



Approximate Bayesian Computation

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18th June 2018

Intractability

- Statistical inference:
 - Given some data
(e.g. forensic evidence at a crime scene)
 - Set up random process – model – that could have produced it
 - Infer unknowns – parameters – in the model
(e.g. identity of perpetrator)
- Standard methods (e.g. maximum likelihood, Bayes) based on probability calculations under the model
- Can be **intractable**: impossible or impractically time consuming!
- Especially for complex modern models

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ABC idea

- Often models are **generative**
- i.e. can simulate data from model given parameters
- Can be used for inference without probability calculations!
- Simulate data under many parameter values
- Accept parameters giving data “close” to observations
- Gives **approximation** to exact inference
- Main idea of approximate Bayesian computation (ABC)
- One of several **likelihood-free** methods

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Example applications

- Population genetics
- Infectious disease epidemiology
- Systems biology / molecular dynamics
- Ecology
- Astrophysics / high energy physics
- Finance
- Agent based models
- Weather / climate

Overview of talk

- Recap of Bayesian inference
- Example of intractable likelihoods
- Introduction to ABC
- Summary statistics I
- Example analysis
- Summary statistics II
- Post-processing
- Efficient ABC algorithms
- Software
- Other likelihood-free methods
- More methodology
- Pros and cons
- References

Bayesian inference

Likelihood

- Observed data y_{obs}
- Model proposed with density $\pi(y|\theta)$
- We wish to infer parameters θ
- The **likelihood function** is $L(\theta) = \pi(y_{\text{obs}}|\theta)$
- Maximum likelihood finds θ maximising $L(\theta)$
- n.b. for discrete data use probabilities instead of densities

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Bayesian inference

- We must specify a **prior distribution** $\pi(\theta)$
 - Beliefs about parameters before data observed
- We're interested in the **posterior distribution** $\pi(\theta|y_{\text{obs}})$
 - Beliefs updated to take data into account
- Posterior depends on prior and likelihood through **Bayes theorem**:

$$\pi(\theta|y_{\text{obs}}) = \pi(\theta)\pi(y_{\text{obs}}|\theta)/Z$$

i.e. posterior \propto prior \times likelihood

- where $Z = \int \pi(\theta)\pi(y_{\text{obs}}|\theta)d\theta$ (normalising constant)

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Monte Carlo

- Direct calculation of posterior generally infeasible
- Common alternative approach is **Monte Carlo**
- Monte Carlo aims to produce a sample $\theta_1, \theta_2, \dots$ from the posterior distribution
- Can then estimate posterior quantities
(point estimates, interval estimates, quantiles etc)
- Or produce density estimates
(histograms, contour plots etc)

Monte Carlo methods

- Many standard Monte Carlo algorithms:
 - Rejection sampling
 - Importance sampling
 - Markov chain Monte Carlo (MCMC)
 - Sequential Monte Carlo (SMC)
- All require many evaluations of the likelihood function
- Not feasible for **intractable likelihoods** - evaluation not possible or very slow
- n.b. some Monte Carlo methods only require **unbiased estimates** of the likelihood function
- Helps with some cases of intractable likelihood

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Examples of intractable likelihoods

Computer models

- Some models exist as computer simulation programs
- Equation for likelihood not available (and would be extremely complicated)
- Example: **agent based models**
- Each agent obeys simple rules, interact to form a complex system
- Applications include
 - ecology (e.g. agents represent animals)
 - systems biology (e.g. agents represent cells)
 - economics (e.g. agents represent firms)

Partial observation

- Suppose we have a tractable probability model $\pi(x, y|\theta)$ for **complete data** (x, y)
- However we only observe that $y = y_{\text{obs}}$ (i.e. **partial data**)
- So x is an unobserved latent variable
- Likelihood is

$$L(\theta) = \pi(y_{\text{obs}}|\theta) = \int \pi(x, y_{\text{obs}}|\theta) dx$$

- Integral typically intractable, especially if x high dimensional

Partial observation: examples

- Epidemic models
 - x is times of all infections/recoveries, y is final number affected
- Biochemical networks
 - x is all reaction times, y is partial measurements of one species
- Population genetics
 - x is coalescent/mutation/recombination history, y is observed sequences

ABC

Likelihood-free inference

- General idea:
 - Simulate data y from various parameter values θ
 - Consider closest matches of y to y_{obs}
 - Use corresponding parameters for inference
- Can be implemented in many different ways
- Many approaches suggested in various fields over last 40+ years
- ABC puts this idea into a Bayesian framework

Likelihood-free inference timeline

1970s Various applications *Hoel and Mitchell, Ross etc*

1984 **Inference for implicit models** *Diggle and Gratton*

1984 Bayesian inference by simulating data *Rubin*

1989 **Simulated method of moments** *McFadden* (Econometrics)

1992 **GLUE** *Beven and Binley* (Hydrology)

1993 **Indirect inference** *Gourieroux et al* (Econometrics)

1997 **ABC** *Tavaré et al/Fu and Li* (Population genetics)

2005 **Convolution filter** *Rossi and Vila*

2006 **Iterated filtering** *Ionides et al*

2010 **Synthetic likelihood** *Wood*

... and many more!

