

Linear Systems: Assignment

Vectors

1. Is set of vectors $\left\{ \begin{bmatrix} 2 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}$ independent?

Explain your answer.

2. Prove the following for $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$

(a) **Triangle Inequality:**

$$\|\mathbf{x} + \mathbf{y}\| \leq \|\mathbf{x}\| + \|\mathbf{y}\|$$

(b) **Backward Triangle Inequality:**

$$\|\mathbf{x} - \mathbf{y}\| \geq \|\mathbf{x}\| - \|\mathbf{y}\|$$

(c) **Parallelogram Identity:**

$$\frac{1}{2} (\|\mathbf{x} + \mathbf{y}\|^2 + \|\mathbf{x} - \mathbf{y}\|^2) = \|\mathbf{x}\|^2 + \|\mathbf{y}\|^2$$

3. Consider a set of vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$. When is $\|\mathbf{x} - \mathbf{y}\| = \|\mathbf{x} + \mathbf{y}\|$? What can you say about the geometry of the vectors \mathbf{x} , \mathbf{y} , $\mathbf{x} - \mathbf{y}$ and $\mathbf{x} + \mathbf{y}$?
4. If $S_1, S_2 \subseteq V$ are subspaces of V , the is $S_1 \cap S_2$ a subspace? Demonstrate your answer.
5. Prove that the sum of two subspaces $S_1, S_2 \subseteq V$ is a subspace.

6. Consider a vector $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$. Express the following

in terms of inner product between a vector \mathbf{u} and \mathbf{v} , and in each case specify the vector \mathbf{u} .

- (a) $\sum_{i=1}^n v_i$
 (b) $\frac{1}{n} \sum_{i=1}^n v_i$
 (c) $\sum_{i=1}^n v_i x^{(n-i)}$, where $x \in \mathbb{R}$
 (d) $\frac{1}{n-1} \sum_{i=1}^n (v_i - \frac{1}{n} \sum_{i=1}^n v_i)^2$
 (e) $\frac{1}{5} \sum_{i=3}^5 v_i$
 (f) $\sum_{i=1}^{n-1} (v_{i+1} - v_i)$
 (g) $\sqrt{v_n}$
 (h) $\sum_{i=1}^n w_i v_i^2$

7. Which of the following are linear functions of $\{x_1, x_2, \dots, x_n\}$?

- (a) $\min_i \{x_i\}_{i=1}^n$
 (b) $(\sum_{i=1}^n x_i^2)^{1/2}$
 (c) x_6

8. Consider a linear function $f: \mathbb{R}^n \rightarrow \mathbb{R}$. Prove that every linear function of this form can be represented in the following form.

$$y = f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} = \sum_{i=1}^n w_i x_i, \quad \mathbf{x}, \mathbf{w} \in \mathbb{R}^n$$

9. An *affine* function f is defined as the sum of a linear function and a constant. It can in general be represented in the form,

$$y = f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + \beta, \quad \mathbf{x}, \mathbf{w} \in \mathbb{R}^n, \beta \in \mathbb{R}$$

Prove that affine functions are not linear. Prove that any affine function can be represented in the form $\mathbf{w}^T \mathbf{x} + \beta$.

10. Consider a function $f: \mathbb{R}^3 \rightarrow \mathbb{R}$, such that,

$$f\left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}\right) = 2; \quad f\left(\begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}\right) = -3; \quad f\left(\begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}\right) = 1;$$

Can you determine the following values of $f(\mathbf{x})$, if you are told that f is linear?

$$f\left(\begin{bmatrix} 2 \\ 2 \\ -2 \end{bmatrix}\right) = ?; \quad f\left(\begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}\right) = ?; \quad f\left(\begin{bmatrix} 0.5 \\ 0.6 \\ -0.1 \end{bmatrix}\right) = ?;$$

Can you find out these values if you are told that f is affine?

11. For the previous question, (a) assume that f is linear and find out $\mathbf{w} \in \mathbb{R}^3$, such that $f(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$; and (b) assume f is affine and find out \mathbf{w}, β such that $f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + \beta$.

12. Consider the weighted norm of vector \mathbf{v} , defined as,

$$\|\mathbf{v}\|_{\mathbf{w}}^2 = \sum_{i=1}^n w_i v_i^2; \quad \mathbf{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$$

Is this a valid norm?

