# /lorayo Ogunsina

+1 (814) 915 1009 | morayo.ogunsina@gmail.com | github.com/moraskool

Computer Scientist seeking full-time opportunities in Scientific Research and Development

# **Experience**

#### CalState LA ECST, Graduate Teaching Associate & Research Assistant | Los Angeles

August 2022 - May 2023

- Instructed students in **Java** and **Python** programming. Offered individual and group tutoring to students.
- Evaluated students' assignments, proctored tests, and supplemented course materials.

### Microsoft - Azure Mobility Group, Software Engineer Intern | Redmond

June 2022 - August 2022

- Engineered software framework via **WSL** to support **k3s** for production workloads on IoT and Edge platforms.
- Utilized C++ to create wrapper interface for a C client library for kubernetes, integrated into framework.
- Incorporated unit, and integrated testing frameworks with VALGRIND and BOOST to validate infrastructure.

#### **Microsoft Research - Sound and Acoustics Grp,** Research Software Engineer Intern | Redmond

June 2019 - Sept 2019

- Integrated API-pipelined Deep Learning model for real-time audio event detection and identification feature into existing software modules.
- · Collaborated with internal teams to fast-track product feature development; Presented research findings and documentation for future work.

#### **Penn State Behrend - Sam and Irene Black School of Business,** Software Engineer | Erie

June 2018 - May 2019

- Designed and developed a full-functioning app for donating and receiving food items using Android Studio.
- Utilized authentication, database design, and location features libraries, including Firebase and Google Places API.
- Adapted UI/UX design patterns to enhance visual appeal; maintained and tracked project codebase with Git.

#### **Chegg**, *STEM Tutor* | Remote

Aug 2016 - May 2018

• Tutored students in Android Development, Logic Design, Algorithms, HCI, Linear Algebra, Number Theory, Vector Math, Basic Chemistry, African History, and Economics. Received **80% positive** ratings from students.

#### **Education**

3.51/4.0 MS in Computer Science, California State University   Los Angeles, USA	2022-23
3.10/4.0 MS in Computer Science, University of Southern California   Los Angeles, USA (transferred out with credits)	2020-21
3,23/4,0 BS in Computer Engineering, Pennsylvania State University   Erie, USA	2015-19

Achievements: 2nd Place, SigmaXi'19 Oral Pres. (BSc. Research and Capstone) | Finalist @ SWE Local'18 Tampa Abstract submissions. **Presentations:** 2 research presentations - MSR Redmond, SigmaXi Behrend.

Relevant Courses / Topics: Adv. Linear Algebra | Path-Planning | RL | ML | Perception | PIDs | ES-EKF | Digital Image Processing

#### Skills

Programming	Python, C/C++, Java, CUDA, Matlab, Git, CMake, LaTeX, MIPS, VHDL, JavaScript, Node.js
Robotics	ROS 1/2, V-Rep, Gazebo, Arduino, Raspberry Pi B3+, Sensor Interfacing, Motion Planning
Software	Linux, Tensorflow, Docker, OpenCV, ImageJ, Solidworks, Kali-Linux, Ubuntu, UE4, Unity3D, Android Studio, Vivado
Certifications	Mathematics for ML, Imperial College – (2020)   Robotics, UPenn – (2021)   Self-Driving Cars, University of Toronto – (2023)
	Reinforcement Learning, University of Alberta – (Ongoing)   CPR + First Aid – (2024)

# Projects\_

# **Operating Systems and IPC**

May 2023

CS 5440 - Adv. Topics in Operating Systems

 Gained proficiency in inter-process communication concepts, including shared memory, pipes, message queues, signals, multithreading, and multiprocessor operations.Implemented IPCs using C++, run on Linux OS via VMWare and PUTTY tools.

#### **Vehicular Kinodynamics**

May 2023

Introduction To Self-Driving Cars

 Implemented longitudinal and lateral controls using classic methods such PIDs, feedforward, and Stanley controls to accurately track an autonomous vehicle in a predefined path with a given speed profile in **CARLA**.

#### **Full Vehicle State Estimator**

July 2023

State Estimation and Localization for Self-Driving Cars

• Implemented **ES-EKF**-solver to compute estimated trajectory of a vehicle given sensor data from LIDAR, IMU and GNSS.

