Calculus, Differential Equations, and Analysis

Muyao Xiao

Dec. 2024

Abstract

Almost every analysis related notes will be added here.

Reference books:

• Calculus:

- [1] J. Stewart, Calculus: early transcendentals, 7th ed. Belmont, CA: Brooks/Cole, Cengage Learning, 2012.
- [1] M. D. Weir, J. Hass, and G. B. Thomas, Thomas' calculus: early transcendentals, Thirteenth edition. Boston: Pearson, 2014.
- Differential Equations:
 - [1] C. H. Edwards, D. E. Penney, and D. Calvis, Elementary differential equations with boundary value problems, 6. ed. Upper Saddle River, NJ: Pearson Prentice Hall, 2009.
- Analysis:
 - [1] S. Abbott, Understanding analysis, 2nd edition. in Undergraduate texts in mathematics. New York: Springer, 2015.
- TBD

Contents

1	First Order Differential Equations		
	1.1	Introduction	2
	1.2	Solution for $dy/dx = f(x)$	3
	1.3	Solution for $dy/dx = f(x,y)$	4
	1.4	Solution for $dy/dx = g(x)h(y)$	5
	1.5	Solution for $dy/dx + P(x)y = Q(x)$ (Linear First-Order Equations)	6
	1.6	Substitution Methods and Exact Equations	8

Chapter 1

First Order Differential Equations

1.1 Introduction

In algebra, we typically seek the unknown numbers that satisfy an equation such as $x^3+7x^2-11x+41=0$. By contrast, we're challenged to find the unknown functions y=f(x) for which an identity such as:

$$\frac{dy}{dx} = 2xy$$

Example. If C is a constant and

$$y(x) = Ce^{x^2}$$

then

$$\frac{dy}{dx} = 2x(Ce^{x^2}) = 2xy\tag{1}$$

Notice (1) satisfy the DE:

$$\frac{dy}{dx} = 2xy$$

Example (Newton's law of cooling). Let

- T: temperature of a body
- \bullet A: temperature of surrounding medium

We have:

$$\frac{dT}{dt} = -k(T - A)$$

Example (Torricelli's law). The *time rate of change* of volume V of water in a draining tank is proportional to the square root of the depth y of water in the tank:

$$\frac{dV}{dy} = -k\sqrt{y}$$

Example. For a DE:

$$\frac{dy}{dx} = y^2$$

The solution can be defined by y(x) = 1/(C-x) for $x \neq C$, because:

$$\frac{dy}{dx} = \frac{1}{(C-x)^2} = y^2$$

Definition 1.1.1 (order). The **order** of a DE is the order of the highest derivative that appears in it.

The most general form of an **nth-order** DE with independent variable x and unknown function or dependent variable y = y(x) is:

$$F(x, y, y', y'', \dots, y^{(n)}) = 0$$

Definition 1.1.2 (solution). The continuous function u = u(x) is a **solution** of the DE **on the** interval I provided that the derivatives $u', u'', \dots, u^{(n)}$ exist on I and:

$$F(x, u, u', u'', \cdots, u^{(n)}) = 0$$

for all x in I.

We say u = u(x) satisfies the DE on I.

Definition 1.1.3 (Ordinary an Partial). **Ordinary** DE means that the unknown function (dependent variable) depends on only a *single* independent variable.

If the dependent variable is a function of two or more independent variables, then partial derivatives are likely to be involved; If they are, the equation is called a **partial** DE.

Example (Termal Diffusivity). The temperature u = u(x,t) of a long thin uniform rod at the point x at time t satisfies:

$$\frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial^2 x}$$

1.2 Solution for dy/dx = f(x)

If the right side of the first order DE does not involve the dependent variable y:

$$\frac{dy}{dx} = f(x) \tag{1}$$

3

It has a solution by integrating both sides:

$$y(x) = \int f(x)dx + C \tag{2}$$

(2) is the **general solution** to (1).

