

Diagonalization by Similarity Transformation

Ex 1.

$$A = \begin{bmatrix} 3 & 4 & 4 \\ 6 & 6 & 6 \\ -6 & -7 & -7 \end{bmatrix} \text{ defines } f: \mathbb{R}^3 \rightarrow \mathbb{R}^3.$$

a) Easiest way to check whether $\underline{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}$, $\underline{v}_2 = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$ and $\underline{v}_3 = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$ are eigenvectors of f ? Show this.

$$A \underline{v}_1 = \begin{bmatrix} 3-4 \\ 6-6 \\ -6+7 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = -1 \cdot \underline{v}_1, \text{ so } \lambda_1 = -1.$$

$$A \underline{v}_2 = \begin{bmatrix} 4-4 \\ 6-6 \\ -7+7 \end{bmatrix} = \underline{0} = 0 \cdot \underline{v}_2, \text{ so } \lambda_2 = 0.$$

$$A \underline{v}_3 = \begin{bmatrix} 3+8-8 \\ 6+12-12 \\ -6-14+14 \end{bmatrix} = \begin{bmatrix} 3 \\ 6 \\ -6 \end{bmatrix} = 3 \cdot \underline{v}_3, \text{ so } \lambda_3 = 3.$$

b) How can we easiest argue that $\underline{v}_1, \underline{v}_2$ and \underline{v}_3 are lin. indept.?

The eigenvalues are distinct, so they are lin. indept. by proposition 13.11.1.

c) How can we easiest show that $f(\mathbb{R}^3) = \text{span}\{\underline{v}_1, \underline{v}_3\}$?

The eigenvectors form an eigenbasis, and $f(\mathbb{R}^3)$ is spanned by the image of the basisvectors.

$$f(\mathbb{R}^3) = \text{span}\{f(\underline{v}_1), f(\underline{v}_2), f(\underline{v}_3)\} = \text{span}\{\underline{v}_1, \underline{v}_3\}.$$

Ex2.

- a) Determine the eigen values and spaces of the projection p onto XY .

We have $\lambda_1 = 1$ with $\text{am}(1) = \text{gm}(1) = 2$,
while $\lambda_2 = 0$ with $\text{am}(0) = \text{gm}(0) = 1$.

$$E_1 = \text{span}\{(1,0,0), (0,1,0)\},$$

$$E_0 = \text{span}\{(0,0,1)\}.$$

- b) Choose two different eigenbases, and determine the diagonal matrix for p in the new bases.

If we use the standard basis, then p has the matrix

$$\underline{P} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Any lin. indept. vectors in the XY -plane will do for $\lambda_1 = 1$, and say $-k$ for $\lambda_2 = 0$. For vectors $(1,1,0)$, $(1,-1,0)$ and $(0,0,-1)$ we also receive the diagonal matrix \underline{P} .

Ex3. The following output is given about a map f with matrix \underline{A} .

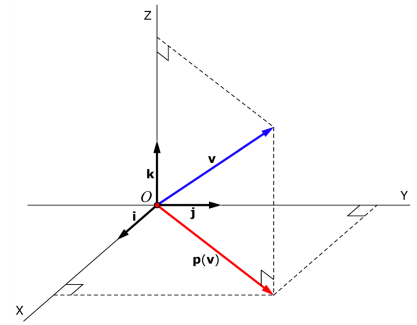
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A:=<16,18,-24|-13,-15,24|-2,-2,4>:
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Eigenvectors(A,output=list)
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$$\left[\begin{bmatrix} 4, 1, \left\{ \begin{bmatrix} -2 \\ -2 \\ 1 \end{bmatrix} \right\} \end{bmatrix}, \begin{bmatrix} 3, 1, \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\} \end{bmatrix}, \begin{bmatrix} -2, 1, \left\{ \begin{bmatrix} -1 \\ 4 \\ -1 \\ 2 \\ 1 \end{bmatrix} \right\} \end{bmatrix} \right]$$