13. Prove that the following modified version of the Cauchy-Bunyakovski-Schwartz Inequality is true.

$$\left| \sum_{i=1}^n u_i v_i w_i \right| \leq \|\mathbf{u}\|_{\mathbf{w}} \|\mathbf{v}\|_{\mathbf{w}}$$

14. Consider a basis $B = \{\mathbf{b}_i\}_{i=1}^n$ of \mathbb{R}^n . Let the vector \mathbf{x} with the following representations in the standard and B basis.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n x_i \mathbf{e}_i \quad \text{and} \quad \mathbf{x}_b = \begin{bmatrix} x_{b1} \\ x_{b2} \\ \vdots \\ x_{bn} \end{bmatrix} = \sum_{i=1}^n x_{bi} \mathbf{b}_i$$

Evaluate the $\|\mathbf{x}\|_2^2$ and $\|\mathbf{x}_b\|_2^2$. Determine what happens to $\|\mathbf{x}_b\|_2^2$ under the following conditions on the basis vectors:

- (a) $\|\mathbf{b}_i\| = 1, \forall i$
 (b) $\|\mathbf{b}_i^T \mathbf{b}_j\| = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$

15. Consider a set of measurements made from adult male subjects, where their height, weight and BMI (body mass index) were recorded as stored as vectors of length three; the first element is the height in cm , second is the weight in Kg , and the last the BMI. Consider the following four subjects,

$$\mathbf{s}_1 = \begin{bmatrix} 167 \\ 102 \\ 36.6 \end{bmatrix}; \mathbf{s}_2 = \begin{bmatrix} 180 \\ 87 \\ 26.9 \end{bmatrix}$$

$$\mathbf{s}_3 = \begin{bmatrix} 177 \\ 78 \\ 24.9 \end{bmatrix}; \mathbf{s}_4 = \begin{bmatrix} 152 \\ 76 \\ 32.9 \end{bmatrix}$$

You can use the distance between these vectors $\|\mathbf{s}_i - \mathbf{s}_j\|_2$ as a measure of the similarity between the the four subjects. Generate a 4×4 table comparing the distance of each subject with respect to another subject; the diagonal elements of this table will be zero, and it will be symmetric about the main diagonal.

- (a) Based on this table, how do the different subjects compare to each other?
- (b) How do the similarities change if the height had been measured in m instead of cm ? Can you explain this difference?
- (c) Is there a way to fix this problem? Consider the weighted norm presented in one of the earlier problems.

$$\|\mathbf{x}\|_{\mathbf{w}} = (w_1 x_1^2 + w_2 x_2^2 + \dots + w_n x_n^2)^{\frac{1}{2}}$$

- (d) What would be a good choice for \mathbf{w} to address the problems with comparing distance between vectors due to change in units?
- (e) Can the angle between two vectors be used as a measure of similarity between vectors? Does this suffer from the problem of $\|\mathbf{x}\|_2$?

Matrices

16. Elements of the matrix $\mathbf{C} \in \mathbb{R}^{m \times n}$ obtained as the product of two matrices $\mathbf{A} \in \mathbb{R}^{m \times p}$ and $\mathbf{B} \in \mathbb{R}^{p \times n}$ is given by,

$$c_{ij} = \sum_{k=1}^p a_{ik} b_{kj}$$

We had discussed four different ways to think of matrix multiplication. By algebraically manipulating the previous equation arrive at these four views (inner product view, column view, row view and outer product view)?

17. Given the matrices $\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ -1 & 3 & -1 & -1 \\ 2 & -2 & 0 & 2 \\ 1 & 0 & -3 & 0 \end{bmatrix}$,

$$\mathbf{B} = \begin{bmatrix} -1 & 1 \\ 0 & 1 \\ -1 & 1 \\ -0 & 1 \end{bmatrix} \text{ and } \mathbf{C} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix}. \text{ Evaluate the}$$

following products.

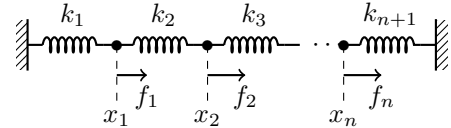
- (a) \mathbf{AB} (b) $\mathbf{A}^2 \mathbf{B}$ (c) $\mathbf{CB}^T \mathbf{A}$ (d) \mathbf{C}^3 (e) \mathbf{ABC}

18. Consider the following matrix,

$$\mathbf{A} = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} \begin{bmatrix} 0.1 & 0 \\ 0 & 0.9 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

Find out the expression for $\mathbf{A}_n = \mathbf{A}^n$. What is $\mathbf{A}_\infty = \lim_{n \rightarrow \infty} \mathbf{A}^n$?

19. Derive force and displacement relationship for a series of $n+1$ springs (with spring constants k_i) connected in a line. There are n nodes, with f_i and x_i representing the force applied and resulting displacement at the i^{th} node.