ABC algorithm - simplest version

Input: observed data y_{obs} , **threshold** $h \geq 0$

For $i = 1, 2, \dots, N$:

- 1 Sample parameter vector θ_i from prior $\pi(\theta)$
- 2 Simulate data from $\pi(y|\theta_i)$
- 3 If $d(y, y_{\text{obs}}) \leq h$ accept θ_i

where $d(y, y_{\text{obs}})$ is a distance function e.g. Euclidean

Output: accepted θ_i values

This is a **rejection sampling** algorithm

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ABC target distribution

- Consider a proposed (θ, y) pair
- Sampled from $\pi(\theta)\pi(y|\theta) = \pi(\theta, y)$
- Acceptance is conditional on $y \approx y_{\text{obs}}$
- So accepted pairs drawn from $\pi(\theta, y|y \approx y_{\text{obs}})$
- And θ from $\pi(\theta|y \approx y_{\text{obs}})$
- An approx to exact posterior $\pi(\theta|y = y_{\text{obs}})$
- Taking $h = 0$ only accepts when $y = y_{\text{obs}}$
- Samples from exact posterior, but typically not practical (acceptances impossible/rare)

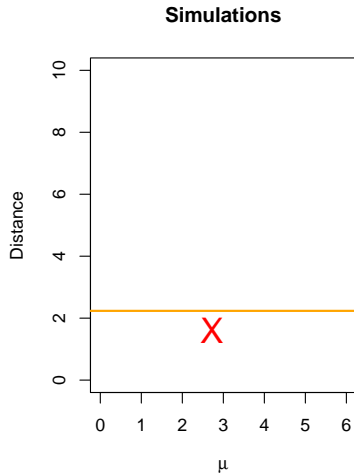
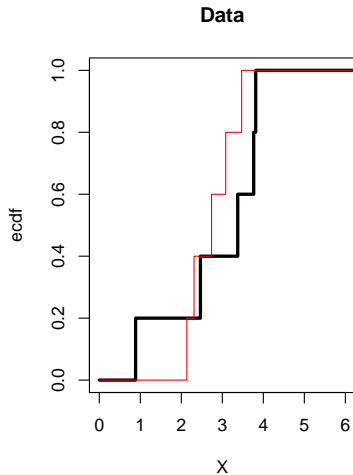
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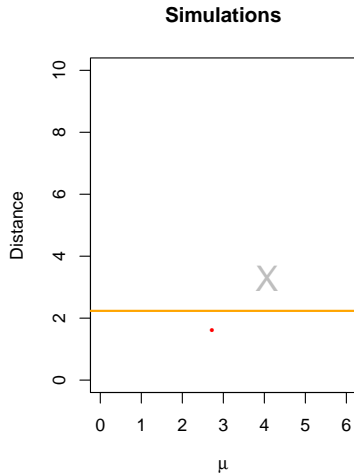
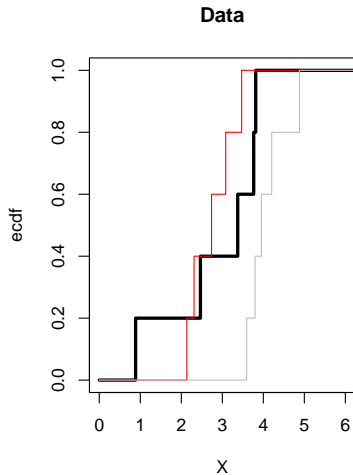
ABC algorithm example

- Model: 5 draws from $N(\mu, 1)$
- Data is ordered draws: $y_1 \leq y_2 \leq \dots \leq y_5$
- Prior: $\text{Uniform}(0, 6)$

