The model of measurement 测量模型

Outline

- 1. Some basics
- 2. A small history
- 3. The types
 - Established CFA models
 - One-factor and two-factor models
 - Mixed models
- 4. Models with link functions

Some basics: important concepts

- parameter 参数:

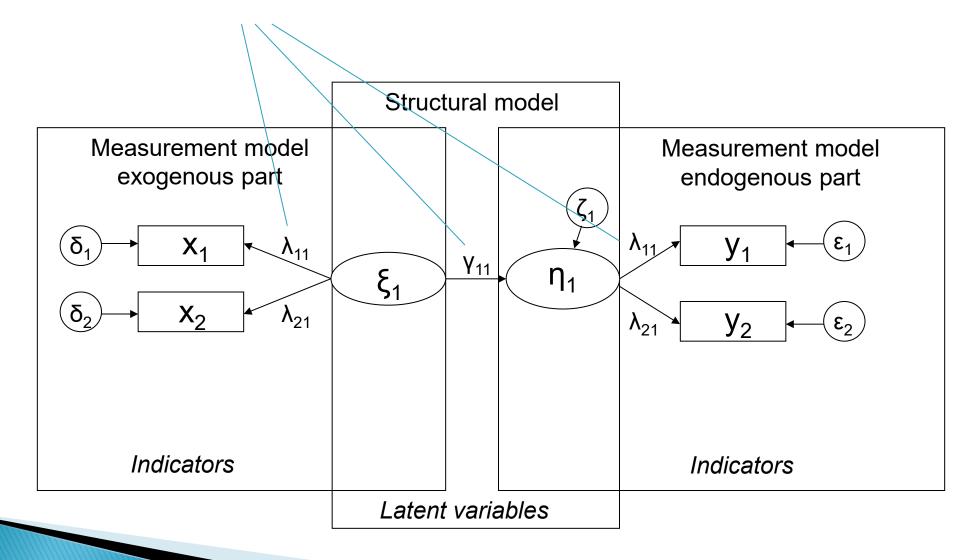
..... is a variable that is part of a model and refers to a property of data (e.g. a regression weight 回归系数 or path coefficient 路径系数)

.... is a quantity

.... is something that needs estimation

.... is something regarding a population

Parameters



Some basics: important concepts

- parameter 参数:

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..... is a variable that is part of a model and measures a characteristic of data (e.g. a regression weight 回归系数 or path coefficient 路径系数)
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.... is a quantity
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.... is something that needs estimation

.... is something regarding a population

- statistic 变量:

.... it is something characterizing a sample

.... mostly it is an estimated value (estimated mean, estimated variance, etc.)

Some basics: a remark

The terms "factor"因子 and "latent variable"潜变量 are often used in this section. Please, be aware

- they are considered as **equivalent**.

"factor" is the originally introduced term; in the attempt to relate the different latent variable approaches to each other it is replace by "latent variable".

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• The idea of the "model of measurement "has grown out of different sources.

• (1) <u>Factor analysis</u>. In an early stage of the development of factor analysis the researchers agreed on assuming a *functional relationship* between a latent source (of responding) and the response.

$$X \sim \xi \qquad [X = f(\xi)]$$

This assumption suggests

that is a kind of a model!

• The idea of the "model of measurement "has grown out of different sources.

• (2) <u>CCT</u>. In early assessment research the idea was established that measurement includes *error*. Even different types of error were distinguished from each other (systematic and random error, etc.) (see Gulliksen, 1950).

This suggested that measurement was a composite of different components instead of a something treated as a whole.

• The idea of the "model of measurement " has grown out of different sources.

• (3) <u>IRT</u>. Item response theory (see Baker & Kim, 2017) (IRT项目反应理论) introduced the idea that an observation / a response could be described by <u>several differing sets of parameters</u>.

- The idea of the "model of measurement " has grown out of different sources.
- Item response theory (IRT项目反应理论) introduced the idea that an observation / a response could be described by several ...
- Furthermore ...
 - ... the term *model* is introduced for the first time
 - ... This term is used *in the sense of a hypothesis* instead of using it as description of reality.

• The idea of the "model of measurement "has grown out of different sources.

• Item response theorie (IRT项目反应理论) introduced the idea ...

In the meantime IRT was especially successful in creating many different IRT models showing different properties. These models refer to different types of data and effects.

