# Linear Systems Matrix Inverses

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# References

- ► S Boyd, Applied Linear Algebra: Chapters 11.
- ▶ G Strang, Linear Algebra: Chapters 1.

▶ Consider the vector space  $\mathbb{R}^n$  with basis  $\{\mathbf{v}_1, \mathbf{v}_2, \dots \mathbf{v}_n\}$ . Any vector in  $\mathbf{b} \in \mathbb{R}^n$  can be representated as a linear combination of  $\mathbf{v}_i$ s.

$$\mathbf{b} = \sum_{i=1}^n \mathbf{v}_i \mathbf{a}_i = \mathbf{V} \mathbf{a}; \ \mathbf{a} \in \mathbb{R}^n, \ \mathbf{V} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \end{bmatrix} \in \mathbb{R}^{n \times n}$$



 $\{\mathbf{v}_1, \mathbf{v}_2\}, \{\mathbf{u}_1, \mathbf{u}_2\}$  and  $\{\mathbf{e}_1, \mathbf{e}_2\}$  are valid basis for  $\mathbb{R}^2$ , and the presentation for  $\mathbf{b}$  in each one of them is different.

lacktriangle Finding out  ${f a}$  is easiest when we are dealing with an orthonormal basis, in which case  ${f a}$  is given by,

$$\mathbf{a} = egin{bmatrix} \mathbf{u}_1^T b \ \mathbf{u}_2^T b \ dots \ \mathbf{b} \end{bmatrix} = \mathbf{U}^T \mathbf{b} \implies \mathbf{b}_U = \sum_{i=1}^n \left( \mathbf{u}_i^T b 
ight) \mathbf{u}_i = \mathbf{U} \mathbf{U}^T \mathbf{b}$$

Consider a vector  $\mathbf{b}$  whose representation in the standard basis is  $\mathbf{b} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$ .

• Consider a basis 
$$V = \left\{ \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}, \begin{bmatrix} -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix} \right\}$$
. Find out  $\mathbf{b}_V$ .

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- $U = \left\{ \begin{bmatrix} 1 \\ \frac{1}{2} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} \right\}$ . Find out  $\mathbf{b}_U$ .

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- $U = \left\{ \begin{bmatrix} 1 \\ \frac{1}{2} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} \right\}$ . Find out  $\mathbf{b}_U$ .
- $W = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ \frac{1}{2} \end{bmatrix} \right\}$ . Find out  $\mathbf{b}_W$ .

- ▶ Consider the equation Ax = y, where  $A \in \mathbb{R}^{n \times n}$  and  $x, y \in \mathbb{R}^n$ .
- **Let** us assume  ${f A}$  is non-singular  $\implies$  columns of  ${f A}$  represent a basis for  ${\mathbb R}^n$ .
- lacktriangle What does x represent? It is the representation of y in the basis consisting of the columns of A.

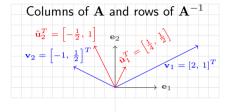
$$\mathbf{y} = \mathbf{A}\mathbf{x} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \dots & \mathbf{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n \mathbf{a}_i x_i \implies \mathbf{x} = \mathbf{A}^{-1}\mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_1^T \\ \tilde{\mathbf{b}}_2^T \\ \vdots \\ \tilde{\mathbf{b}}_n^T \end{bmatrix} \mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_1^T \mathbf{y} \\ \tilde{\mathbf{b}}_2^T \mathbf{y} \\ \vdots \\ \tilde{\mathbf{b}}_n^T \mathbf{y} \end{bmatrix}$$

 $ightharpoonup A^{-1}$  is a matrix that allows change of basis to the columns of A from the standard basis!

