the **core**, if for any coalition $S \subseteq N$, there exists no value profile ξ' such that S strictly prefers ξ' to ξ .

Example 1. Suppose $N = \{1, 2\}$ with $\Phi = \{p, q\}$, $\Phi_1 = \{p\}$, $\Phi_2 = \{q\}$. θ_1 is $(p \wedge \neg q) \vee (\neg p \wedge q)$, θ_2 is $(\neg p \vee q) \wedge (p \vee \neg q)$. Then player 1 gets utility 1 by any value profile that gives p and q different values, while player 2 gets utility 1 by any value profile that gives p and q the same value.

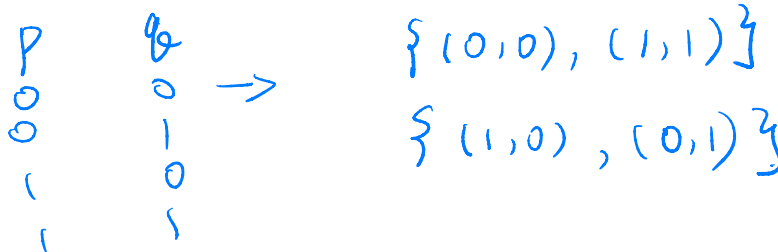
Definition 3. A **stable set** X is a set of value profiles, which have the property that they are both internally and externally stable,

1. **Internal stability:** If a value profile $\xi \in X$, for any coalition $S \subseteq N$, there exists no $\xi' \in X$ such that S strictly prefers ξ' to ξ ;
2. **External stability:** For any $\xi \notin X$, there exist a coalition S and a value profile $\xi' \in X$, such that S strictly prefers ξ' to ξ .

Q1. (6 marks) Given a value profile $\xi = (p = 0, q = 0)$, do there exist a coalition S and a value profile ξ' , such that S strictly prefers ξ' to ξ ? If yes, find the S and ξ' ; if no, explain why.

Q2. (6 marks) For the given example above, does there exist value profile(s) in the core? If yes, list all of them; if no, for each possible value profile ξ , find the corresponding coalition S and another value profile ξ' such that S strictly prefers ξ' to ξ .

Q3. (8 marks) Use the given example to show that there may exist multiple stable sets.



5. Hedonic Games:

In the context of **hedonic games**, a set of players form coalitions, and each player has preferences over which coalition they belong to, based solely on the members of the coalition. Consider the following scenario:

There are 5 players, denoted by $P = \{1, 2, 3, 4, 5\}$. Let \succ_i denote the **strict preference relation** of player i over coalitions. That is, for any two coalitions S and T where $i \in S$ and $i \in T$, we write $S \succ_i T$ if player i strictly prefers to be in coalition S rather than in coalition T . Each player has preferences over coalitions as follows:

- **Player 1:**

$$\{1, 2, 4\} \succ_1 \{1, 2, 3\} \succ_1 \{1\} \succ_1 \dots$$

- **Player 2:**

$$\{2, 3\} \succ_2 \{1, 2, 3\} \succ_2 \{2\} \succ_2 \dots$$

- **Player 3:**

$$\{2, 3\} \succ_3 \{3\} \succ_3 \dots$$

- **Player 4:**

$$\{4, 5\} \succ_4 \{4\} \succ_4 \dots$$

- **Player 5:**

$$\{4, 5\} \succ_5 \{5\} \succ_5 \dots$$

(2 3) (1 4 5)

Based on the preferences above, answer the following questions:

Q1. (5 marks) A coalition structure is **individually rational** if no player strictly prefers being alone (in a singleton coalition) over being in their current coalition. Is the coalition structure $\{\{1, 2\}, \{3, 4, 5\}\}$ individually rational for all players? Why or why not?

No
③

Q2. (5 marks) A coalition structure is in the **core** if there is no coalition S such that every player in S strictly prefers being in S to their current coalition. Is the coalition structure $\{\{1, 2, 3\}, \{4, 5\}\}$ core-stable? Why or why not?

No
→ {2, 3}

Q3. (10 marks) A coalition structure is **Nash-stable** if no player can benefit by unilaterally moving to a different coalition, including forming a singleton coalition. Find a Nash-stable partition. Justify your answer by explaining why no player has an incentive to deviate.

No

① $C = \{ \{2, 3\}, \dots \}$ player 1

② $C = \{ \{3\}, \dots \}$ player 2

③ $C = \{ \text{other than } ①② \}$ player 3