- a) State \underline{A} .

$$\underline{A} = \begin{bmatrix} 16 & -13 & -2 \\ 18 & -15 & -2 \\ -24 & 24 & 4 \end{bmatrix}.$$



b) State eigen information of \underline{A} .

$$\lambda_1 = 4, \text{ am}(4) = \text{gm}(4) = 1 \text{ and } \underline{v}_1 = \begin{bmatrix} -2 \\ -2 \\ 1 \end{bmatrix}.$$

$$\lambda_2 = 3, \text{ am}(3) = \text{gm}(3) = 1 \text{ and } \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

$$\lambda_3 = -2, \text{ am}(-2) = \text{gm}(-2) = 1 \text{ and } \underline{v}_3 = \begin{bmatrix} -1/4 \\ -1/2 \\ 1 \end{bmatrix}.$$

c) Provide a basis of eigenvectors of f .

Using b) we have $\underline{v} = (\underline{v}_1, \underline{v}_2, \underline{v}_3)$.

d) Determine a mapping matrix for f wrt. the basis \underline{v} .

Let $\underline{V} = [\underline{v}_1 \ \underline{v}_2 \ \underline{v}_3]$, then the new matrix $\underline{\Lambda}$ is given by

$$\underline{\Lambda} = \underline{V}^{-1} \underline{A} \underline{V} = \begin{bmatrix} 4 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & -2 \end{bmatrix}$$

e) State \underline{V} and $\underline{\Lambda}$ such that $\underline{\Lambda} = \underline{V}^{-1} \underline{A} \underline{V}$.

This is done in d).

Ex4. Given $\underline{A} = \begin{bmatrix} 9 & -6 \\ 8 & -7 \end{bmatrix}$ investigate whether we may diagonalize \underline{A} .

a)

If possible then do so.

$$P(\lambda) = 0 \Leftrightarrow (9-\lambda)(-7-\lambda) + 48 = 0$$

$$\Leftrightarrow \lambda^2 - 2\lambda - 15 = 0$$

$$\lambda = \frac{2 \pm \sqrt{4 + 60}}{2} = \frac{2 \pm 8}{2} = \begin{cases} 5 \\ -3 \end{cases}$$

Associated eigenvectors are then solved for.

$$\lambda = 5: \begin{bmatrix} 4 & -6 \\ 8 & -12 \end{bmatrix} \underline{u} = \underline{0} \Leftrightarrow \underline{u} = t \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \quad t \in \mathbb{R}.$$

$$\lambda = -3: \begin{bmatrix} 12 & -6 \\ 8 & -4 \end{bmatrix} \underline{v} = \underline{0} \Leftrightarrow \underline{v} = t \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \quad t \in \mathbb{R}.$$

$$\text{Let } \underline{V} = \begin{bmatrix} 3 & 1 \\ 2 & 2 \end{bmatrix}, \quad \text{then } \underline{V}^{-1} = \frac{1}{4} \begin{bmatrix} 2 & -1 \\ -2 & 3 \end{bmatrix}.$$

Now we have $\underline{A} = \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix}$ as expected by the following.

$$\begin{aligned} \underline{V}^{-1} \underline{A} \underline{V} &= \frac{1}{4} \begin{bmatrix} 2 & -1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 9 & -6 \\ 8 & -7 \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 2 & 2 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 2 & -1 \\ -2 & 3 \end{bmatrix} \begin{bmatrix} 15 & -3 \\ 10 & -6 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 20 & 0 \\ 0 & -12 \end{bmatrix} = \begin{bmatrix} 5 & 0 \\ 0 & -3 \end{bmatrix}. \end{aligned}$$

$$b) \text{ Do the same for } \underline{B} = \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix}.$$

$$\begin{aligned} P(\lambda) &= (2-\lambda)(1-\lambda)^2 - (2-\lambda) = (2-\lambda)((1-\lambda)^2 - 1) \\ &= (2-\lambda)(\lambda^2 - 2\lambda) = (2-\lambda)\lambda(\lambda-2) = -\lambda(2-\lambda)^2 \\ \Rightarrow P(\lambda) &= 0 \Leftrightarrow \lambda = 2 \vee \lambda = 0 \end{aligned}$$

