# Linear Systems Positive Definiteness and Matrix Norm

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Department of Bioengineering Christian Medical College, Bagayam Vellore 632002 ▶ G Strang, Linear Algebra: Chapters 6 and 7.

- ▶ We know that  $\mathbf{x}^T\mathbf{x} > 0$  for all  $\mathbf{x} \in \mathbb{R}^n$  and  $\mathbf{x} \neq \mathbf{0}$ .
- ▶ What can we say about  $\mathbf{x}^T \mathbf{A} \mathbf{x}$ , where  $\mathbf{A} \in \mathbb{R}^{n \times n}$ ?
  - ▶ Is it positive for all  $x \neq 0$ ?
  - ► Can it be zero for some  $x \neq 0$ ?
  - Can it be negative some  $\mathbf{x} \neq \mathbf{0}$ ?
- Any matrix **A** for which  $\mathbf{x}^T \mathbf{A} \mathbf{x} > 0$ , for all  $\mathbf{x} \neq \mathbf{0}$  is called a *positive definite matrix*.
- Positive definite matrices are very useful and are commonly encountered in practice: optmization, mechanics (mass matrix, stiffness matrix), stability analysis, co-variance matrices etc.

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Are the following matrices positive definite:  $\begin{bmatrix} 2 & -6 \\ 2 & 1 \end{bmatrix}$ ,  $\begin{bmatrix} 5 & -1 \\ 14 & 11 \end{bmatrix}$ 

- ► The idea of positive definiteness is intimately related to the problem of minimization of a function.
- Consider the following function of a single variable f(x). This function reaches a minimum at x=0, when  $\frac{df(x)}{dx}\big|_{x=0}=0$  and  $\frac{d^2f(x)}{dx^2}\big|_{x=0}>0$ . E.g.,

$$f(x) = 3x^2 \to \frac{df(x)}{dx}\big|_{x=0} = 0, \frac{d^2f(x)}{dx^2}\big|_{x=0} = 3 > 0$$

What about  $f(x_1, x_2) = ax_1^2 + 2bx_1x_2 + cx_2^2$ ? We can extend the previous idea using partial derivatives.

$$\frac{\partial f(x_1, x_2)}{\partial x_1} = 0, \ \frac{\partial f(x_1, x_2)}{\partial x_2} = 0, \ \frac{\partial^2 f(x_1, x_2)}{\partial x_1^2} > 0, \ \frac{\partial^2 f(x_1, x_2)}{\partial x_2^2} > 0$$

Is this enough?  $\frac{\partial^2 f(x_1, x_2)}{\partial x_1 \partial x_2}$  must also be taken into account.

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▶ We can rearrange  $ax_1^2 + 2bx_1x_2 + cx_2^2$  in the following manner,

$$f(x_1, x_2) = ax_1^2 + 2bx_1x_2 + cx_2^2 = a\left(x_1 + \frac{b}{a}x_2\right)^2 + \left(c - \frac{b^2}{a}\right)x_2^2$$

 $f\left(\bullet\right)>0, \forall x_{1},x_{2}\neq0$  when,

$$a>0$$
 and  $c-\frac{b^2}{a}>0 \implies ac>b^2$ 

$$\frac{\partial^2 f\left(x_1, x_2\right)}{\partial x_1^2} > 0 \quad \text{and} \quad \frac{\partial^2 f\left(x_1, x_2\right)}{\partial x_1^2} \frac{\partial^2 f\left(x_1, x_2\right)}{\partial x_2^2} > \left(\frac{\partial^2 f\left(x_1, x_2\right)}{\partial x_1 \partial x_2}\right)^2$$

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 $f(\bullet) > 0, \forall x_1, x_2 \neq 0$  when,

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Verfy this on the following functions: 1)  $x_1^2 + x_1x_2 + x_2^2$ , 2)  $x_1^2 + 2x_1x_2 + x_2^2$ , 3)  $x_1^2 + 3x_1x_2 + x_2^2$ 

 $f(\bullet)$  can be expressed as  $\mathbf{x}^T \mathbf{A} \mathbf{x}$ , where  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ , and  $\mathbf{A} = \begin{bmatrix} a & b \\ b & c \end{bmatrix}$ .  $f(\mathbf{x}) > 0$  for all  $\mathbf{x} \neq \mathbf{0}$ . when  $\mathbf{A}$  is positive definite.

 $\mathbf{x}^T \mathbf{A} \mathbf{x}$  is called a *quadratic form*. For a symmetric matrix  $\mathbf{A}$ ,

$$\mathbf{x}^{T}\mathbf{A}\mathbf{x} = \begin{bmatrix} x_{1} & x_{2} & \dots & x_{n} \end{bmatrix} \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{12} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \dots & a_{nn} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ \vdots \\ x_{n} \end{bmatrix} = \sum_{i=1}^{n} a_{ii}x_{i}^{2} + 2\sum_{i=1}^{n} \sum_{j=1, j \neq i}^{n} a_{ij}x_{i}x_{j}$$

In general,  $\mathbf{A} \in \mathbb{R}^{n \times n}$  is positive definite, if:

- ► The eigenvalues of **A** are all positive.
- ▶ The pivots (without row exchange) are all positive.

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Show that any A is positive definite if the symmetric matrix  $A + A^T$  is positive definite. Note: This should explain why we have only been talking about symmetric matrices.

#### Matrix Norm

- ▶ Since matrices also form vector spaces, we can talk about norms of matrices, which extent the idea of sizes and distances to spaces of matrices.
- lacktriangleright If we think of matrices a set of mn scalars, then we can use the same approach as vectors,

$$\|\mathbf{A}\|_F = \left(\sum_{i=1}^m \sum_{j=1}^n |a_{ij}|^2\right)^{\frac{1}{2}}$$

This is called the Frobinius norm.

#### Matrix Norm

- ► There are other norms defined for matrices that are very useful from the point of the view of linear transformation.
- ► These are called *induced matrix norms*, that looks at how matrices map vectors from the range to domain spaces.
- Let  $\mathbf{A} \in \mathbb{R}^{m \times n} : \mathbb{R}^n \to \mathbb{R}^m$ , and  $\mathbf{x} \in \mathbb{R}^n$ ,  $\mathbf{y} \in \mathbb{R}^m$

$$\|\mathbf{y}\| = \|\mathbf{A}\mathbf{x}\| \le C \|\mathbf{x}\|, \ \forall \mathbf{x} \in \mathbb{R}^n, \ C \ge 0$$

C is the maximum factor by which A amplifies the vector x.

▶ The induced norm of a matrix is defined as.

$$\|\mathbf{A}\|_p = \max_{\mathbf{x}} \frac{\|\mathbf{A}\mathbf{x}\|_p}{\|\mathbf{x}\|_p} = \max_{\|\mathbf{x}\|_p = 1} \|\mathbf{A}\mathbf{x}\|_p$$

#### Matrix Norm

Consider a matrix 
$$\mathbf{A} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{a}}_1^T \\ \tilde{\mathbf{a}}_2^T \end{bmatrix}$$
.

$$\|\mathbf{A}\|_1 = \max_i \|\mathbf{a}_i\|_1$$

$$\left\| \mathbf{A} \right\|_2 = \sqrt{\lambda_{\max}}$$

$$\|\mathbf{A}\|_{\infty} = \max_{i} \|\tilde{\mathbf{a}}_{i}\|_{1}$$





