```
Mass = 185684.17 grams
Volume = 29317348.16 cubic millimeters
Surface area = 3070473.01 square millimeters
Center of mass: ( millimeters )
         X = 79.91
         Y = 66.94
         Z = 55.09
Principal axes of inertia and principal moments of inertia: ( grams * square millimeters )
Tken at the center of mass.
          Ix = (1.00, -0.01, -0.09)
                                       Px = 5254650851.20
          ly = (0.04, 0.95, 0.30)
                                       Py = 8816815448.80
          Iz = (0.08, -0.30, 0.95)
                                       Pz = 9220541052.80
Moments of inertia: ( grams * square millimeters )
Aken at the center of mass and aligned with the output coordinate system.
         Lxx = 5285570665.48
                                       Lxy = -4217343.17 Lxz = -342812970.29
         Lyx = -4217343.17 Lyy = 8853327834.62Lyz = 121048853.38
                                       Lzy = 121048853.38 Lzz = 9153108852.70
         Lzx = -342812970.29
Moments of inertia: ( grams * square millimeters )
Tken at the output coordinate system.
         lxx = 668127202.19 lxy = 95182463.75 lxz = 474591955.15
         lyx = 95182463.75 lyy = 10602566870.12
                                                           lyz = 805781056.09
```

Izx = 474591955.15 Izy = 805781056.09 Izz = 170946639.95

Mass properties of gears Configuration: Default

Coordinate system: -- default --