

To : ???
From : Jan Mooiman
Subject : Brusselator
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1 Brusselator

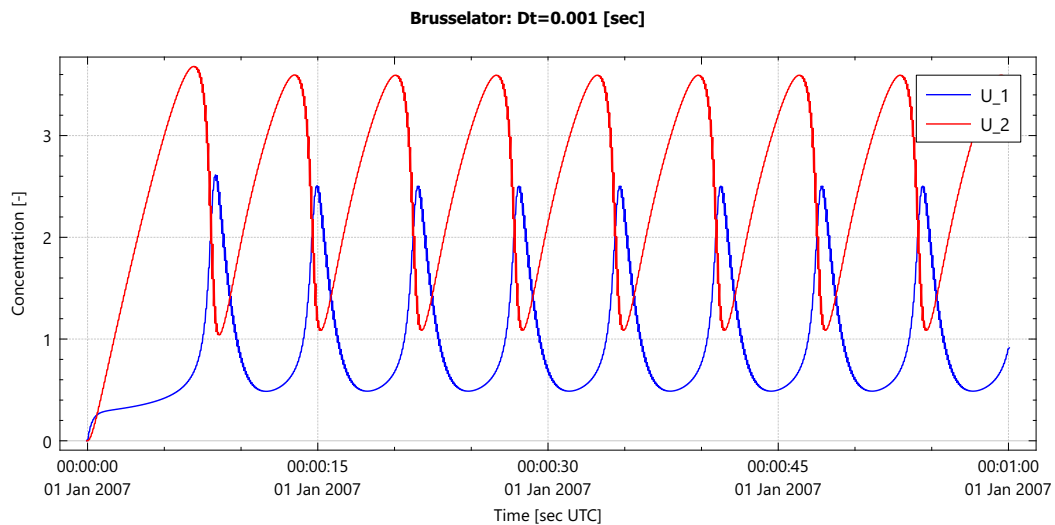
The Brusselator is taken as example to see the behaviour of the fully implicit Δ -formulation for reaction terms only. This is particularly of interest for the water quality computations with lots of processes. Example taken from [Ault and Holmgren \(2003\)](#).

The ODE system reads:

$$\frac{\partial u_1}{\partial t} = 1 - (k_2 + 1)u_1 + k_1 u_1^2 u_2, \quad (1)$$

$$\frac{\partial u_2}{\partial t} = k_2 u_1 - k_1 u_1^2 u_2 \quad (2)$$

with $k_1 = 1$ and $k_2 = 2.5$ and initial values $u_1(0) = 0$ and $u_2(0) = 0$. Some results are:



(a) *Runge-Kutta 4*: $\Delta t = 0.001$, $k_1 = 1$, $k_2 = 2.5$

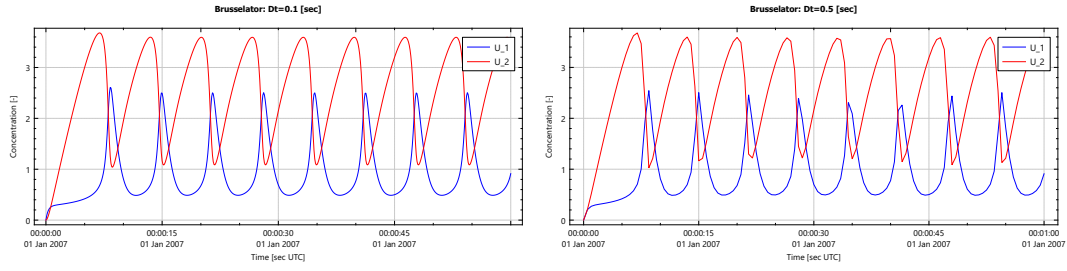
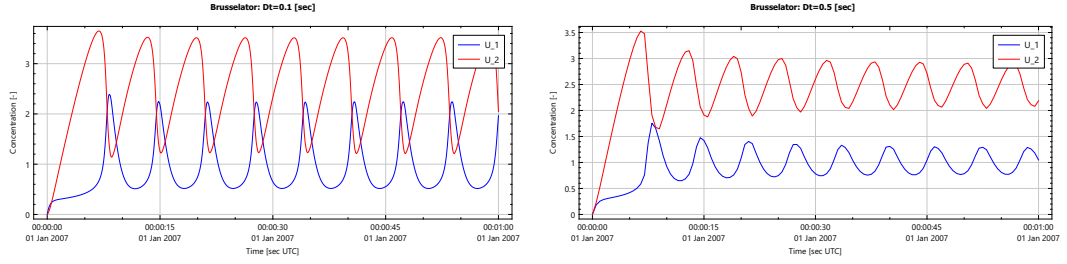
(b) Runge-Kutta 4: $\Delta t = 0.1$, $k_1 = 1$, $k_2 = 2.5$ (c) Runge-Kutta 4: $\Delta t = 0.5$, $k_1 = 1$, $k_2 = 2.5$ (d) Fully Implicit: $\Delta t = 0.1$, $k_1 = 1$, $k_2 = 2.5$ (e) Fully Implicit: $\Delta t = 0.5$, $k_1 = 1$, $k_2 = 2.5$

Figure 1: Result plots for constant value of $k_1 = 1$ and $k_2 = 2.5$, computed with a Runge-Kutta 4 and fully implicit (Δ -formulation) time integration method for different time steps $\Delta t = 0.1, 0.5$.

Extra attention needed for the Fully Implicit time integration with larger time step:

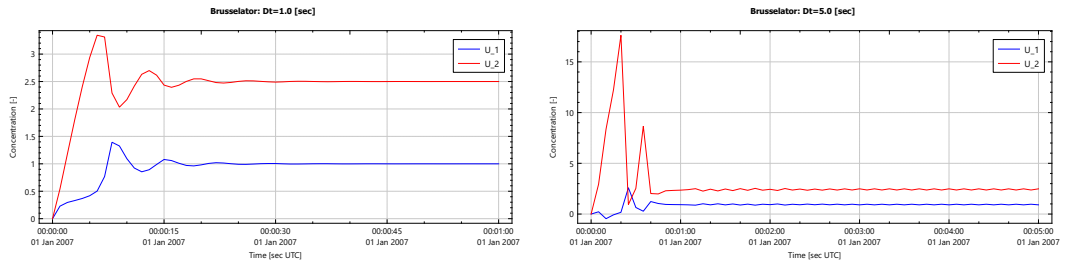
(a) Fully Implicit: $\Delta t = 1.0$, $k_1 = 1$, $k_2 = 2.5$ (b) Fully Implicit: $\Delta t = 5.0$, $k_1 = 1$, $k_2 = 2.5$

Figure 2: Result plots for constant value of $k_1 = 1$ and $k_2 = 2.5$, computed with a fully implicit (Δ -formulation) time integration method for different time steps $\Delta t = 1.0, 5.0$.

Figure 2a converge to the equilibrium state $(u_1, u_2) = (1.0, 2.5)$ and Figure 2b looks to converge to the equilibrium state $(u_1, u_2) = (1.0, 2.5)$ but is still wiggling after 5 min of simulation time (even after one day — not presented).

2 Numerical experiment

Table 1: *Stability of different time integrators for the Brusselator.*

	Time step [s]	Runge-Kutta 4	Fully Implicit Δ -formulation
1	0.1	✓	✓
2	0.2	✓	✓
3	0.5	✓	✓
4	1.0	Unstable	✓
5	2.0		✓
6	5.0		✓

References

Ault, Shaun and Erik Holmgren (2003). *Dynamics of the Brusselator*. URL:
<https://mate.unipv.it/~boffi/teaching/download/Brusselator.pdf>.