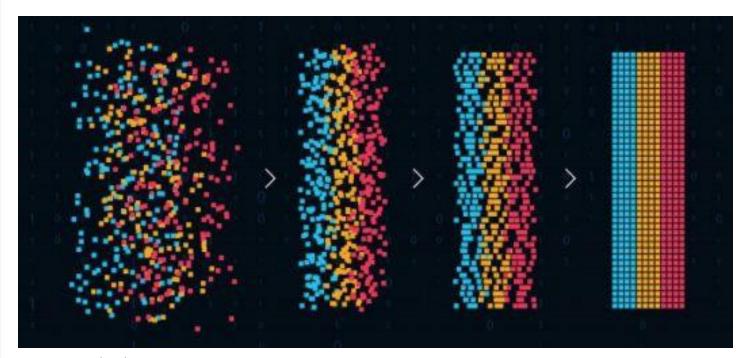




Pattern and Anomaly Detection



B. Tech., CSE + AI/ML

Dr Gopal Singh Phartiyal

18/10/2021

Source: Edureka



Recap: Linear Regression Models

Goal: Find w?

- Why linear model?
- Simple linear regression
- Basis functions
- Solving for w using maximum likelihood and least squares
- For multiple output
- Regularize the model (different regularizers)
- Managing over-fitting via the concept of bias-variance decomposition

So which model to choose?

Remember *model selection* and *cross-validation*



Recap: Bayesian Linear Regression

Posterior distribution

$$p(\mathbf{w}|\mathbf{t}) = \mathcal{N}(\mathbf{w}|\mathbf{m}_N, \mathbf{S}_N)$$

- •With a specific prior $p(\mathbf{w}) = \mathcal{N}(\mathbf{w}|\mathbf{0}, \alpha^{-1}\mathbf{I})$
- Mean and covariance of posterior w

$$\mathbf{m}_N = \beta \mathbf{S}_N \mathbf{\Phi}^{\mathrm{T}} \mathbf{t}$$

 $\mathbf{S}_N^{-1} = \alpha \mathbf{I} + \beta \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi}.$

UPES UNIVERSITY WITH A PURPOSE

Example

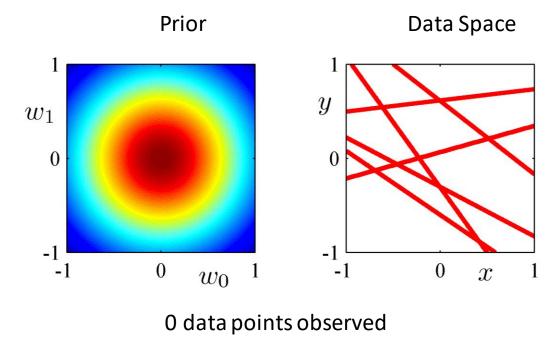
$$y(x, \mathbf{w}) = w_0 + w_1 x.$$

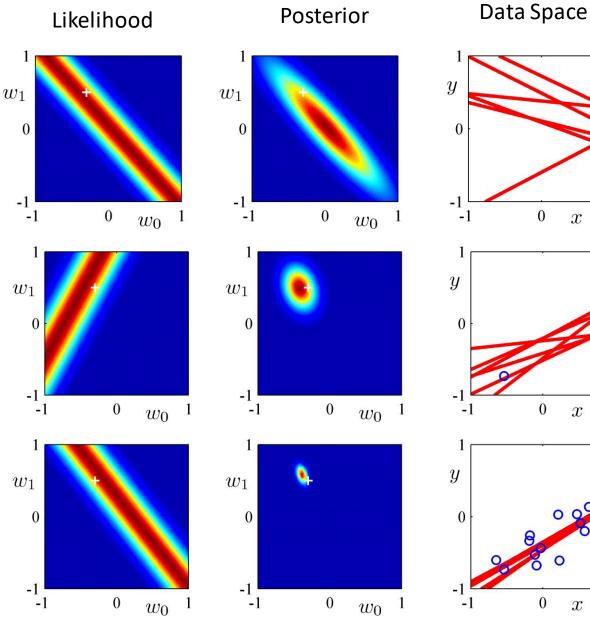
X = U(x | (-1,1), 20 observations

$$W_0 = 0.3$$
, $W_1 = 0.5$

Noise = Gaussian (sigma = 0.2)