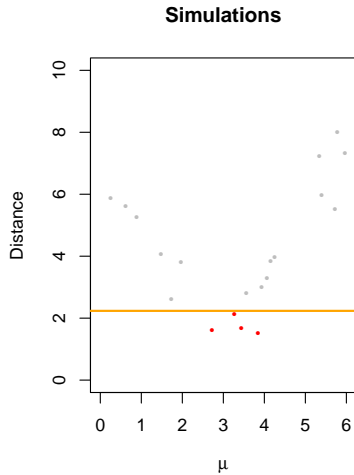
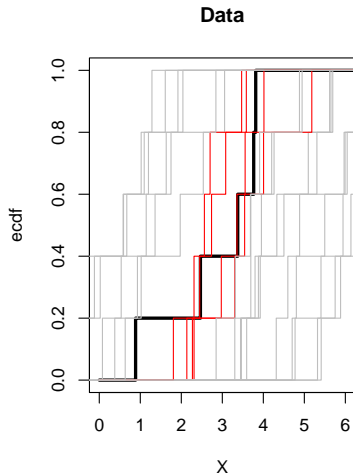
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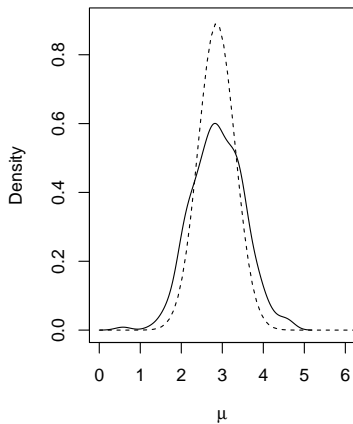


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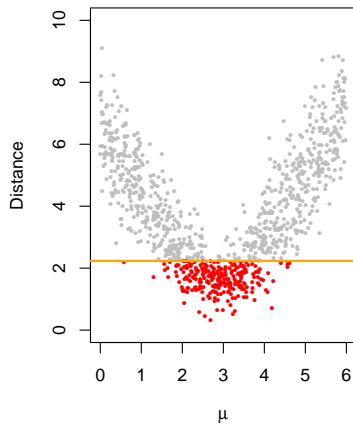


ABC algorithm example

Posterior

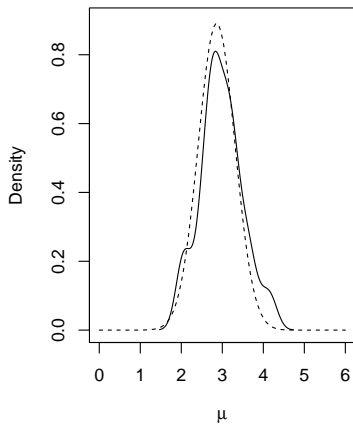


Simulations

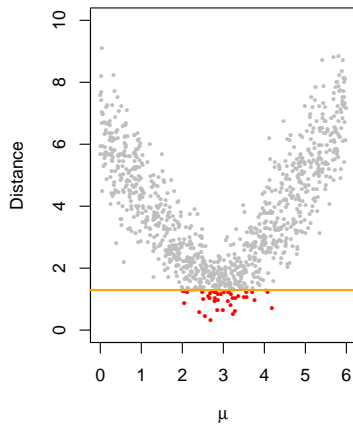


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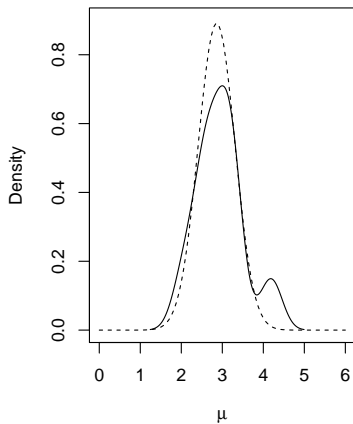


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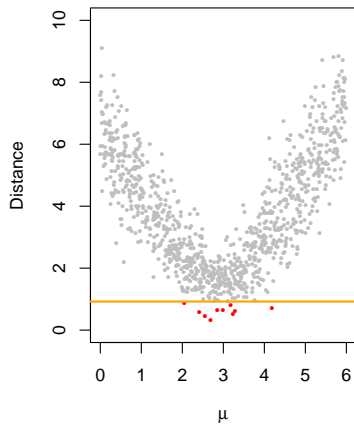


ABC algorithm example

Posterior



Simulations



Tuning ABC

- ABC has several tuning choices
- e.g. threshold h and distance function d
- Affect quality of approximate results
- Some key choices discussed next

ABC algorithm - effect of h

- h too large
 - Some accepted simulations are far from observations
 - Distribution of accepted θ s poor approx of posterior
- h too small
 - Distribution of accepted θ s better approx
 - But too few acceptances to learn distribution well!
- So choosing h is a trade-off between two source of error

Choice of h in practice

- Often rather than choose h in advance, the number k of desired acceptances is specified (e.g. 200)
 - Then h is chosen to achieve k acceptances
 - So chosen **after** distances computed
 - This seems a good pragmatic approach
-
- Also some asymptotic theory available
 - Blum (2010) "Approximate Bayesian Computation: A Nonparametric Perspective" (on h)
 - Biau et al (2014) "New insights into Approximate Bayesian Computation" (on k)

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Choice of d in practice

- Euclidean distance often used i.e.

$$d(a, b) = \left[\sum_i (a_i - b_i)^2 \right]^{1/2}$$

(where i indexes data components)

