

Elements of Statistics

Chapter 8: Estimation

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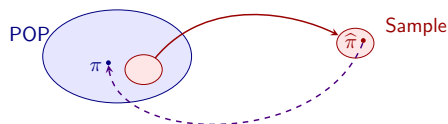
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8. Estimation | 8.1 Fundamentals

General idea

We are interested in population parameters which are generally unknown (here: π).

Before, we analysed populations using methods of descriptive statistics. Now, we draw a sample of the population and analyse this sample. The aim is to transfer results to the population (\rightarrow **point estimation**).



Additionally, we want to specify an interval of *plausible* values (\rightarrow **interval estimation**).

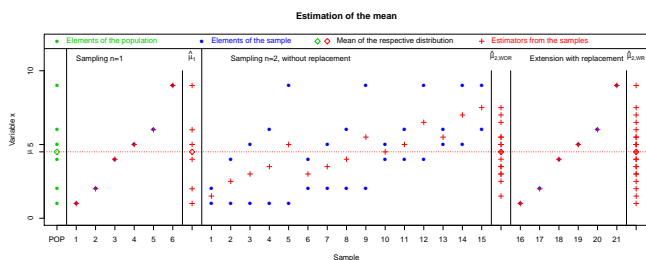
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8. Estimation | 8.1 Fundamentals

Distribution of the sample mean

We draw all possible samples of size $n = 1$ and $n = 2$, respectively, out of a population of $N = 6$ elements. We have:



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8. Estimation | 8.1 Fundamentals

Sample function and estimating function

Specification of an estimating function

An estimating function for an unknown population parameter π is a sample function which qualifies to be used to estimate the parameter π by virtue of its properties. It is labelled $u_\pi(x_1, \dots, x_n)$. The realisation of the estimating function is the estimate $\hat{\pi} = u_\pi(x_1, \dots, x_n)$.

Attention: We distinguish between the parameter to be estimated π , the estimate $\hat{\pi}$ and the distribution of the latter or the corresponding random variable. The latter results when we substitute the sample variables X_1, \dots, X_n for the corresponding realisations x_1, \dots, x_n . To be concrete, e. g. when estimating the mean of the population, we have μ and $\hat{\mu} = \bar{x}$. We label the distribution of the estimator $U_\pi(X_1, \dots, X_n)$ or U , and in this case \bar{X} . We may write $U(X_1, \dots, X_n|\pi)$ as well.

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Example 8.1: Four estimating functions (1)

We want to estimate the mean μ of the population. With a sample size of n we have four estimating functions at our disposal:

$$\hat{\mu}_1 = U_1(X_1, \dots, X_n | \pi) = \frac{1}{n} \sum_{i=1}^n X_i$$

$$\hat{\mu}_2 = U_2(X_1, \dots, X_n | \pi) = \frac{1}{n+1} \cdot \left(2 \cdot X_1 + \sum_{i=2}^n X_i \right)$$

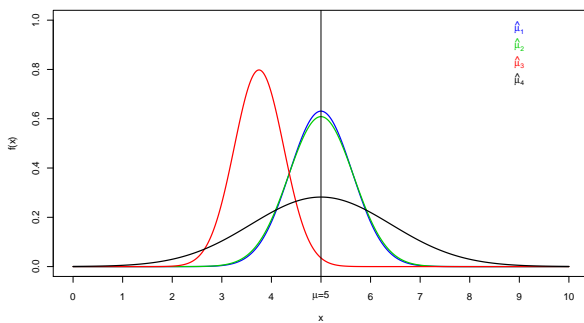
$$\hat{\mu}_3 = U_3(X_1, \dots, X_n | \pi) = \frac{1}{n+6} \cdot \left(2 \cdot X_1 + 2 \cdot X_n + \sum_{i=2}^{n-1} X_i \right)$$

$$\hat{\mu}_4 = U_4(X_1, \dots, X_n | \pi) = \frac{1}{2} \cdot (X_1 + X_n)$$

Notes

Example 8.1: Four estimating functions (2)

Let the population be normally distributed with parameters $\mu = 5$ and $\sigma^2 = 4$. We draw a sample of size $n = 10$ with replacement.



Notes

Example 8.1: Four estimating functions (3)

Calculation of $\hat{\mu}_1$, $\hat{\mu}_2$, $\hat{\mu}_3$ and $\hat{\mu}_4$ in R:

```
mu <- 5
sigma <- sqrt(4)
n <- 10

Mean_U1 <- 1/n * (n * mu)
Mean_U2 <- 1/(n + 1) * (2 * mu + 9 * mu)
Mean_U3 <- 1/(n + 6) * (2 * mu + 2 * mu + 8 * mu)
Mean_U4 <- 1/2 * (2 * mu)

Means <- cbind(Mean_U1, Mean_U2, Mean_U3, Mean_U4)

Means
```

```
      Mean_U1  Mean_U2  Mean_U3  Mean_U4
[1,]      5      5      3.75      5
```

Notes

Example 8.1: Four estimating functions (4)

Calculation of $\hat{\sigma}_1^2$, $\hat{\sigma}_2^2$, $\hat{\sigma}_3^2$ and $\hat{\sigma}_4^2$ in R:

```
Var_U1 <- (1/n)^2 * (n * sigma^2)
Var_U2 <- (2/(n + 1))^2 * sigma^2 + (1/(n + 1))^2 *
(9 * sigma^2)
Var_U3 <- (2/(n + 6))^2 * (2 * sigma^2) +
(1/(n + 6))^2 * (8 * sigma^2)
Var_U4 <- (1/2)^2 * (2 * sigma^2)

Variances <- cbind(Var_U1, Var_U2, Var_U3, Var_U4)

Variances
```

```
      Var_U1  Var_U2  Var_U3  Var_U4
[1,]    0.4 0.4297521    0.25      2
```

Notes

Example 8.1: Four estimating functions (5)

