

CS 6375 Support Vector Machines

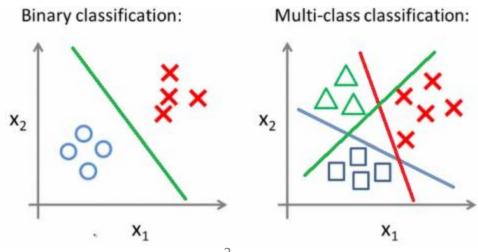
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Recap: Classification



Classification vs Regression

- Input: pairs of points $(x^{(1)}, y^{(1)}), \dots, (x^{(M)}, y^{(M)})$ with $x^{(m)} \in \mathbb{R}^n$
- $y^{(m)} \in [0, k-1]$
- If k = 2, we get Binary classification



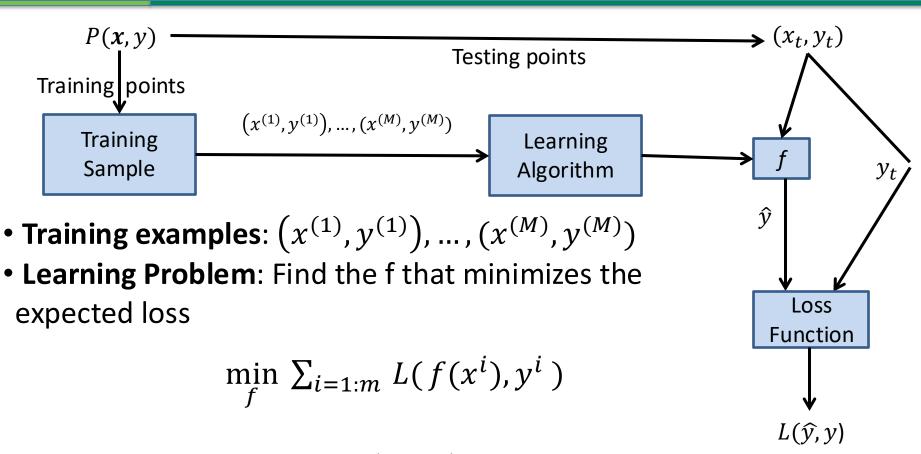
Recap: Hypothesis Space



- Hypothesis space: set of allowable functions $f: X \to Y$
- Goal: find the "best" element of the hypothesis space
 - How do we measure the quality of f?

Recap: Supervised Learning Workflow



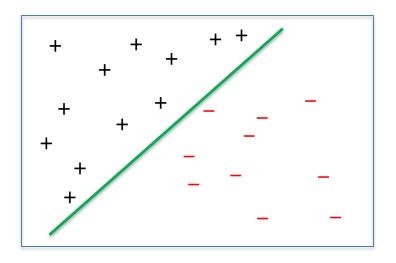


- •**Testing:** Given a new point (x_t, y_t) drawn from P, the classifier is given x and predicts $\hat{y}_t = f(x_t)$
- Evaluation: Measure the error $Err(\hat{y}_t, y_t)$ often same as L

Recap: Binary Classification



- Input $(x^{(1)}, y^{(1)}), \dots, (x^{(M)}, y^{(M)})$ with $x^{(m)} \in \mathbb{R}^n$ and $y^{(m)} \in \{-1, +1\}$
- We can think of the observations as points in \mathbb{R}^n with an associated sign (either +/- corresponding to 0/1)
- An example with n=2



that the observations are linearly separable

0/1 Loss Vs Perceptron Loss

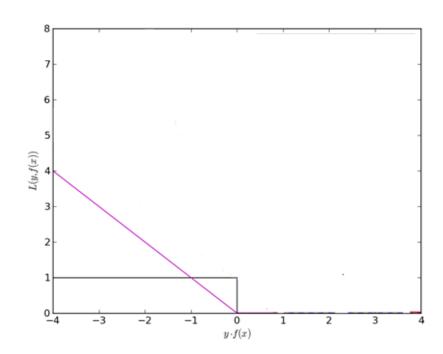


Zero/One Loss which counts the number of mis-classifications:

zero/one loss =
$$\frac{1}{2} \sum_{m} |y^{(m)} - sign(w^{T} x^{(m)} + b)|$$

Perceptron Loss:

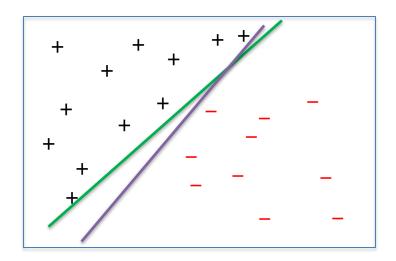
$$perceptron\ loss = \sum_{m} \max\{0, -y^{(m)}(w^{T}x^{(m)} + b)\}$$



Perceptron Drawbacks

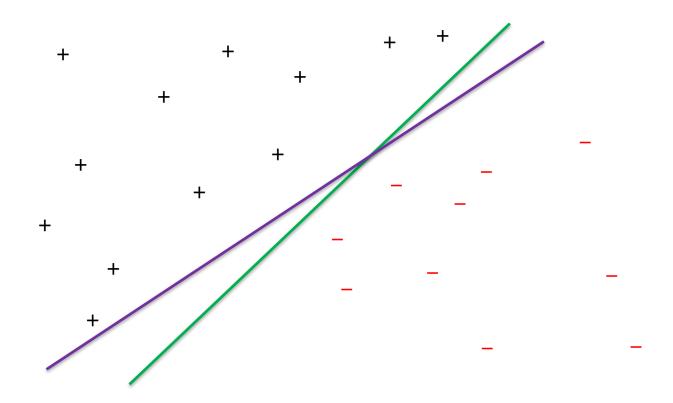


- No convergence guarantees if the observations are not linearly separable
- Can overfit
 - There can be a number of perfect classifiers, but the perceptron algorithm doesn't have any mechanism for choosing between them



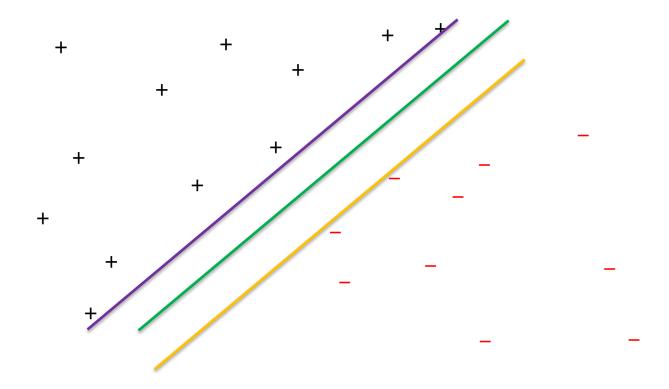


How can we decide between perfect classifiers?



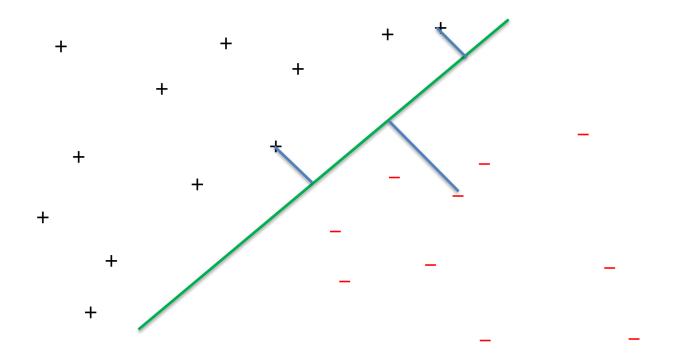


How can we decide between perfect classifiers?