Note $\text{am}(2) = 2$.

$$\lambda = 0: \begin{bmatrix} 2 & 0 & 0 \\ 1 & 1 & 1 \\ -1 & 1 & 1 \end{bmatrix} \underline{v} = \underline{0} \Leftrightarrow \underline{v} = t \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}, \quad t \in \mathbb{R}.$$

$$\lambda = 2: \begin{bmatrix} 0 & 0 & 0 \\ 1 & -1 & 1 \\ -1 & 1 & -1 \end{bmatrix} \underline{u} = \underline{0} \Leftrightarrow \underline{u} = t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \vee \underline{u} = t \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}, \quad t \in \mathbb{R}.$$

Then we can diagonalize with

$$\underline{V} = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & -1 & -1 \end{bmatrix} \quad \text{and we have} \quad \underline{\Lambda} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}.$$

c) Do the same for $\underline{C} = \begin{bmatrix} 3 & 1 & -2 \\ 1 & 3 & 1 \\ 0 & 0 & 2 \end{bmatrix}.$

$$\begin{aligned} P(\lambda) &= (3-\lambda)^2(2-\lambda) - (2-\lambda) = (2-\lambda)(\lambda^2 - 6\lambda + 9 - 1) \\ &= (2-\lambda)(\lambda^2 - 6\lambda + 8) = (2-\lambda)(2-\lambda)(4-\lambda) \end{aligned}$$

$$\Rightarrow P(\lambda) = 0 \Leftrightarrow \lambda = 2 \vee \lambda = 4.$$

Again $\text{am}(2) = 2.$

$$\lambda = 2: \begin{bmatrix} 1 & 1 & -2 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \underline{v} = \underline{0} \Leftrightarrow \underline{v} = t \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}, \quad t \in \mathbb{R}.$$

However, now $\text{gm}(2) = 1 \neq 2$, so there is no diagonalization of \underline{C} .

Ex 5. Given $\underline{A} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$ and $\underline{B} = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}.$

a) Show \underline{A} and \underline{B} are similar.

For both we get $P(\lambda) = \lambda^2 + 1$ which has roots $\lambda = \pm i$.

$$\lambda_A = i: \begin{bmatrix} i & 1 \\ -1 & i \end{bmatrix} \underline{u} = \underline{0} \Leftrightarrow \underline{u}_A = t \begin{bmatrix} i \\ 1 \end{bmatrix}, \quad t \in \mathbb{R}.$$

This implies for $\lambda_A = -i$ we get $\underline{v}_A = t \begin{bmatrix} -i \\ 1 \end{bmatrix}, \quad t \in \mathbb{R}.$

Now onwards with $\underline{\underline{B}}$, and we get the mirrored relation

$$\lambda = i \Rightarrow \underline{\underline{u}}_B = \begin{bmatrix} -i \\ 1 \end{bmatrix} \quad \text{and} \quad \lambda = -i \Rightarrow \underline{\underline{v}}_B = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

up to scalar multiples.

Then with $\underline{\underline{V}} = \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix}$ and $\underline{\underline{U}} = \begin{bmatrix} -i & i \\ 1 & 1 \end{bmatrix}$ we have similarity.

$$\underline{\underline{A}} = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} = \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}} = \underline{\underline{U}}^{-1} \underline{\underline{B}} \underline{\underline{U}}.$$

b) Find $\underline{\underline{M}}$ such that $\underline{\underline{B}} = \underline{\underline{M}}^{-1} \underline{\underline{A}} \underline{\underline{M}}$.