Creation of the graphics in R:

```
x8_1 <- seq(from = 0, to = 10, length.out = 1000)

f_x8_1_1 <- dnorm(x = x8_1, mean = Mean_U1,
                  sd = sqrt(Var_U1))
f_x8_1_2 <- dnorm(x = x8_1, mean = Mean_U2,
                  sd = sqrt(Var_U2))
f_x8_1_3 <- dnorm(x = x8_1, mean = Mean_U3,
                  sd = sqrt(Var_U3))
f_x8_1_4 <- dnorm(x = x8_1, mean = Mean_U4,
                  sd = sqrt(Var_U4))

plot(x = x8_1, y = f_x8_1_1, type = "l", xlab = "x",
     ylab = "f(x)", ylim = c(0,1), lwd = 2, col = "blue")
lines(x=x8_1,y=f_x8_1_2,type="l",lwd=2,col="green")
lines(x=x8_1,y=f_x8_1_3,type="l",lwd=2,col="red")
lines(x=x8_1,y=f_x8_1_4,type="l",lwd=2,col="black")
abline(v = 5)
```

Notes

Properties of estimating functions (1)

Definition 8.1 (Estimation error):

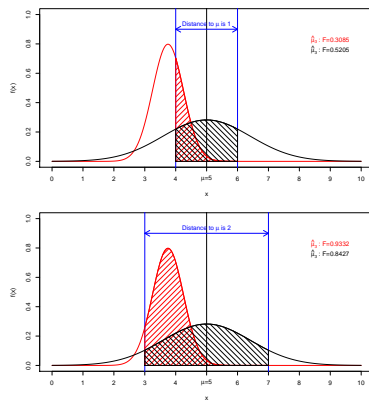
An estimation error e is the actual error resulting from an estimation:

$$e = \hat{\mu} - \mu.$$

- ▶ Sampling is *random*. Therefore, the results of the different estimating functions will most likely lead to different evaluations for different samples.
- ▶ How can we compare estimating functions with regard to differing sample realisations?
- ▶ How should estimating functions behave for large samples ($n \rightarrow \infty$)?
- ▶ To what extent are such considerations useful in practice?

Notes

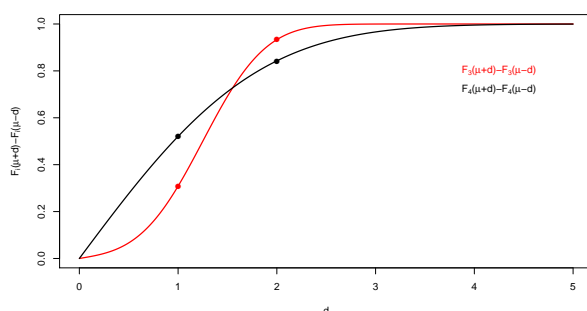
Example 8.2: see Ex. 8.1 (1)



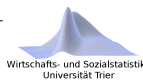
Notes

Example 8.2: see Ex. 8.1 (2)

Probability for the interval $[\mu - d; \mu + d]$ of the distributions of $\hat{\mu}_3$ and $\hat{\mu}_4$:



Notes



Properties of estimating functions (2)

Definition 8.2 (Unbiasedness):

An estimating function $U_\pi(X_1, \dots, X_n)$ (short hand: U) is called unbiased for parameter π if we have

$$E(U) = \pi.$$

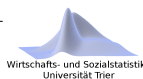
The *average* estimate is equal to the parameter to be estimated π . Otherwise it is called biased. The extent of the bias may be quantified as follows:

$$\text{Bias}(U) = E(U) - \pi.$$

We speak of asymptotical unbiasedness, if the following holds:

$$\lim_{n \rightarrow \infty} E(U_n) = \pi.$$

Notes



Example 8.3: see Ex. 8.1 (1)

The estimating function $U = \sum_i \gamma_i X_i$ with $\sum_i \gamma_i = 1$ is unbiased because

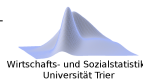
$$E U = \sum_{i=1}^n \gamma_i \cdot \underbrace{E X_i}_{=\mu} = \mu \sum_{i=1}^n \gamma_i = \mu.$$

Therefore, $\hat{\mu}_1$, $\hat{\mu}_2$ and $\hat{\mu}_4$ are unbiased as their weights are $\gamma_i = 1/n$ for $\hat{\mu}_1$, $\gamma_1 = 2/(n+1)$ and $\gamma_i = 1/(n+1)$ ($i > 1$) for $\hat{\mu}_2$ as well as $\gamma_1 = \gamma_n = 1/2$ and $\gamma_i = 0$ ($i \neq 1, n$) for $\hat{\mu}_4$.

For $\hat{\mu}_3$ follows:

$$\begin{aligned} E U_3 &= E \left(\frac{1}{n+6} \cdot (2 \cdot X_1 + 2 \cdot X_n + \sum_{i=2}^{n-1} X_i) \right) \\ &= \frac{1}{n+6} \cdot (2 \cdot E X_1 + 2 \cdot E X_n + \sum_{i=2}^{n-1} E X_i) = \frac{n+2}{n+6} \cdot \mu. \end{aligned}$$

Notes



Example 8.3: see Ex. 8.1 (2)

Calculations for $\hat{\mu}_3$ in R:

```
Mean_U3 <- (n + 2) / (n + 6) * mu
Mean_U3
[1] 3.75
```

U_3 is biased but asymptotically unbiased as $\lim_{n \rightarrow \infty} \frac{n+2}{n+6} \cdot \mu = \mu$.

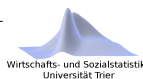
Calculation of the bias of $\hat{\mu}_3$ in R:

```
Bias_U3 <- Mean_U3 - mu
Bias_U3
[1] -1.25
```

Calculation of the bias with $n = 10,000$ in R:

```
n_new <- 10000
Bias_U3_new <- (n_new + 2) / (n_new + 6) * mu - mu
round(Bias_U3_new, digits = 4)
[1] -0.002
```

Notes



Example 8.4:

The estimating function $p = \hat{\theta}$ is unbiased for the proportion θ of a certain type of interest in the population. This follows immediately from an application of the arithmetic mean in Example 8.3 on dichotomous variables.

