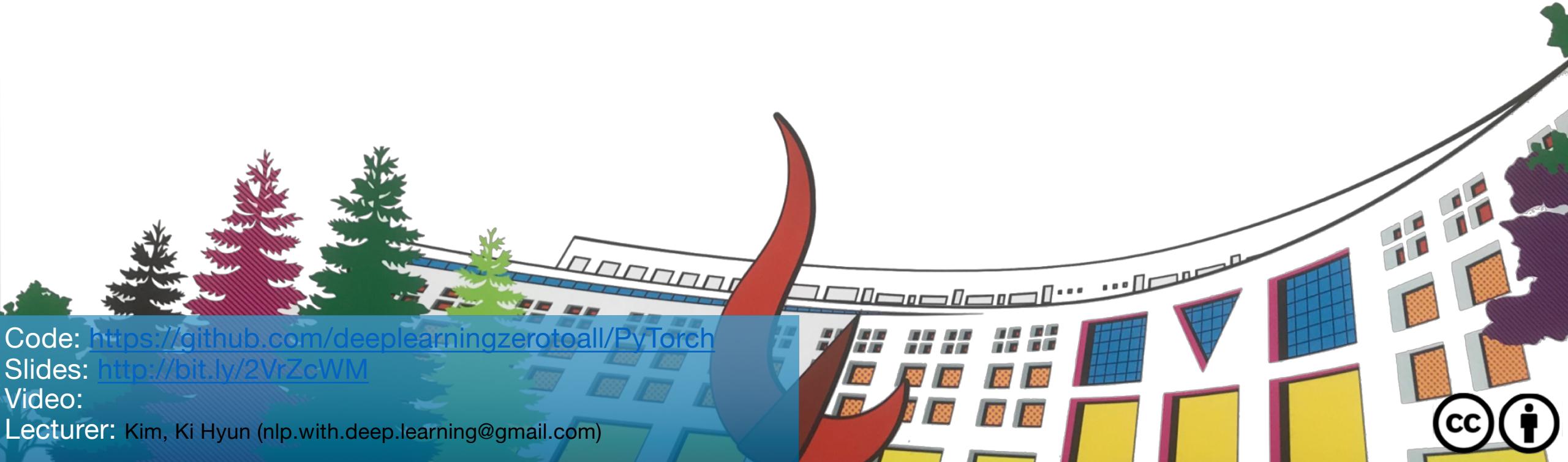


ML/DL for Everyone Season2

with 

PyTorch Basic Tensor Manipulation II



Code: <https://github.com/deeplearningzerotoall/PyTorch>

Slides: <http://bit.ly/2VrZcWM>

Video:

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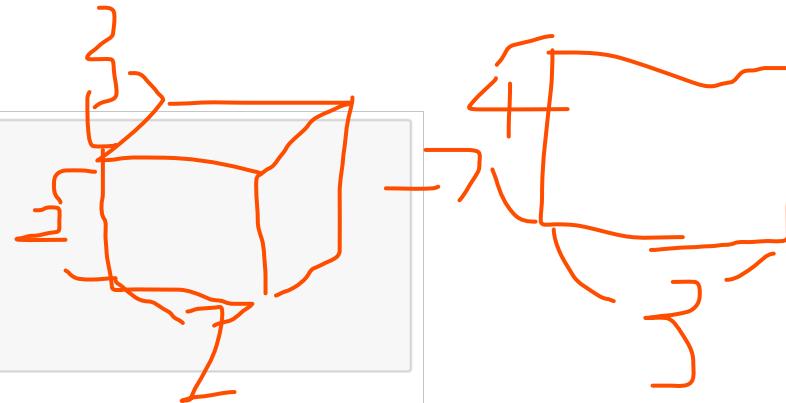


PyTorch Basic Tensor Manipulation

- Vector, Matrix and Tensor
- NumPy Review
- PyTorch Tensor Allocation
- Matrix Multiplication
- Other Basic Ops

View (Reshape)

```
t = np.array([[0, 1, 2],  
             [3, 4, 5],  
             [[6, 7, 8],  
              [9, 10, 11]]])  
ft = torch.FloatTensor(t)  
print(ft.shape)  
  
torch.Size([2, 2, 3])  
  
print(ft.view([-1, 3]))  
print(ft.view([-1, 3]).shape)  
  
tensor([[ 0.,  1.,  2.],  
        [ 3.,  4.,  5.],  
        [ 6.,  7.,  8.],  
        [ 9., 10., 11.]])  
torch.Size([4, 3])  
  
print(ft.view([-1, 1, 3]))  
print(ft.view([-1, 1, 3]).shape)  
  
tensor([[[ 0.,  1.,  2.]],  
       [[ 3.,  4.,  5.]],  
       [[ 6.,  7.,  8.]],  
       [[ 9., 10., 11.]]])  
torch.Size([4, 1, 3])
```



$$\begin{aligned} & \text{Original Shape: } [2, 2, 3] \\ & \text{New Shape: } [2 \times 2 \times 3] = (4, 3) \\ & \text{Dimensions: } 4 \times 3 \times 1 \\ & \text{Final Shape: } [4, 3] \end{aligned}$$

Squeeze

```
ft = torch.FloatTensor([[0], [1], [2]])
print(ft)
print(ft.shape)
```

```
tensor([[0.],
       [1.],
       [2.]])
torch.Size([3, 1])
```

```
print(ft.squeeze())
print(ft.squeeze().shape)
```

```
tensor([0., 1., 2.])
torch.Size([3])
```

