プログラム

実行環境と用いた言語・ライブラリを以下の表 1 に示す。

表 1: プログラムの実行環境

OS : Microsoft Windows 10 Pro (64bit)

CPU : Intel(R) Core(TM) i5-4300U

RAM : 4.00 GB 使用言語 : Python3.6

可視化 : matplotlib ライブラリ

```
Listings 1: assignment1.py
# -*- coding: utf-8 -*-
4 import numpy as np
  import matplotlib.pyplot as plt
  def generate_data(n=200):
       x = np.linspace(0, np.pi, n // 2)
      u = np.stack([np.cos(x) + .5, -np.sin(x)], axis=1) * 10.
      u += np.random.normal(size=u.shape)
11
       v = np.stack([np.cos(x) - .5, np.sin(x)], axis=1) * 10.
      v += np.random.normal(size=v.shape)
      x = np.concatenate([u, v], axis=0)
14
      y = np.zeros(n)
      y[0] = 1
      y[-1] = -1
       return x, y
19
21 def calc_norm(x, c, save_memory=False):
       if save_memory:
22
          n_x = x.shape[1]
          n_c = c.shape[0]
24
          d = x.shape[-1]
25
          norm = np.zeros((n_c, n_x))
          x = np.reshape(x, (n_x, d))
27
          c = np.reshape(c, (n_c, d))
          for i in range(len(x)):
               x_i = x[i]
               norm[i, :] = np.sum((x_i - c) **2, axis=-1)
31
32
       else:
          norm = np.sum((x - c) ** 2, axis=-1)
```

```
return norm
34
35
37 def gauss_kernel(x, c, h, save_memory=False):
38
       norm = calc_norm(x, c, save_memory)
      ker = np.exp(- norm / (2*h**2))
39
       return ker
40
41
42
43 def calc_design_matrix(x, c, h, kernel):
      return kernel(x[None], c[:, None], h)
44
45
  def lrls(x, y, h=1., l=1., nu=1., kernel=gauss_kernel):
47
       .....
48
49
       :param x: data points
50
51
       :param y: labels of data points
       :param h: width parameter of the Gaussian kernel
52
       :param 1: weight decay
53
54
       :param nu: Laplace regularization
       :return:
55
       ....
56
       x_{tilde} = x[y!=0]
57
       K = calc_design_matrix(x, x, h, kernel)
58
       K_tilde = calc_design_matrix(x_tilde, x, h, kernel)
60
       W = K
61
62
       D = np.diag(W.sum(axis=1))
       L = D - W
63
64
       tmp = K_tilde.dot(K_tilde.T) + 1*np.eye(len(K_tilde)) +
65
       2*nu*K.dot(L).dot(K)
       theta = np.linalg.inv(tmp).dot(K_tilde).dot(y[y!=0])
       return theta
67
69
70 def supervised_train(x, y, h=1., l=1., kernel=gauss_kernel):
      K = calc_design_matrix(x, x, h, kernel)
       tmp = K.dot(K.T) + l*np.eye(len(K))
72
       theta = np.linalg.inv(tmp).dot(K).dot(y)
73
74
       return theta
75
n def visualize(x, y, theta, h=1., grid_size=100, path=None):
      plt.xlim(-20., 20.)
78
       plt.ylim(-20., 20.)
79
```

```
grid = np.linspace(-20., 20., grid_size)
80
81
       X, Y = np.meshgrid(grid, grid)
       mesh_grid = np.stack([np.ravel(X), np.ravel(Y)], axis=1)
83
84
       k = np.exp(
85
            -np.sum(
86
                 (x.astype(np.float32)[:, None] -
       mesh_grid.astype(np.float32)[None])**2,
                axis=2).astype(np.float64)
                / (2 * h ** 2)
89
            )
90
       plt.contourf(
           Х, Ү,
92
            np.reshape(np.sign(k.T.dot(theta)), (grid_size, grid_size)),
93
            alpha=.4,
            cmap=plt.cm.coolwarm,
95
96
       plt.scatter(x[y==0][:, 0], x[y == 0][:, 1], marker='$.$', c='black')
97
       plt.scatter(x[y==1][:, 0], x[y == 1][:, 1], marker='$X$', c='red')
       plt.scatter(x[y==-1][:, 0], x[y==-1][:, 1], marker='$0$', c='blue')
       if path:
100
           plt.savefig(path)
101
       plt.show()
102
103
   def main():
105
        # settings
106
       h = 1.0
107
       lamb = 1.0
108
        nu = 1.0
109
       n = 200
110
       fig_path = '../figures/assignment1_result.png'
111
       np.random.seed(0)
112
113
114
115
        # generate data
        x, y = generate_data(n)
116
        #print(x.shape, y.shape)
118
119
120
        # train
       theta = lrls(x, y, h=h, l=lamb, nu=nu)
121
122
        # supervised
123
        \#x, y = x[y!=0], y[y!=0]
