Linear Control and Estimation
Least Squares Methods

Sivakumar Balasubramanian

Department of Bioengineering
Christian Medical College, Bagayam
Vellore 632002

References

- S Boyd, Introduction to Applied Linear Algebra: Chapters 12, 13, 15, 16 and 17.

Overdetermined System of linear equations

▶ For a tall, skinny matrix $\mathbf{A} \in \mathbb{R}^{m \times n}$, there is a solution to $\mathbf{Ax} = \mathbf{b}$, only when $\mathbf{b} \in C(\mathbf{A})$.

$$\mathbf{b} = \sum_{i=1}^{n} \mathbf{v}_i a_i = \mathbf{Va}; \ \ \mathbf{a} \in \mathbb{R}^n, \ \ \mathbf{V} = \begin{bmatrix} \mathbf{v}_1 & \mathbf{v}_2 & \dots & \mathbf{v}_n \end{bmatrix} \in \mathbb{R}^{n \times n}$$

▶ Can we have an approximate solution when $\nexists \mathbf{x}$ such that $\mathbf{Ax} = \mathbf{b}$?
Let us define "approximate" solution $\hat{\mathbf{x}}$ as the one that minimizes
$\|\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}\|_2^2, \ \ \forall \mathbf{x} \in \mathbb{R}^n$. This is the *least squares problem*.

Given $\mathbf{A}$ and $\mathbf{b}$, choose $\hat{\mathbf{x}}$ such that
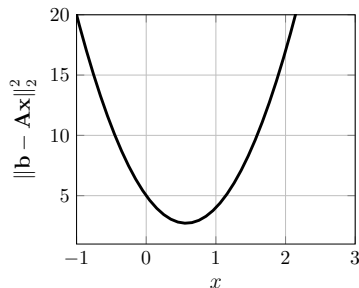
minimize　$\|\mathbf{b} - \mathbf{Ax}\|_2^2$

▶ $\mathbf{A}$ and $\mathbf{b}$ come from the data.

▶ $\|\mathbf{b} - \mathbf{Ax}\|^2$ is called the objective function.

Least Squares Problem

$$\left.\begin{array}{r} 2x = 1 \\ -1x = -2 \\ \sqrt{2}x = 0 \end{array}\right\} \longrightarrow \mathbf{Ax} = \mathbf{b}, \ \mathbf{A} = \begin{bmatrix} 2 \\ -1 \\ \sqrt{2} \end{bmatrix}, \ \mathbf{x} \in \mathbb{R}, \ \mathbf{b} \in \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix}$$

$$\|\mathbf{b} - \mathbf{Ax}\|^2 = (1 - 2x)^2 + (-2 + x)^2 + \left(\sqrt{2}x\right)^2 = 7x^2 - 8x + 5 \geq 0$$

Objective function

The objective function assumes its minimum value, at $\hat{\mathbf{x}} = \frac{4}{7}$

Least Squares Problem

$$\left.\begin{array}{r} 2x_1 - x_2 = 2 \\ -x_1 + x_2 = 1 \\ 3x_1 + 2x_2 = -1 \end{array}\right\} \longrightarrow \mathbf{A}\mathbf{x} = \mathbf{b}, \ \mathbf{A} = \begin{bmatrix} 2 & -1 \\ -1 & 1 \\ 3 & 2 \end{bmatrix}, \ \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \ \mathbf{b} \in \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$$

$$\|\mathbf{b} - \mathbf{A}\mathbf{x}\|^2 = 14x_1^2 + 6x_2^2 + 6x_2 + 6x_1x_2 + 6 \geq 0$$

The objective function assumes it minimum value at, $\hat{x}_1 = \frac{52}{75}$ and $\hat{x}_2 = \frac{3}{25}$.

Least Squares Methods

▶ The general solution to this least squares problem can be derived using calculus. Let $f(\mathbf{x}) = \|\mathbf{b} - \mathbf{A}\mathbf{x}\|$

$$\nabla f(\mathbf{x}) = 0 \longrightarrow \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} = 0$$

Going through the algebra, we end up with the following expression for $\hat{\mathbf{x}}$ that minimizes $f(\mathbf{x})$,
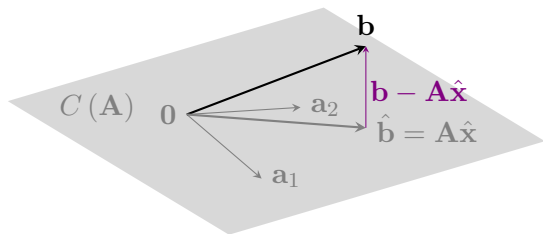
$$\underbrace{\mathbf{A}^T \mathbf{A} \hat{\mathbf{x}} = \mathbf{A}^T \mathbf{b}}_{\text{Normal Equations}}$$

$\mathbf{A}$ is full rank, $\implies \mathbf{A}^T \mathbf{A}$ is invertible.

