



SVMs with Slack (Not Linearly Separable)

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- Allow misclassification
 - Penalize misclassification linearly (just like in the perceptron algorithm)
 - Again, easier to work with than counting misclassifications
 - Objective stays convex
- Will let us handle data that isn't linearly separable!
- Idea: Take the constraints into the main objective
 - The objective function then becomes exactly like what we have seen in Perceptron/Linear Regression

$$\min_{w,b,\xi} \left[\frac{1}{2} \|w\|^2 + c \sum_i \xi_i \right]$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

With Linear Sep:

$$y_i (w^T x^{(i)} + b) \geq 1$$

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

Potentially allows some points to be misclassified/inside the margin

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

Constant c determines
degree to which slack is
penalized

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- How does this objective change with c ?

such that

$$\min_{w,b,\xi} \underbrace{\frac{1}{2} \|w\|^2}_{\text{Margin}} + c \underbrace{\sum_i \xi_i}_{\text{Train Error}}$$
$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$
$$\xi_i \geq 0, \text{ for all } i$$

- How does this objective change with c ?
 - As $c \rightarrow \infty$, requires a perfect classifier
 - As $c \rightarrow 0$, allows arbitrary classifiers (i.e., ignores the data)

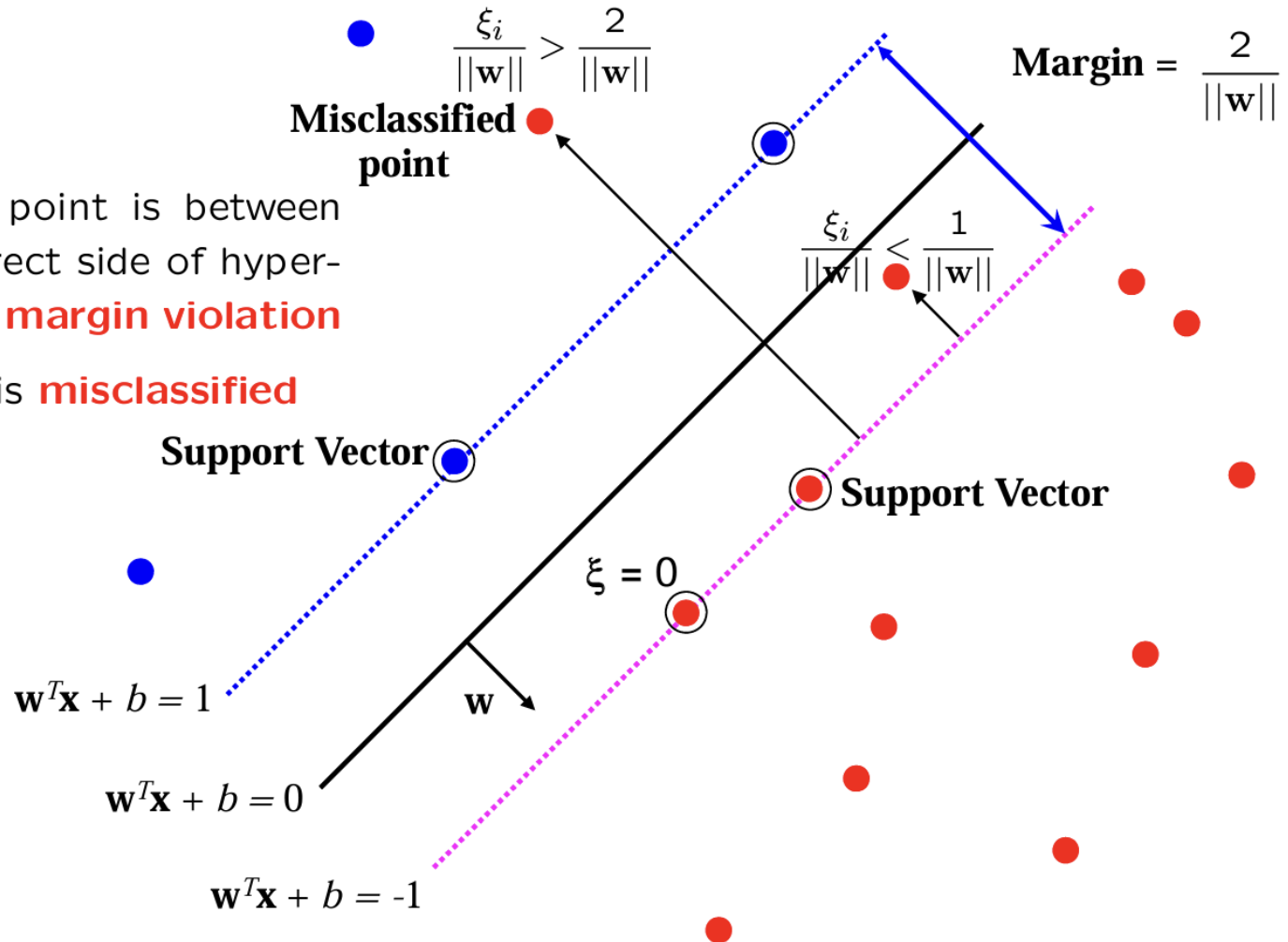
SVMs with Slack: Illustration



$$\xi_i \geq 0$$

for $0 < \xi \leq 1$ point is between margin and correct side of hyper-plane. This is a **margin violation**

for $\xi > 1$ point is **misclassified**



$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- How should we pick c ?

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- How should we pick c ?
 - Divide the data into three pieces training, testing, and **validation**
 - Use the validation set to tune the value of the **hyperparameter c**