- (a) Represent the relationship in the following form,

$$\mathbf{f} = \mathbf{K}\mathbf{x}; \mathbf{f} = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_n \end{bmatrix}; \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

- (b) What kind of a pattern does \mathbf{K} have?
- (c) Consider a specific case where $n = 5$ and $k = 1.5N.m^{-1}$. What should be forces applied at the four nodes in order to displace

$$\text{the spring } \mathbf{x} = \begin{bmatrix} 0.5 \\ -0.5 \\ 0 \\ 0 \end{bmatrix} m.$$

20. Prove that a matrix $\mathbf{M} \in \mathbb{R}^{n \times n}$ can always be written as a sum a symmetric matrix \mathbf{S} and a skew-symmetric matrix \mathbf{A} .

$$\mathbf{M} = \mathbf{S} + \mathbf{A}, \mathbf{S}^T = \mathbf{S} \text{ and } \mathbf{A}^T = -\mathbf{A}$$

Does this property also hold for a complex matrix $\mathbf{M} \in \mathbb{C}^{n \times n}$?

21. The trace of a matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ is defined as, $\text{trace}(\mathbf{A}) = \sum_{i=1}^n a_{ii}$. Prove the following,

- (a) $\text{trace}(\mathbf{A})$ is a linear function of \mathbf{A} .
- (b) $\text{trace}(\mathbf{AB}) = \text{trace}(\mathbf{BA})$
- (c) $\text{trace}(\mathbf{A}^T \mathbf{A}) = 0 \implies \mathbf{A} = 0$

22. Prove that the rank of an outer product \mathbf{xy}^T is 1, where $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $\mathbf{x}, \mathbf{y} \neq 0$.

23. Is there a relationship between the space of solutions to the following two equations?

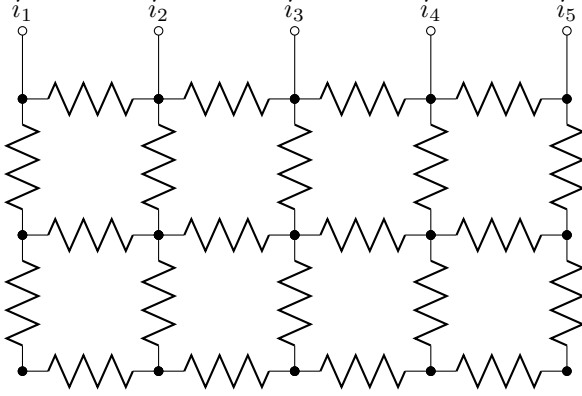
$$\mathbf{y}^T \mathbf{A} = \mathbf{c}^T \text{ and } \mathbf{Ax} = \mathbf{b}$$

If so, how are they related?

24. Consider an upper triangular and lower triangular matrices \mathbf{U} and \mathbf{L} , respectively.

- (a) Is the product of two upper triangular matrices $\mathbf{U}_1 \mathbf{U}_2$ upper triangular?
- (b) Is the product of two lower triangular matrices $\mathbf{L}_1 \mathbf{L}_2$ upper triangular?
- (c) What is the *trace* ($\mathbf{L}\mathbf{U}$)?

25. Consider the following electrical circuit with rectangular grid of resistors R . The input to this grid is a set of current injected at the top node as shown in the figure, such that $\sum_{k=1}^5 i_k = 0$.



Express the relationship between the voltages at the different nodes (represented by \bullet in the figure) and the net current flowing in/out of the node in the following form, $\mathbf{G}\mathbf{v} = \mathbf{i}$. Where, \mathbf{G} is the conductance matrix, \mathbf{v} is the vector of node voltages, and \mathbf{i} is the vector representing the net current flow in/out of the different node.

26. Consider the following system.

$$\begin{bmatrix} 1 & 5 & 1 & 2 \\ 2 & -1 & 0 & 2 \\ 4 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \end{bmatrix} \mathbf{x}_i = b_i$$

Solve the above equation using *LU* factorization for the following \mathbf{b}_i s.

$$\mathbf{b}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \mathbf{b}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \mathbf{b}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \mathbf{b}_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$$

Construct a matrix \mathbf{X} using the four solutions $\mathbf{x}_1, \mathbf{x}_2, \mathbf{x}_3$ and \mathbf{x}_4 as its columns.

$$\mathbf{X} = [\mathbf{x}_1 \quad \mathbf{x}_2 \quad \mathbf{x}_3 \quad \mathbf{x}_4]$$

Find out $\mathbf{X}\mathbf{A}$ and $\mathbf{A}\mathbf{X}$. Based on this what can you say about \mathbf{X} ?

27. How many different reduced row echelon forms can a matrix $\mathbf{A} \in \mathbb{R}^{4 \times 5}$ have? Hint: *Think in terms of basic and non-basic columns.*
28. Consider the system of equation, $\mathbf{A}\mathbf{x} = \mathbf{b}$, such that a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{x}, \mathbf{b} \in \mathbb{R}^n$. Are the following statements true? Explain your answer.
- (a) $\text{rank } \mathbf{A} \leq \min(m, n)$
- (b) The system is consistent if $\text{rank } \mathbf{A} = m$.

- (c) The system has a unique solution if $\text{rank } \mathbf{A} = n$.