$$\begin{aligned} \underline{\underline{U}}^{-1} \underline{\underline{B}} \underline{\underline{U}} &= \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}} \Leftrightarrow \underline{\underline{B}} = \underline{\underline{U}} \underline{\underline{V}}^{-1} \underline{\underline{A}} \underline{\underline{V}} \underline{\underline{U}}^{-1} \\ &= \underline{\underline{M}}^{-1} \underline{\underline{A}} \underline{\underline{M}} \end{aligned}$$

Here $\underline{\underline{M}} = \underline{\underline{V}} \underline{\underline{U}}^{-1}$ and $\underline{\underline{M}}^{-1} = (\underline{\underline{V}} \underline{\underline{U}}^{-1})^{-1}$.

$$\begin{aligned} \underline{\underline{M}} &= \underline{\underline{V}} \underline{\underline{U}}^{-1} = \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \left(\frac{-1}{2i} \begin{bmatrix} 1 & -i \\ -1 & -i \end{bmatrix} \right) \\ &= -\frac{1}{2i} \begin{bmatrix} 2i & 0 \\ 0 & -2i \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}. \end{aligned}$$

c) Now consider $\underline{\underline{A}}$ as the matrix for $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$. Determine a basis m of \mathbb{R}^2 such that f is represented by $\underline{\underline{B}}$.

The basis is given by the matrix $\underline{\underline{M}}$, so $m = ((-1, 0), (0, 1))$.

Ex 6. Given

$$A = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & -1 \\ 5 & 1 & 1 \end{bmatrix}.$$

a) Compute eigenvalues and spaces.

$$P(\lambda) = (3-\lambda)(1-\lambda)^2 + (3-\lambda) = (3-\lambda)(\lambda^2 - 2\lambda + 2)$$

$$\lambda_1 = 3.$$

$$\lambda^2 - 2\lambda + 2 = 0 \Leftrightarrow \lambda = \frac{2 \pm 2i}{2} = \begin{cases} 1+i \\ 1-i \end{cases}$$

For λ_1 we have

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & -2 & -1 \\ 5 & 1 & -2 \end{bmatrix} \underline{v}_1 = \underline{0} \Leftrightarrow \underline{v}_1 = t \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}, \quad t \in \mathbb{R}.$$

$$\lambda = 1-i: \begin{bmatrix} 2+i & 0 & 0 \\ 0 & i & -1 \\ 5 & 1 & i \end{bmatrix} \underline{v}_2 = \underline{0} \Leftrightarrow \underline{v}_2 = t \begin{bmatrix} 0 \\ 1 \\ i \end{bmatrix}, \quad t \in \mathbb{R}.$$

$$\text{It follows that } \underline{v}_3 = t \begin{bmatrix} 0 \\ 1 \\ -i \end{bmatrix}, \quad t \in \mathbb{R}.$$

Now we have $E_3 = \text{span}\{\underline{v}_1\}$, $E_{1-i} = \text{span}\{\underline{v}_2\}$
and $E_{1+i} = \text{span}\{\underline{v}_3\}$.

b) Diagonalize A .

Let \underline{V} be the matrix $\begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 1 \\ 2 & i & -i \end{bmatrix}$, then $\underline{\Lambda}$ is the diagonal matrix

$$\underline{\Lambda} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1-i & 0 \\ 0 & 0 & 1+i \end{bmatrix} = \underline{V}^{-1} \underline{A} \underline{V}$$

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> A:=3,0,0; 0,1,-1; 5,1,1;
V:=1,-1,2; 0,1,1; 0,1,-1;
'Lambda'=-MatrixInverse(V).C.V;
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$$\underline{A} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1 & -1 \\ 5 & 1 & 1 \end{bmatrix}$$

$$\underline{V} = \begin{bmatrix} 1 & 0 & 0 \\ -1 & 1 & 1 \\ 2 & i & -i \end{bmatrix}$$

$$\underline{\Lambda} = \begin{bmatrix} 3 & 0 & 0 \\ 0 & 1-i & 0 \\ 0 & 0 & 1+i \end{bmatrix}$$