

# Robot Navigation



## A QUICK INTRODUCTION

Slides by: Alexander Moriarty

Presented by:

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BRS University of Applied Sciences

# Robot Navigation: What?



- What is Navigation?
- What is Robot Navigation?
- Why is Robot Navigation important?

# Robot Navigation: Robustness.



- What is Robustness?
- Where does the navigation work well?
- How does the system perform in edge cases?
- How do we measure and benchmark 'Robust Navigation?'

# Robot Navigation: Challenges



- **Environments**

- Dynamic
- Time variant
- Shared

- **Costs**

- Sensor and computational costs keep some solutions out of the question for mass production

# Robot Navigation: An example