Example 8.5:

The sample variance

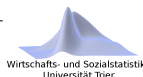
$$S^2 = \frac{1}{n-1} \cdot \sum_{i=1}^n (X_i - \bar{X})^2$$

is unbiased for the population variance σ^2 . Therefore,

$$S^{*2} = \frac{1}{n} \cdot \sum_{i=1}^n (X_i - \bar{X})^2$$

must be biased. Nevertheless, S^{*2} is asymptotically unbiased.

Notes



Example 8.6: Two estimating functions

For the estimation of population parameter π we have two different unbiased estimating functions U_1 and U_2 at our disposal. We only know that $\text{Var } U_1 = 0.9 \cdot \text{Var } U_2$. Using Tchebysheff's inequality (theorem 7.2) we have:

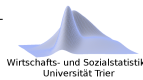
$$P(|U_1 - \pi| \geq \varepsilon) \leq \frac{\text{Var } U_1}{\varepsilon^2} = 0.9 \cdot \frac{\text{Var } U_2}{\varepsilon^2}$$

$$P(|U_2 - \pi| \geq \varepsilon) \leq \frac{\text{Var } U_2}{\varepsilon^2}.$$

The probability of *committing* an estimation error of at least ε is smaller for U_1 and depends on the variance of the estimating functions. In case of biased estimating functions we may use the extended version of Tchebysheff's inequality (see Schaich and Münnich, 2001, p. 21):

$$P(|U_2 - \pi| \geq \varepsilon) \leq \frac{\text{Var } U_2 + (\text{E } U_2 - \pi)^2}{\varepsilon^2} = \frac{\overbrace{\text{Var } U_2 + \text{Bias}^2(U_2)}^{:= \text{MSE}(U_2)}}{\varepsilon^2}.$$

Notes



Properties of estimating functions (3)

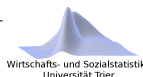
Definition 8.3 (Efficiency):

An unbiased estimating function U is called efficient (best) estimating function for parameter π if there is no other unbiased estimating function U' for π with $\text{Var}(U') \leq \text{Var}(U)$.

Out of a number of unbiased estimating functions we choose the one with the smallest variance.

In practice, it's far from easy to find the best estimating function. With the aid of sufficient estimating functions (estimating functions that use all information of a sample about the parameter that one wants to estimate) and the Rao-Blackwell theorem, one can construct *better* estimating functions (see lecture *Elements of Statistics and Econometrics* in the masters program *M.Sc. Applied Statistics*).

Notes



Example 8.7: Arithmetic mean

Out of the linear unbiased estimating functions, the arithmetic mean is the best estimating function for μ . Using the Lagrange multiplier we get:

$$\frac{\partial \left[\text{Var} \left(\sum_{i=1}^n \gamma_i X_i \right) + \lambda \left(1 - \sum_{i=1}^n \gamma_i \right) \right]}{\partial \gamma_i} =$$

$$\frac{\partial}{\partial \gamma_i} \left[\sum_{i=1}^n \gamma_i^2 \text{Var } X_i + \lambda \left(1 - \sum_{i=1}^n \gamma_i \right) \right] =$$

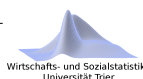
$$\frac{\partial}{\partial \gamma_i} \left[\sigma^2 \cdot \sum_{i=1}^n \gamma_i^2 + \lambda \left(1 - \sum_{i=1}^n \gamma_i \right) \right] =$$

$$\sigma^2 \cdot 2 \cdot \gamma_i - \lambda \stackrel{!}{=} 0.$$

Finally, after equating we get $\gamma_i = \gamma_j$ for all $i, j = 1, \dots, n$ and therefore the proposition.

We say that the arithmetic mean is the *best linear unbiased estimator* (BLUE) for μ .

Notes



Properties of estimating functions (4)

Definition 8.4 (Consistency):

An estimating function $U(X_1, \dots, X_n | \pi)$ is called consistent for the estimation of the population parameter π if

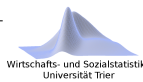
$$\lim_{n \rightarrow \infty} P(|U_n - \pi| > \varepsilon) = 0$$

for any arbitrarily small $\varepsilon > 0$.

We say that U_n converges stochastically to the parameter to be estimated π .

Notes

Example 8.8: Consistency of \bar{X}



\bar{X}_n is the arithmetic mean for sample size n (with replacement). Using Tchebysheff's inequality and $\text{Var } \bar{X}_n = \text{Var } X/n$ (\bar{X}_n is unbiased) we get

$$\begin{aligned} P(|\bar{X}_n - E \bar{X}_n| > \varepsilon) &\leq P(|\bar{X}_n - \mu| \geq \varepsilon) \\ &\leq \frac{\text{Var } \bar{X}_n}{\varepsilon^2} = \frac{\text{Var } X}{n \cdot \varepsilon^2} \end{aligned}$$

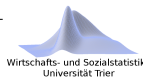
for every $\varepsilon > 0$. Finally, we then have

$$0 \leq \lim_{n \rightarrow \infty} P(|\bar{X}_n - E \bar{X}_n| > \varepsilon) \leq \lim_{n \rightarrow \infty} \frac{\text{Var } X}{n \cdot \varepsilon^2} = 0 \quad .$$

\bar{X}_n is consistent.

Notes

Methods to gain estimating functions



► Ordinary least squares (OLS):

The sum of the squared errors is minimised. Examples are the OLS regression (see Chapter 4) or $\hat{\mu}_{KQ}$:

$$\sum_i (x_i - \hat{\mu}_{KQ})^2 \rightarrow \min \text{ leads to } \hat{\mu}_{KQ} = \bar{x}.$$

► Method of moments:

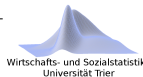
The empirical moments $\frac{1}{n} \sum_i x_i^k$ are made equal to the theoretical moments $E(X^k)$. From this, one obtains the estimates. With $\hat{\mu} = \bar{x}$ and $\hat{\mu}^2 + \hat{\sigma}^2 = \frac{1}{n} \sum_i x_i^2$ for $k = 1, 2$, one would finally $\hat{\sigma}^2 = s^{*2}$ with unknown μ .