#### **Drivable Space and Lane Estimator**

August 2023

Visual Perception For Self-Driving Cars

- Applied stereo depth equations and OpenCV library functions to compute vision tasks like extrinsic camera calibration and depth map to estimate collision/obstacle distance in a driving scenario.
- Implemented drivable space, lane estimation, and obstacle distance from semantic segmentation neural network output.

**Campus Wayfinder** 

December 2022

CS 5337-Advanced Software Engineering

• Utilized Unity3D engine and AR plugin to implement low-resource **indoor navigation** stage for wayfinding Android app.

CS 5781-Computer Networks & Security

- Attained proficiency in packet tracing, network intrusion and vulnerability testing, firewall, and VPN configuration.
- Achieved Platinum level in National Cyber League 2022.

#### **Image Processing + Computer Vision**

April 2021

EE 569 - Digital Image Processing (Course Labs)

- Implemented various image processing algorithms including demosaicing, edge detection, histogram manipulation, half-toning, denoising, geometric modification, texture analysis, and segmentation.
- Developed CNN architecture, derived from LeNet-5, trained and tested on MNIST, Fashion-MNIST and CIFAR-10 dataset with satisfactory results.
- Successfully implemented green learning architectures FeedForward CNN, PixelHop and PixelHop++, with impressive training
  and testing results on MNIST and Fashion-MNIST.

#### Aerial Kinodynamics (UAVs)

May 2020

Robotics: Computational Motion Planning

- Successfully implemented a linear controller and motion planning model for a 3D quadrotor, achieving agile manoeuvres and autonomous operations.
- Attained familiarity with kinodynamic modelling of 1, 2, and 3-D quad controls, including path planning algorithms Dijkstra, A\*.

#### Path Planning + Little Go + PixelHop using Fashion MNIST

Dec 2020

CSCI 561 - Fundamentals of Artificial Intelligence

- Implemented and observed the behaviour of traversal algorithms BFS, DFS, UCS, A\* on a large grided dataset.
- Integrated **RL** strategies for board game play (Little Go); Achieved 100% wins against random, smart, and q-learning opponent agents and over 80% wins against aggressive agents.
- Implemented a classic neural network that classifies the handwritten dataset (MNIST).

## **Emotion Detection and IoT Applications (Senior Design Research Capstone)**

April 2019

Penn State Behrend Wireless & Computer Vision Group

- Employed classical ml algorithms, including **SVM**, in tandem with **image processing** techniques for facial expression recognition (*FER*) using **MATLAB**'s Neural Net Toolbox.
- Configured single-board computer, for **FER** compute including live image acquisition, feature extraction, and localization.
- Integrated deep learning model for emotion prediction into FER compute, replacing classical ml; achieved over 80% success rate.

#### **Amazon Echo Dot Purchase Analytics**

April 2019

MIS 345 - Data Analytics (Course Project)

- Conducted analytics using SPSS, StatTools, R, Excel, including sentiment analysis on customer reviews of the Amazon Echo Dot.
- Generated insight into customer behaviour and trends; positive reviews on the charcoal echo dot tend to drive more purchases.

#### **Embedded Systems C, Microcontrollers**

December 2018

CMPEN 352 - Embedded Systems Design (Course Project)

• Implemented multiple C programs to develop software interfacing with sensors for embedded systems and microcontrollers.

### **Electronic Circuitry Lab**

December 2018

EE 210 - Circuits and Devices

Gained proficiency in using PSpice for OpAmps circuit analysis including frequency response of single-stage amplifiers.

#### **Logic Design for Digital Sound Analyzer - FPGAs**

December 2017

CMPEN 371 - Advanced Digital Logic Design II (Course Project)

- Collaborated in a 2-person team to design and implement digital logic for a unique audio-visual system using VHDL, on the Digilent Nexys 4 DDR FPGA board.
- Implemented module to convert sampled audio signals using FFT modules to simple image representations, displayed on a VGA screen.
- Developed advanced skills in digital logic design and testing, including the design and implementation of standard digital circuits like
   4:1 Multiplexers, and shift registers, as well as modelling complex logic systems using state diagrams and register block diagrams.

Simon Says in MIPS

December 2015

CMPEN 351 - Microprocessors

• Developed a fully functional Simon Says game in **MIPS** Assembly language. Created engaging graphics and gameplay using I/O, arithmetic operations, and program flow components.