/bin/x86\_64-linux-gnu-g++-9 -g -rdynamic CMakeFiles/xolobot\_arm\_server.dir/src/startServerNode.cpp.o CMakeFiles/xolobot\_arm\_server.dir/src/SimulationController.cpp.o CMakeFiles/xolobot\_arm\_server.dir/src/SimulationState.cpp.o CMakeFiles/xolobot\_arm\_server.dir/src/NeuroControllerDriver.cpp.o CMakeFiles/xolobot\_arm\_server.dir/src/SimpleArmDriver.cpp.o CMakeFiles/xolobot\_arm\_server.dir/src/ArmDriver.cpp.o -o devel/lib/xolobot\_arm\_server/xolobot\_arm\_server -Wl,-rpath,/opt/ros/noetic/lib /opt/ros/noetic/lib/libroscpp.so -lpthread /usr/lib/x86\_64-linux-gnu/libboost\_chrono.so.1.71.0 /usr/lib/x86\_64-linux-gnu/libboost\_filesystem.so.1.71.0 /opt/ros/noetic/lib/librosconsole.so /opt/ros/noetic/lib/librosconsole\_log4cxx.so /opt/ros/noetic/lib/librosconsole\_backend\_interface.so -llog4cxx /usr/lib/x86\_64-linux-gnu/libboost\_regex.so.1.71.0 /opt/ros/noetic/lib/libxmlrpcpp.so /opt/ros/noetic/lib/libroscpp\_serialization.so /opt/ros/noetic/lib/librostime.so /usr/lib/x86\_64-linux-gnu/libboost\_date\_time.so.1.71.0 /opt/ros/noetic/lib/libcpp\_common.so /usr/lib/x86\_64-linux-gnu/libboost\_system.so.1.71.0 /usr/lib/x86\_64-linux-gnu/libboost\_thread.so.1.71.0 /usr/lib/x86\_64-linux-gnu/libconsole\_bridge.so.0.4 /usr/lib/x86\_64-linux-gnu/libfmt.a