29. If two systems of linear equations are consistent, with augmented matrices $[\mathbf{A}|\mathbf{b}]$ and $[\mathbf{A}|\mathbf{c}]$. Is $[\mathbf{A}|\mathbf{b} + \mathbf{c}]$ consistent?
30. If a matrix \mathbf{A} has LU decomposition, such that $\mathbf{A} = \mathbf{L}\mathbf{U}$. Demonstrate that it also has a LDU decomposition $\mathbf{A} = \mathbf{L}\mathbf{D}\hat{\mathbf{U}}$, where \mathbf{D} is a diagonal matrix, and $\hat{\mathbf{U}}$ is upper triangular. What happens to the LU and LDU decompositions when a matrix $\mathbf{A} = \mathbf{A}^T$?
31. Write down a basis for the four fundamental subspaces of the following matrix,

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & -3 & 4 & -1 & 0 \\ 4 & 8 & 12 & -8 & 2 & 1 \\ 2 & 3 & 2 & 1 & -2 & 0 \\ -3 & -1 & 1 & -4 & 0 & -1 \\ 1 & -2 & -1 & 0 & 0 & 0 \end{bmatrix}$$

32. Consider a matrix $\mathbf{A} = \begin{bmatrix} 1 & 4 & 5 \\ 4 & 118 & 26 \\ 3 & 16 & 30 \end{bmatrix}$.

- (a) Apply Gaussian elimination to simply this matrix into an upper-triangular matrix \mathbf{U} .
- (b) What is the corresponding upper-triangular matrix $\tilde{\mathbf{U}}$ obtained by applying Gaussian elimination to \mathbf{A}^T ?
- (c) Could you have arrived at $\tilde{\mathbf{U}}$ without having to repeat the Gaussian elimination process on \mathbf{A}^T ?
- (d) Write down the LDU decompositions of \mathbf{A} and \mathbf{A}^T .

33. Derive the inverse of the matrix $\mathbf{A} = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$.

34. Consider the following upper-triangular matrix,

$$\mathbf{U} = \begin{bmatrix} u_{11} & u_{12} & u_{13} & \cdots & u_{1n} \\ 0 & u_{22} & u_{23} & \cdots & u_{2n} \\ 0 & 0 & u_{33} & \cdots & u_{3n} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & u_{nn} \end{bmatrix}$$

where, $u_{ii} \neq 0$, $1 \leq i \leq n$. Do the columns of this matrix form a linearly independent set? Explain your answer.

35. Verify that \mathbf{A} and \mathbf{B} are inverses of each other,
- (a) $\mathbf{A} = \mathbf{I} - \mathbf{u}\mathbf{v}^T$ and $\mathbf{B} = \mathbf{I} + \mathbf{u}\mathbf{v}^T / (1 - \mathbf{v}^T \mathbf{u})$
- (b) $\mathbf{A} = \mathbf{C} - \mathbf{u}\mathbf{v}^T$ and $\mathbf{B} = \mathbf{C}^{-1} + \mathbf{C}^{-1} \mathbf{u}\mathbf{v}^T \mathbf{C}^{-1} / (1 - \mathbf{v}^T \mathbf{C}^{-1} \mathbf{u})$
- (c) $\mathbf{A} = \mathbf{I} - \mathbf{U}\mathbf{V}$ and $\mathbf{B} = \mathbf{I}_n + \mathbf{U}(\mathbf{I}_m - \mathbf{V}\mathbf{U})^{-1} \mathbf{V}$
- (d) $\mathbf{A} = \mathbf{C} - \mathbf{U}\mathbf{D}^{-1} \mathbf{V}$ and $\mathbf{B} = \mathbf{A}^{-1} + \mathbf{A}^{-1} \mathbf{U}(\mathbf{D} - \mathbf{V}\mathbf{A}^{-1} \mathbf{U})^{-1} \mathbf{V}\mathbf{A}^{-1}$

where, $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$, $\mathbf{u}, \mathbf{v} \in \mathbb{R}^n$, $\mathbf{U} \in \mathbb{R}^{n \times m}$, $\mathbf{V} \in \mathbb{R}^{m \times n}$ and $\mathbf{D} \in \mathbb{R}^{m \times m}$.

Orthogonality

36. Consider an orthonormal set of vectors $V = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r\}$, $\mathbf{v}_i \in \mathbb{R}^n \ \forall i \in \{1, 2, \dots, r\}$. If there is a vector $\mathbf{w} \in \mathbb{R}^n$ such that $\mathbf{v}_i^T \mathbf{w} = 0 \ \forall i \in \{1, 2, \dots, r\}$. Prove that $\mathbf{w} \notin \text{span}(V)$.
37. Consider the following set of vectors in \mathbb{R}^4 .

$$V = \left\{ \begin{bmatrix} 1 \\ -2 \\ 0 \\ 3 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ 1 \\ 4 \end{bmatrix} \right\}$$

Find the set of all vectors that are orthogonal to V ?