Alpha = 2 for prior







Posterior

Conditional

Bayesian Linear Regression: Predictive Distribution

Predict t for new values of x by integrating over W:

$$p(t|\mathbf{t}, \alpha, \beta) = \int \underline{p(t|\mathbf{w}, \beta)} p(\mathbf{w}|\mathbf{t}, \alpha, \beta) d\mathbf{w}$$
$$= \mathcal{N}(t|\mathbf{m}_N^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}), \sigma_N^2(\mathbf{x}))$$

where

noise on the data

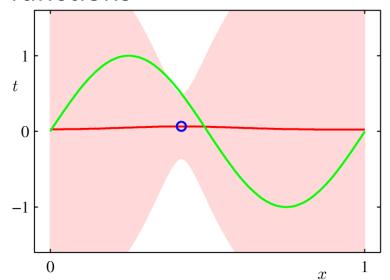
$$\sigma_N^2(\mathbf{x}) = rac{1}{eta} + oldsymbol{\phi}(\mathbf{x})^\mathrm{T} \mathbf{S}_N oldsymbol{\phi}(\mathbf{x}).$$
 uncertainty associated with the parameters $oldsymbol{w}$.

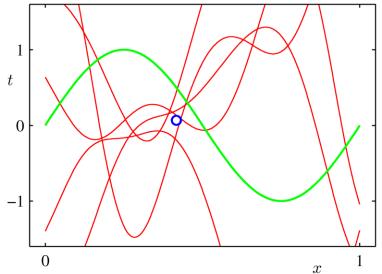


• Example: Sinusoidal data, 9 Gaussian basis functions, 1 data point

$$\phi_j(x) = \exp\left\{-\frac{(x-\mu_j)^2}{2s^2}\right\}$$

Model: Comprising a linear combination of Gaussian basis functions



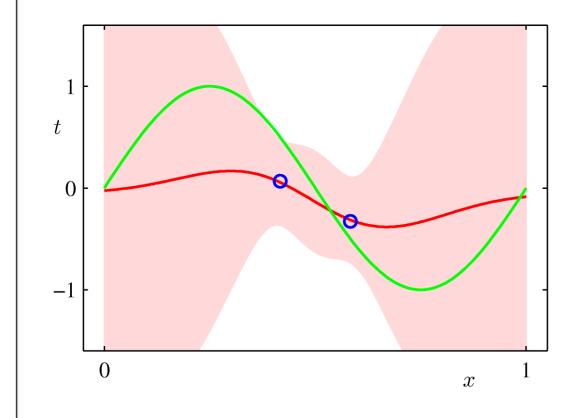


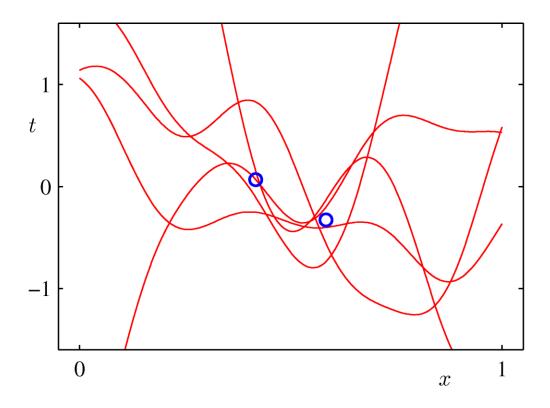
Red curve: Mean of the Gaussian predictive distribution

Shaded region: one standard deviation either side of the mean



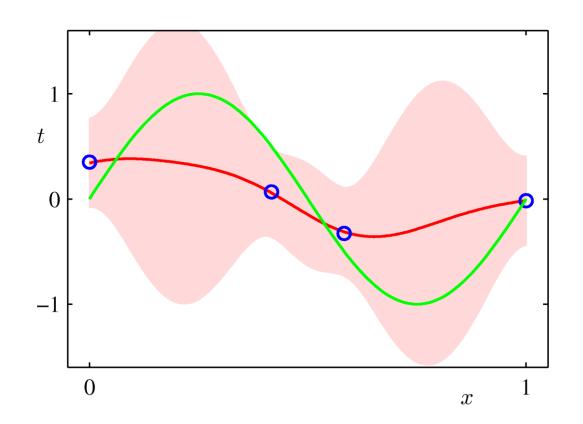
• Example: Sinusoidal data, 9 Gaussian basis functions, 2 data points