► Maximum Likelihood method (ML)

► Bayesian estimation

Notes

Maximum Likelihood method



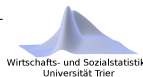
Given the n stochastically independent realisations of a random sample, the explicit parameters of a known distribution have to be estimated. From the set of all possible estimates, those estimates are selected which have the highest probability or probability density given the available sample result. Hence:

$$\begin{aligned} L(x_1, \dots, x_n | \hat{\pi}_1, \dots, \hat{\pi}_r) &= \max_{\pi_1, \dots, \pi_r} L(x_1, \dots, x_n | \pi_1, \dots, \pi_r) \\ &= \max_{\pi_1, \dots, \pi_r} \prod_{i=1}^n f(x_i | \pi_1, \dots, \pi_r) \quad . \end{aligned}$$

In most cases, the log likelihood function $\ln L$ is maximized instead of the likelihood function L , whereby a sum instead of a product is maximized.

Notes

Properties of the Maximum Likelihood method



- Given there is an efficient estimate for a parameter π , the ML method yields it
- ML estimation functions are consistent, but generally not unbiased
- ML estimators are asymptotically normal distributed for $n \rightarrow \infty$
- If U is an ML estimation function for π , then $\tau(U)$ is also an ML estimation function for a wide class of functions τ

Notes



Example 8.9: One urn, two colours (1)

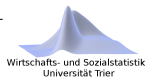
An urn contains $N = 50$ balls. Those balls are either black or yellow but the respective proportions θ are unknown. A sample of size $n = 10$ (WR) yields four black balls. We are looking for the θ which maximizes $b(4|10; \theta)$. Because of $N = 50$, θ can only be a multiple of 0.02. Resulting in:

θ	0.34	0.36	0.38	0.40	0.42	0.44	0.46
$b(4 10; \theta)$	0.2320	0.2424	0.2487	0.2508	0.2488	0.2427	0.2331

Creation of the table in R:

```
x8_9 <- 4
n <- 10
theta <- seq(from = 0.34, to = 0.46, by = 0.02)
theta
[1] 0.34 0.36 0.38 0.40 0.42 0.44 0.46
f_x8_9 <- dbinom(x = x8_9, size = n, prob = theta)
round(f_x8_9, digits = 4)
[1] 0.2320 0.2424 0.2487 0.2508 0.2488 0.2427 0.2331
```

Notes



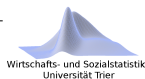
Example 8.9: One urn, two colours (2)

Thus, $\hat{\theta} = 0.4$ is used as the ML estimate in this case.

Determination of $\hat{\theta} = 0.4$ in R:

```
theta_hat <- theta[which.max(f_x8_9)]
theta_hat
[1] 0.4
```

Notes



Example 8.10: ML estimation of θ - Binomial distribution (1)

In a sample of size n , the outcome 1 results $n \cdot p$ times whereas the outcome 0 results $n \cdot (1 - p)$ times. Thus, the likelihood function is given by:

$$L(x_1, \dots, x_n | \theta) = \prod_{i=1}^n \theta^{x_i} \cdot (1 - \theta)^{1-x_i} = \theta^{np} \cdot (1 - \theta)^{n(1-p)}.$$

Taking the logarithm results in:

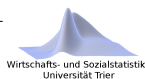
$$\ln L(x_1, \dots, x_n | \theta) = np \ln \theta + n(1 - p) \ln(1 - \theta)$$

finally, differentiation yields

$$\frac{\partial \ln L(x_1, \dots, x_n | \theta)}{\partial \theta} = \frac{np}{\theta} - \frac{n(1-p)}{1-\theta} \stackrel{!}{=} 0.$$

Thus the necessary criterion for a maximum finally results in $\hat{\theta} = p$.
Sufficient criterion still has to be checked!

Notes



Example 8.10: ML estimation of θ - Binomial distribution (2)

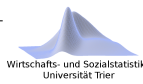
Log likelihood and partial derivative in R:

```
Log_Likelihood <- expression(n * p * log(Theta) +
                             n * (1 - p) * log(1 - Theta))

D_Log_Likelihood <- D(expr = Log_Likelihood, name = "Theta")
Log_Likelihood
expression(n * p * log(Theta) + n * (1 - p) * log(1 - Theta))

D_Log_Likelihood
n * p * (1/Theta) - n * (1 - p) * (1/(1 - Theta))
```

Notes



Example 8.11:

ML estimation of μ and σ^2 of a normal distribution I

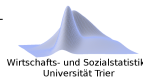
The following is valid:

$$\begin{aligned} L(x_1, \dots, x_n | \mu; \sigma^2) &= \prod_{i=1}^n \frac{1}{\sqrt{2\pi}\sigma} \cdot \exp\left(-\frac{1}{2}\left(\frac{x_i - \mu}{\sigma}\right)^2\right) \\ &= \left(\frac{1}{2\pi\sigma^2}\right)^{n/2} \cdot \exp\left(-\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2\right) \end{aligned}$$

or:

$$\ln L(x_1, \dots, x_n | \mu; \sigma^2) = -\frac{n}{2} \ln(2\pi\sigma^2) - \frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2.$$

Notes



Example 8.11:

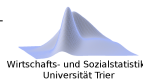
ML estimation of μ and σ^2 of a normal distribution II

Finally, partial derivation with respect to the parameters μ and σ^2

$$\begin{aligned} \frac{\ln L(x_1, \dots, x_n | \mu; \sigma^2)}{\partial \mu} &= \frac{1}{2\sigma^2} \cdot 2 \cdot \sum_{i=1}^n (x_i - \mu) \stackrel{!}{=} 0 \quad \text{and} \\ \frac{\ln L(x_1, \dots, x_n | \mu; \sigma^2)}{\partial \sigma^2} &= -\frac{n}{2} \cdot \frac{1}{\sigma^2} + \frac{1}{2\sigma^4} \sum_{i=1}^n (x_i - \mu)^2 \stackrel{!}{=} 0 \end{aligned}$$

yields the estimators $\hat{\mu} = \bar{x}$ and $\hat{\sigma}^2 = s^{*2}$.