- Not sensible if data on widely different scales
- A popular alternative is weighted Euclidean distance,

$$d(a, b) = \left[\sum_i \left(\frac{a_i - b_i}{\sigma_i} \right)^2 \right]^{1/2}$$

- Here σ_i could be standard deviation of i th data component samples
- Many other distances possible - impact on results modest in general

Choice of d for repeated observations

- Special case: data is IID (e.g. repeated time series)
- Recent work has found good ABC distance measures here:
 - Kernel MMD (Park et al 2016)
 - Wasserstein distance (Bernton et al 2017)
 - Kullback-Leibler divergence (Jiang et al 2018)

Summary statistics

Summary statistics in ABC

- Earlier algorithm accepts when $d(y, y_{\text{obs}}) \leq h$
- In practice the data is usually reduced to a vector of **summary statistics** $s = S(y)$
- Acceptance occurs when $d(s, s_{\text{obs}}) \leq h$ (where $s_{\text{obs}} = S(y_{\text{obs}})$)
- Clearly necessary for non-numeric data such as genetic sequences
- Also turns out to be necessary more generally

Need for summary statistics

- Beaumont et al (2002), reviewing early work on ABC:
“A crucial limitation of the . . . method is that only a small number of summary statistics can usually be handled. Otherwise, either acceptance rates become prohibitively low or the tolerance . . . must be increased, which can distort the approximation.”
- Crucial that only a small number of summaries used
- Recognised from earliest work on ABC

Curse of dimensionality

- Quote is about a **curse of dimensionality** problem in ABC
- Informal statement:
 - More summary statistics means more opportunities for mismatches between $S(y)$ and $S(y_{\text{obs}})$
 - So distances $d(S(y), S(y_{\text{obs}}))$ typically larger
 - Need large h , which causes approximation error
- Formal statement:
 - ABC converges to correct posterior as $h \rightarrow 0, N \rightarrow \infty$
 - Asymptotic rate of convergence worsens with $\dim y$
 - Proved (at least partially) for most varieties of ABC

Curse of dimensionality

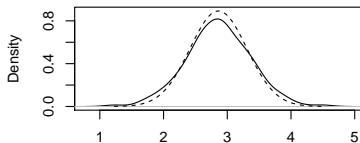
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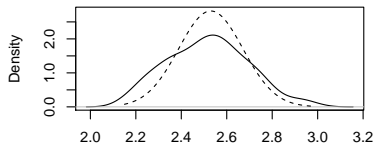
- Same example as before but with higher dimensional data
- Model: d draws from $N(\mu, 1)$
- Data is ordered draws: $y_1 \leq y_2 \leq \dots \leq y_d$
- Uniform prior on $[0, 6]$
- $N = 10^4$ ABC iterations
- $k = 200$ acceptances
- Density estimate of ABC output compared to true posterior

Curse of dimensionality example

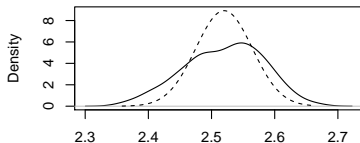
5 summaries



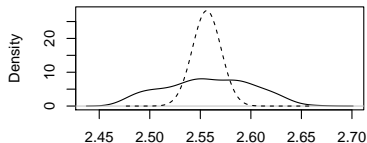
50 summaries



500 summaries



5000 summaries



Need for summary statistics

- Dimension of data usually high so must be replaced with **low-dimensional summaries**
- Now ABC approximates $\pi(\theta|s_{\text{obs}})$
- i.e. posterior conditional on observed summaries
- We want this to be similar to $\pi(\theta|y_{\text{obs}})$
- So we want **informative summaries** about θ
- How to meet both requirements?

Sufficient statistics

- **Sufficient statistics** satisfy $\pi(\theta|s_{\text{obs}}) = \pi(\theta|y_{\text{obs}})$
- Low dimensional sufficient statistics would be ideal for ABC
- However they essentially only exist for exponential family models
- Very few intractable likelihood models are in this class
- So generally we must use **insufficient statistics** and accept some loss of information

