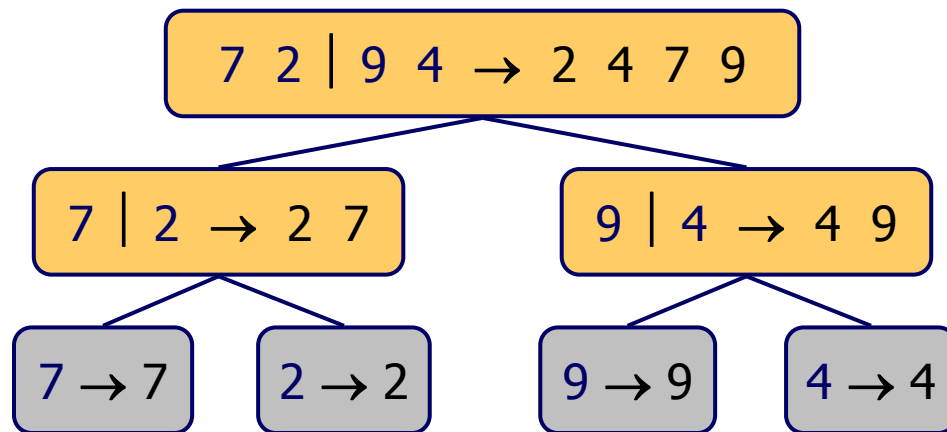







Merge Sort



Outline

 Divide-and-conquer paradigm

 Merge-sort

-  Algorithm
-  Merging two sorted sequences
-  Merge-sort tree
-  Execution example
-  Analysis

Divide-and-Conquer



Divide-and conquer is a general algorithm design paradigm:

- ✉ **Divide:** divide the input data S in two disjoint subsets S_1 and S_2
- ✉ **Recur:** solve the subproblems associated with S_1 and S_2
- ✉ **Conquer:** combine the solutions for S_1 and S_2 into a solution for S



The base case for the recursion are subproblems of size 0 or 1



Merge-sort is a sorting algorithm based on the divide-and-conquer paradigm



Like heap-sort

- ✉ It uses a comparator
- ✉ It has $O(n \log n)$ running time



Unlike heap-sort

- ✉ It does not use an auxiliary priority queue
- ✉ It accesses data in a sequential manner (suitable to sort data on a disk)

Merge-Sort



Merge-sort on an input sequence S with n elements consists of three steps:

- ☒ **Divide:** partition S into two sequences S_1 and S_2 of about $n/2$ elements each
- ☒ **Recur:** recursively sort S_1 and S_2
- ☒ **Conquer:** merge S_1 and S_2 into a unique sorted sequence

Algorithm *mergeSort*(S, C)

Input sequence S with n elements, comparator C

Output sequence S sorted according to C

if $S.size() > 1$

$(S_1, S_2) \leftarrow partition(S, n/2)$

mergeSort(S_1, C)

mergeSort(S_2, C)

$S \leftarrow merge(S_1, S_2)$

Merging Two Sorted Sequences



The conquer step of merge-sort consists of merging two sorted sequences A and B into a sorted sequence S containing the union of the elements of A and B



Merging two sorted sequences, each with $n/2$ elements and implemented by means of a doubly linked list, takes $O(n)$ time

Algorithm *merge*(A, B)

Input sequences A and B with $n/2$ elements each

Output sorted sequence of $A \cup B$

$S \leftarrow$ empty sequence

while $\neg A.isEmpty() \wedge \neg B.isEmpty()$

if $A.first().element() < B.first().element()$

$S.insertLast(A.remove(A.first()))$

else

$S.insertLast(B.remove(B.first()))$

while $\neg A.isEmpty()$

$S.insertLast(A.remove(A.first()))$

while $\neg B.isEmpty()$

$S.insertLast(B.remove(B.first()))$

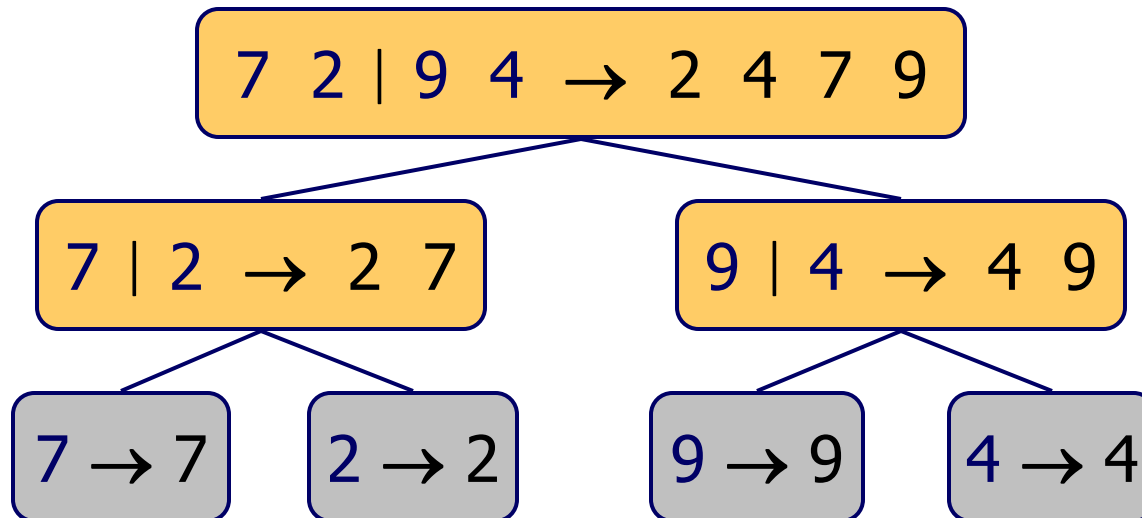
return S

Merge-Sort Tree



An execution of merge-sort is depicted by a binary tree

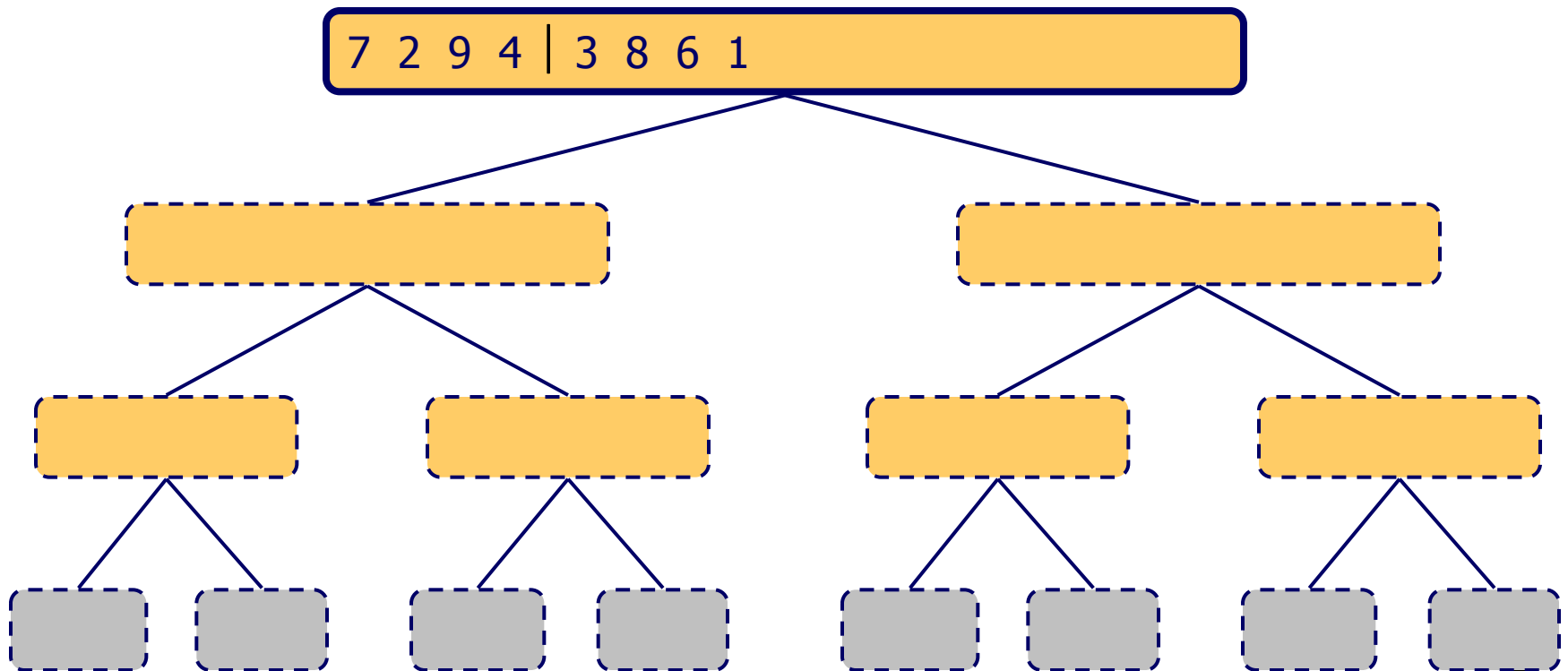
- ☒ each node represents a recursive call of merge-sort and stores
 - 🎵 unsorted sequence before the execution and its partition
 - 🎵 sorted sequence at the end of the execution
- ☒ the root is the initial call
- ☒ the leaves are calls on subsequences of size 0 or 1