Select Hyperparameters on Val Set

Training (Tr)	Test (Te)	Val (V)
70%	15%	15%

Model: (w, b)

Hyper-params: c

Range of c : $c \in [10^{-5}, 10^{-4}, 10^{-3}, \dots, 10^4, 10^5]$

for $c \in C$:

$w_c, b_c = \text{Train}(\text{Tr}, c)$

$\text{Test}(V, (w_c, b_c))$

$\text{Acc}_c =$

$c^* = \max_c \text{Acc}_c$

Final model = (w_{c^*}, b_{c^*})

Get test accuracy
on Test set.

↳ Generalization of
model at Deployment.

- General learning strategy
 - Build a classifier using the training data
 - Select hyperparameters using validation data
 - Evaluate the chosen model with the selected hyperparameters on the test data → what we expect the model to perform at deployment.

How can we tell if we overfit the training data?

validation data

- Gather Data + Labels
- Select feature vectors
- Randomly split into three groups
 - Training set
 - Validation set
 - Test set
- Experimentation cycle
 - Select a “good” hypothesis from the hypothesis space
 - Tune hyper-parameters using validation set
 - Compute accuracy on test set (fraction of correctly classified instances)

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- What is the optimal value of ξ for fixed w and b ?

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- What is the optimal value of ξ for fixed w and b ?
 - If $y_i(w^T x^{(i)} + b) \geq 1$, then $\xi_i = 0$
 - If $y_i(w^T x^{(i)} + b) < 1$, then $\xi_i = 1 - y_i(w^T x^{(i)} + b)$

$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + c \sum_i \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

- We can formulate this slightly differently
 - $\xi_i = \max\{0, 1 - y_i(w^T x^{(i)} + b)\}$
 - Does this look familiar?
 - Hinge loss provides an upper bound on Hamming loss

0/1 loss

Hinge Loss Formulation



- Obtain a new objective by substituting in for ξ

$$\min_{w,b} \underbrace{\frac{1}{2} \|w\|^2}_{\text{generalization}} + c \sum_i \underbrace{\max\{0, 1 - y_i(w^T x^{(i)} + b)\}}_{\text{train error}}$$

Can minimize with gradient descent!