Notes



Bayesian estimation (see Fahrmeir et al., 2016)

- ▶ x_1, \dots, x_n are n independent realisations of a random variable X which follows a distribution F with parameter θ
- ▶ θ is a realisation of a random variable Θ
- ▶ $f(x, \theta)$ is the joint density; $f(x|\theta)$ is the conditional and $f(x)$ the boundary distribution of X
- ▶ $f(\theta)$ is the a-priori distribution of the parameter Θ
- ▶ $f(\theta|x)$ is the a-posteriori distribution of Θ

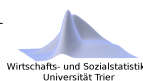
Bayesian inference

Let $f(x|\theta)$ be the density of X given θ and $L(\theta) = f(x_1, \dots, x_n|\theta)$ constitutes the corresponding likelihood function. Then, the a-priori density $f(\theta)$ can be used to derive the a-posteriori density of θ

$$f(\theta|x_1, \dots, x_n) = \frac{f(x_1|\theta) \dots f(x_n|\theta) \cdot f(\theta)}{\int f(x_1|\theta) \dots f(x_n|\theta) \cdot f(\theta) d\theta} = \frac{L(\theta)f(\theta)}{\int L(\theta)f(\theta) d\theta}$$

(discrete distributions and multidimensional Θ are also possible).

Notes



Bayesian estimator und Bayesian learning

A-posteriori expected value

$$\hat{\theta}_E = E(\theta|x_1, \dots, x_n) = \int \theta f(\theta|x_1, \dots, x_n) d\theta$$

Maximum a-posteriori estimator (MAP)

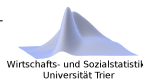
$$\hat{\theta}_{\text{MAP}} = \arg \max_{\theta} L(\theta)f(\theta) \quad \text{or} \quad \hat{\theta}_{\text{MAP}} = \arg \max_{\theta} (\ln L(\theta) + \ln f(\theta))$$

The calculation of the a-posteriori density of θ is often no longer analytically feasible \rightarrow numerical or Monte Carlo integration or MCMC.

If the a-priori distribution of Θ is very *flat* (non-informative prior), then one obtains the Maximum Likelihood estimation. Otherwise, the subjective conceptions of the a-priori distribution is used in the estimation.

Notes

Example 8.12: see Fahrmeir et al., 2016



Let x_1, \dots, x_n be independent realisations from $X \sim N(\mu, \sigma^2)$ with known σ^2 . We want to estimate the parameter μ . We use $N(\mu_0, \sigma_0^2)$ as a-priori density for the parameter we want to estimate. σ_0^2 controls the precision of the a-priori information.

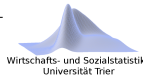
With some effort, we can show that the a-posteriori distribution of μ is

$$\mu | x_1, \dots, x_n \sim N\left(\frac{n\sigma_0^2}{n\sigma_0^2 + \sigma^2} \bar{X} + \frac{\sigma^2}{n\sigma_0^2 + \sigma^2} \mu_0; \frac{\sigma^2}{n + \sigma^2/\sigma_0^2}\right)$$

The *trust parameter* σ_0^2 controls the evaluation of the sample information. If σ_0^2 is very large ($\rightarrow \infty$), then we obtain the classical MLE. If on the other hand σ_0^2 is very small, then the a-priori information changes little with the sample information.

Notes

General idea of interval estimation



Besides the point estimate derived from the sample, we need some kind of *quality criterion* for this point estimate. Some options:

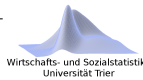
- ▶ Variance of the estimator
(requires an approximate normal distribution)
- ▶ Standard error (standard deviation of estimator)
- ▶ Coefficient of variation of estimate

The problem of each of those options is that missing information regarding the population forces us to *estimate* their respective values using the sample.

Another option is to state a certain *range of variation* around the point estimate. We would like to state an interval based on quantiles of an estimator's distribution, like $[x_{0.025}; x_{0.975}]$.

Notes

Example 8.13: Random interval (1)



Let the random variable X be normally distributed with known variance $\sigma^2 = 900$. To estimate the population mean μ we draw a sample of size $n = 36$ with replacement.

We use the estimator \bar{X} . We use

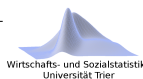
- ▶ $\bar{X}_l = \bar{X} + z(0.025) \cdot \frac{\sigma}{\sqrt{n}} = \bar{X} - 1.96 \cdot 5 = \bar{X} - 9.8$
- ▶ $\bar{X}_u = \bar{X} + z(0.975) \cdot \frac{\sigma}{\sqrt{n}} = \bar{X} + 1.96 \cdot 5 = \bar{X} + 9.8$

as the limits of the interval motivated above. We get the following random interval $[\bar{X}_l, \bar{X}_u] = [\bar{X} - 9.8; \bar{X} + 9.8]$.

What is the probability that the parameter to be estimated μ lies within the limits of this random interval?

Notes

Example 8.13: Random interval (2)



$$\begin{aligned} P(\bar{X}_l \leq \mu \leq \bar{X}_u) &= P(\bar{X} - 9.8 \leq \mu \leq \bar{X} + 9.8) \\ &= P(-9.8 \leq \bar{X} - \mu \leq 9.8) \\ &= P\left(-1.96 \leq \underbrace{\frac{\bar{X} - \mu}{5}}_{\sim \text{SND}} \leq 1.96\right) \\ &= 0.975 - 0.025 = 0.95 \end{aligned}$$

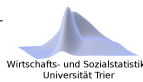
A random interval constructed in this fashion *covers* the true parameter μ with a probability of 95%.

Data input of relevant parameters in R:

```
alpha <- 0.05
sigma <- 30
n <- 36
```

Notes

Example 8.13: Random interval (3)

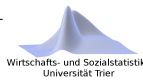


Attention:

Such a statement may only be given in terms of probabilities and therefore only **before** an experiment is carried out. As soon as a concrete interval $[\bar{x}_l, \bar{x}_u]$ is determined, we can only state if the true parameter is covered by the interval or not. But in reality this information will not be available in most cases.

