Linear Algebra + Principal Component Analysis

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Sumit Kumar Yadav

Department of Management Studies Indian Institute of Technology, Roorkee

Recap and Today

- k-Means/GMM for Image
- Performance Metrics
- Linear Algebra (to prepare for Principal Component Analysis)

 $\mbox{Accuracy} = \frac{\mbox{Number of correct predictions}}{\mbox{Total number of predictions}}$

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Is this enough??

Consider the scenario where 1000 people go for X-ray to detect Covid. They also undergo RT-PCR test for the same. Assuming RT-PCR gives the result with 100% accuracy, this is what was observed, what is the accuracy??

	X-ray	Covid +ve	Covid - ve
RT-PCR			
Covid +ve		50	20
Covid -ve		80	850

Consider another scenario where 1000 people go to a magician/future teller/optimistic person to detect Covid. They also undergo RT-PCR test for the same. Assuming RT-PCR gives the result with 100% accuracy, this is what was observed, what is the accuracy now??

	X-ray	Covid +ve	Covid - ve
RT-PCR			
Covid +ve		0	70
Covid -ve		0	930

Can we conclude that the magician is better than X-ray?

	X-ray	Covid +ve	Covid - ve	
RT-PCR				
Covid +ve		True Positive(TP)	False Negative (FN)	
Covid -ve		False Positive(FP)	True Negative (TN)	

$$\mathsf{Precision}(\mathsf{P}) = \tfrac{\mathsf{TP}}{\mathsf{TP} + \mathsf{FP}}$$

$$Recall(R) = \frac{TP}{TP + FN}$$

F-1 score is the harmonic mean of Precision and Recall

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$$\frac{2PR}{P+R}$$

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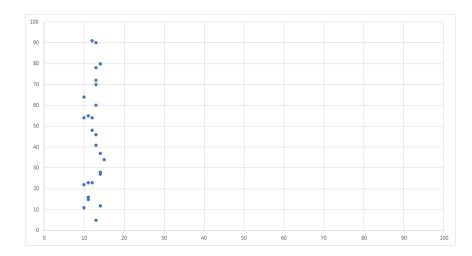
What is meant by positive and negative when we have more than 2 classes?

- To reduce the number of dimensions in the data
- To visualize the data
- To avoid over fitting

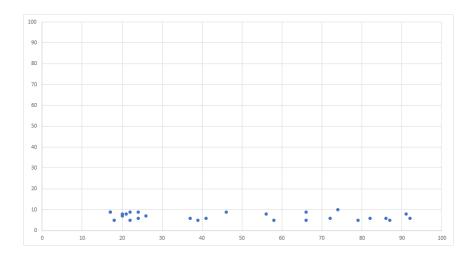
- To reduce the number of dimensions in the data
- To visualize the data
- To avoid over fitting

	Location	City	Society	Ambience	Airport
House 1	8	4	9	1	5
House 2	9	6	9	5	5
House 3	10	8	9	7	5
House 4	10	5	9	6	5
House 5	5	4	9	2	5
House 6	2	7	9	9	5
House 7	7	5	9	8	6
House 8	3	4	9	8	5
House 9	4	2	9	7	5
House 10	1	4	9	10	5

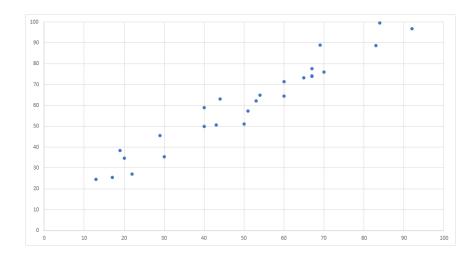
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Looks like we are trying to capture as much variance as possible while reducing the number of dimensions.

Linear Algebra Revisit

What is a vector?

- a mathematical object that encodes a length and direction
- A vector is often represented as a 1-dimensional array of numbers, referred to as components and is displayed either in column form or row form
- Represented geometrically, vectors typically represent coordinates within a n-dimensional space

Vectors in R^n /Concept of Vector Space

- Vector Space Closed under addition and multiplication
- Vectors on line y = 2 * x + 1 form a vector space??
- Addition/Subtraction (Graphical Representation)
- Multiplication by a scalar
- Dot Product (Inner Product)
- Length/Magnitude
- Angle between two vectors $\cos \theta = \frac{\vec{x}.\vec{y}}{||\vec{x}||.||\vec{y}||}$
- Dot product of perpendicular vectors = ??

Linearly Independent and Dependent Vectors

concept of zero vector

Consider m vectors in \mathbb{R}^n , If $\alpha_1 \vec{v_1} + \alpha_2 \vec{v_2} + \cdots + \alpha_n \vec{v_n}$ implies $\alpha_1 = \alpha_2 = \cdots = \alpha_m = \vec{0}$, then the vectors are said to be linearly independent.

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PCA

Matrices

In mathematics, a matrix (plural matrices) is a rectangular array or table of numbers, symbols, or expressions, arranged in rows and columns, which is used to represent a mathematical object or a property of such an object. - Wikipedia

- Matrix Size
- Representing any element of a matrix
- (1,n) and (m,1) matrices
- Square Matrix

Operations on Matrices

- Addition/Subtraction
- Multiplication of Matrix by a scalar
- Transpose of a Matrix
- Multiplication of two Matrices

Matrix as Linear Transformation

Types of Matrices

- Diagonal
- Identity
- Upper Triangular
- Symmetric
- Singular
- Mirror Matrix

Matrices contd.