Execution Example

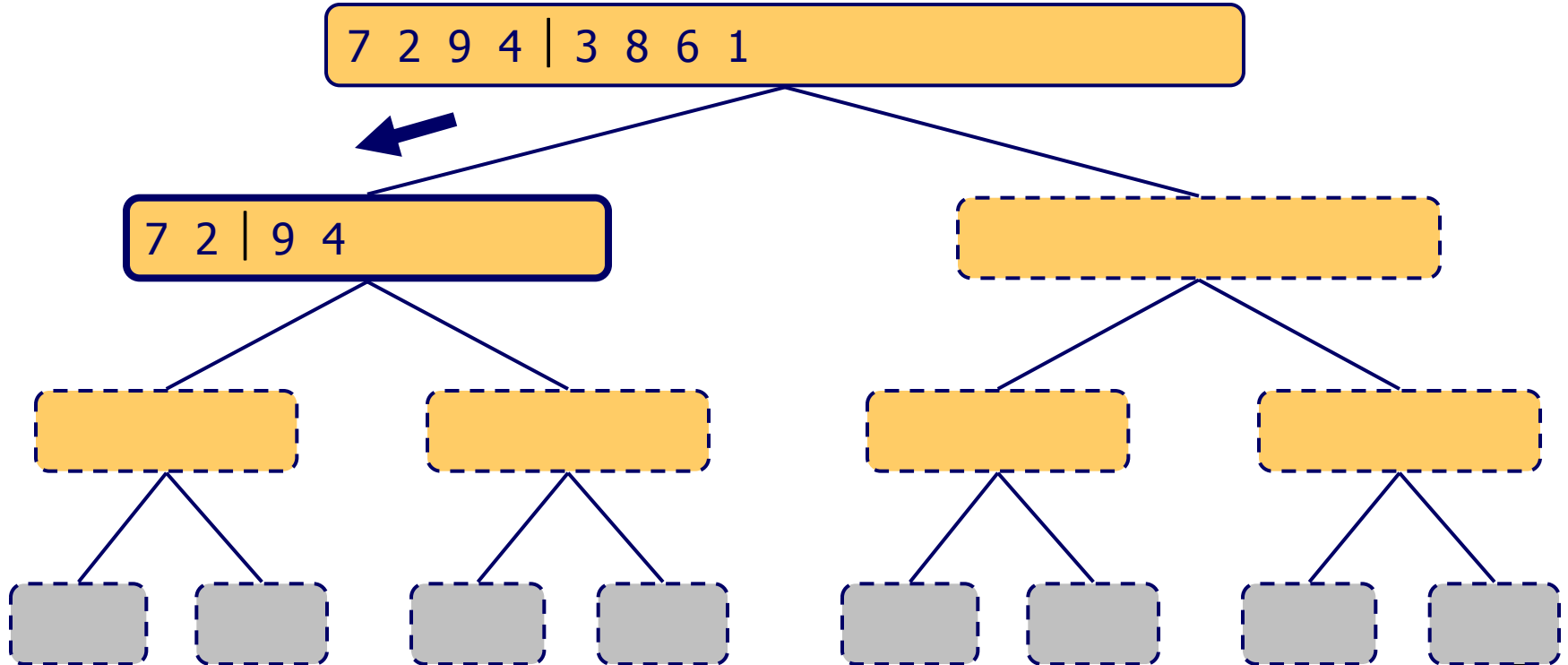


Partition



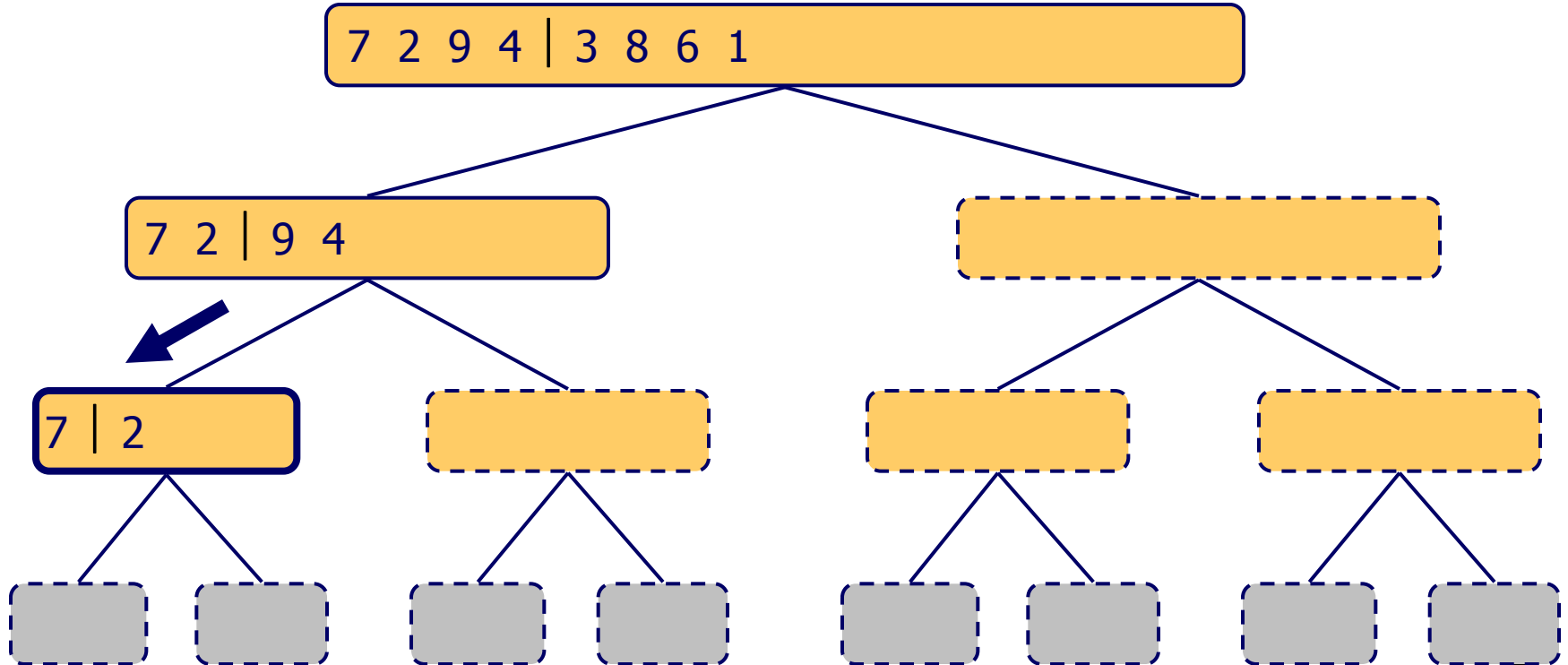
Execution Example (cont.)

📞 Recursive call, partition



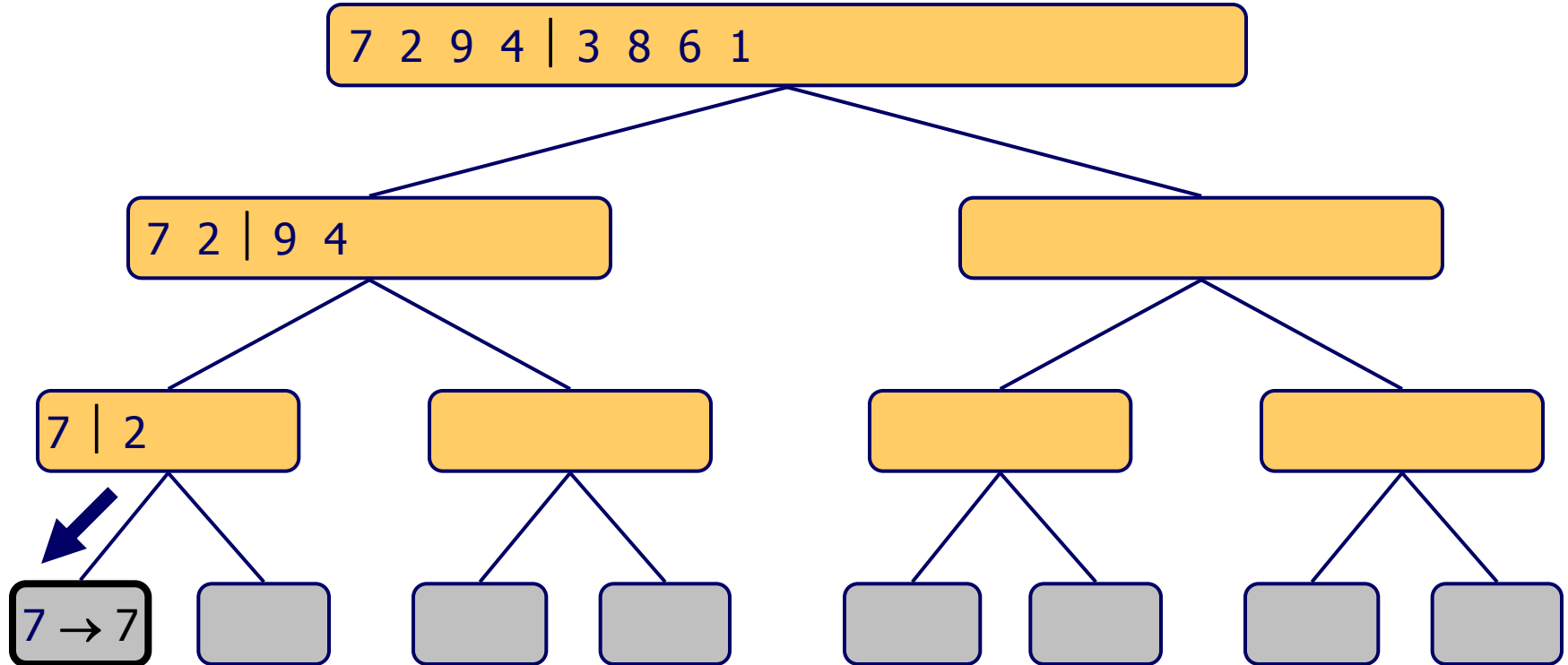
Execution Example (cont.)