38. For a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, prove that $C(\mathbf{A}) \perp N(\mathbf{A}^t)$ and $C(\mathbf{A}^T) \perp N(\mathbf{A})$.
39. If the columns of a matrix $\mathbf{A} \in \mathbb{R}^{n \times n}$ are orthonormal, prove that $\mathbf{A}^{-1} = \mathbf{A}^T$. What is $\mathbf{A}^T \mathbf{A}$ when \mathbf{A} is rectangular ($\mathbf{A} \in \mathbb{R}^{m \times n}$) with orthonormal columns?
40. What will happen when the Gram-Schmidt procedure is applied to: (a) orthonormal set of vectors; and (b) orthogonal set of vectors? If the set of vectors are columns of a matrix \mathbf{A} , then what are the corresponding \mathbf{Q} and \mathbf{R} matrices for the orthonormal and orthogonal cases?
41. Consider the linear map, $\mathbf{y} = \mathbf{A}\mathbf{x}$, such that $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $\mathbf{A} \in \mathbb{R}^{n \times n}$. Let us assume that \mathbf{A} is full rank. What conditions must \mathbf{A} satisfy for the following statements to be true,
- $\|\mathbf{y}\|_2 = \|\mathbf{x}\|_2$, for all \mathbf{x}, \mathbf{y} such that $\mathbf{y} = \mathbf{A}\mathbf{x}$.
 - $\mathbf{y}_1^T \mathbf{y}_2 = \mathbf{x}_1^T \mathbf{x}_2$, for all $\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}_1, \mathbf{y}_2$ such that $\mathbf{y}_1 = \mathbf{A}\mathbf{x}_1$ and $\mathbf{y}_2 = \mathbf{A}\mathbf{x}_2$.
42. Prove that the rank of an orthogonal projection matrix $\mathbf{P}_S = \mathbf{U}\mathbf{U}^T$ onto a subspace S is equal to the $\dim S$, where the columns of \mathbf{U} form an orthonormal basis of S .
43. If the columns of $\mathbf{A} \in \mathbb{R}^{m \times n}$ represent a basis for the subspace $S \subset \mathbb{R}^m$. Find the orthogonal projection matrix \mathbf{P}_S onto the subspace S . Hint: Gram-Schmidt orthogonalization.
44. Consider two orthogonal matrices \mathbf{Q}_1 and \mathbf{Q}_2 . Is the $\mathbf{Q}_2^T \mathbf{Q}_1$ an orthogonal matrix? If yes, prove that it is so, else provide a counter-example showing $\mathbf{Q}_2^T \mathbf{Q}_1$ is not orthogonal.
45. Let \mathbf{P}_S represent an orthogonal projection matrix onto to the subspace $S \subset \mathbb{R}^n$. What can you say about the rank of the matrix \mathbf{P}_S ? Explain how you can obtain an orthonormal basis for S from \mathbf{P}_S .
46. Consider a 1 dimensional subspace spanned by the vector $\mathbf{u} \in \mathbb{R}^n$. What kind of a geometric operation does the matrix $\mathbf{I} - 2\frac{\mathbf{u}\mathbf{u}^T}{\mathbf{u}^T \mathbf{u}}$ represent?
47. Prove that when a triangular matrix is orthogonal, it is diagonal.

48. If an orthogonal matrix $\mathbf{Q} \in \mathbb{R}^{n \times n}$ is to be partitioned such that, $\mathbf{Q} = [\mathbf{Q}_1 \ \mathbf{Q}_2]$, then prove that $C(\mathbf{Q}_1) \perp C(\mathbf{Q}_2)$.
49. Find an orthonormal basis for the subspace spanned by $\left\{ \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 3 \end{bmatrix} \right\}$.

Matrix Inverses

50. Consider the following bases for \mathbb{R}^3 .

$$\mathbf{A}^S = \left\{ \frac{1}{\sqrt{3}} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{\sqrt{6}} \begin{bmatrix} -1 \\ 2 \\ -1 \end{bmatrix}, \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$$

$$\mathbf{B}^A = \left\{ \frac{1}{\sqrt{5}} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}, \frac{1}{\sqrt{5}} \begin{bmatrix} -1 \\ 2 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$$

Where, X^Y is the basis X represented in another basis Y ; S stands for the standard basis. Let \mathbf{b}_X stand for the representation of vector in \mathbb{R}^3 in the basis X .

- Consider a vector $\mathbf{b}_S = \begin{bmatrix} -1 \\ 0 \\ 2 \end{bmatrix}$ represented in the standard basis. What is the representation of \mathbf{b}_S in the other four basis A , and B ?
- Consider a vector $\mathbf{d}_B = \begin{bmatrix} -1 \\ -1 \\ 0 \end{bmatrix}$ represented in the basis B . What is the representation of this vector in the standard basis?