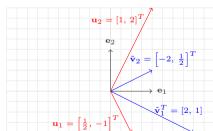
- ▶ Consider the equation  $\mathbf{A}\mathbf{x} = \mathbf{y}$ , where  $\mathbf{A} \in \mathbb{R}^{n \times n}$  and  $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ .
- Let us assume **A** is non-singular  $\implies$  columns of **A** represent a basis for  $\mathbb{R}^n$ .
- $\triangleright$  What does x represent? It is the representation of y in the basis consisiting of the columns of A.

$$\mathbf{y} = \mathbf{A}\mathbf{x} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \dots & \mathbf{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n \mathbf{a}_i x_i \implies \mathbf{x} = \mathbf{A}^{-1}\mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_1^T \\ \tilde{\mathbf{b}}_2^T \\ \vdots \\ \tilde{\mathbf{b}}_n^T \end{bmatrix} \mathbf{y} = \begin{bmatrix} \tilde{\mathbf{b}}_1^T \mathbf{y} \\ \tilde{\mathbf{b}}_2^T \mathbf{y} \\ \vdots \\ \tilde{\mathbf{b}}_n^T \mathbf{y} \end{bmatrix}$$

- $ightharpoonup A^{-1}$  is a matrix that allows change of basis to the columns of A from the standard basis!
- $W = \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ \frac{1}{2} \end{bmatrix} \right\}$ . Find  $\mathbf{b}_W$  by calculating the inverse of the matrix  $\mathbf{W} = \begin{bmatrix} 1 & -1 \\ 1 & \frac{1}{2} \end{bmatrix}$ . Does your answer match that of the previous approach?
- What about  $V = \left\{ \begin{bmatrix} 1/\sqrt{5} \\ 2/\sqrt{5} \end{bmatrix}, \begin{bmatrix} -2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix} \right\}$ . What is  $\mathbf{b}_V$ ?



Rows of  ${\bf A}$  and columns of  ${\bf A}^{-1}$ 



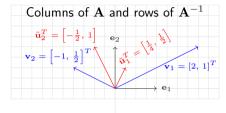
$$\mathbf{V} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 \end{bmatrix} = \begin{bmatrix} 2 & -1 \\ 1 & \frac{1}{2} \end{bmatrix}$$

$$\mathbf{V}^{-1} = \begin{bmatrix} \tilde{\mathbf{u}}_1^T \\ \tilde{\mathbf{u}}_2^T \end{bmatrix} = \frac{1}{2} \begin{bmatrix} \frac{1}{2} & 1 \\ -1 & 2 \end{bmatrix}$$

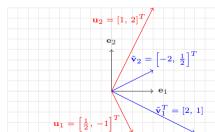
$$\mathbf{v}_1^T \tilde{\mathbf{u}}_1 = \mathbf{v}_2^T \tilde{\mathbf{u}}_2 = \tilde{\mathbf{v}}_1^T \mathbf{u}_1 = \tilde{\mathbf{v}}_2^T \mathbf{u}_2 = 1$$

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Rows of  ${\bf A}$  and columns of  ${\bf A}^{-1}$ 



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Verify these for 
$$\mathbf{W} = \begin{bmatrix} 1 & -1 \\ 1 & \frac{1}{2} \end{bmatrix}$$
 and 
$$\begin{bmatrix} 1/\sqrt{5} & -2/\sqrt{5} \end{bmatrix}$$

$$\mathbf{V} = \begin{bmatrix} 1/\sqrt{5} & -2/\sqrt{5} \\ 2/\sqrt{5} & 1/\sqrt{5} \end{bmatrix}.$$

- ▶ Consider a rectangular matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$ . There exists no inverse  $\mathbf{A}^{-1}$  for this matrix.
- ▶ But, does there exist two matrices  $\mathbf{B}, \mathbf{C} \in \mathbb{R}^{n \times m}$ , such that,

$$\mathbf{C}\mathbf{A} = \mathbf{I}_n$$
 and  $\mathbf{A}\mathbf{B} = \mathbf{I}_m$ 

- ▶ Both cannot be true for a rectangular matrix, only one can be true when the matrix is full rank.
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Consider a matrix 
$$\mathbf{A} = \begin{bmatrix} 1 & -2 \\ 2 & 1 \\ 1 & 1 \end{bmatrix}$$
. Let  $\mathbf{B}, \mathbf{C} \in \mathbb{R}^{2 \times 3}$ . Can you explain why only  $\mathbf{C}\mathbf{A} = \mathbf{I}_2$  can be true and not  $\mathbf{A}\mathbf{B} = \mathbf{I}_2$ ? Can you also explain why  $\mathbf{C}$  is not unique?

true and not  $AB = I_3$ ? Can you also explain why C is not unique?