☎ Recursive call, partition



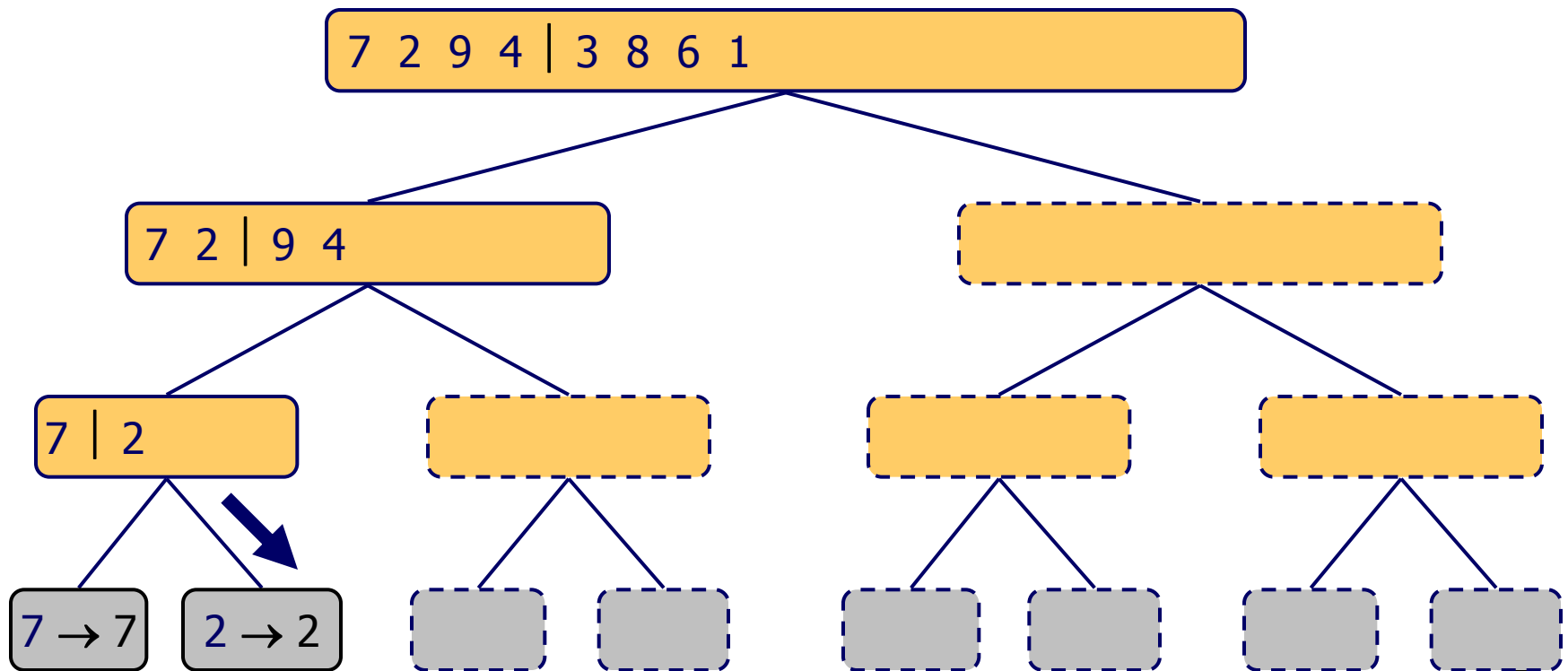
Execution Example (cont.)

☎ Recursive call, base case



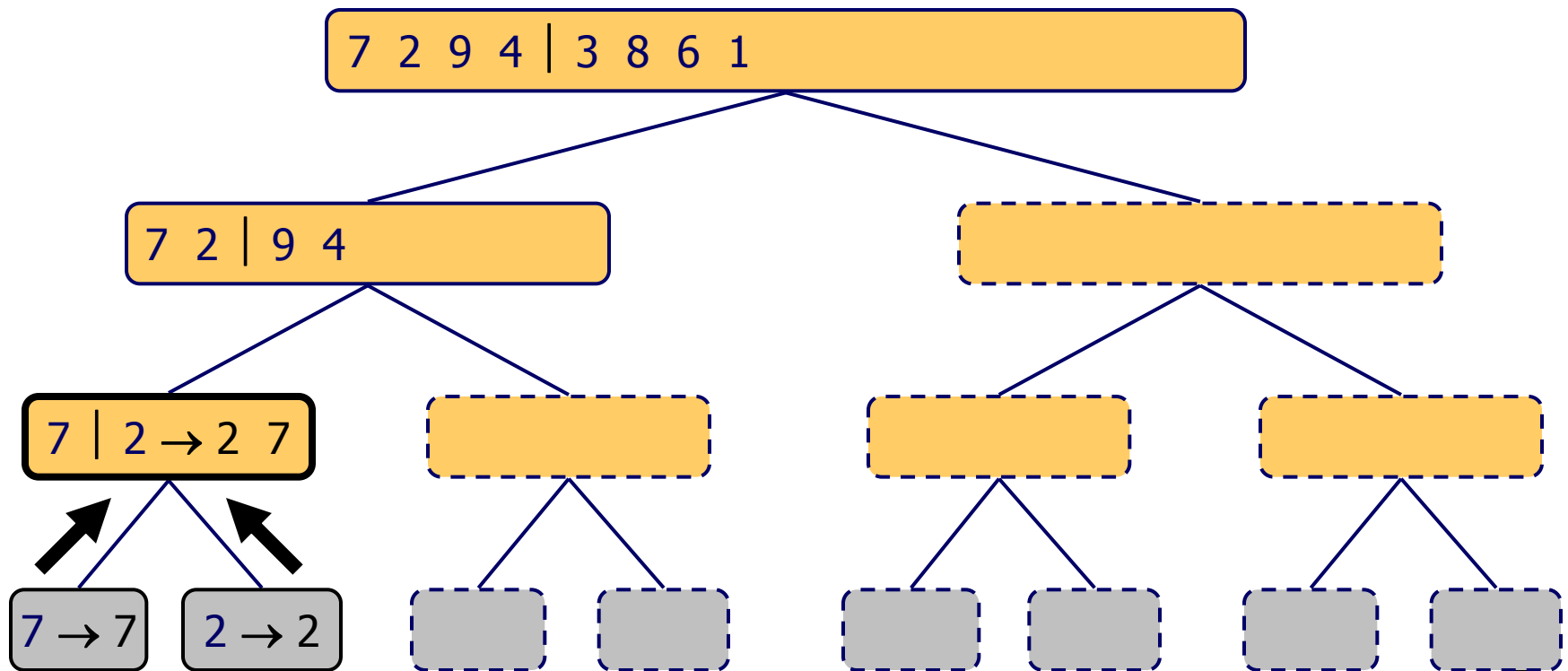
Execution Example (cont.)

☎ Recursive call, base case



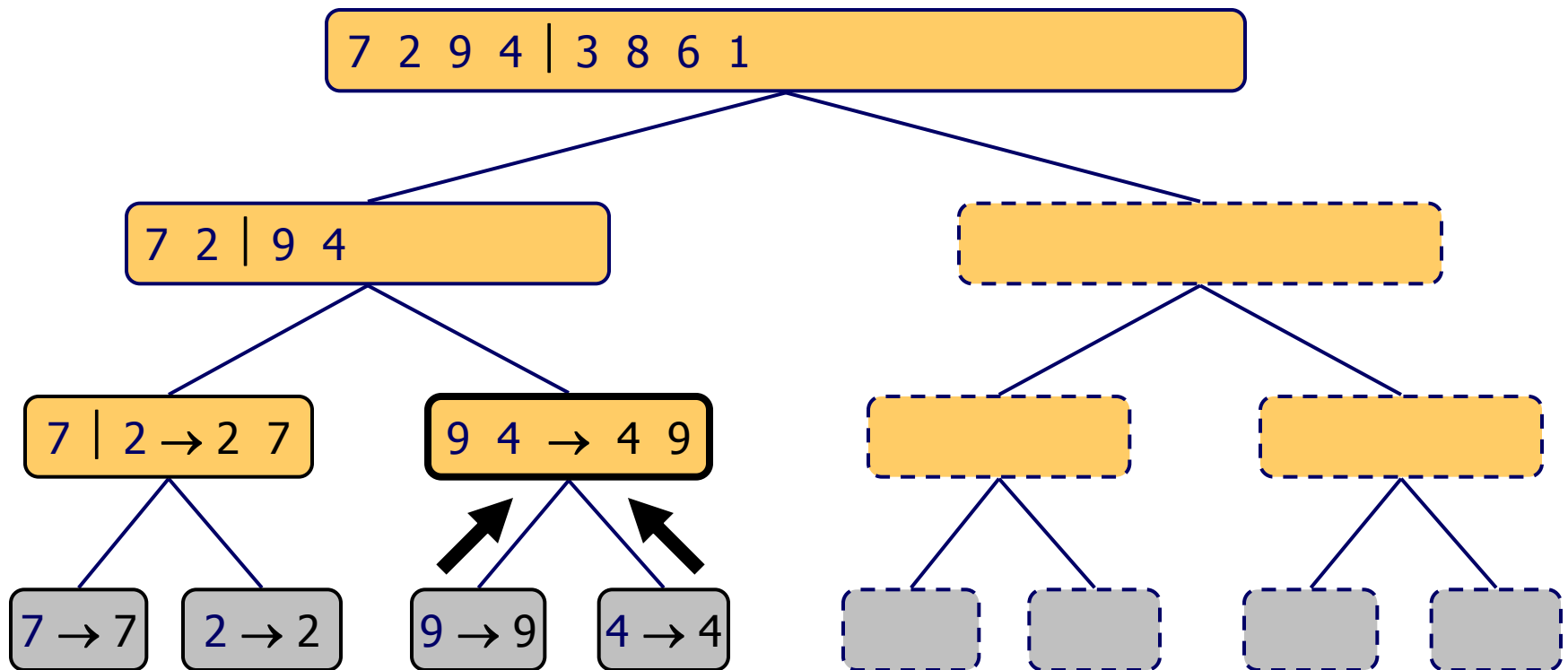
Execution Example (cont.)

