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Exercise Sheet 6

Exercise 1: Markov Model Forward Problem (20 P)

A Markov Model can be seen as a joint distribution over states at each time step q_1, \ldots, q_T where $q_t \in \{S_1, \ldots, S_N\}$, and where the probability distribution has the factored structure:

$$P(q_1, \dots, q_T) = P(q_1) \cdot \prod_{t=2}^{T} P(q_t | q_{t-1})$$

Factors are the probability of the initial state and conditional distributions at every time step.

(a) Show that the following relation holds:

$$P(q_{t+1} = S_j) = \sum_{i=1}^{N} P(q_t = S_i) P(q_{t+1} = S_j | q_t = S_i)$$

for
$$t \in \{1, ..., T-1\}$$
 and $j \in \{1, ..., N\}$.

Exercise 2: Hidden Markov Model Forward Problem (20 P)

A Hidden Markov Model (HMM) can be seen as a joint distribution over hidden states q_1, \ldots, q_T at each time step and corresponding observation O_1, \ldots, O_T . Like for the Markov Model, we have $q_t \in \{S_1, \ldots, S_N\}$. The probability distribution of the HMM has the factored structure:

$$P(q_1, \dots, q_T, O_1, \dots, O_T) = P(q_1) \cdot \prod_{t=2}^T P(q_t | q_{t-1}) \cdot \prod_{t=1}^T P(O_t | q_t)$$

Factors are the probability of the initial state and conditional distributions at every time step.

(a) Show that the following relation holds:

$$P(O_1, \dots, O_t, O_{t+1}, q_{t+1} = S_j) = \sum_{i=1}^{N} P(O_1, \dots, O_t, q_t = S_i) P(q_{t+1} = S_j | q_t = S_i) P(O_{t+1} | q_{t+1} = S_j)$$

for
$$t \in \{1, ..., T-1\}$$
 and $j \in \{1, ..., N\}$.

Exercise 3: Programming (60 P)

Download the programming files on ISIS and follow the instructions.