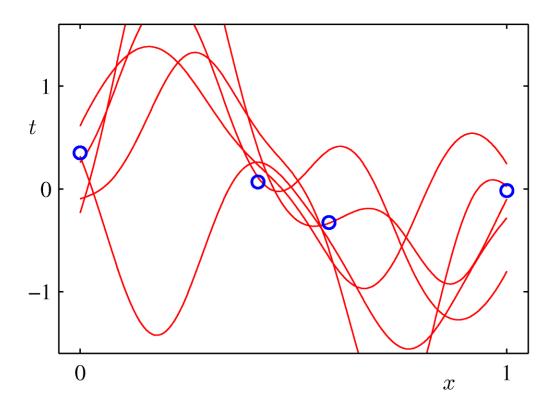






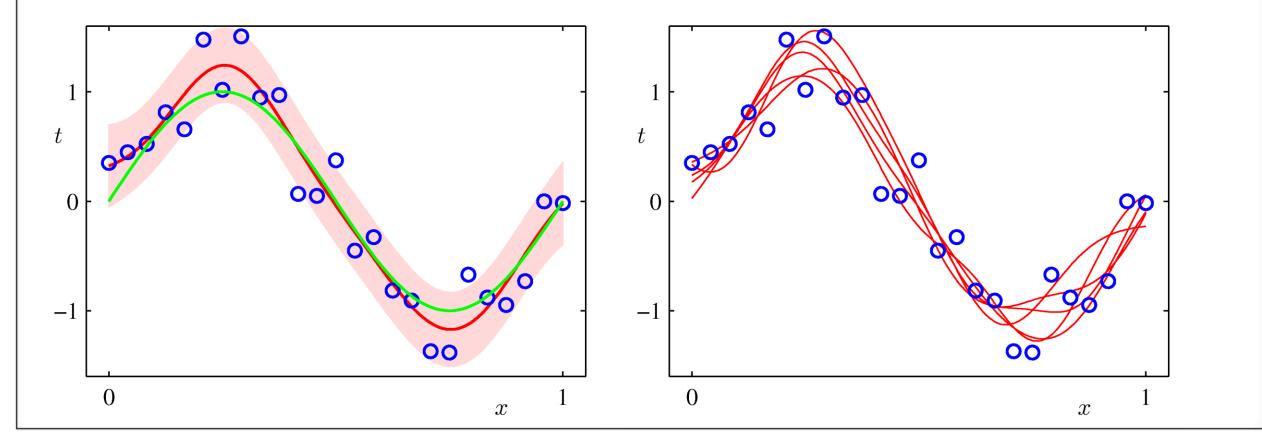
• Example: Sinusoidal data, 9 Gaussian basis functions, 4 data points







• Example: Sinusoidal data, 9 Gaussian basis functions, 25 data points





Equivalent Kernel

Remember

$$y(\mathbf{x}, \mathbf{w}) = w_0 + w_1 x_1 + \dots$$

$$y(\mathbf{x}, \mathbf{w}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}) = \mathbf{w}^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x})$$

smoother matrix.

The predictive mean can be written

$$y(\mathbf{x}, \mathbf{m}_N) = \mathbf{m}_N^{\mathrm{T}} \boldsymbol{\phi}(\mathbf{x}) = \beta \boldsymbol{\phi}(\mathbf{x})^{\mathrm{T}} \mathbf{S}_N \boldsymbol{\Phi}^{\mathrm{T}} \mathbf{t}$$

$$= \sum_{n=1}^N \beta \boldsymbol{\phi}(\mathbf{x})^{\mathrm{T}} \mathbf{S}_N \boldsymbol{\phi}(\mathbf{x}_n) t_n$$

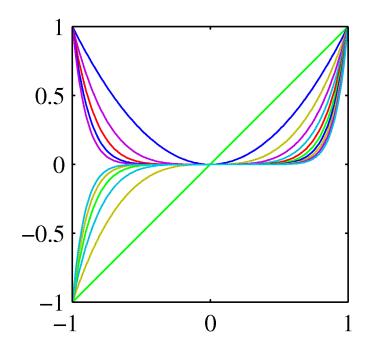
$$= \sum_{n=1}^N k(\mathbf{x}, \mathbf{x}_n) t_n.$$
 Equivalent kernel or

$$\mathbf{S}_N^{-1} = \alpha \mathbf{I} + \beta \mathbf{\Phi}^{\mathrm{T}} \mathbf{\Phi}$$

• This is a weighted sum of the training data target values, t_n.