 Merge



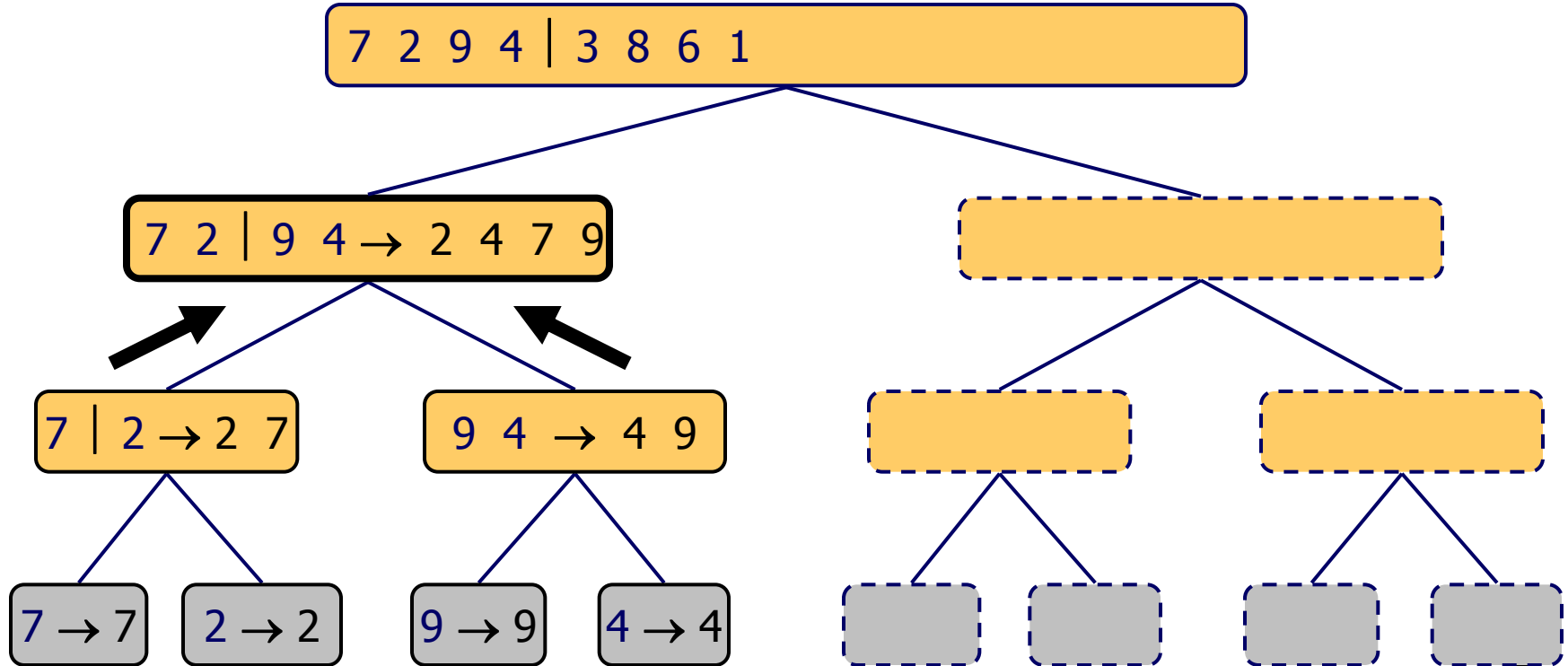
Execution Example (cont.)

☎ Recursive call, ..., base case, merge



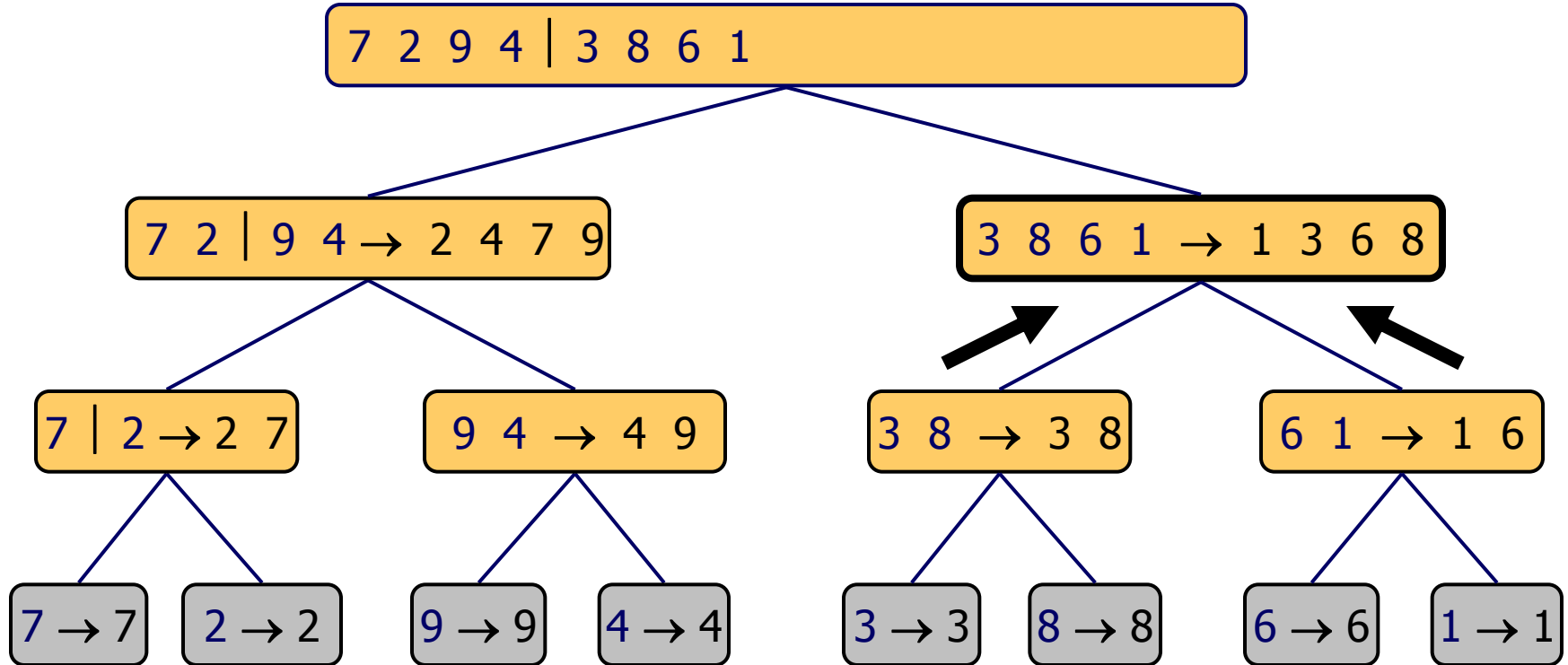
Execution Example (cont.)

 Merge



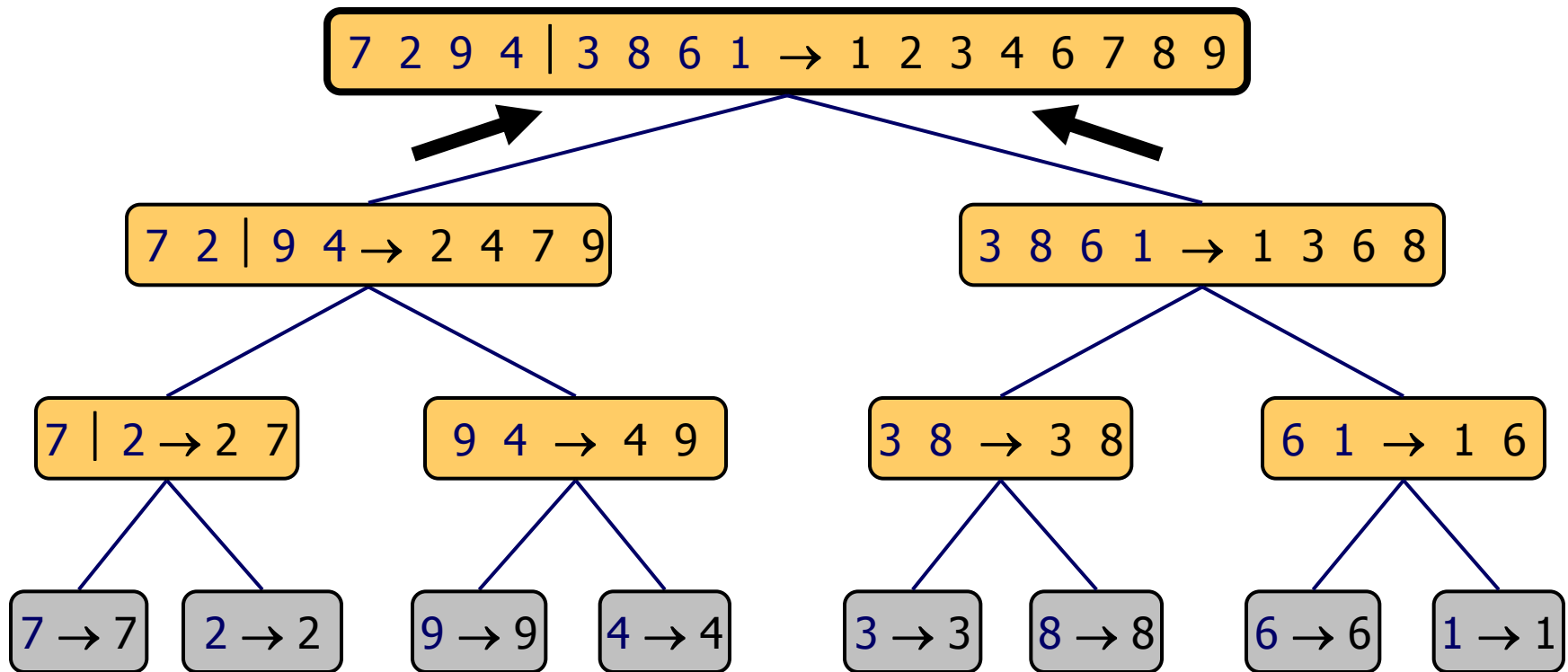
Execution Example (cont.)