$$\implies \hat{\mathbf{x}} = \underbrace{\left(\mathbf{A}^T \mathbf{A}\right)^{-1} \mathbf{A}^T}_{\text{Pseudo-inverse}} \mathbf{b} = \mathbf{A}^\dagger \mathbf{b}$$

Least Squares Methods

- $\hat{\mathbf{x}}$ is the approximate least squares solution. $\hat{\mathbf{b}} = \mathbf{A}\hat{\mathbf{x}}$, which is in general not equal to $\mathbf{b}$. *When is $\mathbf{b} = \hat{\mathbf{b}}$?*

- We know two things about $\hat{\mathbf{b}}$,
  1. $\hat{\mathbf{b}} \in C(\mathbf{A})$: $\hat{\mathbf{b}}$ is the column space of $\mathbf{A}$.
  2. $\left\| \mathbf{b} - \hat{\mathbf{b}} \right\|$ is minimum.

$\|\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}\|_2^2$ is minimum $\implies (\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}) \perp \mathbf{A}\hat{\mathbf{x}}$

$(\mathbf{A}\hat{\mathbf{x}})^T (\mathbf{b} - \mathbf{A}\hat{\mathbf{x}}) = 0 \implies \hat{\mathbf{x}}^T \underbrace{\left(\mathbf{A}^T\mathbf{b} - \mathbf{A}^T\mathbf{A}\hat{\mathbf{x}} \right)}_{\text{Normal Equations}} = 0$

The least squares approximate solution of $\mathbf{A}\mathbf{x} = \mathbf{b}$ is the solution solution to the equation $\mathbf{A}\mathbf{x} = \hat{\mathbf{b}}$, where $\hat{\mathbf{b}}$ is the projection of $\mathbf{b}$ onto the column space of $\mathbf{A}$ $(C(\mathbf{A}))$.

Multi-Objective Least Squares

▶ There are applications where there is more than one objective that must be optimized,

$$J_1 = \|\mathbf{A}_1\mathbf{x} - \mathbf{b}_1\|^2, \ J_2 = \|\mathbf{A}_2\mathbf{x} - \mathbf{b}_2\|^2, \ \ldots \ J_k = \|\mathbf{A}_k\mathbf{x} - \mathbf{b}_k\|^2,$$

and often these are conflicting objectives.

▶ We can define a single objective function J that is takes into account the different objective functions.

$$J = \sum_{i=1}^{k} \rho_i J_i, \ \ \rho_i > 0, \ \ \forall 1 \leq i \leq k$$

▶ The ρ_is indicate the relative weightage given to the individual objectives.

$$J = J_1 + \sum_{i=2}^{k} \rho_i J_i$$

Multi-Objective Least Squares

$$J = \rho_1 \|\mathbf{A}_1\mathbf{x} - \mathbf{b}_1\|^2 + \ldots + \rho_k \|\mathbf{A}_k\mathbf{x} - \mathbf{b}_k\|^2$$
$$= \|\sqrt{\rho_1}\mathbf{A}_1\mathbf{x} - \sqrt{\rho_1}\mathbf{b}_1\|^2 + \ldots + \rho_k \|\sqrt{\rho_k}\mathbf{A}_k\mathbf{x} - \sqrt{\rho_k}\mathbf{b}_k\|^2$$

$$J = \left\| \begin{bmatrix} \sqrt{\rho_1}\mathbf{A}_1 \\ \sqrt{\rho_2}\mathbf{A}_2 \\ \vdots \\ \sqrt{\rho_k}\mathbf{A}_k \end{bmatrix} \mathbf{x} - \begin{bmatrix} \sqrt{\rho_1}\mathbf{b}_1 \\ \sqrt{\rho_2}\mathbf{b}_1 \\ \vdots \\ \sqrt{\rho_k}\mathbf{b}_k \end{bmatrix} \right\|^2 = \left\| \tilde{\mathbf{A}}\mathbf{x} - \tilde{\mathbf{b}} \right\|^2 \implies \hat{x} = \left(\tilde{\mathbf{A}}^T\tilde{\mathbf{A}} \right)^{-1} \tilde{\mathbf{A}}^T\tilde{\mathbf{b}}$$

The columns of $\tilde{\mathbf{A}}$ are must be independent, which happens if the columns of at least one of the $\mathbf{A}_i$s is independent.
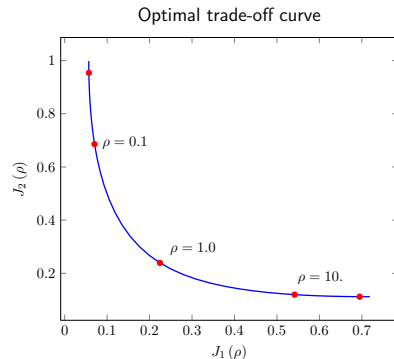
Consider a two objective case, $J = J_1 + \rho J_2$.

$$\hat{\mathbf{x}} = \begin{cases} \mathrm{argmin}_x \|\mathbf{A}_1\mathbf{x} - \mathbf{b}_1\|^2 & \rho = 0 \\ \mathrm{argmin}_x \|\mathbf{A}_2\mathbf{x} - \mathbf{b}_2\|^2 & \rho \to \infty \end{cases}$$

