# Digital Signal Processing: Theory and Practice

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# What is signal processing?

"Signal processing is an enabling technology that encompasses the fundamental theory, applications, algorithms, and implementations of processing or transferring information contained in many different physical, symbolic, or abstract formats broadly designated as signals and uses mathematical, statistical, computational, heuristic, and/or linguistic representations, formalisms, and techniques for representation, modeling, analysis, synthesis, discovery, recovery, sensing, acquisition, extraction, learning, security, or forensics."

Moura, J.M.F. (2009). "What is signal processing?, Presidents Message". IEEE Signal Processing Magazine 26 (6). doi:10.1109/MSP.2009.934636

## What is a signal?

Any physical quantity carrying information that varies with one or more independent variables.

$$s(t) = 1.23t^{2} - 5.11t + 41.5$$
$$s(x, y) = e^{-(x^{2} + y^{2} + 0.5xy)}$$

Mathematical representation will not be possible (e.g. physiological signals, either because the exact function is not known or is too complicated.)

# What is a signal? (Contd ...)

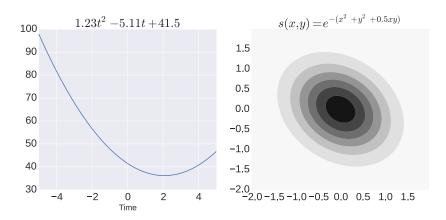


Figure : Example of 1D and 2D signals

Can you think of examples of 3D and 4D signals?

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#### Classification of signals

- ▶ Based on the signal dimensions. e.g. 1D, 2D ...
- ► Scalar vs. Vector signals: e.g. gray scale versus RGB image

$$I_g(x,y) \in \mathbb{R} \text{ and } I_{color}(x,y) \in \mathbb{R}^3$$

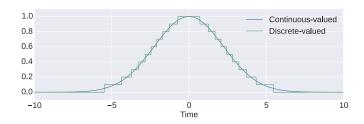
► Continuous-time vs. Discrete-time: based on the values assumed by the independent variable.

$$\begin{cases} x(t) = e^{-0.1t^2}, \ t \in \mathbb{R} & \text{Continuous-time} \\ x[n] = e^{-0.1n^2}, \ n \in \mathbb{Z} & \text{Discrete-time} \end{cases}$$

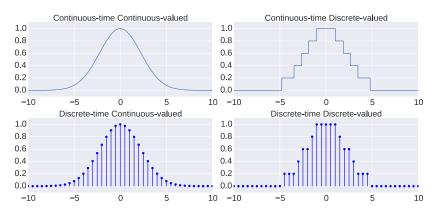


▶ Continuous-valued vs. Discrete-valued: based on the values assumed by the dependent variable.

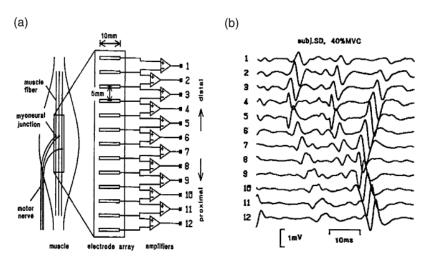
$$\begin{cases} x(t) \in [a, b] & \text{Continuous-valued} \\ x(t) \in \{a_1, a_2, \dots\} & \text{Discrete-valued} \end{cases}$$



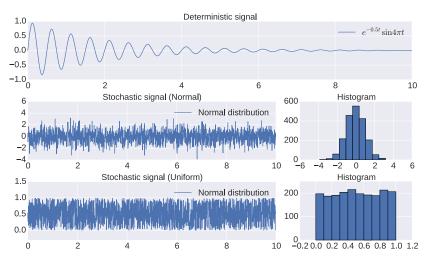
#### Four types of signals



#### Example of a Continuous-valued discrete-time signal



▶ Deterministic vs. Stochastic: e.g. EMG is an example of a stochastic signal.