51. When does the following diagonal matrix have an inverse?

$$\mathbf{D} = \begin{bmatrix} d_1 & 0 & 0 & \dots & 0 \\ 0 & d_2 & 0 & \dots & 0 \\ 0 & 0 & d_3 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & d_n \end{bmatrix}$$

Write down an expression for \mathbf{D}^{-1} .

52. Prove that the inverse of a non-singular upper-triangular matrix is upper-triangular. Using this show that for a lower triangular matrix it is lower-triangular.
53. Consider a 2×2 block matrix, $\mathbf{A} = \begin{bmatrix} \mathbf{B} & \mathbf{C} \\ \mathbf{D} & \mathbf{E} \end{bmatrix}$, where $\mathbf{A} \in \mathbb{R}^{m \times m}$. Find an expression for the inverse \mathbf{A}^{-1} in terms of the block components and their inverses (if they exist) of \mathbf{A} . Hint: Consider $\mathbf{A}^{-1} = \begin{bmatrix} \mathbf{P} & \mathbf{Q} \\ \mathbf{R} & \mathbf{S} \end{bmatrix}$, and solve $\mathbf{A}\mathbf{A}^{-1} = \mathbf{I}$.
54. Express the inverse of the following matrix in terms of \mathbf{A} and \mathbf{b} .

$$\mathbf{H} = \begin{bmatrix} \mathbf{A} & \mathbf{b} \\ \mathbf{0} & 1 \end{bmatrix} \in \mathbb{R}^{(n+1) \times (n+1)}$$

where, $\mathbf{A} \in \mathbb{R}^{n \times n}$ and $\mathbf{b} \in \mathbb{R}^n$.

55. Consider a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ with linearly independent columns. Prove that the Gram matrix $\mathbf{A}^T \mathbf{A}$ is invertible.
56. Find all possible left/right inverses for the following matrices, if they exist.

(a) $\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ -1 & -2 & -3 & -4 \end{bmatrix}$

(b) $\mathbf{A} = \begin{bmatrix} 1 & -1 & 0 & 0 & -2 \\ 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 1 & -1 \end{bmatrix}$

(c) $\mathbf{A} = \begin{bmatrix} 1 & 2 \\ -1 & 0 \\ -3 & 4 \end{bmatrix}$

(d) $\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 & 2 \\ 1 & 2 & 3 & 3 & 3 \\ 1 & 2 & 3 & 4 & 5 \\ 1 & 2 & 3 & 4 & 5 \end{bmatrix}$

For each of these matrices find the corresponding pseudo-inverse \mathbf{A}^\dagger , and verify that the pseudo-inverse has the minimum squared sum of its components.

57. Prove that the inverse of a non-singular symmetric matrix is symmetric.
58. Consider the scalar equation, $ax = ay$. Here we can cancel a from the equation when $a \neq 0$. When can we carry out similar cancellations for matrices?
- (a) $\mathbf{A}\mathbf{X} = \mathbf{A}\mathbf{Y}$. Prove that here $\mathbf{X} = \mathbf{Y}$ only when \mathbf{A} is left invertible.
- (b) $\mathbf{X}\mathbf{A} = \mathbf{Y}\mathbf{A}$. Prove that here $\mathbf{X} = \mathbf{Y}$ only when \mathbf{A} is right invertible.
59. Consider two non-singular matrices $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$. Explain whether or not the following matrices are invertible. If they are, then provide an expression for its inverse.

(a) $\mathbf{C} = \mathbf{A} + \mathbf{B}$

(b) $\mathbf{C} = \begin{bmatrix} \mathbf{A} & \mathbf{0} \\ \mathbf{0} & \mathbf{B} \end{bmatrix}$

(c) $\mathbf{C} = \begin{bmatrix} \mathbf{A} & \mathbf{A} + \mathbf{B} \\ \mathbf{0} & \mathbf{B} \end{bmatrix}$

(d) $\mathbf{C} = \mathbf{A}\mathbf{B}\mathbf{A}$

60. Consider the matrices $\mathbf{A} \in \mathbb{R}^{m \times l_1}$ and $\mathbf{B} \in \mathbb{R}^{l_2 \times m}$. Can you find the requirements for matrices \mathbf{A} and \mathbf{B} , such that $\mathbf{A}\mathbf{X}\mathbf{B} = \mathbf{I}$, where $\mathbf{X} \in \mathbb{R}^{l_1 \times l_2}$? Assuming those conditions are satisfied, find an expression for \mathbf{X} ?
61. Consider a matrix $\mathbf{C} = \mathbf{A}\mathbf{B}$, where $\mathbf{A} \in \mathbb{R}^{m \times n}$ and $\mathbf{B} \in \mathbb{R}^{n \times m}$. Explain why \mathbf{C} is not invertible when $m > n$. Suppose $m < n$, under what conditions is \mathbf{C} invertible?
62. For a non-singular square matrix \mathbf{A} , prove that $(\mathbf{A}^T)^{-1} = (\mathbf{A}^{-1})^T$.