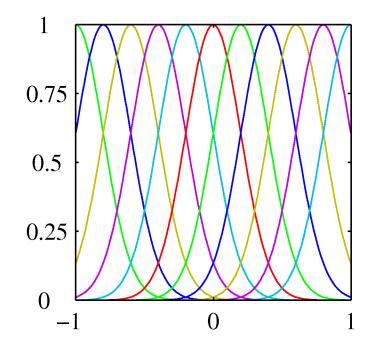


Basis Functions



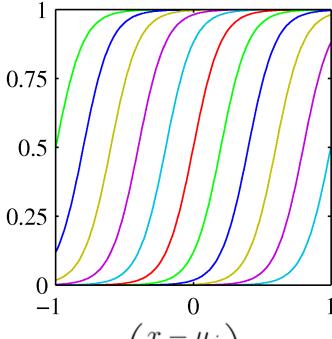
$$\phi_j(x) = x^j.$$

Polynomial basis functions



$$\phi_j(x) = \exp\left\{-\frac{(x-\mu_j)^2}{2s^2}\right\}$$

Gaussian basis functions



$$\phi_j(x) = \sigma\left(rac{x-\mu_j}{s}
ight)$$
 where $\sigma(a) = rac{1}{1+\exp(-a)}$

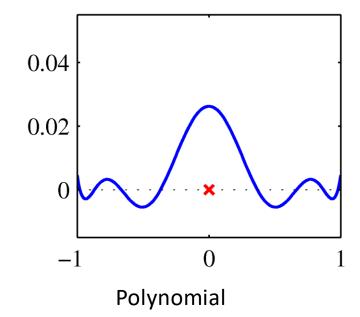
Sigmoidal basis functions

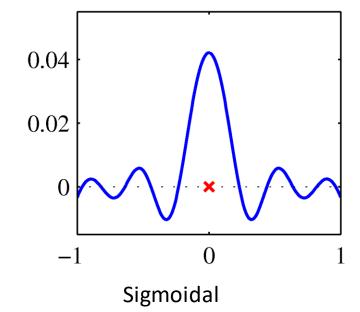


Equivalent Kernel

• Non-local basis functions have local equivalent kernels:

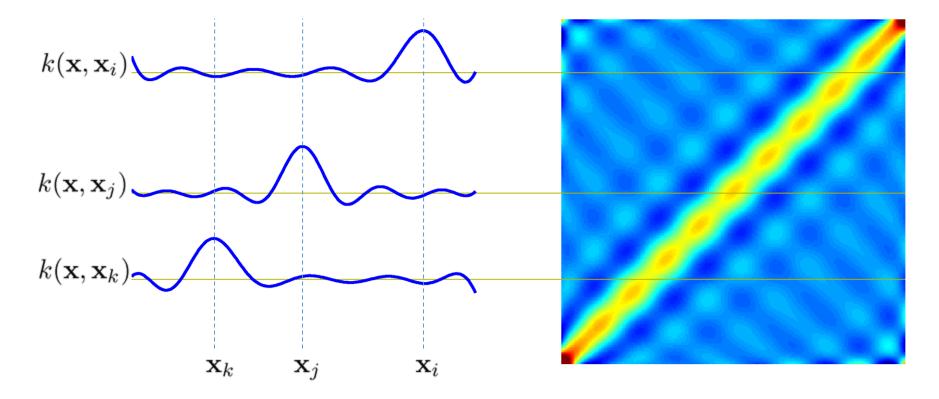
$$k(\mathbf{x}, \mathbf{x}') = \beta \phi(\mathbf{x})^{\mathrm{T}} \mathbf{S}_N \phi(\mathbf{x}')$$







Equivalent Kernel



Weight of t_n depends on distance between x and x_n ; nearby x_n carry more weight.

Thank You