What is a model of measurement in CFA and SEM today?

- It is a hypothesis regarding the structure of data
- It describes the manifest variables as composites of latent variables and error variables
- Its appropriateness can be checked by goodness-of-fit testing

A note

A model of measurement always includes vectors 向量, but not single variables 单个方程.

$$>$$
 equation of variables: $a_1 = b_1 + c_1$

> equation of variables:
$$a_1 = b_1 + c_1$$
> equation of vectors: $\mathbf{a} = \mathbf{b} + \mathbf{c}$, $\begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_p \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_p \end{bmatrix} + \begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_p \end{bmatrix}$

A note

A model of measurement always includes vectors 向量, but not single variables 单个方程.

Reason:

There must be the possibility to disprove the model of measurement (remember model identification)

A note

A model of measurement always includes vectors 向量, but not single variables 单个方程.

i.e. investigating a model of measurement can yield a *good* or *bad* account of the data.

A bad account means that the model has to be rejected and replaced by another one.

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The types

There is *not* one model of measurement. A number of specific models of measurement were proposed (vgl. Graham, 2006). They differ according to ...

• ... the *number* of components (the standard is one true and one error component; but there may be several true components)

The types

There is *not* one model of measurement. A number of specific model of measurement were proposed (vgl. Graham, 2006). They differ according to ...

- ... the *number* of components,
- ... the *relationships* among the components,
- ... the consideration of *intercepts*.
- ... the parameters are either estimated or fixed.

The types

A list of the types:

- -model of parallel measurement
- -model of τ -equivalent measurement
- -model of essentially τ -equivalent measurement
- -congeneric model

The model of parallel measurement (= model of CTT)

$$X = \tau + \varepsilon$$

X: observations观测值, τ : true components真值, ϵ : error components误差

• It is assumed that all items of a scale are exactly equivalent in all measurements.

The model of parallel measurement (= model of CTT)

$$X = \tau + \varepsilon$$

X: observations, τ : true components, ϵ : error components

• It is assumed that all items of a scale are exactly equivalent in all measurements.

(i.e. the items of a scale are assumed not to differ from each other but the persons may differ)

The model of parallel measurement (= model of CTT)

$$X = \tau + \varepsilon$$

X: observations, τ : true components, ϵ : error components

• It is assumed that all items of a scale are exactly equivalent in all measurements.

This is the justification for computing scores by the summation of the responses coded as numbers!

The model of parallel measurement (= model of CTT)

$$X = \tau + \varepsilon$$

Example: a simple math problem (e.g. 3+4=?)

- X: ... correctness of the response (coded as 1 or 0)
- $-\tau$: ... true score contribution of e.g. latent fluid intelligence
- $-\epsilon$: ... error contribution to response

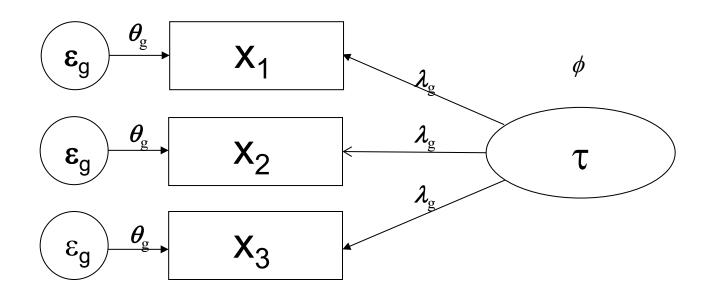
The model of parallel measurement (= model of CTT)

