Linear Control and Estimation: Assignment

Vectors

- 1. Is set of vectors $\left\{ \begin{bmatrix} 2\\1\\1 \end{bmatrix}, \begin{bmatrix} 0\\0\\0 \end{bmatrix}, \begin{bmatrix} 0\\1\\0 \end{bmatrix} \right\}$ independent? Explain your answer.
- 2. Prove the following for $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$
 - (a) Triangle Inequality:

$$\|\mathbf{x} + \mathbf{y}\| \le \|\mathbf{x}\| + \|\mathbf{y}\|$$

(b) Backward Triangle Inequality:

$$\|\mathbf{x} - \mathbf{y}\| \ge |\|\mathbf{x}\| - \|\mathbf{y}\||$$

(c) Parallelogram Idenitity:

$$\frac{1}{2} \left(\| \mathbf{x} + \mathbf{y} \|^2 + \| \mathbf{x} - \mathbf{y} \|^2 \right) = \| \mathbf{x} \|^2 + \| \mathbf{y} \|^2$$

- 3. Consider a set of vectors $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$. When is $\|\mathbf{x} \mathbf{y}\| = \|\mathbf{x} + \mathbf{y}\|$? What can you say about the geometry of the vectors $\mathbf{x}, \mathbf{y}, \mathbf{x} \mathbf{y}$ and $\mathbf{x} + \mathbf{y}$?
- 4. If $S_1, S_2 \subseteq V$ are subspaces of V, the is $S_1 \cap S_2$ a subspace? Demonstrate your answer.
- 5. Prove that the sum of two subspaces $S_1, S_2 \subseteq V$ is a subspace.
- 6. Consider a vector $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$. Express the following

in terms of inner product between a vector \mathbf{u} and \mathbf{v} , and in each case specify the vector \mathbf{u} .

- (a) $\sum_{i=1}^n v_i$
- (b) $\frac{1}{n} \sum_{i=1}^{n} v_i$
- (c) $\sum_{i=1}^{n} v_i x^{(n-i)}$, where $x \in \mathbb{R}$
- (d) $\frac{1}{n-1} \sum_{i=1}^{n} \left(v_i \frac{1}{n} \sum_{i=1}^{n} v_i \right)^2$
- (e) $\frac{1}{5} \sum_{i=3}^{5} v_i$
- (f) $\sum_{i=1}^{n-1} (v_{i+1} v_i)$
- (g) $\sqrt{v_n}$
- $(h) \sum_{i=1}^{n} w_i v_i^2$
- 7. Which of the following are linear functions of $\{x_1, x_2, \dots, x_n\}$?
 - (a) $\min_i \left\{ x_i \right\}_{i=1}^n$
 - (b) $\left(\sum_{i=1}^{n} x_i^2\right)^{1/2}$
 - (c) x_6
- 8. Consider a linear function $f: \mathbb{R}^n \to \mathbb{R}$. Prove that every linear function of this form can be represented in the following form.

$$y = f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} = \sum_{i=1}^n w_i x_i, \quad \mathbf{x}, \mathbf{w} \in \mathbb{R}^n$$

9. An affine function f is defined as the sum of a linear function and a constant. It can in general be represented in the form,

$$y = f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + \beta, \quad \mathbf{x}, \mathbf{w} \in \mathbb{R}^n, \, \beta \in \mathbb{R}$$

Prove that affine functions are not linear. Prove that any affine function can be represented in the form $\mathbf{w}^T \mathbf{x} + \beta$.

10. Consider a function $f: \mathbb{R}^3 \to \mathbb{R}$, such that,

$$f\left(\begin{bmatrix}1\\0\\0\end{bmatrix}\right)=2;\ f\left(\begin{bmatrix}0\\1\\0\end{bmatrix}\right)=-3;\ f\left(\begin{bmatrix}0\\0\\1\end{bmatrix}\right)=1;$$

Can you determine the following values of $f(\mathbf{x})$, if you are told that f is linear?

$$f\left(\begin{bmatrix}2\\2\\-2\end{bmatrix}\right)=?;\ f\left(\begin{bmatrix}-1\\2\\0\end{bmatrix}\right)=?;\ f\left(\begin{bmatrix}0.5\\0.6\\-0.1\end{bmatrix}\right)=?;$$

Can you find out these values if you are told that f is affine?