Example analysis

Application

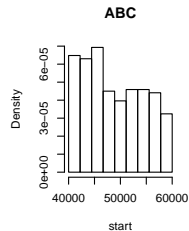
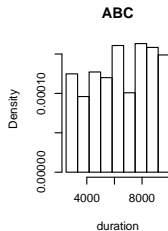
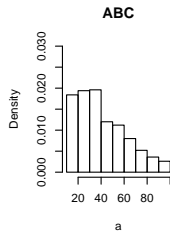
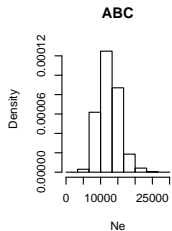
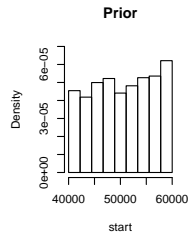
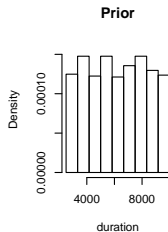
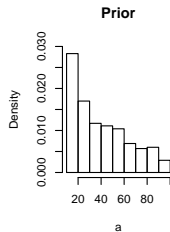
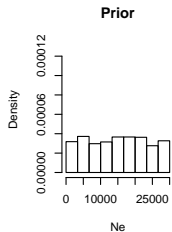
- We analyse the “**human**” dataset from the abc R package
- Population genetic data from Italy population (16 individuals)
- A coalescent model investigated with a population bottleneck.
Parameters are:
 - Ne: Effective population size
 - a: Intensity of bottleneck (ratio of pop size before and during)
 - duration: Bottleneck duration
 - start: Start of bottleneck
- Data is genetic sequences from various regions of genome
- 3 summary statistics used, believed to be informative about demographic history
 - Average nucleotide diversity, $\bar{\pi}$
 - Mean of Tajima's D
 - Variance of Tajima's D

ABC setup

- $N = 50,000$ ABC iterations
- $k = 500$ acceptances (1%)
- Weighted Euclidean distance used

```
library(abc)
data(human)
## Initialise data
sumstats = subset(stat.3pops.sim, models=="bott")
params = par.italy.sim
sumstats.obs = stat.voight[2,]
## Tuning choice
mytol = 500/nrow(sumstats) # i.e. 500 acceptances
## Do ABC
abc.out = abc(target=sumstats.obs, param=params,
              sumstat=sumstats, tol=mytol,
              method="rejection")
```

ABC output histograms



Choosing summary statistics

Recap

- We typically have high dimensional data y
- Want summary statistics $S(y)$ which are:
 - (1) **Low dimensional**
 - (2) **Informative about θ**
- How to choose these?

Choosing summary statistics

- One option is to make a subjective choice
- More automatic methods have been proposed:
 - **Subset selection**
Find best subset of many *candidate summaries*. e.g. run ABC for each subset on test datasets and minimise error.
 - **Projection**
Find projections of many *data features* $z(y)$ which are informative about θ . e.g. fit $\theta \sim N(Az(y), \Sigma)$ or use machine learning
 - **Auxiliary model**
Use a tractable *auxiliary model*. e.g. let $S(y)$ be its MLEs.
- These methods typically do better than subjective choice
- But no obvious best method
- Lots of user input still required in choosing/tuning/testing method

Choosing summary statistics

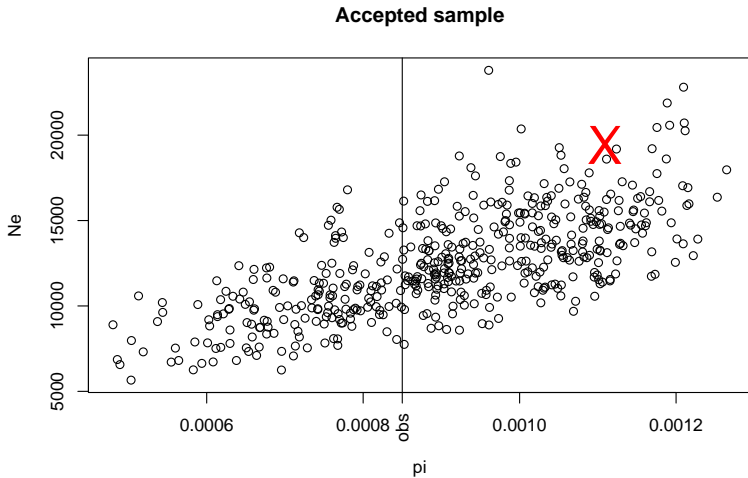
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Post-processing

Idea

- ABC accepts a sample $\theta_1, \theta_2, \dots, \theta_k$
- The associated summary statistics are s_1, s_2, \dots, s_k
- Can we **correct** θ_i to take account of the difference between s_i and s_{obs} ?