$$X = \tau + \varepsilon$$

Example: a simple math problem

```
\begin{array}{ll} -3+4=?\\ -\ldots =7\\ -\ldots =7\\ -\ldots = f_{cognitive\_processes}(\tau + \epsilon) \end{array}
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The model of parallel measurement (= model of CTT)

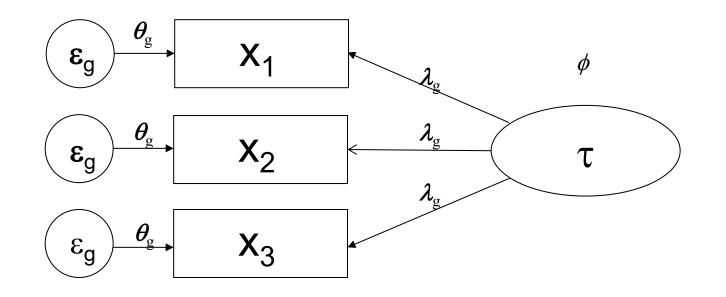


The model of parallel measurement (= model of CTT)

... as formal model of measurement

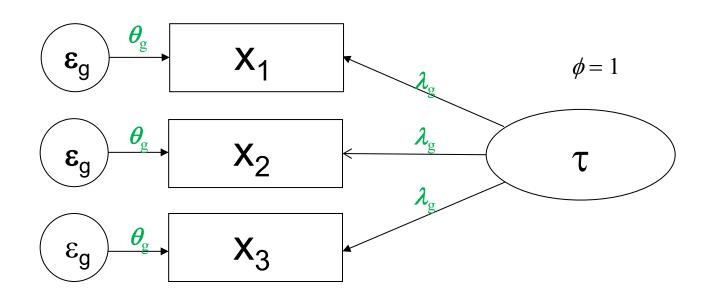
$$e \in \Re > 0$$

Practice: *determine the degree of freedom* (df = s-t)



Which one of the following numbers gives the degree of freedom?

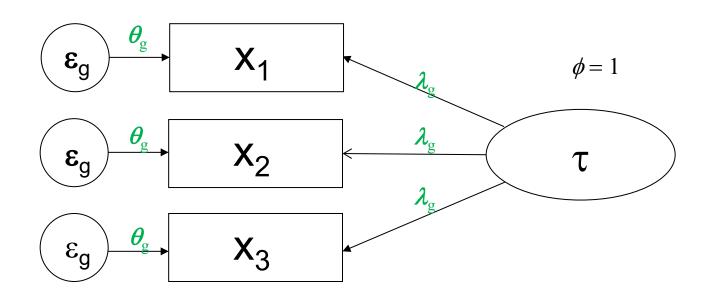
Practice: *determine the degree of freedom* (df = s-t)



Which one of the following numbers gives the degree of freedom?

$$df = 6 - 2 = 4$$

Practice: *determine the degree of freedom* (df = s-t)



A Note

In this case ϕ is set equal to 1 because of the need for scaling. Scaling will be explained in another course unit.

The model of τ -equivalent measurement

$$X = \tau + \varepsilon$$

X: observations, τ : true components, ϵ : error components

• It is assumed that only the *true components* of all items of a scale are exactly equivalent in measurement.

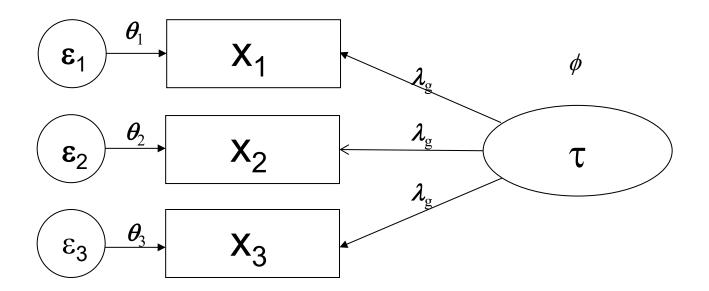
The model of τ -equivalent measurement

$$X = \tau + \varepsilon$$

X: observations, τ : true component, ϵ : error component

In contrast, the responses to items may show different error contributions (i.e. the error components differ across the items)

The model of τ -equivalent measurement

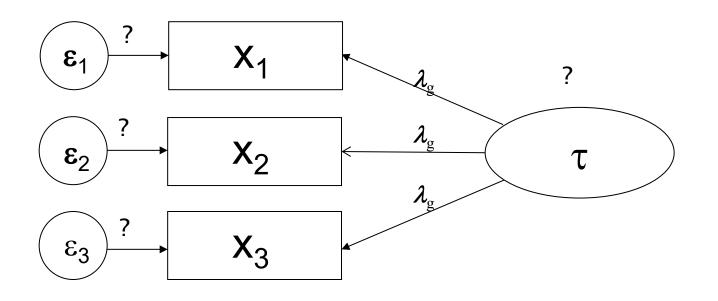


The model of τ -equivalent measurement

... as formal model of measurement

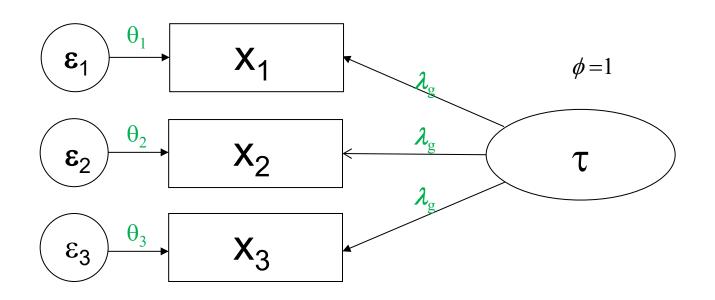
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Practice: *determine the degree of freedom* (df = s-t)



Which one of the following numbers gives the degree of freedom?

Practice: *determine the degree of freedom* (df = s-t)