- ▶ Any non-zero  $\mathbf{a} \in \mathbb{R}^{n \times 1}$  is left invertible:  $\mathbf{b}\mathbf{a} = 1, \ \mathbf{b} \in \mathbb{R}^{1 \times n}; \ \mathbf{b}^T = \frac{\mathbf{a}}{\|\mathbf{a}\|^2} + \alpha \mathbf{a}^{\perp}$
- ▶ This can be generalized to  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , m > n.

$$\left(\mathbf{C}+\hat{\mathbf{C}}
ight)\mathbf{A}=\mathbf{I}_{m} \ \ \mathsf{where} \ \mathbf{C},\hat{\mathbf{C}}\in\mathbb{R}^{n imes m}, \ \ \hat{\mathbf{C}}\mathbf{A}=\mathbf{0}$$

- ► Condition for left inverse of **A** to exist: *Colmuns of* **A** *must be independent.* 
  - $\longrightarrow rank(\mathbf{A}) = n \longrightarrow \mathbf{A}\mathbf{x} = 0 \implies \mathbf{x} = 0.$
- ▶ Ax = b can be solved, if and only if A(Cb) = b, where  $CA = I_n$ .

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• Let 
$$\mathbf{A} = \begin{bmatrix} 1 & -2 \\ 2 & 1 \\ 1 & 1 \end{bmatrix}$$
. Find a complete solution for the left inverse of  $\mathbf{A}$  such that  $\left(\mathbf{C} + \hat{\mathbf{C}}\right) = \mathbf{I}_n$ .

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- Consider the system,  $\mathbf{A}\mathbf{x} = \mathbf{b}$ .  $\mathbf{A} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ,  $\mathbf{x} = \begin{bmatrix} x \end{bmatrix}$ , and  $\mathbf{b} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ . Find  $\mathbf{x}$ .

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- Consider the system,  $\mathbf{A}\mathbf{x} = \mathbf{b}$ .  $\mathbf{A} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ ,  $\mathbf{x} = \begin{bmatrix} x \end{bmatrix}$ , and  $\mathbf{b} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ . Find  $\mathbf{x}$ .
- What happens when  $\mathbf{b} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ . What is  $\mathbf{x}$ ?

- ▶ For  $A \in \mathbb{R}^{m \times n}$ , n > m with full rank,  $AB = I_m \longrightarrow B$  is the right inverse.
- ▶ Right inverse of  $\mathbf{A}$  exists only if the rows of  $\mathbf{A}$  are independent, i.e.  $rank(\mathbf{A}) = m$   $\longrightarrow \mathbf{A}^T \mathbf{x} = \mathbf{0} \implies \mathbf{x} = \mathbf{0}$
- ▶ Ax = b can be solved for any b.  $x = Bb \implies A(Bb) = b$ .
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- $ightharpoonup \mathbf{A}\mathbf{x} = \mathbf{b}$  can be solved for any b.  $\mathbf{x} = \mathbf{B}\mathbf{b} \implies \mathbf{A}\left(\mathbf{B}\mathbf{b}\right) = \mathbf{b}$ .
- ightharpoonup There are an infitnite number of Bs  $\implies$  an infinite number of solutions  ${f x}$ .
- Let  $\mathbf{A} = \begin{bmatrix} 1 & -2 & 1 \\ 2 & 1 & -1 \end{bmatrix}$ . Find a complete solution for the right inverse of  $\mathbf{A}$ .
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- Let  $AB = I_m$ . What about the relationship between  $A^T$  and  $B^T$ ?