- 11. For the previous question, (a) assume that f is linear and find out $w \in \mathbb{R}^3$, such that $f(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$; and (b) assume f is affine and find out \mathbf{w}, β such that $f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + \beta$.
- 12. Consider the weighted norm of vector **v**, defined as,

$$\|\mathbf{v}\|_{\mathbf{w}}^2 = \sum_{i=1}^n w_i v_i^2; \quad \mathbf{w} = \begin{bmatrix} w_1 \\ w_2 \\ \vdots \\ w_n \end{bmatrix}$$

Is this a valid norm?

13. Prove that the following modified version of the Cauchy-Bunyakovski-Schwartz Inequality is true.

$$\left| \sum_{i=1}^{n} u_i v_i w_i \right| \le \|\mathbf{u}\|_{\mathbf{w}} \|\mathbf{v}\|_{\mathbf{w}}$$

14. Consider a basis $B = \{\mathbf{b}_i\}_{i=1}^n$ of R^n . Let the vector \mathbf{x} with the following representations in the standard and B basis.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n x_i e_i \quad \text{and} \quad \mathbf{x}_b = \begin{bmatrix} x_{b1} \\ x_{b2} \\ \vdots \\ x_{bn} \end{bmatrix} = \sum_{i=1}^n x_{bi} b_i$$

Evaluate the $\|\mathbf{x}\|_2^2$ and $\|\mathbf{x}_b\|_2^2$. Determined what happens to $\|\mathbf{x}_b\|_2^2$ under the following conditions on the basis vectors:

(a) $\|\mathbf{b}_i\| = 1, \forall i$

1

(b)
$$\|\mathbf{b}_i^T \mathbf{b}_j\| = \begin{cases} 1 & i = j \\ 0 & i \neq j \end{cases}$$

15. Consider a set of measurements made from adult male subjects, where their height, weight and BMI (body moass index) were recorded as stored as vectors of length three; the first element is the height in cm, second is the weight in Kg, and the alst the the BMI. Consider the following four subjects,

$$\mathbf{s}_1 = \begin{bmatrix} 167 \\ 102 \\ 36.6 \end{bmatrix}; \ \mathbf{s}_2 = \begin{bmatrix} 180 \\ 87 \\ 26.9 \end{bmatrix}$$

$$\mathbf{s}_3 = \begin{bmatrix} 177 \\ 78 \\ 24.9 \end{bmatrix}; \ \mathbf{s}_4 = \begin{bmatrix} 152 \\ 76 \\ 32.9 \end{bmatrix}$$

You can use the distance between these vectors $\|\mathbf{s}_i - \mathbf{s}_j\|_2$ as a measure of the similarity between the the four subjects. Generate a 4×4 table comparing the distance of each subject with respect to another subject; the diagonal elements of this table will be zero, and it will be symmetric about the main diagonal.

- (a) Based on this table, how do the different subjects compare to each other?
- (b) How do the similarities change if the height had been measured in m instead of cm? Can you explain this difference?
- (c) Is there a way to fix this problem? Consider the weighted norm presented in one of the earlier problems.

$$||x||_{\mathbf{w}} = (w_1 x_1^2 + w_2 x_2^2 + \dots + w_n x_n^2)^{\frac{1}{2}}$$

- (d) What would be a good choice for \mathbf{w} to address the problems with comparing distance between vectors due to change in units?
- (e) Can the angle between two vectors be used as a measure of similarity between vectors? Does this suffer from the problem of $\|\mathbf{x}\|_2$?

References

[1] G. Strang Introduction to linear algebra. Wellesley-Cambridge Press Wellesley, MA, USA, 1993