Notes

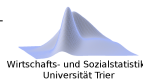
Confidence intervals (1)



- ▶ As we assume that the probability of the interval $[\bar{X}_l, \bar{X}_u]$ covering the true parameter μ is 0.95 before the experiment is carried out,
 - ▶ we have a respective level of *confidence* that
 - ▶ the true parameter actually lies within the limits of the confidence interval after the experiment has been carried out.
- ▶ Therefore, the interval $[\bar{X}_l, \bar{X}_u]$ is called 95% confidence interval for μ .
- ▶ Generally, depending on the question at hand, we use values of 0.95, 0.99 or 0.90.

Notes

Confidence intervals (2)



Definition 8.5 (Confidence interval):

Let the confidence level $(1 - \alpha)$ be given. The interval $[\pi_l, \pi_u]$ with $\pi_l = f(X_1, \dots, X_n)$ and $\pi_u = f(X_1, \dots, X_n)$ ($\pi_l \leq \pi_u$) is called $(1 - \alpha)$ confidence interval for π , if we have $P(\pi_l \leq \pi \leq \pi_u) = 1 - \alpha$.

Questions about the properties of such a confidence interval, like its symmetry or its minimal length, immediately arise.

Notes

CI for μ , POP is normally distributed, σ^2 is known

The random variable

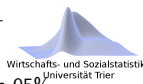
$$Z = \frac{\bar{X} - \mu}{\sigma} \cdot \sqrt{n}$$

follows the standard normal distribution. The resulting $(1 - \alpha)$ confidence interval is

$$\left[\bar{X} - z(1 - \alpha/2) \cdot \frac{\sigma}{\sqrt{n}}; \bar{X} + z(1 - \alpha/2) \cdot \frac{\sigma}{\sqrt{n}} \right].$$

- ▶ This $(1 - \alpha)$ confidence interval is as short as possible and is symmetric to \bar{X} .
- ▶ The larger σ , the longer the CI
- ▶ The larger n , the shorter the CI
- ▶ The larger $(1 - \alpha)$, the longer the CI

Notes



Example 8.14: see Ex. 8.13

The evaluation of the sample yielded $\bar{x} = 72$. Therefore, the 95% confidence interval is

$$\left[72 - 1.96 \cdot \frac{30}{\sqrt{36}}; 72 + 1.96 \cdot \frac{30}{\sqrt{36}}\right]$$

and finally

$$[62.2; 81.8]$$

95% confidence interval in R:

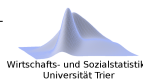
```
SpMean <- 72
CI <- vector()
CI[1] <- SpMean - qnorm(p = 1 - (alpha/2))*(sigma/sqrt(n))
CI[2] <- SpMean + qnorm(p = 1 - (alpha/2))*(sigma/sqrt(n))

CI_lower_alternative <- SpMean + qnorm(p = alpha/2) *
  (sigma/sqrt(n))

round(CI, digits = 1)

[1] 62.2 81.8
```

Notes



CI for μ , POP is normally distributed, σ^2 is unknown

The random variable

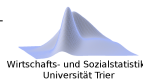
$$T = \frac{\bar{X} - \mu}{S} \cdot \sqrt{n}$$

follows the t distribution with $n - 1$ degrees of freedom. The resulting $(1 - \alpha)$ confidence interval is

$$\left[\bar{X} - t\left(1 - \frac{\alpha}{2}, n - 1\right) \cdot \sqrt{\frac{S^2}{n}}; \bar{X} + t\left(1 - \frac{\alpha}{2}, n - 1\right) \cdot \sqrt{\frac{S^2}{n}}\right].$$

- ▶ We have $\frac{n-1}{\sigma^2} \cdot S^2 = \frac{1}{\sigma^2} \sum_{i=1}^n (X_i - \bar{X})^2 \sim \chi_{n-1}^2$.
- ▶ Cochran's theorem holds and therefore $\frac{1}{\sigma^2} S^2(n-1)$ and $\frac{1}{\sigma} \cdot (\bar{X} - \mu) \cdot \sqrt{n}$ are stochastically independent.
- ▶ $\frac{1}{\sigma} \cdot (\bar{X} - \mu) \cdot \sqrt{n} / \sqrt{\left(\frac{1}{\sigma^2} S^2(n-1)\right) / (n-1)} = \frac{\bar{X} - \mu}{S} \cdot \sqrt{n}$

Notes



Example 8.15: Unknown variance (1)

Now, let σ^2 be unknown. As an estimate of σ^2 we use $s^2 = 33^2$ which is derived from the sample. We get the 95% confidence interval

$$\left[72 - 2.0315 \cdot \frac{33}{\sqrt{36}}; 72 + 2.0315 \cdot \frac{33}{\sqrt{36}}\right]$$

and finally

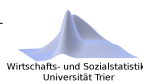
$$[72 - 11.173; 72 + 11.173] = [60.8268; 83.1733]$$

Attention:

$t(0.975; 35)$ is not tabulated. We used the arithmetic mean of the tabulated values $t(0.975; 30)$ and $t(0.975; 40)$ as the normal approximation would still yield inexact values (small n).

Thanks to R, this is not a problem anymore (see next slide).

Notes



Example 8.15: Unknown variance (2)

95% Confidence interval in R:

```
alpha <- 0.05
SpMean <- 72
SpVar <- 33^2
n <- 36

CI <- vector()
CI[1] <- SpMean - qt(p = 1 - (alpha/2), df = n - 1) *
  sqrt(SpVar/n)
CI[2] <- SpMean + qt(p = 1 - (alpha/2), df = n - 1) *
  sqrt(SpVar/n)

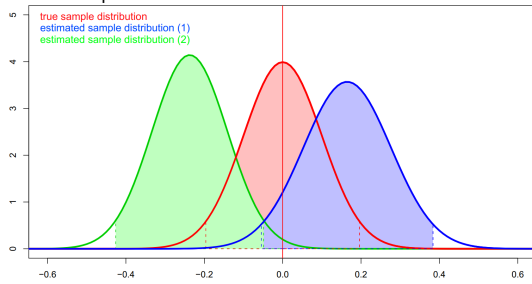
round(CI, digits = 1)

[1] 60.8 83.2
```

Notes

Example 8.16: Sample distributions (1)

Let the population be normally distributed with unknown variance σ^2 . A sample of size $n = 10$ is drawn. We can compare the true but unknown sample distribution as well as two estimated distributions resulting from two different samples.