- Inverse of a Matrix
- Trace of a Matrix
- Relationship of Eigenvalues with trace and Determinant
- Symmetric Matrix
- Orthogonal Matrix

Eigenvalues and Eigenvectors

Let M be a $n\times n$ matrix. A non-zero vector \vec{X} is said to be an eigenvector of M corresponding to eigenvalue λ if

Spectral Decomposition

A n*n matrix can be written in terms of its eigenvalues and eigenvectors as follows -

$$M = \lambda_1 \vec{v_1} \vec{v_1}^T + \lambda_2 \vec{v_2} \vec{v_2}^T + \dots + \lambda_n \vec{v_n} \vec{v_n}^T$$

Positive Semi-definite Matrix

又 (1×1)

$$\vec{x} = \begin{bmatrix} x_1 \\ y_2 \end{bmatrix}$$

All the eigenvalues are greater than zero.

$$\begin{bmatrix} x_{1} \\ y_{1} \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{1} \end{bmatrix} \\
= \begin{bmatrix} 2 x_{1} + 3x_{1} \\ x_{1} \end{bmatrix} = \begin{bmatrix} 2 x_{1}^{1} + 3x_{1}x_{2} + 3x_{1}^{2} \\ x_{1} + 2x_{1} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{1} \end{bmatrix} = \begin{bmatrix} 2 x_{1}^{1} + x_{1}^{2} + (x_{1} + x_{2})^{2} \\ x_{1} + 2x_{1} \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{1} \end{bmatrix} = \begin{bmatrix} x_{1}^{1} + x_{1}^{2} + (x_{1} + x_{2})^{2} \\ x_{1} + 2x_{1} \end{bmatrix}$$

PCA

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PCA - Objectives

We have a Data Matrix(D), whose dimension is n * f.

$$\begin{bmatrix} d_{11} & d_{12} & \dots & d_{1f} \\ d_{21} & d_{22} & \dots & d_{2f} \\ \vdots & \vdots & \dots & \vdots \\ d_{(n-1)1} & d_{(n-1)2} & \dots & d_{(n-1)f} \\ d_{n1} & d_{n2} & \dots & d_{nf} \end{bmatrix}$$

We want to reduce the number of features to f_s .

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```

We want to reduce the number of features to f_s .

Let us solve a simpler problem first. Let us say we want to reduce the number of dimensions/features to just 1. Which is the best way to go about it?

PCA Objective

We are looking for a unit vector $\vec{v} = (v_1, v_2, ..., v_f)$ such that the variance of $D\vec{v}$ is as large as possible.

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Variance($D\vec{v}$) can be written as $\vec{v}^T \Sigma \vec{v}$, where Σ is the variance covariance matrix of D. (Try to prove this or atleast verify this)

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Variance $(D\vec{v})$ can be written as $\vec{v}^T \Sigma \vec{v}$, where Σ is the variance covariance matrix of D. (Try to prove this or atleast verify this)

$$\Sigma = \begin{bmatrix} \sigma_1^2 & \sigma_{12} & \dots & \sigma_{1f} \\ \sigma_{21} & \sigma_{22} & \dots & \sigma_{2f} \\ \vdots & \vdots & \dots & \vdots \\ \sigma_{(f-1)1} & \sigma_{(f-1)2} & \dots & \sigma_{(f-1)f} \\ \sigma_{1f} & \sigma_{f2} & \dots & \sigma_{f}^2 \end{bmatrix}$$

Maximize -
$$\vec{v}^T \Sigma \vec{v}$$

such that
$$||\vec{v}|| = 1$$

 Σ can be shown to be positive semi-definite. Thus, all the eigenvalues are greater than zero, and all eigenvectors are orthogonal.

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$$\Sigma = \lambda_1 \vec{v_1} \vec{v_1}^T + \lambda_2 \vec{v_2} \vec{v_2}^T + \dots + \lambda_0 \vec{v_p} \vec{v_p}^T$$

$$\lambda_1 \geq \lambda_2 \geq \geq \lambda_{f}$$

$$\begin{aligned} & \overrightarrow{V_i} \quad \overrightarrow{V_i} \quad \overrightarrow{V_i} \quad | = 1 \\ & \left(\overrightarrow{A_i V_i} + \overrightarrow{A_i V_i} \overrightarrow{V_i} + \overrightarrow{A_i} \overrightarrow{V_i} \overrightarrow{V_i} \right) \end{aligned}$$

$$\text{Maximize} \quad \overrightarrow{V^T} \left(\lambda_1 \overrightarrow{V_i} \overrightarrow{V_i}^T + \lambda_2 \overrightarrow{V_2} \overrightarrow{V_2}^T + \dots + \lambda_F \overrightarrow{V_F} \overrightarrow{V_F}^T \right) \overrightarrow{V}$$

$$\text{such that } ||\overrightarrow{V}|| = 1 \qquad \qquad \overrightarrow{A_i} + \overrightarrow{A_i} + \dots + \overrightarrow{A_F} \overrightarrow{V_F} = 1$$

$$\frac{1}{(1,2,3)} = 1 \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + 2 \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} + 3 \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$



$$\lambda_{1} \vec{v}_{1} \vec{v}_{1} \vec{v}_{1} \vec{v}_{1} \vec{v}_{2} \vec{v}_{2} \vec{v}_{2} \vec{v}_{1} \vec{v}_{2} \vec{v}$$

All $\vec{v_i}'s$ are unit vectors and orthogonal to each other, so the best choice for \vec{v} is ??

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We can now try to maximize the sum of the variance terms in the 2 projected directions.

So, it looks like that the most logical thing to do is to pick up the eigenvector corresponding to the second largest eigenvector. This is what we do in PCA.

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Reconstructing the data

One could start with the objective that we want to minimize the reconstruction error, and we would get the same result as what we have described above.

Thank you for your attention