☎ Recursive call, ..., merge, merge



Execution Example (cont.)

 Merge



- 





Outline

Quick-sort

-  Algorithm

-  Partition step

-  Quick-sort tree

-  Execution example

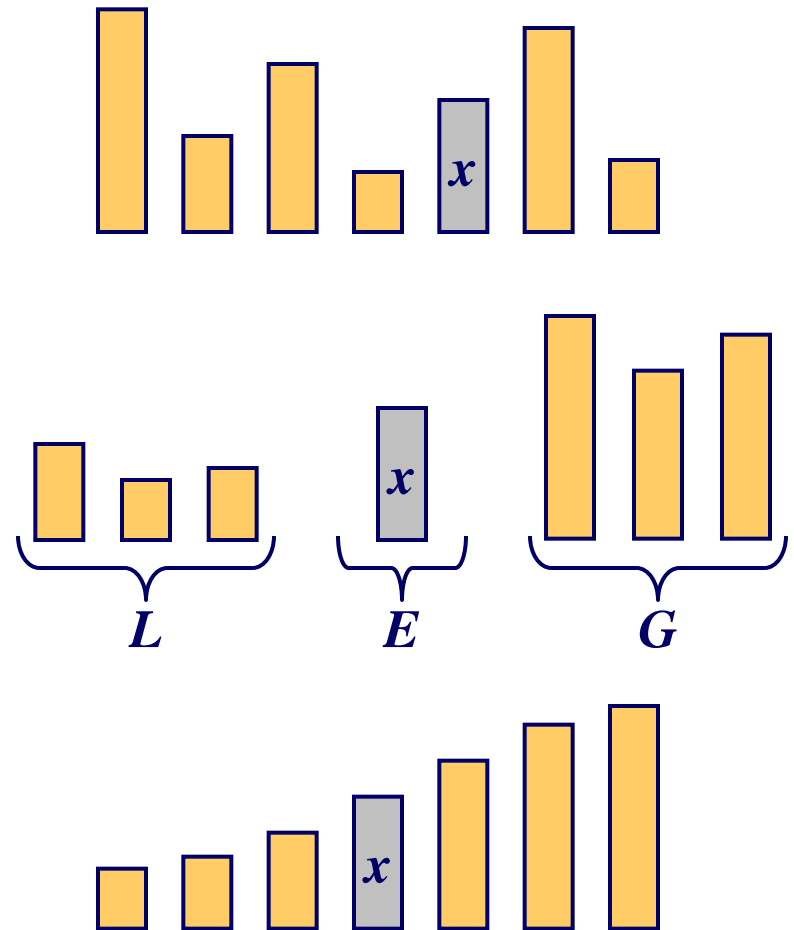
Analysis of quick-sort

Summary of sorting algorithms

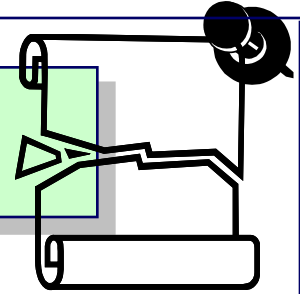
Quick-Sort

📞 Quick-sort is a randomized sorting algorithm based on the divide-and-conquer paradigm:

- ✉ Divide: pick a random element x (called pivot) and partition S into
 - 🎵 L elements less than x
 - 🎵 E elements equal x
 - 🎵 G elements greater than x
- ✉ Recur: sort L and G
- ✉ Conquer: join L , E and G



Partition



We partition an input sequence as follows:

- ⊠ We remove, in turn, each element y from S and
- ⊠ We insert y into L, E or G , depending on the result of the comparison with the pivot x



Each insertion and removal is at the beginning or at the end of a sequence, and hence takes $O(1)$ time



Thus, the partition step of quick-sort takes $O(n)$ time

Algorithm *partition*(S, p)

Input sequence S , position p of pivot

Output subsequences L, E, G of the elements of S less than, equal to, or greater than the pivot, resp.

$L, E, G \leftarrow$ empty sequences

$x \leftarrow S.remove(p)$

while $\neg S.isEmpty()$

$y \leftarrow S.remove(S.first())$

if $y < x$

$L.insertLast(y)$

else if $y = x$

$E.insertLast(y)$

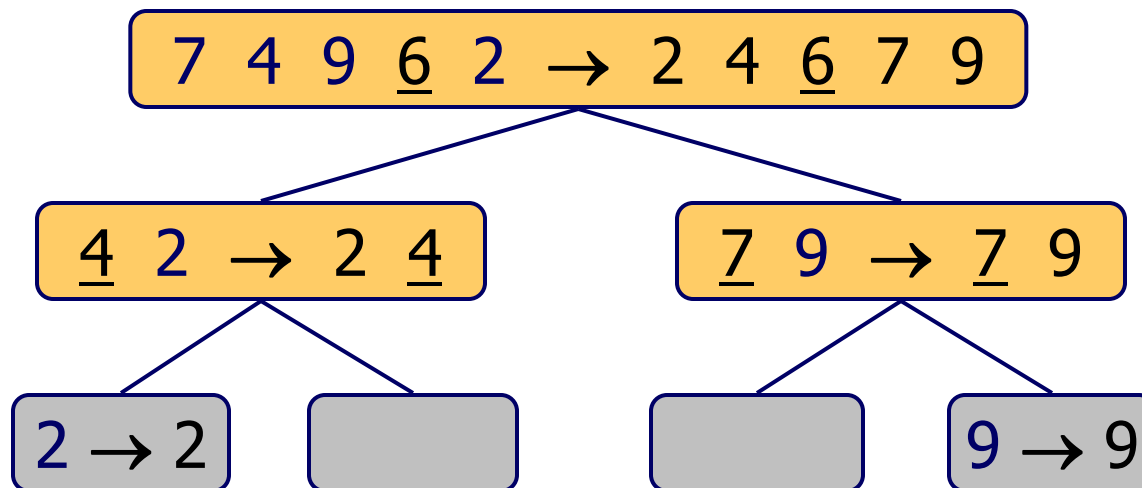
else $\{ y > x \}$

$G.insertLast(y)$

return L, E, G

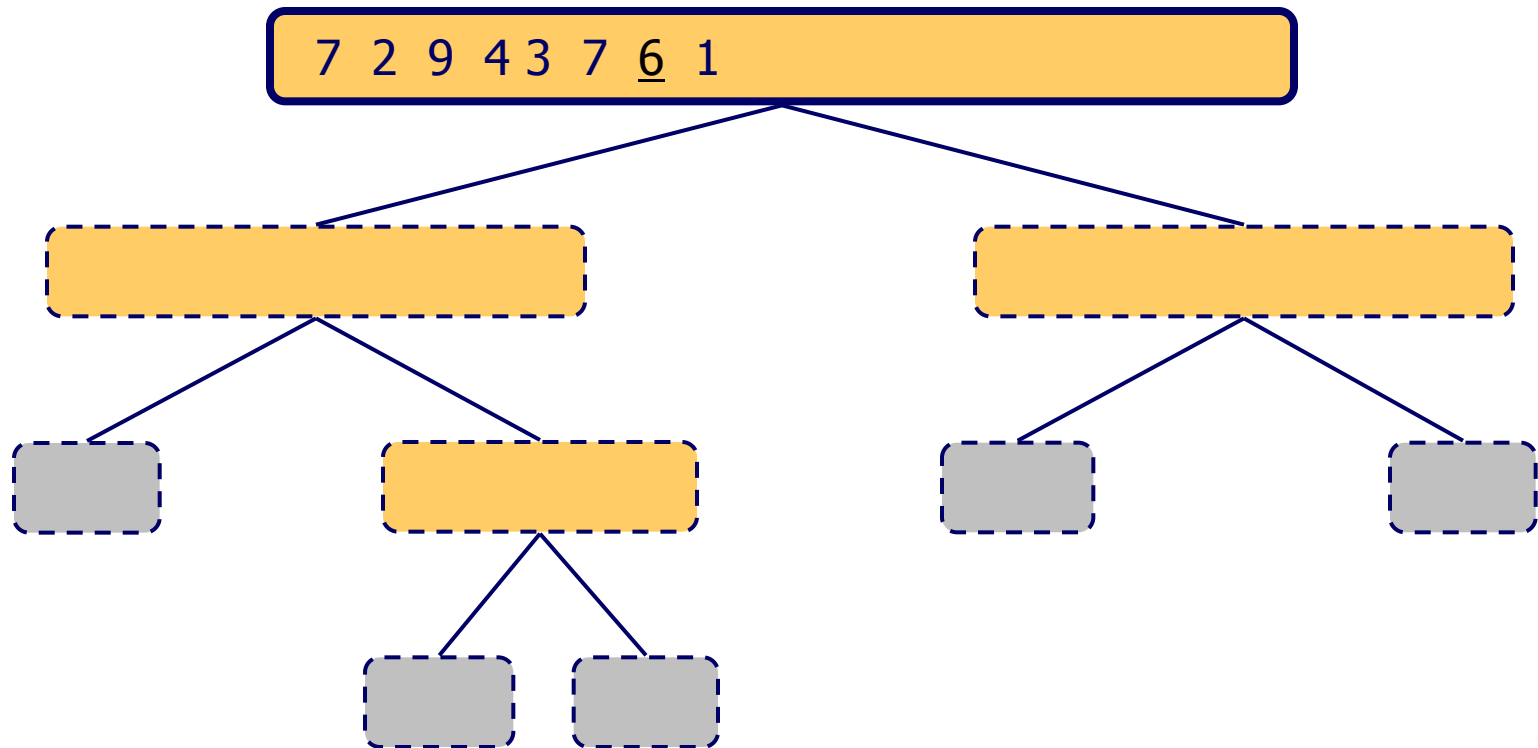
Quick-Sort Tree

- ☎ An execution of quick-sort is depicted by a binary tree
 - ✉ Each node represents a recursive call of quick-sort and stores
 - 🎵 Unsorted sequence before the execution and its pivot
 - 🎵 Sorted sequence at the end of the execution
 - ✉ The root is the initial call
 - ✉ The leaves are calls on subsequences of size 0 or 1