Which one of the following numbers gives the degree of freedom?

$$df = 6 - 4 = 2$$

The model of the essentially τ -equivalent measurement

$$X = (\alpha + \tau) + \varepsilon$$

X: observations, α : item-characteristic constants, τ : true components, ϵ : error components,

• It is assumed that the true parts of the items differ by a constant and all the rest is the same as for the τ -equivalent model.

The model of the essentially τ -equivalent measurement

... as formal model of measurement

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \\ \vdots \\ \alpha_p \end{bmatrix} + \begin{bmatrix} \tau_g \\ \tau_g \\ \tau_g \\ \vdots \\ \tau_g \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \vdots \\ \varepsilon_p \end{bmatrix}$$

Practice: *determine the degree of freedom* (df = s-t)

$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} + \begin{bmatrix} \tau_{g} \\ \tau_{g} \\ \tau_{g} \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \end{bmatrix}$$

Which one of the following numbers gives the degree of freedom?

Practice: *determine the degree of freedom* (df = s-t)

$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \alpha_3 \end{bmatrix} + \begin{bmatrix} \tau_g \\ \tau_g \\ \tau_g \end{bmatrix} + \begin{bmatrix} \mathcal{E}_1 \\ \mathcal{E}_2 \\ \mathcal{E}_3 \end{bmatrix}$$

To-be-considered parameters: α_1 , α_2 , α_3 , ε_1 , ε_2 , ε_3 , τ_g

Which one of the following numbers gives the degree of freedom?

$$df = 6 - 7 = -1$$

... more items should be considered!

The congeneric model (Jöreskog, 1971)

- standard model of CFA 验证性因素分析and SEM结构方程模型):

$$X = (\lambda \times \xi) + \varepsilon$$
 $(\lambda \times \xi)$ takes the role of τ)

X: observations观测值,

 λ : factor loadings因子载荷 (also known as item-scale correlations/ discriminability parameters),

ξ: factor 因子,

ε: error components误差,

 λ is specific for the item, ξ can be considered specific for the person (- not specified)

The congeneric model: a supplement – an innovation