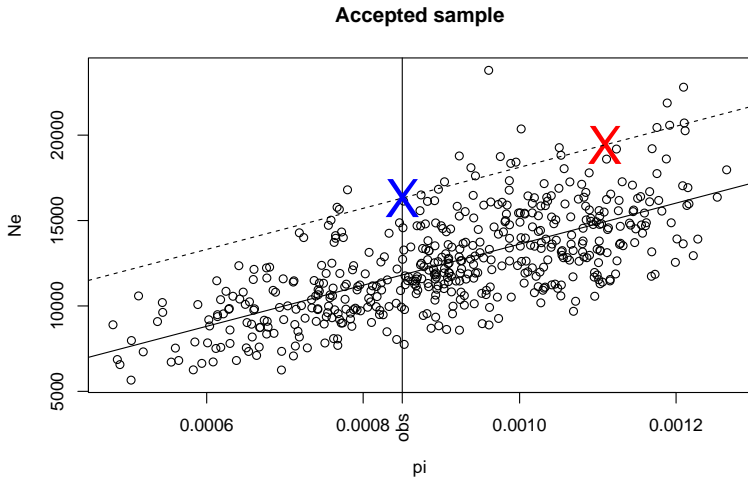
Illustration: human dataset



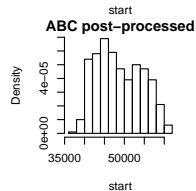
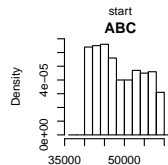
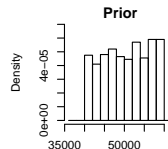
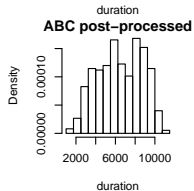
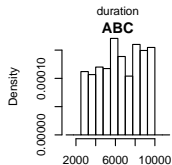
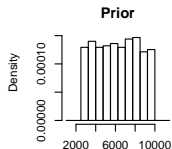
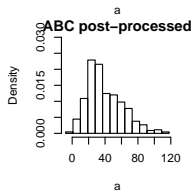
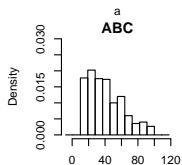
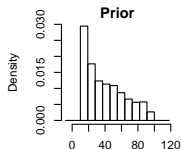
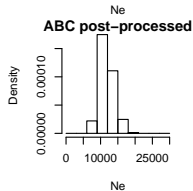
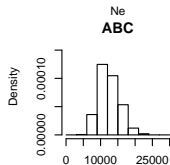
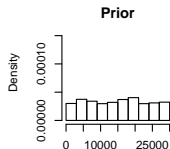
Approach

- Fit a model to the accepted (θ_i, s_i) pairs
- e.g. regression $\theta \sim N(As + b, \Sigma)$ (Beaumont et al 2002)
- So $E(\theta|s) = As + b$
- Now correct θ_i to $\theta_i - E(\theta|s_i) + E(\theta|s_{\text{obs}})$
- i.e. to $\theta_i + A(s_{\text{obs}} - s_i)$

Illustration: human dataset



Example: human dataset



Variations

- Regression correction can be applied to output of most ABC algorithms
- Methods using more flexible regression models have been proposed
- e.g. heteroskedastic regression, neural networks (Blum and François 2010)
- Similar ideas for ABC model choice (Beaumont et al 2008)

Usefulness

- Originally hoped post-processing would reduce curse of dimensionality
- However it's been proved that the rate of convergence issue is essentially unchanged (Blum 2010)
- Nonetheless post-processing sometimes improves results greatly in practice (Blum et al 2013)
- Li and Fearnhead (2018) give some asymptotic support for use in case of large data
- But Frazier et al (2018) argue it's poor under misspecified models

More efficient ABC algorithms

Inefficiency of rejection ABC

- Always samples θ from prior distribution
- Typically posterior is much more concentrated than prior
- Therefore most simulations will be very poor
- We'd like to propose better θ values
- Ideally learn good proposal distribution during algorithm

ABC importance sampling

Input: y_{obs} , $h \geq 0$, $d(\cdot, \cdot)$, **importance density** $g(\theta)$

For $i = 1, 2, \dots, N$:

- 1 Sample parameter vector θ_i from $g(\theta)$
- 2 Simulate data from $\pi(y|\theta_i)$
- 3 If $d(y, y_{\text{obs}}) \leq h$ accept θ_i with weight $w_i = \pi(\theta)/g(\theta)$

Output: accepted (θ_i, w_i) pairs

Monte Carlo inference now possible as for standard importance sampling

Issue: need a sensible choice of g

ABC-SMC (very rough overview)

- Run standard ABC with threshold h_1
 - Use output to choose importance density $g(\theta)$
 - Run ABC importance sampling with threshold $h_2 < h_1$
 - And so on
-
- Adaptively learns $g(\theta)$
 - Various schemes along these lines
 - (Technical point: some are population Monte Carlo methods and others are true SMC algorithms)

ABC-MCMC

- 0 Initialise some θ_0 and simulate corresponding y . Let $t = 0$.
 - 1 Propose θ' from $q(\cdot|\theta_t)$ e.g. $\theta' \sim N(\theta_t, \Sigma)$
 - 2 Simulate y' from model conditional on θ'
 - 3 Calculate $\alpha = \min \left[1, \frac{\pi(\theta')q(\theta_t|\theta')\mathbb{1}[d(s(y'), s_{\text{obs}}) \leq h]}{\pi(\theta_t)q(\theta_t|\theta')\mathbb{1}[d(s(y), s_{\text{obs}}) \leq h]} \right]$
 - 4 With probability α accept
Acceptance: Let $\theta_{t+1} = \theta'$ and $y = y'$
Rejection: Let $\theta_{t+1} = \theta_t$ and leave y unchanged
 - 5 Increment t and return to 1
- Discard initial results as burn-in
 - Remainder can be used as Monte Carlo sample

