

## Eigen Things

The basics: Lat  $\underline{A}$  vera ein  $n \times n$  matrica, so hefur henda fastar rætrir, fixed directions, trs. vektorar  $\underline{r}$  sum eru ein skalering  $\lambda$  af sér sjálfum undir árnýndun við  $\underline{A}$ .

Vit skrifa altso  $\underline{A}\underline{r} = \lambda\underline{r}$

$$\Leftrightarrow \underline{A}\underline{r} - \lambda\underline{r} = \underline{0}$$

$$\Leftrightarrow (\underline{A} - \lambda\underline{I})\underline{r} = \underline{0}$$

Löysun  $\underline{r} = \underline{0}$  er trivíel og sigur einhi um geometrína hjá  $\underline{A}$ . Vit leita eftir löysum við  $\underline{r} \neq \underline{0}$ .

Í so fall finst ein löysn tá determinanturinn er 0, so at

$$\det(\underline{A} - \lambda\underline{I}) = 0.$$

Vit fáa altso karakteristiska polynóm á  $n$ 'ta stigi, har ræturnar eru eiginvirdini.

Dæmi 15.1 Lat  $\underline{A} = \begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 3 & 1 & 0 \\ 0 & 0 & 4 & 1 \\ 0 & 0 & 0 & 2 \end{bmatrix}$ , so er  $p(\lambda) = \det(\underline{A} - \lambda\underline{I}) = \begin{vmatrix} 1-\lambda & 1 & 0 & 0 \\ 0 & 3-\lambda & 1 & 0 \\ 0 & 0 & 4-\lambda & 1 \\ 0 & 0 & 0 & 2-\lambda \end{vmatrix}$ .

Hetta er ein óvara trihantsmatrica, so

$$p(\lambda) = (1-\lambda)(3-\lambda)(4-\lambda)(2-\lambda),$$

har ræturnar eru  $\lambda_1=4$ ,  $\lambda_2=3$ ,  $\lambda_3=2$  og  $\lambda_4=1$ .

Vit sön, at determinanturinn er varðveittur undir Gauss elimination, men so er ekki við eiginvirdini.

Ein general  $n \times n$  matrica hefur  $p(\lambda)$  á  $n$ 'ta stigi, og eingin beinleidis formil finst til at lösa rætur í polynóm við stig  $n \geq 5$ . Aðrar metodur kunnu brúkast, men typisk er at lösa numerískt við CAS ambót.

Mínst til at  $p(0) = \det(\underline{A}) = \lambda_1 \cdot \lambda_2 \cdot \dots \cdot \lambda_n$ .

## Dæmi 15.3

Vit finna eiginvektorar við innsetan af okkurn eiginvirdi og lösa.

$$\lambda_1 = 4: \begin{bmatrix} -3 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -2 \end{bmatrix} \underline{r}_1 = \underline{0} \Leftrightarrow \underline{r}_1 = \begin{bmatrix} 1/3 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

$$\lambda_2 = 3 \quad \begin{bmatrix} -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & -1 \end{bmatrix} \underline{r}_2 = \underline{0} \Leftrightarrow \underline{r}_2 = \begin{bmatrix} 1/2 \\ 1 \\ 0 \\ 0 \end{bmatrix}$$

Umframant hetta fáa vit

$$\underline{r}_3 = \begin{bmatrix} 1/2 \\ 1/2 \\ -1/2 \\ 1 \end{bmatrix} \quad \text{og} \quad \underline{r}_4 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

Dæmi 15.4 Lat  $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix}$  so er  $\lambda_1 = \lambda_2 = 2$  og  $\lambda_3 = 1$ .

Fyrir  $\lambda_1$  og  $\lambda_2$ :  $\begin{bmatrix} -1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \underline{r}_1 = \underline{0} \Leftrightarrow \underline{r}_1 = \begin{bmatrix} 5 \\ 1 \\ 1 \end{bmatrix}$

$\lambda_3 = 1$ :  $\begin{bmatrix} 0 & 2 & 3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \underline{r}_3 = \underline{0} \Leftrightarrow \underline{r}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

Vit fáa tvær fastar rætingar. Eginivíð 2 sigst at hafa algebraískan multiplicitet á 2 og geometriskan multiplicitet á 1.

Rotationsmatricur eru dæmi, har bert ein rætingur er fastur.

Dæmi 15.6 Symmetriskar matricur hafa reel eginivíð og hafa eigendekomposition.

Lat

$$A = \begin{bmatrix} 3 & 0 & 1 \\ 0 & 3 & 0 \\ 1 & 0 & 3 \end{bmatrix}, \quad \det(A - \lambda I) = (3-\lambda)^3 - (3-\lambda) = 0, \quad \lambda = 3-\lambda$$

$$\Leftrightarrow \lambda^3 - \lambda = 0$$

$$\Leftrightarrow \lambda(\lambda^2 - 1) = 0$$

$$\Leftrightarrow \lambda_1 = 4, \lambda_2 = 3, \lambda_3 = 2.$$

$\lambda_1 = 4$ :  $\begin{bmatrix} -1 & 0 & 1 \\ 0 & -1 & 0 \\ 1 & 0 & -1 \end{bmatrix} \underline{r}_1 = \underline{0} \Leftrightarrow \underline{r}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} \sqrt{2}/2 \\ 0 \\ \sqrt{2}/2 \end{bmatrix}$

$\lambda_2 = 3$ :  $\begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \underline{r}_2 = \underline{0} \Leftrightarrow \underline{r}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

$\lambda_3 = 2$ :  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \underline{r}_3 = \underline{0} \Leftrightarrow \underline{r}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} -\sqrt{2}/2 \\ 0 \\ \sqrt{2}/2 \end{bmatrix}$

Við

$$\Lambda = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 2 \end{bmatrix} \quad \text{og} \quad R = \begin{bmatrix} \sqrt{2}/2 & 0 & -\sqrt{2}/2 \\ 0 & 1 & 0 \\ \sqrt{2}/2 & 0 & \sqrt{2}/2 \end{bmatrix}$$

so er  $\underline{A} = R \Lambda R^T$ .

Projektións matricur eru eitt sindur lættari, þi tæu senda minst eina dimensión burtur, so tã er minst eitt eginvirdi 0.

Trace

Vit definera nú sporið á eini matricu  $\underline{A}$ . Hetta kallast trace.

$$\begin{aligned} \text{tr}(\underline{A}) &= \lambda_1 + \lambda_2 + \dots + \lambda_n \\ &= a_{11} + a_{22} + \dots + a_{nn} \end{aligned}$$

Til tíðis ber til at brúka  $\text{tr}(\underline{A})$  og  $\det(\underline{A})$  til at angera eginvirdir!

Fyrir  $2 \times 2$  :

$$\lambda_{1,2} = \frac{\text{tr}(\underline{A}) \pm \sqrt{(\text{tr}(\underline{A}))^2 - 4 \det(\underline{A})}}{2}$$

The Power  
Method