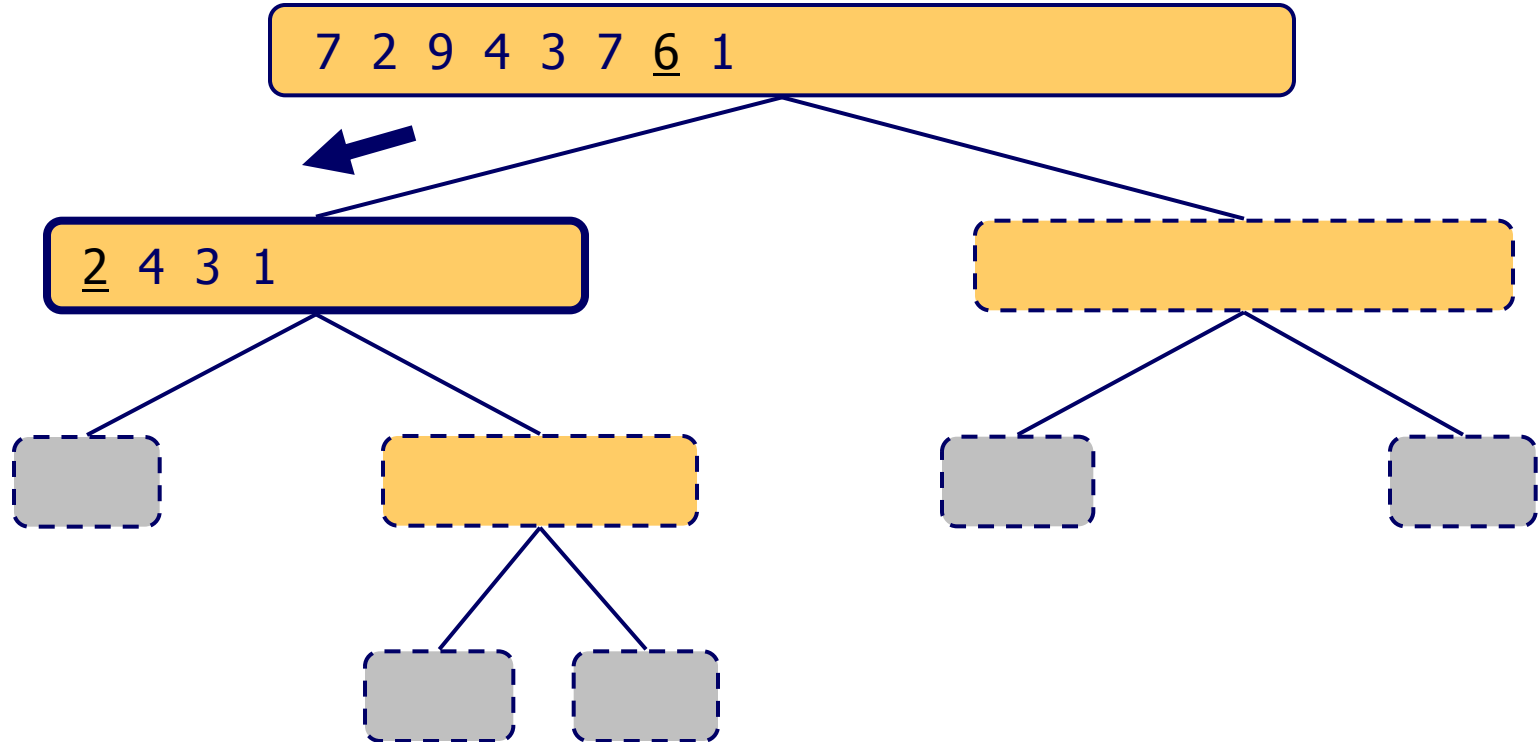
Execution Example

📞 Pivot selection



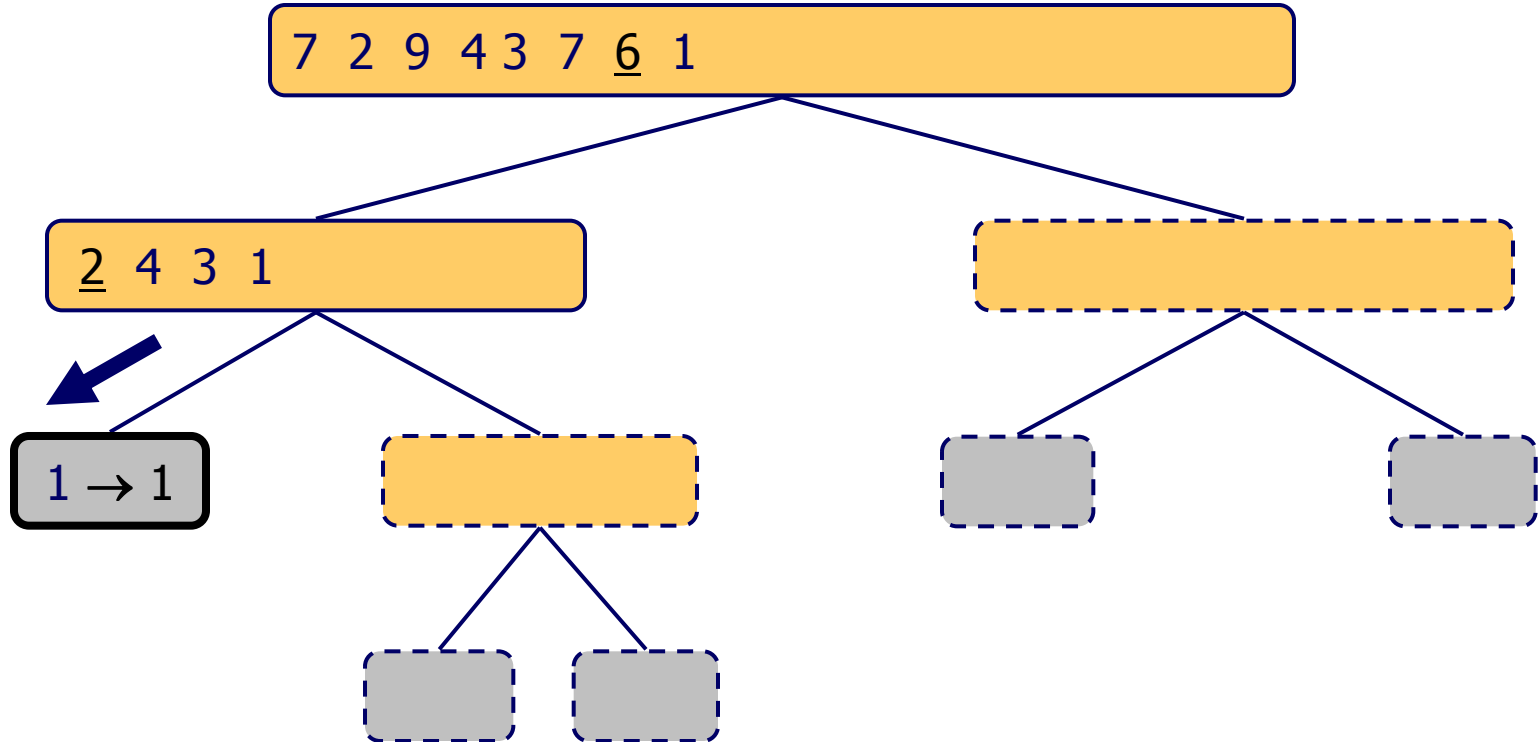
Execution Example (cont.)

☎ Partition, recursive call, pivot selection



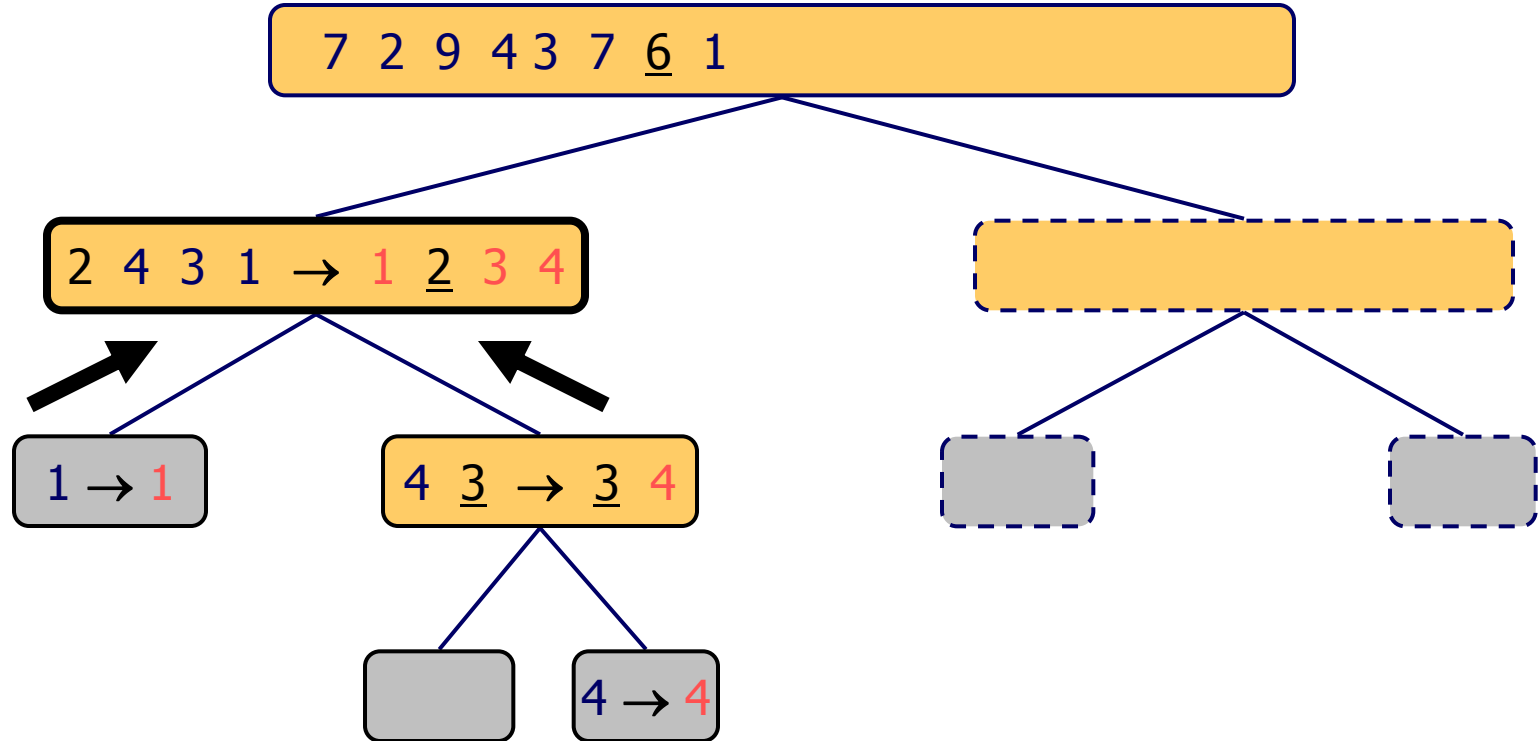
Execution Example (cont.)

