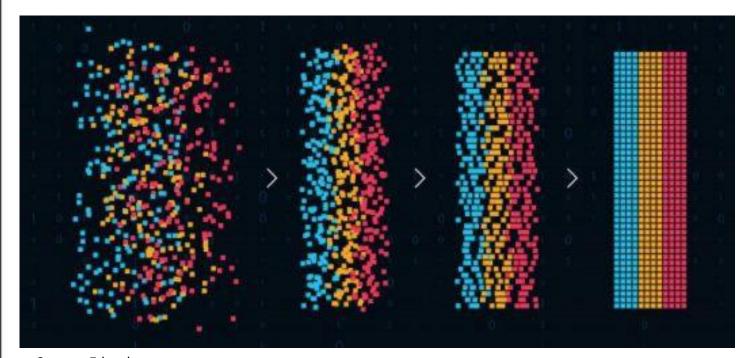




Pattern and Anomaly Detection



B. Tech., CSE + AI/ML

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Source: Edureka



- So far: The linear and non-linear models developed do not use training data during prediction.
- Once the model is trained, the prediction is made on new input purely based on model parameters.
- Premise: How about involving training data during predictions.
- Parzen probability density model: linear combination of kernel functions cantered to each training data point.
- Nearest neighbours are another examples
- Generic termimology for such models: Memory based



- Memory based methods: Store all training data to use it during prediction.
- These models always uses some measure or metric to indicate similarity between samples in input space.
- Fast to train but slow to predict

 A majority of linear models can be cast into equivalent "Dual Representation" where predictions are also based on linear combination of kernel functions evaluated at training samples.



• For a fixed non-linear feature space, the kernel function is

$$k(\mathbf{x}, \mathbf{x}') = \boldsymbol{\phi}(\mathbf{x})^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}').$$

If ø is 'linear', then

$$k(\mathbf{x}, \mathbf{x}') = \mathbf{x}^{\mathrm{T}} \mathbf{x}'.$$

Is a linear kernel.

Imagine rebuilding the well-known models (NNs, PCA, SVMs, etc.) with this 'kernel' perspective. The approach is also known as kernel substitution.



Stationary kernels (not affected by translation in input space)

$$k(\mathbf{x}, \mathbf{x}') = k(\mathbf{x} - \mathbf{x}')$$

Homogeneous kernels

$$k(\mathbf{x}, \mathbf{x}') = k(\|\mathbf{x} - \mathbf{x}'\|)$$

• Example: radial basis function kernels



• Ina a standard linear model, the regularized sum-of-squares error

function is as follows

$$J(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^{N} \left\{ \mathbf{w}^{\mathrm{T}} \phi(\mathbf{x}_n) - t_n \right\}^2 + \frac{\lambda}{2} \mathbf{w}^{\mathrm{T}} \mathbf{w}$$

• Solving for w yields
$$\mathbf{w} = -rac{1}{\lambda} \sum_{n=1}^N \left\{ \mathbf{w}^{\mathrm{T}} oldsymbol{\phi}(\mathbf{x}_n) - t_n \right\} oldsymbol{\phi}(\mathbf{x}_n)$$

$$a_n = -\frac{1}{\lambda} \left\{ \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}_n) - t_n \right\}$$

$$= \sum_{n=1}^{\infty} a_n \phi(\mathbf{x}_n) = \mathbf{\Phi}^{\mathrm{T}} \mathbf{a}$$



• Writing the regularized sum-of-squares error function in terms of a.

$$J(\mathbf{a}) = \frac{1}{2}\mathbf{a}^{\mathrm{T}}\boldsymbol{\Phi}\boldsymbol{\Phi}^{\mathrm{T}}\boldsymbol{\Phi}\boldsymbol{\Phi}^{\mathrm{T}}\mathbf{a} - \mathbf{a}^{\mathrm{T}}\boldsymbol{\Phi}\boldsymbol{\Phi}^{\mathrm{T}}\mathbf{t} + \frac{1}{2}\mathbf{t}^{\mathrm{T}}\mathbf{t} + \frac{\lambda}{2}\mathbf{a}^{\mathrm{T}}\boldsymbol{\Phi}\boldsymbol{\Phi}^{\mathrm{T}}\mathbf{a}$$

• Define Gram matrix

$$\mathbf{K} = \mathbf{\Phi} \mathbf{\Phi}^{\mathrm{T}}$$

$$K_{nm} = \phi(\mathbf{x}_n)^{\mathrm{T}} \phi(\mathbf{x}_m) = k(\mathbf{x}_n, \mathbf{x}_m)$$

Re-writing J(a)

$$J(\mathbf{a}) = \frac{1}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{K} \mathbf{a} - \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{t} + \frac{1}{2} \mathbf{t}^{\mathrm{T}} \mathbf{t} + \frac{\lambda}{2} \mathbf{a}^{\mathrm{T}} \mathbf{K} \mathbf{a}.$$

$$\mathbf{a} = (\mathbf{K} + \lambda \mathbf{I}_N)^{-1} \mathbf{t}.$$

Solving for a

$$y(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{a}^{\mathrm{T}} \boldsymbol{\Phi} \boldsymbol{\phi}(\mathbf{x}) = \mathbf{k}(\mathbf{x})^{\mathrm{T}} (\mathbf{K} + \lambda \mathbf{I}_{N})^{-1} \mathbf{t}$$



- From here, you can make changes in any direction
 - Multiple output regression
 - Binary Classification
 - Multi-class classification
- Non-fixed basis function models
- Margin based models
- Projection based models
- Sparse kernel models

Next time: Combining Models for Pattern Recognition

Thank You