... the introduction of this model is accompanied by a change of what was so far considered as **error**

... the remainder could now be considered as unique systematic variation

Therefore, it is now addressed as <u>residual</u>

The congeneric model (Jöreskog, 1971)

updated version (standard model of CFA 验证性因素分析and SEM结构方程模型):

$$\mathbf{X} = (\lambda \mathbf{X} \boldsymbol{\xi}) + \boldsymbol{\varepsilon}$$
 $(\lambda \mathbf{X} \boldsymbol{\xi})$ takes the role of $\boldsymbol{\tau}$)

(... after change to modern notation used for models of measurement)

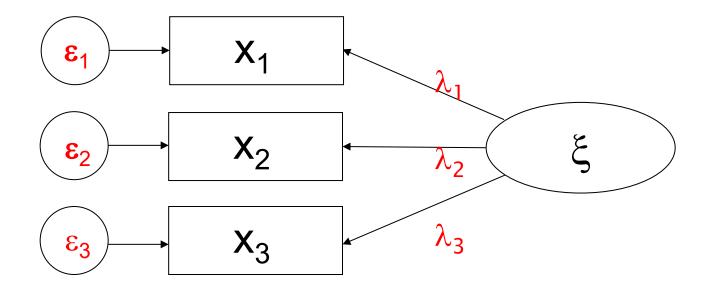
x: vector of manifest variables 观测值,

 λ : vector of factor loadings因子载荷 (also known as item-scale correlations/ discriminability parameters),

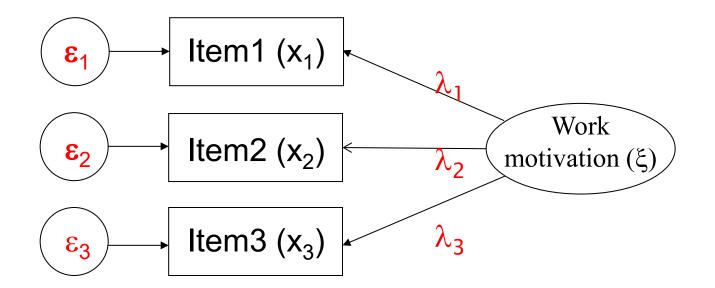
ξ: factor 因子,

 ϵ : vector of residual components误差,

The congeneric model (Jöreskog, 1971)



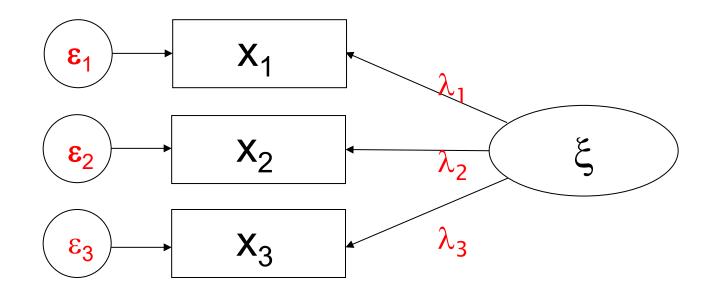
The congeneric model (Jöreskog, 1971) – example



The congeneric model (Jöreskog, 1971)

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \lambda_2 \\ \vdots \\ \xi_2 \\ \mathcal{E}_3 \\ \vdots \\ \lambda_p \end{bmatrix}$$

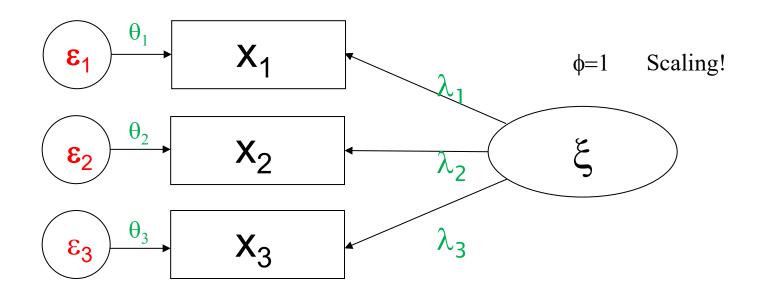
Practice: *determine the degrees of freedom* (df = s-t)



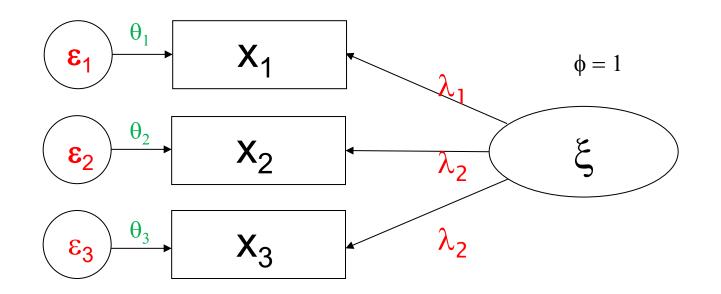
Which one of the following numbers gives the degree of freedom?

(

Practice: *determine the degrees of freedom* (df = s-t)



Practice: *determine the degrees of freedom* (df = s-t)



Which one of the following numbers gives the degree of freedom?

$$df = 6 - 6 = 0$$

The congeneric model (Jöreskog, 1971)

- original version (standard model of CFA and SEM)
- extended version: linear mixed model

$$X = (\mu + \lambda \times \xi) + \varepsilon$$

X: vector of manifest variables, μ : vector of item characteristic constants, ξ : latent variable (= factor), δ : vector of residual variables, λ : vector of factor loadings (item-scale correlations/ discriminability parameters)

