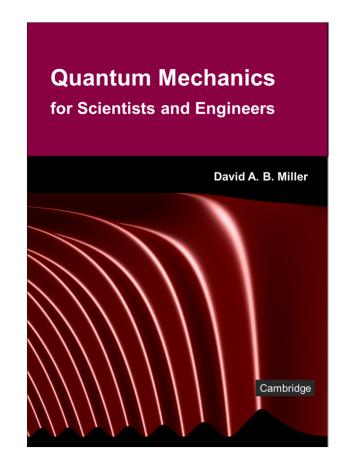
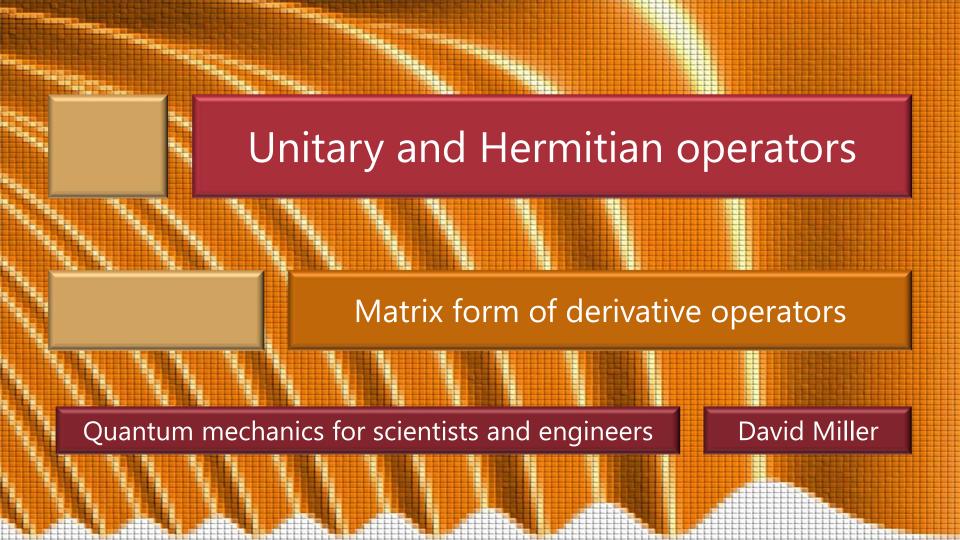
6.2 Unitary and Hermitian operators

Slides: Video 6.2.5 Matrix form of derivative operators

Text reference: Quantum Mechanics for Scientists and Engineers

Section 4.12 – 4.13





Matrix form of derivative operators

Returning to our original discussion of functions as vectors we can postulate a form for the differential operator

$$\frac{d}{dx} \equiv \begin{bmatrix} & \ddots & & \\ & \cdots & -\frac{1}{2\delta x} & 0 & \frac{1}{2\delta x} & 0 & \cdots \\ & \cdots & 0 & -\frac{1}{2\delta x} & 0 & \frac{1}{2\delta x} & \cdots \\ & & \ddots & & & \ddots \end{bmatrix}$$

where we presume we can take the limit as $\delta x \rightarrow 0$

Matrix form of derivative operators

If we multiply the column vector whose elements are the values of the function then

where we are taking the limit as $\delta x \rightarrow 0$

Hence we have a way of representing a derivative as a matrix

Matrix form of derivative operators

Note this matrix is antisymmetric in reflection about the diagonal and it is not Hermitian Indeed somewhat surprisingly d/dx is not Hermitian By similar arguments, though d^2/dx^2 gives a symmetric matrix and is Hermitian

Matrix corresponding to multiplying by a function

```
We can formally "operate" on the function f(x)
  by multiplying it by the function V(x)
     to generate another function g(x) = V(x) f(x)
Since V(x) is performing the role of an operator
  we can if we wish represent it as a (diagonal) matrix
     whose diagonal elements are
        the values of the function at each of the
         different points
If V(x) is real
  then its matrix is Hermitian as required for \hat{H}
```