Unsqueeze

```
ft = torch.Tensor([0, 1, 2])
print(ft.shape)
```

```
torch.Size([3])
```

```
print(ft.unsqueeze(0))
print(ft.unsqueeze(0).shape)
```

```
tensor([[0., 1., 2.]])
torch.Size([1, 3])
```

```
print(ft.view(1, -1))
print(ft.view(1, -1).shape)
```

```
tensor([[0., 1., 2.]])
torch.Size([1, 3])
```

```
print(ft.unsqueeze(1))
print(ft.unsqueeze(1).shape)
```

```
tensor([[0.],
       [1.],
       [2.]])
torch.Size([3, 1])
```

```
print(ft.unsqueeze(-1))
print(ft.unsqueeze(-1).shape)
```

```
tensor([[0.],
       [1.],
       [2.]])
torch.Size([3, 1])
```

Type Casting

```
lt = torch.LongTensor([1, 2, 3, 4])
print(lt)
```

```
tensor([1, 2, 3, 4])
```

```
print(lt.float())
```

```
tensor([1., 2., 3., 4.])
```

```
bt = torch.ByteTensor([True, False, False, True])
print(bt)
```

```
tensor([1, 0, 0, 1], dtype=torch.uint8)
```

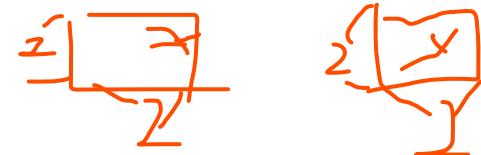
```
print(bt.long())
print(bt.float())
```

```
tensor([1, 0, 0, 1])
```

```
tensor([1., 0., 0., 1.])
```

Concatenate

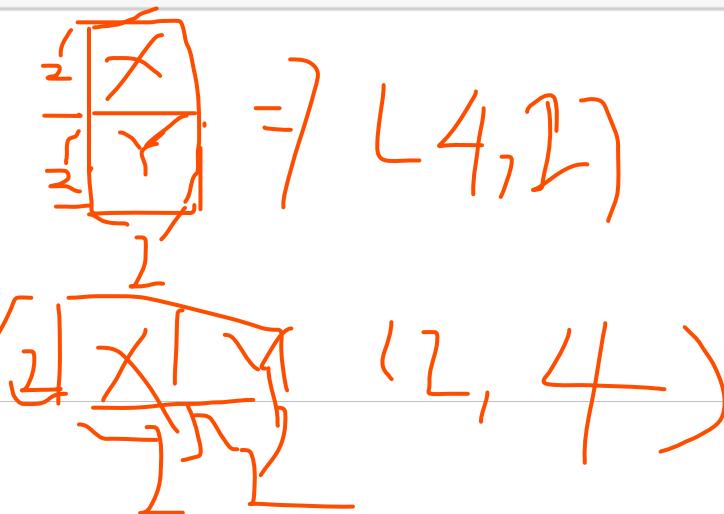
$$1 \times 1 = 1 \times 1 = (1, 1)$$



```
x = torch.FloatTensor([[1, 2], [3, 4]])  
y = torch.FloatTensor([[5, 6], [7, 8]])
```

```
print(torch.cat([x, y], dim=0))  
print(torch.cat([x, y], dim=1))
```

```
tensor([[1., 2.],  
        [3., 4.],  
        [5., 6.],  
        [7., 8.]])  
tensor([[1., 2., 5., 6.],  
        [3., 4., 7., 8.]])
```



Stacking

$X_1 = |y_1| \otimes z_1 = (z_1)$

```
x = torch.FloatTensor([1, 4])
y = torch.FloatTensor([2, 5])
z = torch.FloatTensor([3, 6])
```

```
print(torch.stack([x, y, z]))
```

```
print(torch.stack([x, y, z], dim=1))
```

```
tensor([[1., 4.],
        [2., 5.],
        [3., 6.]])
tensor([[1., 2., 3.],
        [4., 5., 6.]])
```



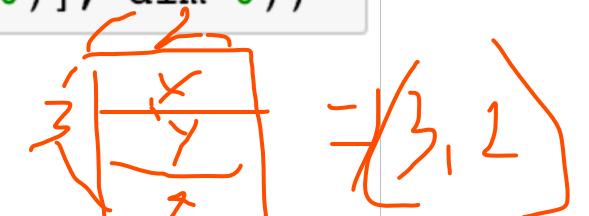
```
print(torch.cat([x.unsqueeze(0), y.unsqueeze(0), z.unsqueeze(0)], dim=0))
```

```
tensor([[1., 4.],
        [2., 5.],
        [3., 6.]])
```

(1,2)

(1,2)

(1,2)



Ones and Zeros

```
x = torch.FloatTensor([[0, 1, 2], [2, 1, 0]])  
print(x)
```

tensor([[0., 1., 2.],
 [2., 1., 0.]])

$|X| = (2 \times 3)$

```
print(torch.ones_like(x))  
print(torch.zeros_like(x))
```

tensor([[1., 1., 1.],
 [1., 1., 1.]])
tensor([[0., 0., 0.],
 [0., 0., 0.]])

In-place Operation

```
x = torch.FloatTensor([[1, 2], [3, 4]])
```

```
print(x.mul(2.))
print(x)
print(x.mul_(2.))
print(x)
```

```
tensor([[2., 4.],
       [6., 8.]])
tensor([[1., 2.],
       [3., 4.]])
tensor([[2., 4.],
       [6., 8.]])
tensor([[2., 4.],
       [6., 8.]])
```