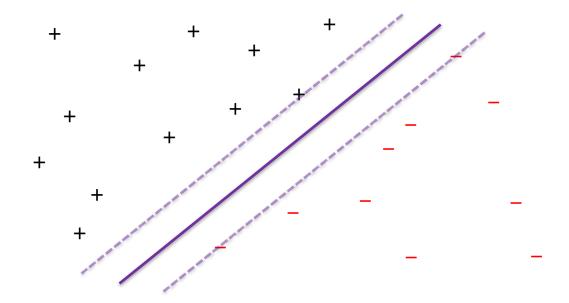


 Define the margin to be the distance of the closest data point to the classifier



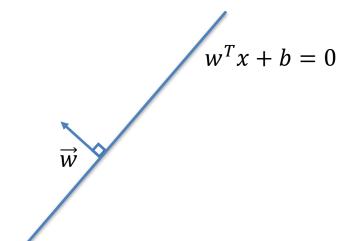


Support vector machines (SVMs)



- Choose the classifier with the largest margin
 - Has good practical and theoretical performance





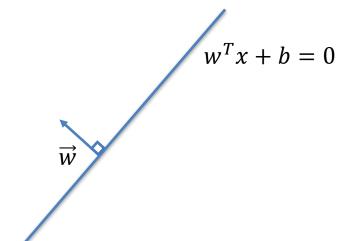
• In n dimensions, a hyperplane is a solution to the equation

$$w^T x + b = 0$$

with $w \in \mathbb{R}^n$, $b \in \mathbb{R}$

 The vector w is sometimes called the normal vector of the hyperplane





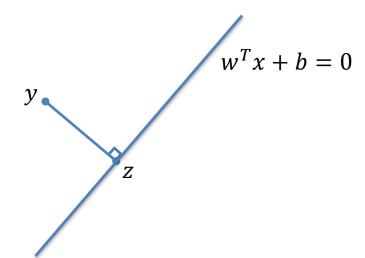
• In n dimensions, a hyperplane is a solution to the equation

$$w^T x + b = 0$$

Note that this equation is scale invariant for any scalar c

$$c \cdot (w^T x + b) = 0$$



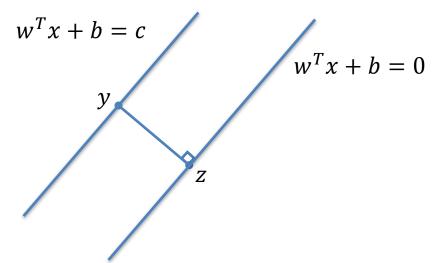


- The distance between a point y and a hyperplane $w^T + b = 0$ is the length of the segment perpendicular to the line to the point y
- The vector from y to z is given by

$$y - z = ||y - z|| \frac{w}{||w||}$$

Scale Invariance





- By scale invariance, we can assume that c=1
- The maximum margin is always attained by choosing $w^Tx + b = 0$ so that it is equidistant from the closest data point classified as +1 and the closest data point classified as -1

Scale Invariance



$$w^{T}x + b = c \qquad w^{T}x + b = 0 \qquad w^{T}x + b = -c$$

We want to maximize the margin subject to the constraints that

$$y^{(i)}\big(w^Tx^{(i)}+b\big) \ge 1$$

But how do we compute the size of the margin?



$$w^{T}x + b = 1$$

$$y$$

$$z$$

$$w^{T}x + b = 0$$

$$w^{T}x + b = -1$$

Putting it all together

$$y - z = ||y - z|| \frac{w}{||w||}$$

and

$$w^T y + b = 1$$
$$w^T z + b = 0$$

$$w^{T}(y-z) = 1$$

and
 $w^{T}(y-z) = ||y-z|| ||w||$
which gives
 $||y-z|| = 1/||w||$



This analysis yields the following optimization problem

$$\max_{w,b} \frac{1}{\|w\|}$$

such that

$$y^{(i)}(w^Tx^{(i)}+b) \ge 1$$
, for all i

Or, equivalently,

$$\min_{w,b} ||w||^2$$

such that

$$y^{(i)}(w^Tx^{(i)}+b) \ge 1$$
, for all i



$$\min_{w,b} ||w||^2$$

such that

$$y^{(i)}(w^Tx^{(i)}+b) \ge 1$$
, for all i

- This is a standard quadratic programming problem
 - Falls into the class of convex optimization problems
 - Can be solved with many specialized optimization tools (e.g., quadprog() in MATLAB)