• μ and λ are item specific (与特定项目相关)

Ranking of models of measurement regarding degree of freedom

from simple to elaborate

- **♦** model of τ-equivalent measurement
- ★ model of essentially t-equivalent measurement
- **♦** congeneric model

Linear mixed congeneric model

How to select the model of measurement?

◆ follow the <u>simplicity principle</u>

(theories, hypotheses ... should be as simple as possible)

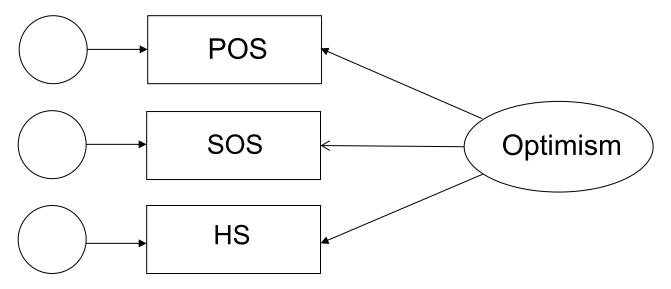
An example of selecting the model of measurement:

Assume that it is necessary to design a model of measurement for the personality construct "optimism". In order to establish such a construct, it is necessary to find appropriate indicators in the first step. Since the construct optimism shows several facets (e.g. personal facet, social facet, opt. regarding the future, etc), it is possible to look for operationalizations of facets in the second step. Assume this search for indicators leads to three scales as candidates:

- Personal optimism scale (POS)
- Social optimism scale (SOS)
- Hopefulness scale (HS)

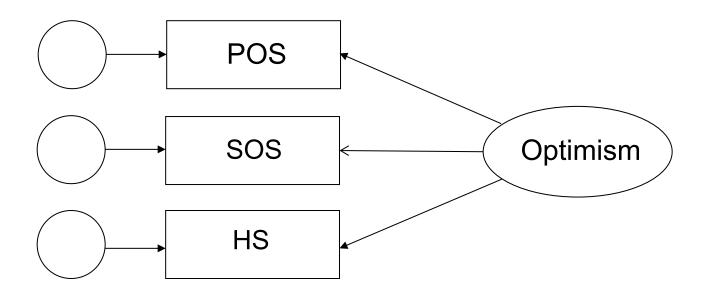
An example of selecting the model of measurement :

One latent variable and three indicators (manifest variables) lead to the following structure of the model of measurement:



An example of selecting the model of measurement :

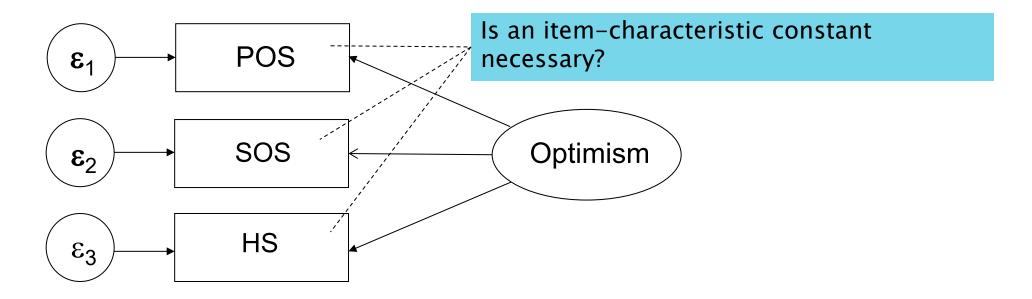
Next, the type of the model has to be selected:



The *principle* suggests to check whether there is reason for selecting a model type with a large degree of freedom!

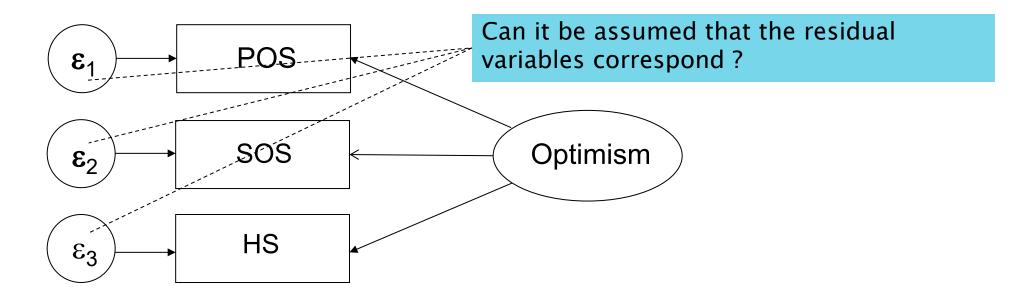
An example of selecting the model of measurement :

Next, the type of the model has to be selected:



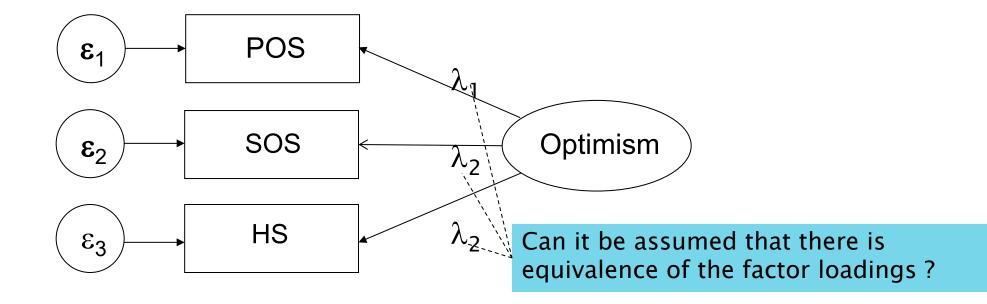
An example of selecting the model of measurement :

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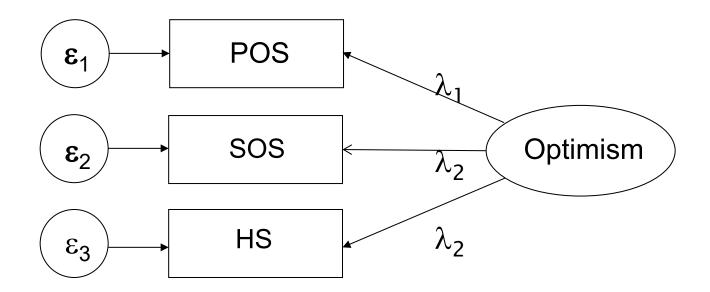


An example of selecting the model of measurement :

