

1. Drive board parameters

input Voltage: $\pm 15\text{VDC}$

Analog Signal input range: $\pm 5\text{V}$ 、 $\pm 10\text{V}$ (Optional)

Analog Signal Input resistance: $200\text{K}\Omega \pm 1\%$ (Differential input)

Position signal Input resistance: $1\text{K}\Omega \pm 1\%$

Position signal input Scale factor: $0.33\text{V}/^\circ$

Position signal output Scale factor: $0.33\text{V}/^\circ$

temperature drift: $40\text{PPM}/^\circ\text{C}$ (maximum $40\text{PPM}/^\circ\text{C}$)

working temperature: $0^\circ\text{C}-45^\circ\text{C}$

Storage temperature: -10 至 $+60^\circ\text{C}$

Drive board size (L * w * h): $60\text{mm} \times 56\text{mm} \times 33\text{mm}$

2. Scanning motor parameters

Maximum scan angle: $\pm 30^\circ$) Optical angle (factory setting $+ 15^\circ$)

working temperature: $0^\circ\text{C}-45^\circ\text{C}$

Storage temperature: -10 至 $+60^\circ\text{C}$

Working noise: $\leq 30\text{db}$

Average operating current: 0.5A

peak current: 1.5A

Linearity: 99.9%

Small step response time: $\leq 0.50\text{ms}$

Long time drift (Continuous work 8 hours): $< 0.5\text{mRad.}$

Proportional drift: $< 50\text{PPM}/^\circ\text{C}$

Zero drift: $< 15\mu\text{Rad.}/^\circ\text{C}$

Repeat accuracy: $8\mu\text{Rad}$

Coil resistance: $4\Omega \pm 10\%$

Coil inductance: $200\mu\text{H} \pm 10$

Coil temperature: $\leq 95^\circ\text{C}$

Lens size: $12\text{mm} \times 7\text{mm} \times 0.9\text{mm}$ (High quality dielectric film)

Lens reflectivity: $> 99\%$ 45° Incident angle (Coverage wavelength $400\text{nm}-700\text{nm}$)