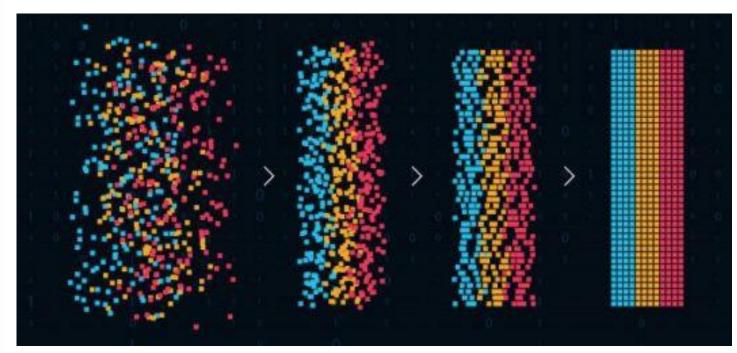




Pattern and Anomaly Detection



B. Tech., CSE + AI/ML

Dr Gopal Singh Phartiyal

16/11/2021

Source: Edureka



Use of gradient information

$$\mathbf{w}^{(\tau+1)} = \mathbf{w}^{(\tau)} - \eta \nabla E(\mathbf{w}^{(\tau)})$$

- **Gradient descent** algorithm: change win a way that a small step is taken in the direction of negative gradient.
 - At each step, the weight vector is moved in the direction of the greatest rate
 of decrease of the error function
 - After each step, the gradient is re-evaluated and it goes on again and again until termination criteria s met.
 - In batch type gradient descent methods: weights are updated only after the model has seen all training samples once and only once.
 - Conjugate gradients and quasi-Newton are variants of batch gradient descent.
 - Issue: Local minima, all points are required, computationaly expensive



- Stochastic GD:
- Motivation:-Updating weight on all training samples in one go is equivalent to updating weights after training with one sample at a time.

- Advantages: Easier to implement
- Computationally cheap
- Randomization leads to generalization

$$E(\mathbf{w}) = \sum_{n=1}^{N} E_n(\mathbf{w}).$$

$$\mathbf{w}^{(\tau+1)} = \mathbf{w}^{(\tau)} - \eta \nabla E_n(\mathbf{w}^{(\tau)}).$$



- Error Backpropagation
- Method of evaluating the gradient of error function in a feedforward neural network
- Local message passing scheme (forward and backword propagation of information)
- To understand
 - Forward pass (output based on updated weights)
 - Backward pass (backpropagation of error)
 - Weight update
- In general, backpropagation can be used elsewhere.



Neural Networks: Network Training: Errors

- Error Functions in NN based models
- 1. Regression: When the output layer of the NN has linear or identity activation function $\frac{\partial E}{\partial a_k} = y_k t_k$
- 2. Classification
 - Binary: Two class
 - Multiple two-class
 - Multi-class

$$E(\mathbf{w}) = -\sum_{n=1}^{N} \{t_n \ln y_n + (1 - t_n) \ln(1 - y_n)\}$$

$$E(\mathbf{w}) = -\sum_{n=1}^{N} \sum_{k=1}^{K} \{t_{nk} \ln y_{nk} + (1 - t_{nk}) \ln(1 - y_{nk})\}$$

$$E(\mathbf{w}) = -\sum_{n=1}^{N} \sum_{k=1}^{K} t_{kn} \ln y_k(\mathbf{x}_n, \mathbf{w}).$$



- Error Backpropagation:
- For one sample

$$E_n = \frac{1}{2} \sum_{k} (y_{nk} - t_{nk})^2$$

$$\frac{\partial E_n}{\partial w_{ji}} = (y_{nj} - t_{nj})x_{ni}$$

$$a_j = \sum_i w_{ji} z_i$$

$$z_{i} \bigcirc \underbrace{\delta_{j}}_{w_{kj}} \bigcirc \delta_{k}$$

$$z_{j} \bigcirc \delta_{k}$$

$$\delta_{1}$$

$$\frac{\partial E_n}{\partial w_{ji}} = \delta_j z_i.$$

$$\frac{\partial E_n}{\partial w_{ji}} = \frac{\partial E_n}{\partial a_j} \frac{\partial a_j}{\partial w_{ji}}$$

$$\partial a_i$$

$$\frac{\partial a_j}{\partial w_{ji}} = z_i$$



- Error Backpropagation
- •

$$\delta_j \equiv \frac{\partial E_n}{\partial a_j} = \sum_k \frac{\partial E_n}{\partial a_k} \frac{\partial a_k}{\partial a_j}$$

$$\delta_j = h'(a_j) \sum_k w_{kj} \delta_k$$

For batch methods

$$\frac{\partial E}{\partial w_{ji}} = \sum_{n} \frac{\partial E_n}{\partial w_{ji}}.$$

Next time: Neural Networks

Thank You