☎ Partition, recursive call, base case



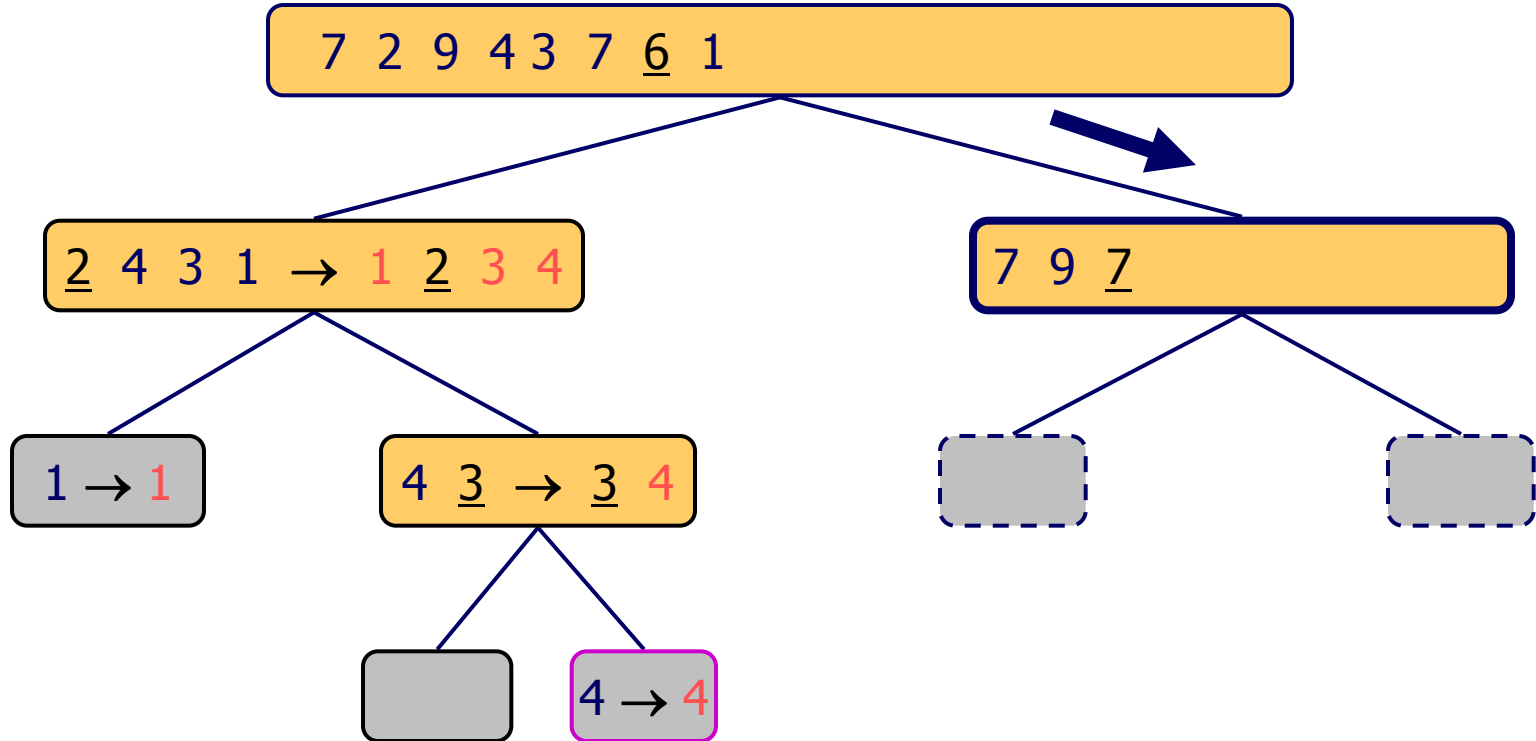
Execution Example (cont.)

☎ Recursive call, ..., base case, join



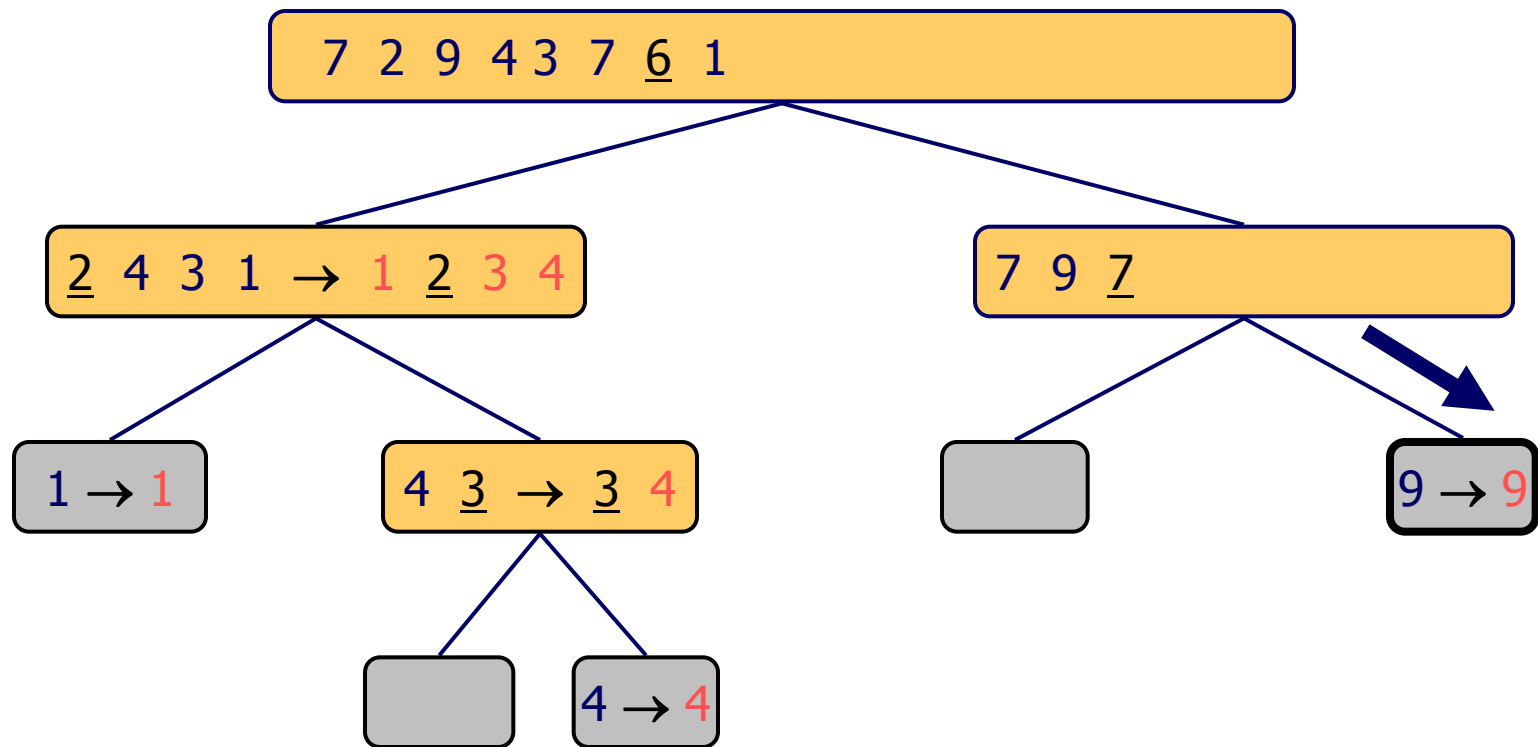
Execution Example (cont.)