124
        #theta = supervised_train(x, y, h=h, l=lamb,)
125
```

```
126
127
       # result
129
       print(f'#data: {n}')
       print(f'h = {h} lambda = {lamb} nu = {nu}')
130
       #print('theta = \n', theta)
131
132
133
      visualize(x, y, theta, path=fig_path)
134
135
136 if __name__ == '__main__':
137
      main()
```

```
Listings 2: assignment3.py
1 # -*- coding: utf-8 -*-
4 import numpy as np
5 import matplotlib.pyplot as plt
8 def generate_data(n_total, n_positive):
      x = np.random.normal(size=(n_total, 2))
      x[:n_positive, 0] -= 2
10
       x[n_positive:, 0] += 2
11
      x[:, 1] *= 2.
12
      y = np.empty(n_total, dtype=np.int64)
13
       y[:n_positive] = 0
14
      y[n_positive:] = 1
15
      return x, y
17
18
def calc_A(y, y_tilde, x_train, y_train):
      indices_i = np.where(y_train == y)[0]
20
21
       indices_i_tilde = np.where(y_train == y_tilde)[0]
22
      if len(indices_i) * len(indices_i_tilde) == 0:
23
           return 0
25
      x_tilde = x_train[indices_i_tilde]
26
       A = 0
27
      for idx_i in indices_i:
28
           A += np.sum(np.sqrt(np.sum((x_train[idx_i] - x_tilde)**2, axis=0)))
      A /= (len(indices_i) * len(indices_i_tilde))
30
       return A
31
32
33
34 def calc_b(y, x_train, y_train, x_test):
      x_i = x_{test}[y_{train} == y]
35
36
       if len(x_i) * len(x_test) == 0:
37
           return 0
38
39
      b = 0
40
      for x_i_dash in x_test:
41
          b \leftarrow np.sum(np.sqrt(np.sum((x_i_dash - x_i)**2, axis=0)))
       b /= (len(x_i) * len(x_test))
43
       return b
44
45
46
```

```
def estimate_pi(x_train, y_train, x_test):
48
       x, y = x_train, y_train
       A_pp = calc_A(1, 1, x, y)
       A_pm = calc_A(1, -1, x, y)
50
51
       A_mm = calc_A(-1, -1, x, y)
      b_p = calc_b(1, x_train, y_train, x_test)
52
53
       b_m = calc_b(-1, x_train, y_train, x_test)
54
       pi_hat = (A_pm - A_mm - b_p + b_m) / (2*A_pm - A_pp - A_mm)
55
       pi_hat = min(1, max(0, pi_hat))
       return pi_hat
57
58
  def cwls(train_x, train_y, test_x, is_weighted=True):
60
       n = train_y.shape[0]
61
62
       if is_weighted:
63
64
           pi_hat = estimate_pi(train_x, train_y, test_x)
           Pi = np.zeros(n)
65
           Pi[train_y == 1] = pi_hat
66
           Pi[train_y == -1] = 1 - pi_hat
           Pi = np.diag(Pi)
68
       else:
69
           Pi = np.eye(n)
70
71
72
       Phi = np.concatenate([np.ones(n)[:, np.newaxis], train_x], axis=1)
73
74
       theta =
      np.linalg.inv(Phi.T.dot(Pi).dot(Phi)).dot(Phi.T).dot(Pi).dot(train_y)
       return theta
75
76
77
78 def visualize(train_x, train_y, test_x, test_y, theta, is_weighted=True):
       str_weighted = 'weighted' if is_weighted else 'unweighted'
79
       for x, y, name in [(train_x, train_y, 'train'), (test_x, test_y,
80
      'test')]:
           plt.xlim(-5., 5.)
81
           plt.ylim(-7., 7.)
82
           lin = np.array([-5., 5.])
           plt.plot(lin, -(theta[2] + lin * theta[0]) / theta[1])
84
           plt.scatter(x[y==0][:, 0], x[y==0][:, 1], marker='$0$', c='blue')
85
           plt.scatter(x[y==1][:, 0], x[y==1][:, 1], marker='$X$', c='red')
87
      plt.savefig('../figures/assignment3_result_{}}.png'.format(str_weighted,
      name))
          plt.show()
88
89
```

```
91 def main():
       # settings
92
       is_weighted = False
93
94
       np.random.seed(0)
95
       # generate data
97
       train_x, train_y = generate_data(n_total=100, n_positive=90)
98
       eval_x, eval_y = generate_data(n_total=100, n_positive=10)
100
101
        # train
102
       theta = cwls(train_x, train_y, eval_x, is_weighted=is_weighted)
103
104
        # result
106
       print('result')
107
       visualize(train_x, train_y, eval_x, eval_y, theta,
108
       is_weighted=is_weighted)
109
110
iii if __name__ == '__main__':
112
      main()
```