63. For a square matrix \mathbf{A} with non-singular $\mathbf{I} - \mathbf{A}$, prove that $\mathbf{A}(\mathbf{I} - \mathbf{A})^{-1} = (\mathbf{I} - \mathbf{A})^{-1}\mathbf{A}$.
64. Consider the non-singular matrices \mathbf{A} , \mathbf{B} and $\mathbf{A} + \mathbf{B}$. Prove that,

$$\mathbf{A}(\mathbf{A} + \mathbf{B})^{-1}\mathbf{B} = \mathbf{B}(\mathbf{A} + \mathbf{B})^{-1}\mathbf{A} = (\mathbf{A}^{-1} + \mathbf{B}^{-1})^{-1}$$

Least Squares

65. The least square approximate solution to problem $\mathbf{A}\mathbf{x} = \mathbf{b}$, $\mathbf{A} \in \mathbb{R}^{m \times n}$ is obtained by minimizing the following objective function,

$$O(\mathbf{x}) = \|\mathbf{A}\mathbf{x} - \mathbf{b}\|^2 = \sum_{i=1}^m (\tilde{\mathbf{a}}_i^T \mathbf{x} - \mathbf{b}_i)^2$$

If the objective function was defined differently, where the different components were given different weights for the different terms,

$$O_w(\mathbf{x}) = \sum_{i=1}^m w_i (\tilde{\mathbf{a}}_i^T \mathbf{x} - \mathbf{b}_i)^2$$

This is the *weighted least squares*. Find the expression for the approximate solution of the weighted least squares problem.

66. Consider a matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$ with independent columns. There is no matrix \mathbf{X} , such that $\mathbf{A}\mathbf{X} = \mathbf{I}$. Find an expression for the matrix \mathbf{X} , such that $\|\mathbf{A}\mathbf{X} - \mathbf{I}\|^2$ is minimum. Hint: Consider the individual columns of \mathbf{X} and \mathbf{I} .
67. Consider the following polynomial equation,

$$y = \sum_{i=0}^n \beta_i x^i, \quad x, y, \beta_i \in \mathbb{R}$$

This expression is linear in the polynomial coefficients. Fitting a polynomial to data can be done through a linear least square procedure. Consider a set of measurements $\{(x_l, y_l)\}_{l=1}^m$. We are interested in fitting a polynomial that fits this data, such that the difference between the polynomial and data is as low as possible.

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^n \\ 1 & x_1 & x_1^2 & \dots & x_1^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_m & x_m^2 & \dots & x_m^n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{bmatrix}$$

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta}$$

\mathbf{X} is called the *Vandermonde* matrix. To estimate $\boldsymbol{\beta}$ through a least squares procedure, \mathbf{X} must have independent columns. Prove that for a set of different x_i s the *Vandermonde* matrix has independent columns.

You are provided with CSV format data file (poly-fit.csv) containing data $\{(x_l, y_l)\}_{l=1}^m$, to which you are required to fit a polynomial function. The choice of the order of the polynomial is up to you. This can be come from *a priori* knowledge of the system from which data is collected, or it can be decided based on eyeballing the scatter plot between x_i and y_i .

- (a) **Data fitting error:** Fit polynomials of orders 0 to 10 to the given data, and for each order determine the data fitting error.

$$e_n = \|\mathbf{X}\hat{\beta} - \mathbf{y}\|$$

Plot e_n versus the polynomial model order n . You should observe the fitting error to monotonically decrease as a function of n . Why is this? Can e_n ever be zero?

- (b) **Model validation:** Even though increasing the polynomial order decreases the data fitting error, this is not always desirable. Given that noise is ubiquitous in all measurements, increasing model order will result in a polynomial that not only fits the general trend in the data, but also the observed measurement noise. Thus, the optimal choice for the model order is determined through a validation procedure, where the data is split into two sets - *training* set and a *testing* set. In order to understand this, you are required to:

- i. Split your data D into two sets of size 80% and 20%, corresponding to the *training* D_{train} and *testing* D_{test} sets; these percentages are arbitrary. Split your data randomly, such that each data entry is randomly assigned to D_{train} and D_{test} .
- ii. Fit the polynomial model of a particular order to D_{train} . Let the model parameters obtained be $\hat{\beta}$. The validation error for this model is defined as the following.

$$e_n^{val} = \|\mathbf{X}\hat{\beta} - \mathbf{y}\|$$

where, \mathbf{X} and \mathbf{y} comes from the test data set D_{test} . Estimate the validation error for different models order 0 to 10, and plot e_n^{val} versus the polynomial model order n . How is this plot different from the plot e_n versus n ? What is the optimal choice for the model order based on the validation procedure?