Next, the type of the model has to be selected:



Finally, if there are only "no"s, the search ends up with the congeneric model:



Models can include a second factor so that there are ...

- two overlapping factors
- two non-overlapping (but correlated) factors

Models can include a second factor so that there are ...

- two overlapping factors
- two non-overlapping (but correlated) factors

The bifactor model 双因子模型:

(individual equations of such a model)

$$\begin{aligned} & \textbf{X}_i = \lambda_{i1} \times \xi_1 + 0 & + \epsilon_i \\ & \textbf{X}_k = \lambda_{k1} \times \xi_1 + \lambda_{k2} \times \xi_2 + \epsilon_k \end{aligned} \qquad \text{(for (at least) one item)}$$

Models can include a second factor so that there are ...

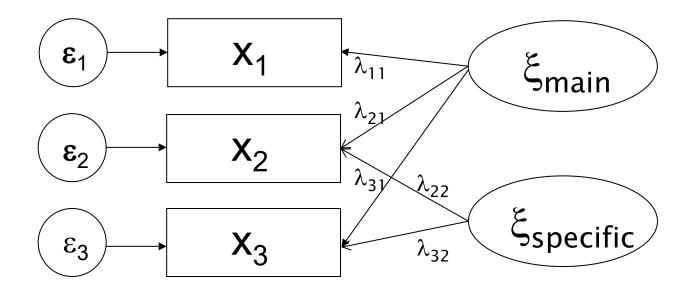
- two overlapping factors
- two non-overlapping (but correlated) factors

The bifactor model 双因子模型:

(individual equations of a model)

$$\mathbf{X}_1 = \lambda_{11} \times \xi_1 + 0 \times \xi_2 + \varepsilon_1$$
 (for (at least) one item) $\mathbf{X}_i = \lambda_{i1} \times \xi_1 + \lambda_{i2} \times \xi_2 + \varepsilon_i$ (for all other items)

An example of a bifactor model:



Formal description of the bifactor model

$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} \lambda_{\text{1main}} \\ \lambda_{\text{2main}} \\ \lambda_{\text{3main}} \\ \vdots \\ \lambda_{\text{pmain}} \end{bmatrix} \boldsymbol{\xi}_{\text{main}} + \begin{bmatrix} 0 \\ \lambda_{\text{2specific}} \\ \lambda_{\text{3specific}} \\ \vdots \\ \lambda_{\text{pspecific}} \end{bmatrix} \boldsymbol{\xi}_{\text{specific}} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \vdots \\ \varepsilon_p \end{bmatrix}$$

Models can include a second factor so that there are ...

- two overlapping factors
- two non-overlapping (but correlated) factors

Models can include a second factor so that there are ...

- two overlapping factors
- two non-overlapping (but correlated) factors