When bringing up with the initial condition, say $y(x_0) = y_0$, we can solve the constant C, and that is called **particular solution**.

Example.

$$\frac{dy}{dx} = 2x + 3, \quad y(1) = 2$$

A general solution is:

$$y(x) = \int (2x+3)dx + C = x^2 + 3x + C$$

Considering the initial condition, we have C = -2, so a particular solution is:

$$y(x) = x^2 + 3x - 2$$

We can also extend this to **Second-order equations**. For

$$\frac{d^2y}{dx^2} = g(x)$$

We have

$$\frac{dy}{dx} = \int g(x)dx = G(x) + C_1$$

and

$$y(x) = \int [G(x) = C_1]dx = \int G(x)dx + C_1x + C_2$$

1.3 Solution for dy/dx = f(x,y)

This form cannot be easily expressed in terms of the ordinary elementary functions. We have to use graphical and numerical methods to construct approximate solutions.

1.3.1 Slope Fields and Graphical Solutions

Consider a function like:

$$y' = f(x, y)$$

At each point (x, y) in xy plane, we know its slope m is m = f(x, y). For a solution y = y(x), each point of it (that is (x, y(x))) must have the correct slope.

Example (y' = x - y). For y' = x - y, let's check for different points:

- (0,0)=0
- (0,1) = -1
- (0,-1)=1
- (1,0) = 1
- (-1,0)=0

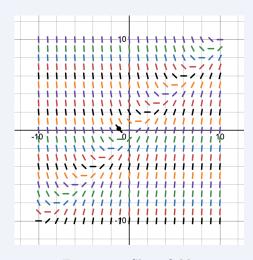


Figure 1.1: Slope fields

If we are assigned the initial condition, we can draw a curve from it.

Theorem 1.3.1 (Solution number). Suppose that both function f(x,y) and its partial derivative $D_y f(x,y)$ are continuous on some rectangle R in the xy-plane that contains the point (a,b) in its interior. The for some open interval I containing the point a, the initial value problem:

$$\frac{dy}{dx} = f(x,y), \quad y(a) = b$$

has one and only one solution that is defined on the interval I.

Example. This example will use the above theorem:

$$x\frac{dy}{dx} = 2y$$

Notice that to rewrite the formula into the form of the theorem, we have:

$$\frac{dy}{dx} = 2y/x$$

so we have f(x,y)=2y/x, thus $\frac{\partial f}{\partial y}=2/x$. Both functions are continuous if $x\neq 0$.

1.4 Solution for dy/dx = g(x)h(y)

The first-order differential equation:

$$\frac{dy}{dx} = H(x, y)$$

is called **separable** provided that H(x, y) can be written as the product of a function of x and a function of y:

$$\frac{dy}{dx} = g(x)h(x) = \frac{g(x)}{f(y)}$$

where h(y) = 1/f(y).

The solution will be like this:

$$f(y)dy = g(x)dx$$

$$f(y)\frac{dy}{dx} = g(x)$$

$$\int f(y(x))\frac{dy}{dx}dx = \int g(x)dx + C$$

$$\int f(y)dy = \int g(x)dx + C$$

Example. Solve this problem:

$$\frac{dy}{dx} = 7xy, \quad y(0) = 7$$

We can separate:

$$\frac{1}{y}dy = -6xdx$$

Integrate both sides:

$$ln|y| = -3x^2 + C$$
$$y = e^{-3x^2 + C}$$
$$y = Ae^{-3x^2}$$

Bring in the initial condition we know that A = 7, so $y(x) = 7e^{-3x^2}$.

Notice that we drop the absolute value because we know the initial condition, if the initial condition changes, we may want to change it to -y.

Example. Sometimes we can not solve y to an explicit form. Suppose we have:

$$\frac{dy}{dx} = \frac{4 - 2x}{3y^2 - 5}$$

This will be solved to:

$$y^3 - 5y = 4x - x^2 + C$$

and we can't make progress here, we call this an implicit solution.