Notes

Example 8.16: Sample distributions (2)

Confidence interval simulations (see next slide)

Point vs. variance estimates (upper left)

→ Cochran's theorem (given normal distribution)

Estimated distributions (lower left)

True distribution and estimated distributions of \bar{X}

Confidence intervals (upper right)

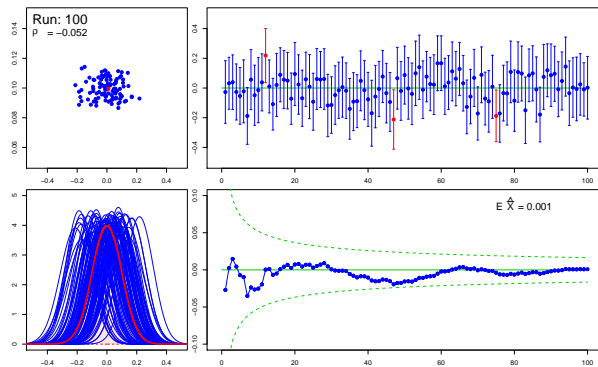
For $R = 100$ simulation runs;
red intervals do not cover true value

Convergence of $E(\bar{X})$ (lower right)

For r -th simulation run;
check of law of large numbers

Notes

Simulation of standard normal distribution



Notes

CI for σ^2 , POP is normally distributed

The random variable

$$\frac{n-1}{\sigma^2} \cdot S^2$$

follows a χ^2 distribution with $n-1$ degrees of freedom. We get the $(1-\alpha)$ confidence interval

$$\left[\frac{(n-1)S^2}{\chi^2(1-\frac{\alpha}{2}; n-1)}, \frac{(n-1)S^2}{\chi^2(\frac{\alpha}{2}; n-1)} \right]$$

► The CI follows from a rearrangement of

$$\chi^2(\frac{\alpha}{2}; n-1) \leq \frac{n-1}{\sigma^2} \cdot S^2 \leq \chi^2(1-\frac{\alpha}{2}; n-1).$$

► The CI does not have a minimal length. For very large n the normal approximation ensures the property of symmetry and minimal length.

Notes

Example 8.17: CI for variance (1)

Let a population be normally distributed. A sample of size $n = 25$ yields $s^2 = 7.244$. We search the 90% confidence interval for σ^2 .

We have $\chi^2(0.05; 24) = 13.848$ and $\chi^2(0.95; 24) = 36.415$. Therefore, we get the 90% confidence interval

$$\left[\frac{24 \cdot 7.244}{36.415}; \frac{24 \cdot 7.244}{13.848} \right]$$

and finally

$$[4.774; 12.555].$$

Notes

Example 8.17: CI for variance (2)

90% confidence interval in R:

```
alpha <- 0.1
n <- 25
SpVar <- 7.244

CI <- vector()

CI[1] <- ((n - 1) * SpVar) /
  qchisq(p = 1 - alpha/2, df = n-1)

CI[2] <- ((n - 1) * SpVar) /
  qchisq(p = alpha/2, df = n-1)

round(CI, digits = 3)

[1] 4.774 12.554
```

Notes

CI for $E X$, arbitrary distribution, $\text{Var } X$ known

The random variable

$$Z = \frac{\bar{X} - E X}{\sqrt{\text{Var } \bar{X}}} \cdot \sqrt{n}$$

does approximatively follow a standard normal distribution. For $n > 30$, following the central limit theorem of Lindeberg and Lévy, the $(1 - \alpha)$ confidence interval is

$$\left[\bar{X} - z(1 - \alpha/2) \cdot \sqrt{\frac{\text{Var } X}{n}}; \bar{X} + z(1 - \alpha/2) \cdot \sqrt{\frac{\text{Var } X}{n}} \right].$$

Notes

Example 8.18: see Ex. 8.13

Now, let a normal distribution of the population be questionable. As the sample size is $n = 36$, we again have the 95% confidence interval $[62.2; 81.8]$, but now it is not exact but approximative.

95% confidence interval in R:

```
n <- 36
alpha <- 0.05
VarX <- 30^2

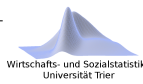
CI_new <- vector()
CI_new[1] <- SpMean - qnorm(p=1-alpha/2) * sqrt(VarX/n)
CI_new[2] <- SpMean + qnorm(p=1-alpha/2) * sqrt(VarX/n)

round(CI_new, digits = 1)

[1] 62.2 81.8
```

Notes

CI for $E X$, arbitrary distribution, Var X unknown



The random variable

$$Z = \frac{\bar{X} - E X}{\sqrt{S^2}} \cdot \sqrt{n}$$

does approximately follow a standard normal distribution. For $n > 30$, following the central limit theorem of Lindeberg and Lévy, the $(1 - \alpha)$ confidence interval is

$$\left[\bar{X} - z(1 - \alpha/2) \cdot \sqrt{\frac{S^2}{n}}; \bar{X} + z(1 - \alpha/2) \cdot \sqrt{\frac{S^2}{n}} \right].$$

Notes

Example 8.19: see Ex. 8.15 (1)

Analogously to Example 8.18 as an approximative 95% confidence interval we have

$$\left[72 - 1.96 \cdot \frac{33}{\sqrt{36}}; 72 + 1.96 \cdot \frac{33}{\sqrt{36}} \right]$$

and therefore

$$[72 - 10.78; 72 + 10.78] = [61.22; 82.78] .$$

Check of approximation conditions in R:

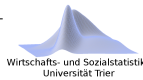
```
SpVar <- 33^2
n > 30
[1] TRUE
```

95% confidence interval in R:

```
CI_new <- vector()
CI_new[1] <- SpMean - qnorm(p = 1 - alpha/2) *
  sqrt(SpVar/n)
CI_new[2] <- SpMean + qnorm(p = 1 - alpha/2) *
  sqrt(SpVar/n)
round(CI_new, digits = 2)
[1] 61.22 82.78
```

Notes

Example 8.19: see Ex. 8.15 (2)

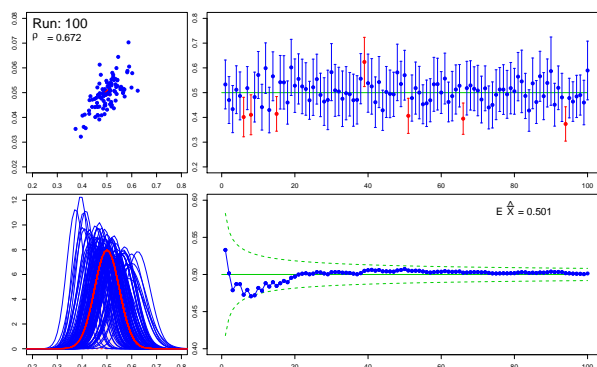
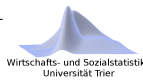


This approximative CI is shorter than the respective CI using the t distribution: $[60.8268; 83.1733]$. Notice the problems which may arise when using approximations.

The following examples illustrate this effect, e.g. that approximations may not always be used without concern.

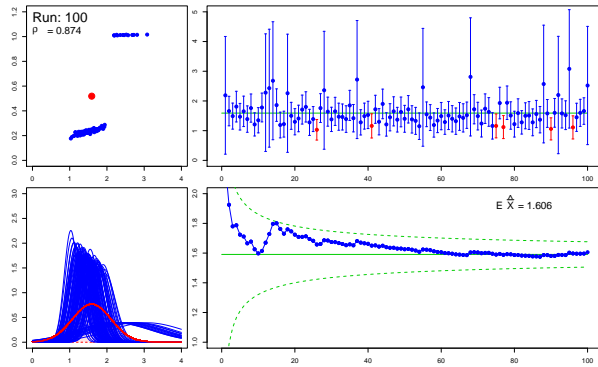
Notes

Simulation using the exponential distribution ($\lambda = 2$)



Notes

Simulation using discrete distribution with outlier



Notes

CI for $E X$, arbitrary distribution, $\text{Var } X$ unknown, without replacement

The random variable

$$Z = \frac{\bar{X} - E X}{\sqrt{\frac{S^2}{n} \cdot \frac{N-n}{N-1}}}$$

does approximately follow a standard normal distribution. For $n > 30$, following the central limit theorem of Lindeberg and Lévy, the $(1 - \alpha)$ confidence interval is

$$\left[\bar{X} - z(1 - \alpha/2) \cdot \sqrt{\frac{S^2}{n} \cdot \frac{N-n}{N-1}}; \bar{X} + z(1 - \alpha/2) \cdot \sqrt{\frac{S^2}{n} \cdot \frac{N-n}{N-1}} \right]$$

- In case $\text{Var } X$ is known, we substitute $\text{Var } X$ for S^2 .
- Mind the approximation conditions: n large and n not close to N

Notes

CI for proportions, variance unknown

Instead of \bar{X} we use the sample proportion P . We estimate the population variance using $P \cdot (1 - P)$. As the estimator distribution, using de Moivre and Laplace's theorem, the standard normal distribution is used. Mind the approximation conditions. We forego the continuity correction. The $(1 - \alpha)$ confidence interval is

$$\left[P - z(1 - \frac{\alpha}{2}) \cdot \sqrt{\frac{P(1-P)}{n}}; P + z(1 - \frac{\alpha}{2}) \cdot \sqrt{\frac{P(1-P)}{n}} \right]$$

Notes

Example 8.20: CI for proportions (1)

A survey of $n = 100$ students yielded a number of 15 students having a job. We get the 99% confidence interval

$$\left[0.15 - 2.575 \cdot \sqrt{\frac{0.15 \cdot 0.85}{100}}; 0.15 + 2.575 \cdot \sqrt{\frac{0.15 \cdot 0.85}{100}} \right] = [0.058; 0.242]$$

Data input in R:

```
alpha <- 0.01
n <- 100
p <- 15/100
```

Check of approximation conditions in R:

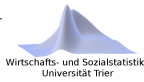
```
n * p * (1 - p) > 9
```

```
[1] TRUE
```

```
0.1 <= p & p <= 0.9
```

```
[1] TRUE
```

Notes



Notes

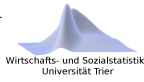
Example 8.20: CI for proportions (2)

99% confidence interval in R:

```
CI <- vector()
CI[1] <- p - qnorm(p = 1 - alpha/2)*sqrt((p * (1 - p))/n)
CI[2] <- p + qnorm(p = 1 - alpha/2)*sqrt((p * (1 - p))/n)

round(CI, digits = 3)

[1] 0.058 0.242
```



Notes

Example 8.21: see Ex. 8.14 (1)

Determination of needed sample size

We search the sample size for which the 95% CI is at most 5 units long.

We have

$$\left[72 - 1.96 \cdot \frac{30}{\sqrt{n}}; 72 + 1.96 \cdot \frac{30}{\sqrt{n}}\right].$$

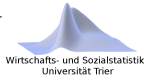
This yields a length of $d = 2 \cdot 1.96 \cdot 30/\sqrt{n}$. Using

$$2 \cdot 1.96 \cdot \frac{30}{\sqrt{n}} \leq 5$$

we finally get

$$n \geq \left(2 \cdot 1.96 \cdot \frac{30}{5}\right)^2 = 553.1904 \quad .$$

We need a sample size of $n \geq 554$.



Notes

Example 8.21: see Ex. 8.14 (2)

Calculation of n in R:

```
alpha <- 0.05
Quantile <- qnorm(p = 1 - alpha/2)
sigma <- 30
d <- 5

n_min <- ceiling((2 * Quantile * sigma/d)^2)

n_min

[1] 554
```

Notes