```
(individual equations of a model)  \begin{aligned} x_i &= \lambda_{i1} \times \xi_1 + 0 \times \xi_2 + \epsilon_i \\ x_k &= 0 \times \xi_1 + \lambda_{k2} \times \xi_2 + \epsilon_k \end{aligned} \end{aligned} \text{ (for some items)}
```

Formal description of the two-factor model

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ \vdots \\ x_p \end{bmatrix} = \begin{bmatrix} \lambda_{1A} \\ \dots \\ \lambda_{i_A A} \\ 0 \\ \dots \\ 0 \end{bmatrix} \boldsymbol{\xi}_{A} + \begin{bmatrix} 0 \\ \dots \\ 0 \\ \lambda_{j_B} \\ \dots \\ \lambda_{p_B} \end{bmatrix} \boldsymbol{\xi}_{B} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \vdots \\ \varepsilon_p \end{bmatrix}$$

- ◆Mixed models include *factors* representing *random* effects and *factors* representing *fixed effects*.
- ◆Distinguishing between fixed and random effects is taken over from analysis of variance 方差分析.

- **♦**
- ◆Distinguishing between fixed and random effects is taken over from analysis of variance.
 - Fixed effects: there are clearly distinguishable levels e.g. the effects due to the different experimental treatments
 - Random effects: there are no distinguishable levels
 e.g. the dosage of a drug administered to sick persons varies according to their sickness

- ◆Mixed models include *fixed factors* and *random factors* for representing fixed effects and random effects respectively.
- ◆The formal mixed model of measurement is given by

$$X = \alpha + \beta_{\text{fixed_effect}} \times \xi_{\text{fixed_effect}} + \beta_{\text{random_effect}} \times \xi_{\text{random_effect}} + \epsilon$$

- $-\beta_{\text{fixed effect}}$: regression weight for fixed effects
- $\beta_{random\ effect}$: regression weight for random effects

- **♦**....
- ◆The formal mixed model of measurement: example
- extended version of congeneric model: *linear mixed model*

$$X = (\mu + \lambda \times \xi) + \varepsilon$$

A Remark:

The mixed models are used in the context of multilevel modeling 多水平模型.

适用于不同组(如, 男生/女生)之间的比较

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Models with link functions

... (for example) used in combination with probability-based covariances

Models with link functions

Link functions are used as part of generalized linear models for relating variables following different distributions to each other.

e.g. there may be one variable A follwing the normal distribution and another variable B following the binomial distribution. In this case the corresponding link function g() is used for establishing equivalence:

$$B \neq A$$

$$B = g(A)$$

Models with link functions

Turning the congeneric model into a generalized linear model gives

$$\mathbf{x} = \mathbf{g} (\lambda \times \xi) + \varepsilon$$

x: vector of manifest variables, ξ : latent variable (= factor), λ : vector of factor loadings, ϵ : vector of residual variables, g(): link function

Note: residuals are assumed to always follow the normal distribution

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Summary and brush up:

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... models developed to represent hypotheses

... measurement models show a typical linear structure (... a sum of two components)

... remember: the congeneric model of measurement

... there are generalized linear models

Questions regarding course unit 4

- What are the components of the congeneric model of measurement?
- Which parameter is only specific for the item?
- What is the major difference between the congeneric model and the bifactor model?

Literature

Basic literature:

- ▶ Baker, F. B., & Kim, S.-H. (2017). The basics of itm response theory using R. Heidelberg: Springer.
- Graham, J. M. (2006). Congeneric and (essentially) tauequivalent estimates of score reliability. *Educational and Psychological Measurement*, 66, 930-944.
- Schweizer, K. (2012). The position effect in reasoning items considered from the CFA perspective. *International Journal of Educational and Psychological Assessment*, 11, 44–58.