Multi-Objective Least Squares
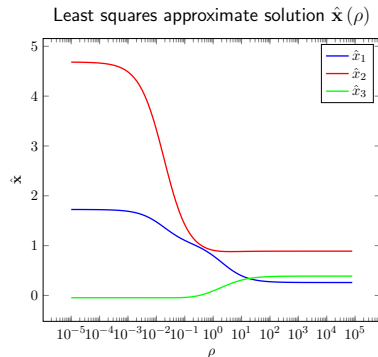
Any solution that lies on this curve is called the *Pareto optimal* solution. There exists no solution $\tilde{\mathbf{x}}$, such that $J_1(\tilde{\mathbf{x}}) \leq J_1(\hat{\mathbf{x}})$ and $J_2(\tilde{\mathbf{x}}) \leq J_2(\hat{\mathbf{x}})$ where, both inqualities hold strictly.

Least squares approximate solution $\hat{\mathbf{x}}(\rho)$

Optimal trade-off curve

Multi-Objective Least Squares

▶ Multi-objective least squares methods play an important role in both control and estimation problems.

▶ Appropriate choice of the objective functions can also help deal with conditions where the columns of A_i are not independent. Consider the following example,

$$J_1 = \|\mathbf{A}_1\mathbf{x} - \mathbf{b}_1\|^2 \quad \text{and} \quad J_2 = \|\mathbf{A}_2\mathbf{x} - \mathbf{b} - 2\|^2$$

where, $\mathbf{A}_1 \in \mathbb{R}^{m_1 \times n}$ and $\mathbf{A}_2 \in \mathbb{R}^{m_2 \times n}$, such that $m_1, m_2 < n$. Thus, the columns of A_1 and A_2 are not independent! However, if $m_1 + m_2 \geq n$, then it is possible that the columns of $\tilde{A}$ are independent.

▶ This is called **regularized least squares**.

▶ **Tichonov regularization**: $J = \|\mathbf{A}\mathbf{x} - \mathbf{y}\|^2 + \rho \|\mathbf{x}\|^2$, where $\rho > 0$.

$$\tilde{\mathbf{A}} = \begin{bmatrix} \mathbf{A} \\ \sqrt{\rho}\mathbf{I} \end{bmatrix} \implies \hat{\mathbf{x}} = \left(\mathbf{A}^T\mathbf{A} + \rho\mathbf{I}\right)^{-1}\mathbf{A}^T\mathbf{b}$$

Multi-Objective Least Squares

- **Tichonov regularization**: $J = \|\mathbf{A}\mathbf{x} - \mathbf{y}\|^2 + \rho \|\mathbf{x}\|^2$, where $\rho > 0$.

$$\tilde{\mathbf{A}} = \begin{bmatrix} \mathbf{A} \\ \sqrt{\rho}\mathbf{I} \end{bmatrix} \implies \hat{\mathbf{x}} = \left(\mathbf{A}^T\mathbf{A} + \rho\mathbf{I}\right)^{-1}\mathbf{A}^T\mathbf{b}$$

- $\hat{\mathbf{x}}$ gives a unique solution in minimizing J, even when $\mathbf{A}$ is not full rank.

- Even when $\mathbf{A}$ is full rank, the regularization term can be used to improve the condition number of the matrix.

Constrained Least Squares

▶ **Problem**:

$$\text{minimize } \|\mathbf{Ax} - \mathbf{b}\|^2$$
$$\text{subject to } \mathbf{Cx} = \mathbf{d}$$

where, $\mathbf{A} \in \mathbb{R}^{m \times n}$, $\mathbf{x} \in \mathbb{R}^n$, $\mathbf{b} \in \mathbb{R}^m$, $\mathbf{C} \in \mathbb{R}^{p \times n}$ and $\mathbf{d} \in \mathbb{R}^p$.

▶ This can be solved using the *method of Lagrange multipliers*. When we do this, we finally arrive the following set of equations, called the *Karush-Kuhn-Tucker* (KKT) equation,

$$2\left(\mathbf{A}^T\mathbf{A}\right)\hat{\mathbf{x}} - 2\mathbf{A}^T\mathbf{b} + \mathbf{C}^T\hat{z} = 0$$

$$\begin{bmatrix} 2\left(\mathbf{A}^T\mathbf{A}\right) & \mathbf{C}^T \\ \mathbf{C} & 0 \end{bmatrix} \begin{bmatrix} \hat{\mathbf{x}} \\ \hat{\mathbf{z}} \end{bmatrix} = \begin{bmatrix} 2\mathbf{A}^T\mathbf{b} \\ \mathbf{d} \end{bmatrix}$$

▶ The coefficient matrix on the LHS of the KKT equation a square matrix of dimensions $(n + p) \times (n + p)$ is invertible, if and only if, $\begin{bmatrix} \mathbf{A} \\ \mathbf{C} \end{bmatrix}$ is full rank.