- $ightharpoonup \mathbf{A} \in \mathbb{R}^{m \times n}, \ rank\left(\mathbf{A}\right) = n$
- ► Subspaces of **A**:

$$C\left(\mathbf{A}
ight) \in \mathbb{R}^{m} \quad N\left(\mathbf{A}^{T}
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ight) = \{\mathbf{0}\}$$

- ▶ Let  $\mathbf{C} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ , such that  $\mathbf{C}\mathbf{A} = \mathbf{I}_n$ . What is  $rank(\mathbf{C})$ ?
- What about the subspaces of the left inverse?
  - $ightharpoonup C(\mathbf{C})$
  - $ightharpoonup N\left(\mathbf{C}^{T}\right)$
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  - ▶ N(**C**)

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- ▶ Let  $\mathbf{C} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ , such that  $\mathbf{C}\mathbf{A} = \mathbf{I}_n$ . What is  $rank(\mathbf{C})$ ?
- What about the subspaces of the left inverse?
  - $C(\mathbf{C}) = C(\mathbf{A}^T) = \mathbb{R}^n$
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#### Left Inverse

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► Subspaces of **A**:

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#### Left Inverse

- $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $rank(\mathbf{A}) = n$
- Subspaces of A:

$$C\left(\mathbf{A}\right) \in \mathbb{R}^{m} \quad N\left(\mathbf{A}^{T}\right) \in \mathbb{R}^{m}$$
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- ▶ Let  $\mathbf{C} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ . such that  $CA = I_n$ . What is rank(C)?
- What about the subspaces of the left inverse?

$$C(\mathbf{C}) = C(\mathbf{A}^T) = \mathbb{R}^n$$

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- $\mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $rank(\mathbf{A}) = m$
- Subspaces of A:  $C(\mathbf{A}) = \mathbb{R}^m \quad N(\mathbf{A}^T) = \{\mathbf{0}\}$  $C\left(\mathbf{A}^{T}\right) \in \mathbb{R}^{n}$   $N\left(\mathbf{A}\right) \in \mathbb{R}^{n}$
- ▶ Let  $\mathbf{B} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ . such that  $AB = I_m$ . What is rank(B)?
- What about the subspaces of the left inverse?
  - $ightharpoonup C(\mathbf{B})$
  - $ightharpoonup N\left(\mathbf{B}^{T}\right)$
  - $ightharpoonup C\left(\mathbf{B}^{T}\right)$
  - ► N(**B**)

#### Left Inverse

- $ightharpoonup \mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $rank(\mathbf{A}) = n$
- ► Subspaces of **A**:

$$C\left(\mathbf{A}\right) \in \mathbb{R}^{m} \quad N\left(\mathbf{A}^{T}\right) \in \mathbb{R}^{m}$$
 $C\left(\mathbf{A}^{T}\right) = \mathbb{R}^{n} \quad N\left(\mathbf{A}\right) = \{\mathbf{0}\}$ 

- ▶ Let  $\mathbf{C} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ , such that  $\mathbf{C}\mathbf{A} = \mathbf{I}_n$ . What is  $rank(\mathbf{C})$ ?
- What about the subspaces of the left inverse?

$$C(\mathbf{C}) = C(\mathbf{A}^T) = \mathbb{R}^n$$

$$N(\mathbf{C}^T) = N(\mathbf{A}) = \{\mathbf{0}\}\$$

$$ightharpoonup C\left(\mathbf{C}^{T}\right) = C\left(\mathbf{A}\right) \in \mathbb{R}^{m}$$

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- $ightharpoonup \mathbf{A} \in \mathbb{R}^{m \times n}$ ,  $rank(\mathbf{A}) = m$
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- ▶ Let  $\mathbf{B} \in \mathbb{R}^{n \times m}$  be the left inverse of  $\mathbf{A}$ , such that  $\mathbf{AB} = \mathbf{I}_m$ . What is  $rank(\mathbf{B})$ ?
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- Subspaces of A:  $C(A) \in \mathbb{R}^m \quad N(A)$

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  - $ightharpoonup C\left(\mathbf{B}^{T}\right) = C\left(\mathbf{A}\right) = \mathbb{R}^{m}$
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## Pseudo Inverse

▶ Consider a tall, skinny matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$  with independent columns. It turns out the Gram matrix  $\mathbf{A}^T \mathbf{A} \in \mathbb{R}^{n \times n}$  is invertible. If that is the case then,

$$\left(\mathbf{A}^T\mathbf{A}\right)^{-1}\mathbf{A}^T\mathbf{A}=\mathbf{I}_n; \ \ \left(\mathbf{A}^T\mathbf{A}\right)^{-1}\mathbf{A}^T$$
 is a left inverse.