Definition 1.4.1 (Sigular Solutions). It is common for a nonlinear first-order DE to have both a general solution involving an arbitrary constant C and one or several particular solutions that cannot be obtained by selecting a value for C. These exceptional solutions are frequently called **singular solutions**.

Example (singular solution). Find all solutions of the DE:

$$\frac{dy}{dx} = 6x(y-1)^{2/3}$$

Separation of the variables gives:

$$\int \frac{1}{3(y-1)^{2/3}} dy = \int 2x dx$$
$$(y-1)^{1/3} = x^2 + C$$
$$y(x) = 1 + (x^2 + C)^3$$
 (general solutions)

But the there's a singular solution $y(x) \equiv 1$ when separating the variables.

1.5 Solution for dy/dx + P(x)y = Q(x) (Linear First-Order Equations)

Example (Integrating Fatcor). To solve an equation like this:

$$\frac{dy}{dx} = 2xy(y > 0)$$

we multiply both sides by the factor 1/y to get

$$\frac{1}{y} \cdot \frac{dy}{dx} = 2x;$$
 that is, $D_x(lny) = D_x(x^2)$

For this reason, the function $\rho(y) = 1/y$ is called an **integrating factor**.

With the aid of appropriate integrating factor, we have a standard technique to solve the **linear first-order equation**:

$$\frac{dy}{dx} + P(x)y = Q(x)$$

on an interval on which the coefficient functions P(x) and Q(x) are continuous. We multiply both sides with integrating factor

$$\rho(x) = e^{\int P(x)dx}$$

the result is

$$e^{\int P(x)dx}\frac{dy}{dx} + P(x)e^{\int P(x)dx}y = Q(x)e^{\int P(x)dx}$$

notice that the left side is $(ye^{\int P(x)dx})'$, so we have

$$D_x[ye^{\int P(x)dx}] = Q(x)e^{\int P(x)dx}$$

finally:

$$y(x)e^{\int P(x)dx} = \int (Q(x)e^{\int P(x)dx})dx + C$$

$$y(x) = e^{-\int P(x)dx} \left[\int (Q(x)e^{\int P(x)dx})dx + C\right]$$

Example. Solve the problem:

$$\frac{dy}{dx} - y = \frac{11}{8}e^{-x/3}, \quad y(0) = -1$$

In this example, P(x) = -1, $Q(x) = \frac{11}{8}e^{-x/3}$, the integrating factor is $e^{\int (-1)dx} = e^{-1}$. We can get the general solution:

$$y(x) = -\frac{33}{32}e^{-x/3} + Ce^x$$

Bring the initial condition we can get $C = \frac{1}{32}$

About where the solution defined, we have the theorem:

Theorem 1.5.1. If the function P(x) and P(x) are continuous on the open interval I containing the point x_0 , then the initial value problem

$$\frac{dy}{dx} + P(x)y = Q(x), \quad y(x_0) = y_0$$

has a unique solution y(x) on I.

Remark. The theorem tells us that every solution is included in the general solution. Thus a linear first-order DE has no singular solutions.

Remark. The appropriate value of the constant in the general solution can be selected "automatically" by writing

$$\rho(x) = \exp(\int_{x_0}^x P(t)dt),$$

$$y(x) = \frac{1}{\rho(x)} [y_0 + \int_{x_0}^x \rho(t)Q(t)dt]$$

Example (Think about the interval!). Solve the initial value problem

$$x^2 \frac{dy}{dx} + xy = \sin x, \quad y(1) = y_0$$

The function can be transformed to

$$\frac{dy}{dx} + \frac{1}{x}y = \frac{\sin x}{x}$$

with $P(x) = \frac{1}{x}$ and $Q(x) = \frac{\sin x}{x}$, we have $\rho(x) = \exp(\int_1^x \frac{1}{t} dt) = x$, so the particular solution can be given by:

$$y(x) = \frac{1}{x} [y_0 + \int_1^x \frac{\sin t}{t} dt]$$

1.6 Substitution Methods and Exact Equations

We have done equations which are separable or linear. Now we introduce **substitution methods** which sometimes transform a given DE to the form we know how to solve.