Comparison of ABC algorithms

- All sample from **same** approximate distribution given h etc.
- So can choose based on efficiency/convenience
- ABC rejection
 - Least efficient
 - But simple to implement, esp parallelisation
 - Simulations can be reused for other analyses e.g. checking performance on simulated datasets
 - Model choice version easy
- ABC-SMC
 - Allows adaptation of h
 - Complicated to code
 - Some parallelisation possible
 - Lots of tuning choices
 - Model choice version easy

Comparison of ABC algorithms, continued

■ ABC-MCMC

- Must fix h in advance (some research on varying it)
- Parallelisation not possible
- Several tuning choices
- Model choice version tricky
- Some convergence theory exists
(which shows alternative “one-hit” MCMC kernel is more efficient)

Software for ABC

Software options

- python: “ABCPy” and “PyABC” (many algorithms, very up to date)
- python: “ABCSysBio” (sequential ABC algorithm, systems biology)
- R: “abc” package (rejection sampling)
- R: “easyABC” package (multiple algorithms)
- standalone: “DIY-ABC” (rejection sampling, population genetics)
- standalone: “pop-ABC” (rejection sampling, population genetics)
- ...
- Or code your own!
 - Especially feasible for rejection ABC as algorithm v simple

Alternatives to ABC

Other likelihood-free methods

- Indirect inference
 - Tries to find θ minimising average distance $d(s, s_{\text{obs}})$
 - Can be viewed as maximum likelihood analogue of ABC
- Synthetic likelihood
- Likelihood-free expectation propagation
- History matching
- Conditional density estimation (e.g. via random forests or deep learning)
- Bayesian optimisation of estimated likelihoods
- Likelihood ratio estimation

Conclusion

Summary

- ABC is a likelihood-free method for inference
 - Useful for generative models with intractable likelihood
 - Idea is to find θ values that produce $S(y) \approx S(y_{\text{obs}})$
 - These approximate posterior
-
- Informative low-dimensional summaries crucial for method to work well
 - Lots of algorithms/methodology exists to improve the method
 - Research in more general likelihood-free methods very active!

Strengths

- The **only** way to do inference in some situations!
- Lots of freedom in what model can be used
 - Just need to be able to simulate data in reasonable time
- Simplicity
 - Simplest ABC algorithm very easy to understand/implement

Weaknesses

- Tuning requirements
 - Acceptance threshold, summary statistics, algorithm specific choices. . .
- Results are approximate
 - And it's hard to quantify how approximate
- Computationally expensive
 - Since very large number of simulations often required
- Only possible for a small number of parameters (up to around 10)
 - ABC curse of dimensionality limits number of summary statistics
 - Identifiability generally requires at least one summary statistic for each parameter

References

Review papers

- Beaumont et al “Approximate Bayesian computation in evolution and ecology” (2010)
- Bertorelle et al “ABC as a flexible framework to estimate demography over space and time: some cons, many pros” (2010)
- Csillery et al “Approximate Bayesian computation (ABC) in practice” (2010)
- Marin et al “Approximate Bayesian computational methods” (2011)
- Sunnaker et al “Approximate Bayesian computation” (2013) (basis of the ABC wikipedia page!)
- Baragatti and Pudlo “An overview on approximate Bayesian computation” (2014)
- Lintusaari et al “Fundamentals and recent developments in approximate Bayesian computation” (2017)
- Handbook of ABC (2018)

Bonus material!

ABC for model choice

Bayesian model choice

- Suppose there are several proposed models for the data
- i.e. M_1, M_2, \dots, M_k
- We'll usually consider $k = 2$ or 3
- Each has a pdf $\pi(y|\theta, M_i)$ and a prior $\pi(\theta|M_i)$
- n.b. θ may represent **different** set of parameters for each model
- We also have prior model weights $\pi(M_1), \pi(M_2), \dots$
- We want posterior models weights $\pi(M_1|y_{\text{obs}}), \dots$
- Maybe also parameter estimates $\pi(\theta|y_{\text{obs}}, M_1), \dots$
- All based on Bayes theorem

Difficulties with Bayesian model choice

- **Computational**

Likelihood-based calculation of posterior model weights notoriously hard in sufficiently complicated problems

Motivates methods like reversible-jump MCMC etc

- **Robustness**

Results can be very sensitive to details of prior distributions

Sensitivity analysis required

- **Interpretation**

Depends on whether we assume one model really is correct

Or that we search for the best approximation

- However still useful in practice!