Perceptron: $\min_{w,b} \sum_i \max(0, -y_i(w^T x^{(i)} + b))$

Hinge Loss Formulation



- Obtain a new objective by substituting in for ξ

$$\min_{w,b} \underbrace{\frac{1}{2} \|w\|^2}_{\text{Penalty to prevent overfitting}} + c \underbrace{\sum_i \max\{0, 1 - y_i(w^T x^{(i)} + b)\}}_{\text{Hinge loss (Minimizing loss on Train Set)}}$$

Penalty to prevent
overfitting

Hinge loss
(Minimizing loss on Train Set)

- Until now, we have seen the following optimization problems:

$$\min_{w,b} \sum_i L(f(x^{(i)}, w, b), y_i)$$

- In the case of Linear regression, L was the squared loss
- In Perceptron, L was Perceptron Loss
- The regularized version of this is:

$$\min_{w,b} \frac{1}{2} \|w\|^2 + c \sum_i L(f(x^{(i)}, w, b), y_i)$$

- c is a hyper-parameter (again, to be tuned on validation set)

Perceptron vs Hinge vs Square vs Zero-One Loss



Hinge loss \geq 0/1 loss Everywhere

- If the data is imbalanced (i.e., more positive examples than negative examples), may want to evenly distribute the error between the two classes

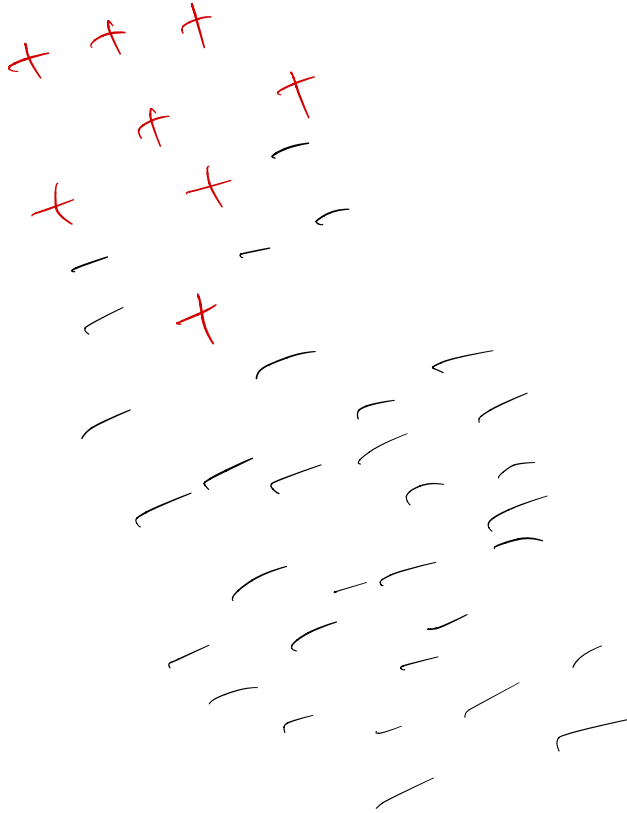
$$\min_{w,b,\xi} \frac{1}{2} \|w\|^2 + \frac{c}{N_+} \sum_{i:y_i=1} \xi_i + \frac{c}{N_-} \sum_{i:y_i=-1} \xi_i$$

such that

$$y_i(w^T x^{(i)} + b) \geq 1 - \xi_i, \text{ for all } i$$

$$\xi_i \geq 0, \text{ for all } i$$

Why is Imbalance a Problem?



- We argued, intuitively, that SVMs generalize better than the perceptron algorithm
 - How can we make this precise?

There exists a theoretical connection
between Margin & Generalization.

- Where are we headed?
 - Other simple hypothesis spaces for supervised learning
 - k nearest neighbor
 - Decision trees
 - Probabilistic Methods
 - Bayesian Methods
 - Naïve Bayes
 - Logistic Regression