$$w^{T}x + b = 1 \qquad w^{T}x + b = 0 \qquad w^{T}x + b = -1$$

- Where does the name come from?
 - The set of all data points such that $y^{(i)}(w^Tx^{(i)}+b)=1$ are called support vectors
 - The SVM classifier is completely determined by the support vectors (you could delete the rest of the data and get the same answer)



• What if the data isn't linearly separable?

• What if we want to do more than just binary classification (i.e., if $y \in \{1,2,3\}$)?

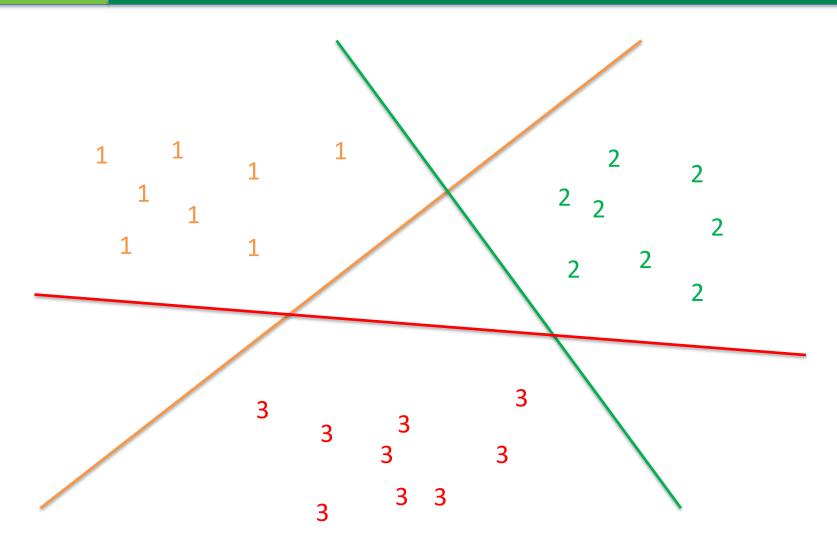


- What if the data isn't linearly separable?
 - Use feature vectors
 - Relax the constraints (coming soon)
- What if we want to do more than just binary classification (i.e., if $y \in \{1,2,3\}$)?