- $oldsymbol{A}^{\dagger} = \left( oldsymbol{A}^T oldsymbol{A} 
  ight)^{-1} oldsymbol{A}^T$  is called the *pseudo inverse* or the *Moore-Penrose inverse*.
- For the case of a fat, wide matrix, we have  $\mathbf{A}^{\dagger} = \mathbf{A}^T \left( \mathbf{A} \mathbf{A}^T \right)^{-1}$ .
- When **A** is square and invertible,  $\mathbf{A}^{\dagger} = \mathbf{A}^{-1}$ .

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- Solve Ax = b using the  $A^{\dagger}$ .  $A = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ , and  $b = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ . Find x.

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- When  ${\bf A}$  is square and invertible,  ${\bf A}^\dagger={\bf A}^{-1}$ .
- Solve  $\mathbf{A}\mathbf{x} = \mathbf{b}$  using the  $\mathbf{A}^{\dagger}$ .  $\mathbf{A} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$ , and  $\mathbf{b} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$ . Find  $\mathbf{x}$ .
- Compare  $\mathbf{A}^{\dagger}$  with that of the general left inverse  $\mathbf{C}$ . Calculate  $\|\mathbf{C}\|^2$  and find out the  $\min \|\mathbf{C}\|^2$ . What is  $\|\mathbf{A}^{\dagger}\|^2$ ?

### Matrix Inverse and Pseudo Inverse through QR factorization

▶ Consider an invertible, square matrix  $\mathbf{A} \in \mathbb{R}^{n \times n}$ .

$$\mathbf{A} = \mathbf{Q}\mathbf{R} \implies \mathbf{A}^{-1} = (\mathbf{Q}\mathbf{R})^{-1} = \mathbf{R}^{-1}\mathbf{Q}^{-1} = \mathbf{R}^{-1}\mathbf{Q}^{T}$$

where,  $\mathbf{R}, \mathbf{Q} \in \mathbb{R}^{n \times n}$ .  $\mathbf{R}$  is upper triangular, and  $\mathbf{Q}$  is an orthogonal matrix.

▶ In the case of a left invertible rectangular matrix  $\mathbf{A} \in \mathbb{R}^{m \times n}$ , we can factorize  $\mathbf{A} = \mathbf{Q}\mathbf{R}$ , with  $\mathbf{Q} \in \mathbb{R}^{m \times n}$  and  $\mathbf{R} \in \mathbb{R}^{m \times m}$ .

$$\mathbf{A}^{\dagger} = \left(\mathbf{A}^T \mathbf{A}\right)^{-1} \mathbf{A}^T = \left(\mathbf{R}^T \mathbf{Q}^T \mathbf{Q} \mathbf{R}\right)^{-1} \mathbf{R}^T \mathbf{Q}^T = \left(\mathbf{R}^T \mathbf{R}\right)^{-1} \mathbf{R}^T \mathbf{Q}^T = \mathbf{R}^{-1} \mathbf{Q}^T$$

ightharpoonup For a right invertible wide, fat matrix, we can find out the pseudo-inverse of  $\mathbf{A}^T$ , and then take the transpose of the pseudo-inverse.

$$\mathbf{A}\mathbf{A}^{\dagger} = \mathbf{I} \implies \left(\mathbf{A}^{\dagger}\right)^{T}\mathbf{A}^{T} = \left(\mathbf{A}^{T}\right)^{\dagger}\mathbf{A}^{T} = \mathbf{I}$$

$$\mathbf{A}^T = \mathbf{Q}\mathbf{R} \implies \left(\mathbf{A}^T\right)^\dagger = \mathbf{R}^{-1}\mathbf{Q}^T = \left(\mathbf{A}^\dagger\right)^T \implies \mathbf{A}^\dagger = \mathbf{Q}\mathbf{R}^{-T}$$