Example. The problem is in the following:

$$\frac{dy}{dx} = f(x, y), \quad v = \alpha(x, y)$$

We can get $y = \beta(x, v)$ from $v = \alpha(x, y)$ and substitute the original formula:

$$\frac{dy}{dx} = \frac{\partial \beta}{\partial x} + \frac{\partial \beta}{\partial v} \frac{dv}{dx}$$

Then we have:

$$\frac{dy}{dx} = \frac{\partial \beta}{\partial x} + \frac{\partial \beta}{\partial v} \frac{dv}{dx} = f(x, \beta(x, v))$$

Example. Solve the equation:

$$\frac{dy}{dx} = (x+y+3)^2$$

solution. We have v = x + y + 3, that is

$$y = v - x - 3 \tag{1}$$

According to (1), we have:

$$\frac{dy}{dx} = \frac{dv}{dx} - 1\tag{2}$$

Using v to substitute the original formula we have:

$$\frac{dy}{dx} = v^2 \tag{3}$$

Based on (2) and (3) we have:

$$\frac{dv}{dx} = v^2 + 1$$

Now this is a separable equation, we have:

$$dx = \frac{dv}{v^2 + 1}$$

$$x = tan^{-1}v + C$$

$$x - C = tan^{-1}v$$

$$v = tan(x - C)$$

$$y = tan(x - C) - x - 3$$

1.6.1 Homogeneous Equations

Definition 1.6.1. A homogeneous first-order equation is one that can be written in the form:

$$\frac{dy}{dx} = F(\frac{y}{x})$$

The substitution strategy is to use $v = \frac{y}{x}$.

Example. Solve the DE:

$$2xy\frac{dy}{dx} = 4x^2 + 3y^2$$

solution. Transform the DE into:

$$2\frac{dy}{dx} = 4x/y + 3y/x$$

We use v = y/x to substitute the DE, we have:

$$2\frac{dy}{dx} = 4/v + 3v$$

Also, because v = y/x we have:

$$\frac{dy}{dx} = v + \frac{dv}{dx}x$$

So we have:

$$v + \frac{dv}{dx}x = 2/v + 3v/2$$

(omit the rest parts)

1.6.2 Bernoulli Equations

Definition 1.6.2. A first-order DE of the form:

$$\frac{dy}{dx} + P(x)y = Q(x)y^n$$

is called a Bernoulli equation.

Notice if n = 0 or n = 1 then this is a linear DE. Otherwise we can do this substitution: $v = y^{1-n}$

Example. Solve this DE:

$$x\frac{dy}{dx} + 6y = 3xy^{4/3}$$

solution. Transform the DE:

$$\frac{dy}{dx} + (6/x)y = 3y^{4/3}$$

So we have P(x) = 6/x, Q(x) = 3, $v = y^{-1/3}$ that is $y = v^{-3}$.

Substitute and we have:

$$-3v^{-4}\frac{dv}{dx} + \frac{6v^{-3}}{x} = 3v^{-4}$$

We can transform it into a linear DE:

$$\frac{dv}{dx} + (-\frac{2}{x})v = -1$$

This is a linear first-order equations, we can multiply a factor $\rho(x) = e^{\int P(x)dx} = x^{-2}$:

$$x^{-2}\frac{dv}{dx} - \frac{2}{x^3}v = -x^{-2}$$

$$(x^{-2}v), = -x^{-2}$$

$$x^{-2}v = \int -x^{-2}$$

$$x^{-2}v = x^{-1} + C$$

$$v = x + Cx^2$$

$$y = \frac{1}{(x + Cx^2)^3}$$