ABC model choice

- Some or all models may have intractable likelihoods
- Human dataset example:
 - 3 coalescent models compared representing different demographic histories
 - 1 Model 1: bottleneck
 - 2 Model 2: constant population
 - 3 Model 3: exponential population growth
 - Each model has different number of parameters
- ABC algorithms can be adapted to this problem

ABC model choice: rejection sampling

Input: $y_{\text{obs}}, h, d(\cdot, \cdot), S(\cdot)$

For $i = 1, 2, \dots, N$:

- 1 Sample model m_i from model prior
- 2 Sample parameter vector θ_i from prior $\pi(\theta|m_i)$
- 3 Simulate data from $\pi(y|\theta_i, m_i)$
- 4 If $d(S(y), s_{\text{obs}}) \leq h$ accept (m_i, θ_i)

Output: accepted (m_i, θ_i) values

Estimate posterior weight of model M_i by its frequency in output

Example: human dataset

- Equal prior model weights
- $N = 150,000$ ABC iterations
- $k = 500$ acceptances (0.3%)
- Results for 3 sets of observed data: Hausa (Cameroon), Chinese and Italian (each 16 individuals)
- Same ABC simulations used for each analysis
- Output proportions:

Population	Bottleneck	Constant	Exp growth
Hausa	0.012	0.288	0.702
Chinese	0.776	0.226	0.000
Italian	0.966	0.036	0.000

- Especially important to do sensitivity analyses etc. See abc package vignette for worked details.

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Summary statistics for ABC model choice

- Can't simply use good parameter inference summaries
- Example: suppose x_1, x_2, \dots, x_n iid $N(\mu, 1)$
 - Then sample mean good to infer μ
 - But sample variance needed for model comparison
- Various summary statistic selection methods can be generalised to model choice

ABC model choice and classification

- ABC model choice similar to classification
- We simulate data-label pairs (y_i, m_i)
- Aim is to infer label for a further point y_{obs}
- Many statistics/machine learning methods for this
- Could be used to choose ABC summary statistics (Prangle et al 2013)
- Or to replace ABC entirely (Pudlo et al 2014 advocate random forest classifiers instead)

Weighted distances

Why weight distances

- So far ABC simulations are accepted or rejected
- Discards some information about distance of accepted simulations
- Instead we can **weight** close matches higher
- We introduce a **ABC kernel** $K(x)$
- Then $K([s - s_{\text{obs}}]/h)$ maps summaries s to a weight
- h affects the scale, acting as a “bandwidth”
- Examples:
 - Uniform kernel: $K(x) = \begin{cases} 1 & \text{for } x^T x \leq 1 \\ 0 & \text{otherwise} \end{cases}$
 - Gaussian kernel: $K(x) = \exp(-x^T x)$
- So uniform kernel gives an accept/reject algorithm
- (n.b. can easily include weight terms in kernels)

ABC algorithm with kernel

Input: y_{obs} , $h \geq 0$, $S(\cdot)$, **ABC kernel** $K(x)$.

For $i = 1, 2, \dots, N$:

- 1 Sample parameter vector θ_i from prior $\pi(\theta)$
- 2 Simulate data from $\pi(y|\theta_i)$
- 3 Let $w_i = K([S(y) - s_{\text{obs}}]/h)$

Output: accepted (θ_i, w_i) pairs

Use for Monte Carlo as in importance sampling

n.b. distance $d(\cdot, \cdot)$ no longer used – $K(\cdot)$ performs similar role.

Kernels in other ABC algorithms

- Same idea can be used in all the algorithms described earlier
- Can help ABC-MCMC/ABC-SMC work well
- Alternatively can modify algorithms to **accept** with probability w_j
- Little theory on best choice of kernel
- Practice suggests it's not as important to results as summary statistics

Effect of kernel

- Assume K is a pdf
- Then ABC samples from posterior for a **misspecified model**

$$\text{summary statistics} \sim \text{model of interest} + hz$$

- where z is an independent draw from $K(\cdot)$
- See “Approximate Bayesian computation (ABC) gives exact results under the assumption of model error” - Wilkinson 2013
- Can occasionally allow exact inference if model can be expressed in this form
- Or can be used to capture effect of model misspecification

Sequential ABC analysis

Motivation

- Time series setting
 - We have data at every time point
 - If model has a helpful structure we can do inference **sequentially**
 - i.e. analyse data at $t = 1$ by ABC, then data at $t = 2, \dots$
 - Each step has low dimensional data! So low approximation error
-
- Can be done by an ABC version of **particle filtering**
 - For a review see Jasra (2014) “Approximate Bayesian computation for a class of time series models”

Challenges

- Sequential ABC is promising
- Algorithms have been developed with good theoretical properties
- But still challenging in practice
- Can be very computationally demanding
- Prone to getting “stuck” at outlying observations
- Tuning well is difficult
- Data at each time point could be complicated, requiring introduction of summaries