📞 Recursive call, pivot selection



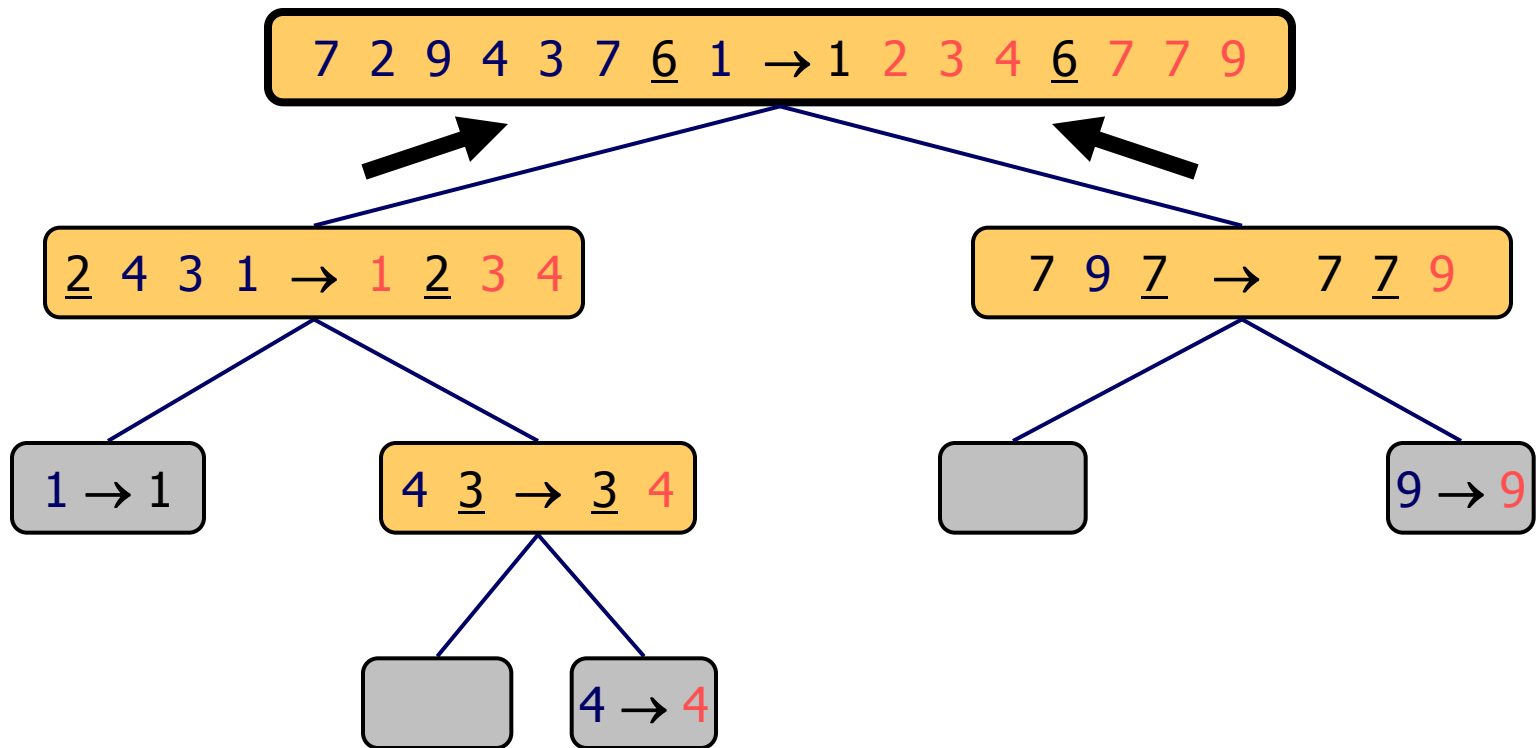
Execution Example (cont.)

☎ Partition, ..., recursive call, base case



Execution Example (cont.)

📞 Join, join



Worst-case Running Time

- ☎ The worst case for quick-sort occurs when the pivot is the unique minimum or maximum element
- ☎ One of L and G has size $n - 1$ and the other has size 0
- ☎ The running time is proportional to the sum
$$n + (n - 1) + \dots + 2 + 1$$
- ☎ Thus, the worst-case running time of quick-sort is $O(n^2)$

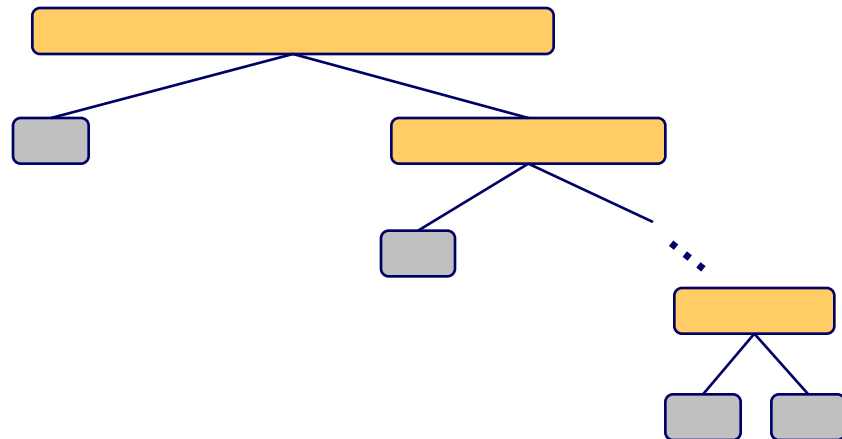
depth	time
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0	n
---	-----

1	$n - 1$
---	---------

...	...
-----	-----

$n - 1$	1
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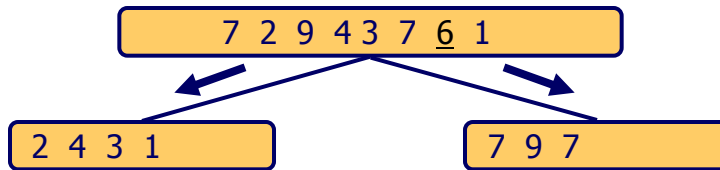


Expected Running Time

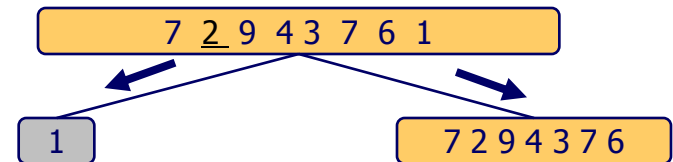


Consider a recursive call of quick-sort on a sequence of size s

- ☒ **Good call:** the sizes of L and G are each less than $3s/4$
- ☒ **Bad call:** one of L and G has size greater than $3s/4$



Good call



Bad call

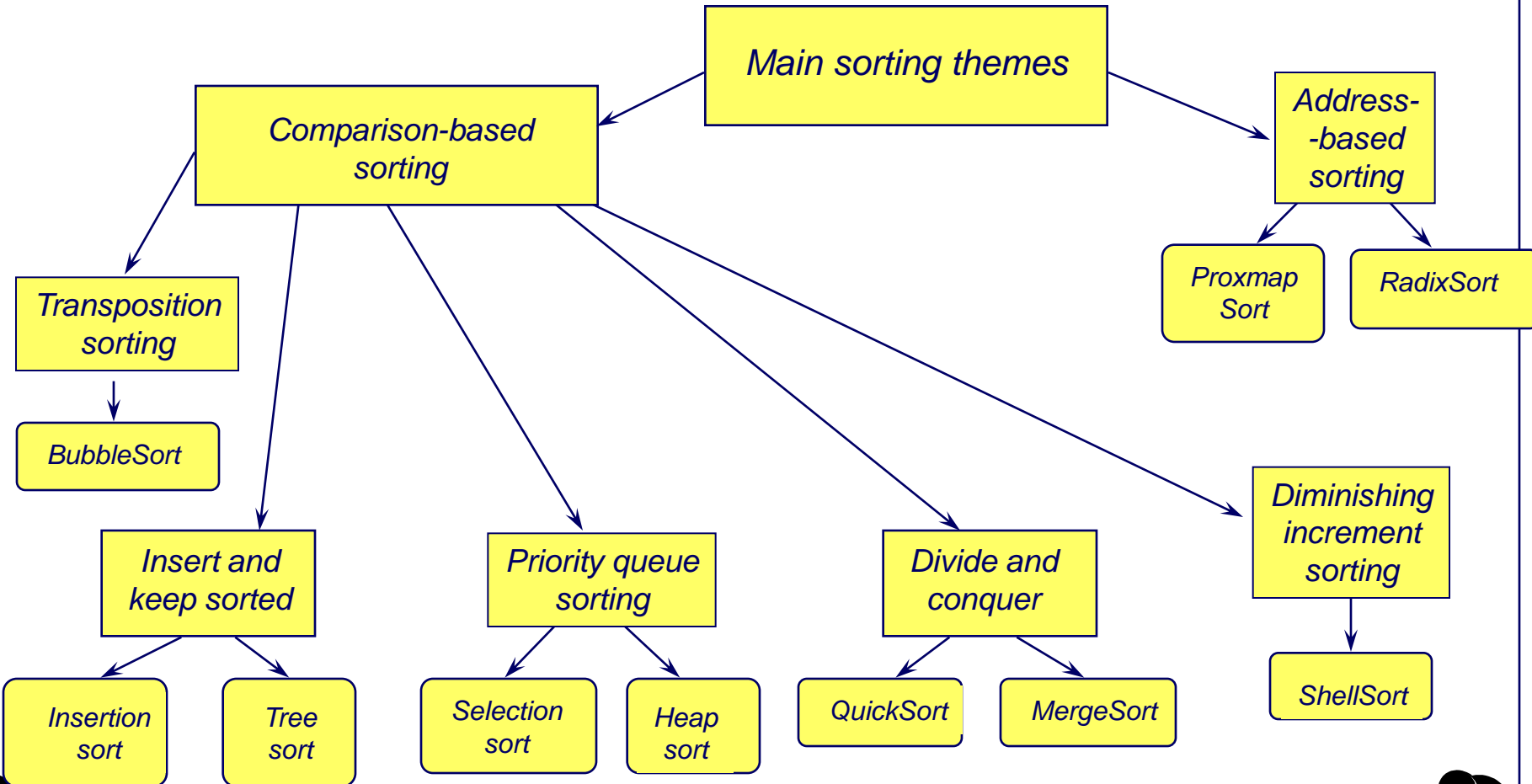


A call is good with probability $1/2$











- ☒ $1/2$ of the possible pivots cause good calls:



The family of sorting methods



Summary of Sorting Algorithms

Algorithm	Time	Notes
selection-sort	$O(n^2)$	 in-place  slow (good for small inputs)
insertion-sort	$O(n^2)$	 in-place  slow (good for small inputs)
quick-sort	$O(n \log n)$ expected	 in-place, randomized  fastest (good for large inputs)
heap-sort	$O(n \log n)$	 in-place  fast (good for large inputs)
merge-sort	$O(n \log n)$	 sequential data access  fast (good for huge inputs)