▶ Even vs. Odd: based on the symmetry about the t = 0 axis.

$$\begin{cases} x(t) = x(-t), & \text{Even signal} \\ x(t) = -x(-t), & \text{Odd signal} \end{cases}$$

Can there be signals that are neither even nor odd?

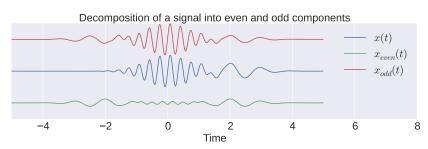
#### Theorem

Any arbitrary function can be represented as a sum of an odd and even function.

$$x(t) = x_{even}(t) + x_{odd}(t)$$

where, 
$$x_{even}(t) = \frac{x(t) + x(-t)}{2}$$
 and  $x_{odd}(t) = \frac{x(t) - x(-t)}{2}$ .

# Decomposition of an arbitrary signal into even and odd components



▶ Periodic vs. Non-periodic: a signal is periodic, if and only if

$$x(t) = x(t+T), \forall t$$

where, T is the fundamental period.

▶ Energy vs. Power: indicates if a signal is short-lived.

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt$$
  $P = \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$ 

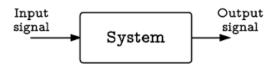
$$E = \sum_{-\infty}^{\infty} |x(t)|^2$$
  $P = \frac{1}{2N+1} \sum_{-N}^{N} |x(t)|^2$ 

A signal is an **energy** signal, if  $0 < E < \infty$ . A signal is an **power** signal, if  $0 < P < \infty$ .

#### What is a system?

A collection of objects united by some form of interaction or interdependence<sup>2</sup>.

From the signal processing point of view, a system is any physical device or algorithm that performs some operation on a signal to transform it into another signal.



Can be thought of a mapping function. e.g.

$$y = f(x) = kx$$

<sup>&</sup>lt;sup>2</sup>Zadeh, Lotfi A., and Charles A. Deoser. *Linear system theory*. New York: McGraw Hill, 1963.

#### Classification of systems

Based on the properties of the system.

▶ Linearity: satisfies the properties of scaling and superposition.

Let us assume,

$$f: x_i(t) \mapsto y_i(t)$$

The system f is linear, if and only if,

$$f: \sum_{i} a_i x_i(t) \mapsto \sum_{i} a_i y_i(t)$$

Which of these systems are linear?

1. 
$$y(t) = k_1 x(t) + k_2 x(t-2)$$

2. 
$$y(t) = \int_{t-T}^{t} x(\tau) d\tau$$

3. 
$$y(t) = 0.5x(t) + 1.5$$

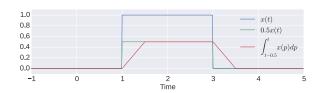
## Classification of systems

Based on the properties of the system.

▶ Memory: a system whose output depends on past or future values of its input is a system with memory, else the system is memoryless.

Note: the system may or may not depends on its present.

$$\begin{cases} y(t) = 0.5x(t) & \textbf{Memoryless system} \\ y(t) = \int_{t-0.5}^{t} x(\tau) d\tau & \textbf{System with memory} \end{cases}$$



#### Classification of systems

▶ Causality: a system whose output depends on the past and present only values of the input is a causal system.

$$\begin{cases} y(t) = \int_{t-0.5}^t x(\tau) d\tau & \textbf{Causal} \\ y(t) = \int_{t-0.5}^{t+0.5} x(\tau) d\tau & \textbf{Non-causal} \end{cases}$$

► Time invariance: system remains the same with time. If s system is time-invariant, then

$$f: x(t) \mapsto y(t) \iff f: x(t-t_0) \mapsto y(t-t_0)$$

► Stability: bounded input produces bounded output.

$$|x(t)| < M_x < \infty \mapsto |y(t)| < M_y < \infty$$

▶ Invertibility: input can be recovered from output.