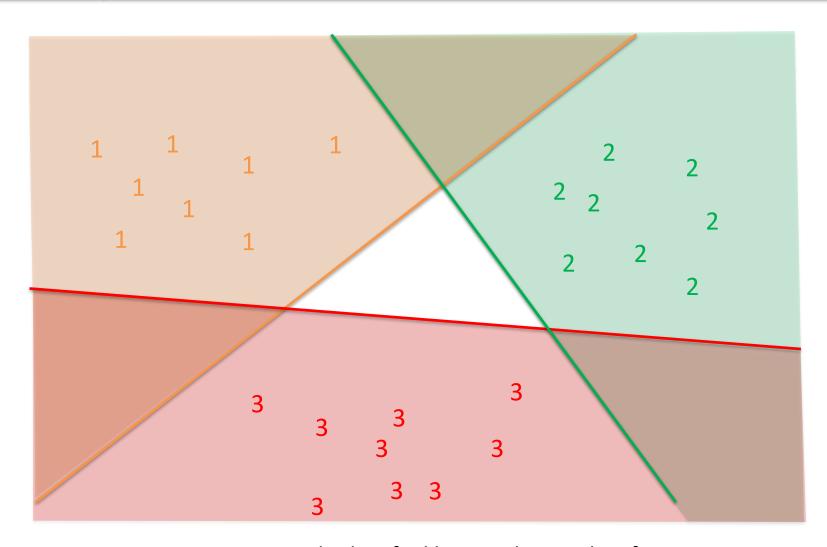
Multiclass Classification











Regions correctly classified by exactly one classifier

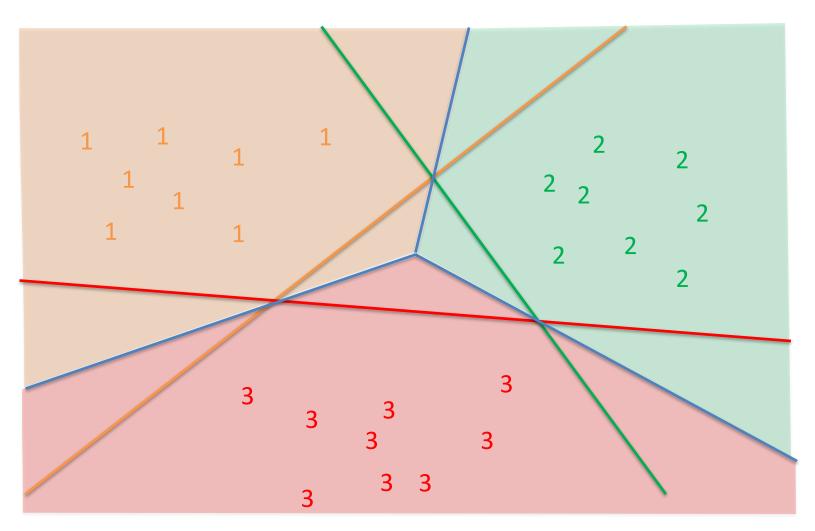


- Compute a classifier for each label versus the remaining labels (i.e., and SVM with the selected label as plus and the remaining labels changed to minuses)
- Let $f^k(x) = w^{(k)^T}x + b^{(k)}$ be the classifier for the k^{th} label
- For a new datapoint x, classify it as

$$k' \in \operatorname{argmax}_k f^k(x)$$

- Drawbacks:
 - If there are L possible labels, requires learning L classifiers over the entire data set





Regions in which points are classified by highest value of $w^Tx + b$

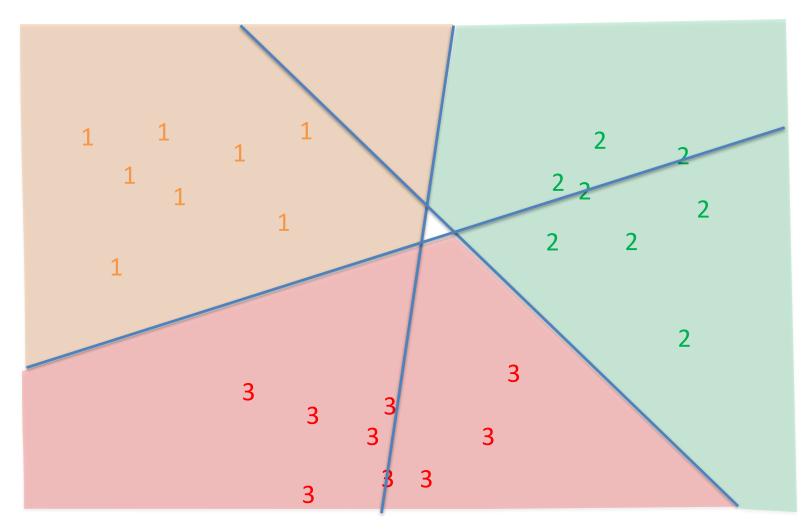
One-Versus-One SVMs



- Alternative strategy is to construct a classifier for all possible pairs of labels
- Given a new data point, can classify it by majority vote (i.e., find the most common label among all of the possible classifiers)
- If there are L labels, requires computing $\binom{L}{2}$ different classifiers each of which uses only a fraction of the data
- Drawbacks: Can overfit if some pairs of labels do not have a significant amount of data (plus it can be computationally expensive)

One-Versus-One SVMs





Regions determined by majority vote over the classifiers