- (c) **Regularized data fitting:** Instead of minimizing $\|\mathbf{X}\beta - \mathbf{y}\|^2$ of the data, now fit a model that minimizes, $\|\mathbf{X}\beta - \mathbf{y}\|^2 + \lambda\beta^T\beta$, where $\lambda \geq 0$. In this particular case fit the model order to a high value (e.g. 10) and the entire data set D . Perform the data fitting procedure for different values of λ . Plot $\|\mathbf{X}\beta - \mathbf{y}\|$ versus λ . Compare the values of $\hat{\beta}$ for the different values of λ and compare these to your optimal choice of model parameters from the previous question.

68. Consider a time series $\mathbf{x} = \{x_0, x_1, \dots, x_{N-1}\}$ consisting of N data points, where n indicates time index. The time series is corrupted by noise, and we are interested in filtering the time series to obtain a smooth estimate of the the general trend in the time series. This can be posed a problem of estimating a new time series $\hat{\mathbf{x}}$, such that the difference

$\mathbf{x} - \hat{\mathbf{x}}$ is minimized and $\hat{\mathbf{x}}$ is smooth, i.e. the adjacent values of the signal do not change abruptly.

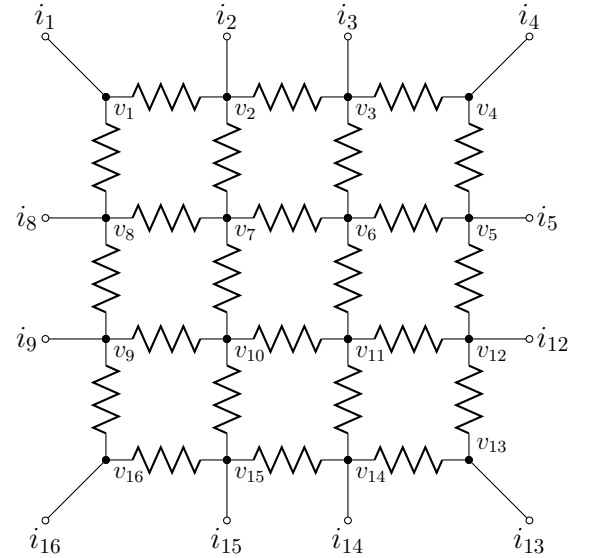
$$O(\hat{\mathbf{x}}) = \sum_{i=1}^N (x_i - \hat{x}_i)^2 + \lambda \sum_{i=2}^{N-1} (2\hat{x}_i - \hat{x}_{i-1} - \hat{x}_{i+1})^2$$

If \mathbf{x} and $\hat{\mathbf{x}}$ are considered as N -vectors, then this can be written as

$$O(\hat{\mathbf{x}}) = \|\mathbf{x} - \hat{\mathbf{x}}\|^2 + \lambda \|\mathbf{D}\hat{\mathbf{x}}\|^2$$

You are provided with a CSV data file (time-series.csv) consisting of a time series. Filter this time series by minimizing $O(\hat{\mathbf{x}})$ for different values of λ . Plot \mathbf{x} and $\hat{\mathbf{x}}$ for different values of λ . What role does λ play in the minimization problem?

69. Consider the following resistive network, where the value of each resistance is $R = 1\Omega$. Your goal is to determine a set of currents in the $\mathbf{i} = [i_1 \ i_2 \ \dots \ i_{16}]^T$, so as to achieve a particular distribution of potentials at the different nodes of the network. Node that we have control only over the currents at the edge nodes, and in the internal nodes the current is zero, i.e. $i_6 = i_7 = i_{10} = i_{11} = 0$.



Let $\mathbf{v} = [v_1 \ v_2 \ \dots \ v_{16}]$ represent the vector of potential distributions in the network. Then determine \mathbf{i} such that $\|\mathbf{v}_T - \mathbf{v}\|^2$ is minimized for the following desired potential distribution (Note that the potentials are arranged in a matrix $\mathbf{V}_{map} =$

$$\begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_8 & v_7 & v_6 & v_5 \\ v_9 & v_{10} & v_{11} & v_{12} \\ v_{16} & v_{15} & v_{14} & v_{13} \end{bmatrix}$$

$$(a) \mathbf{V}_{map} = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

$$(b) \mathbf{V}_{map} = \begin{bmatrix} 2 & 2 & 2 & 2 \\ 2 & 1 & 1 & 2 \\ 2 & 1 & 1 & 2 \\ 2 & 2 & 2 & 2 \end{bmatrix}$$

$$(c) \quad \mathbf{V}_{map} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

for some desired potential distribution \mathbf{v}_T , subject to the constraint $\sum_{k=1}^{16} i_k = 0$.

References

- [1] G. Strang *Introduction to linear algebra*. Wellesley-Cambridge Press Wellesley, MA, USA, 1993