

401. 
$$\begin{cases} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} 2 & 3 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 2 \\ 0 \end{pmatrix} u(t) \\ y = (3 \quad 4) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \end{cases}$$

(a) Finn  $H(s)$ .  $(A-sI) = \begin{pmatrix} 2-s & 3 \\ 0 & 4-s \end{pmatrix}$ ,  $(A-sI)^{-1} = \frac{1}{(2-s)(4-s)} \begin{pmatrix} 4-s & -3 \\ 0 & 2-s \end{pmatrix}$ .

$$H(s) = -(3 \quad 4) \frac{1}{(2-s)(4-s)} \begin{pmatrix} 4-s & -3 \\ 0 & 2-s \end{pmatrix} \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$= \frac{1}{(2-s)(4-s)} \cdot (-(3 \quad 4)) \begin{pmatrix} 8-2s \\ 0 \end{pmatrix} = \frac{1}{(2-s)(4-s)} \cdot (6s-24)$$

$$= \frac{-6(4-s)}{(2-s)(4-s)} = \frac{6}{s-2}, \quad s \notin \{2, 4\}.$$

(b) Finn  $y$  til  $u(t) = e^{st}$ .

$$H(s) = \frac{6}{s-2} = 2 \Rightarrow y(t) = H(s) e^{st} = 2e^{st}.$$

402. 
$$\begin{cases} \frac{dx}{dt} = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} x(t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} u(t) \\ y(t) = x_2(t) \end{cases}$$

(i) Finn  $H(s)$ .  $A-sI = \begin{pmatrix} -s & 1 \\ 0 & 1-s \end{pmatrix}$ ,  $(A-sI)^{-1} = \frac{1}{s(s-1)} \begin{pmatrix} 1-s & -1 \\ 0 & -s \end{pmatrix}$ .

$$H(s) = -(0 \quad 1) \frac{1}{s(s-1)} \begin{pmatrix} 1-s & -1 \\ 0 & -s \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$= \frac{-1}{s(s-1)} (0 \quad 1) \begin{pmatrix} -1 \\ -s \end{pmatrix} = \frac{-1}{s(s-1)} \cdot (-s)$$

$$= \frac{1}{s-1}, \quad s \notin \{0, 1\}.$$

(ii) Finn  $y$  til  $u(t) = e^{-t}$ .

$$H(-1) = \frac{1}{-1-1} = -\frac{1}{2} \Rightarrow y(t) = H(-1) e^{-t} = -\frac{1}{2} e^{-t}.$$



422.

Kanna um systemið er stöðugt ella asymptóðískt stöðugt.

Vit minna á, at eitt asymptóðískt stöðugt system er stöðugt.

$$(i) \quad \dot{x} = \begin{pmatrix} 1 & 7 \\ 3 & -2 \end{pmatrix} x$$

$$\det(A - \lambda I) = (1 - \lambda)(-2 - \lambda) - 21 = \lambda^2 + \lambda - 23 = 0$$

$$\Leftrightarrow \lambda = \frac{-1 \pm \sqrt{1 - 4(-23)}}{2} = -\frac{1}{2} \pm \frac{\sqrt{93}}{2}.$$

Áv þi at  $\operatorname{Re}(\lambda) > 0$ , so er systemið óstöðugt per setning 2.34.

$$(ii) \quad \dot{x} = \begin{pmatrix} -1 & 1 & 0 \\ -8 & -1 & 1 \\ -7 & 0 & 1 \end{pmatrix} x$$

$$\det(A - \lambda I) = (-1 - \lambda)^2(1 - \lambda) - 7 + 5(1 - \lambda) = 0$$

$$\Leftrightarrow (\lambda^2 + 2\lambda + 1)(1 - \lambda) - 5\lambda - 2 = 0$$

$$\Leftrightarrow -\lambda^3 - \lambda^2 + \lambda + 1 - 5\lambda - 2 = 0$$

$$\Leftrightarrow -\lambda^3 - \lambda^2 - 4\lambda - 1 = 0$$

$$\Leftrightarrow \lambda^3 + \lambda^2 + 4\lambda + 1 = 0$$

Koefficientarnir eru allir meiri en 0 og  $\det \begin{pmatrix} 1 & 1 \\ 1 & 4 \end{pmatrix} = 3 > 0$ , so per korollar 2.41 hafa allar rótarnar  $\operatorname{Re}(\lambda) < 0$ .

Áv þi at  $\operatorname{Re}(\lambda) < 0$  fyrir öll eiginvörð  $\lambda$ , so gefur setningur 2.36, at systemið er asymptóðískt stöðugt.

$$(iii) \quad \dot{x} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & -1 & -1 \\ -1 & 0 & -1 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix} x, \quad \text{vit útvikla í fyrsta rað.}$$

$$A - \lambda I = \begin{pmatrix} -\lambda & 0 & 0 & 1 \\ 0 & -1-\lambda & -1 & -1 \\ -1 & 0 & -1-\lambda & -1 \\ 0 & 0 & 1 & -\lambda \end{pmatrix}$$

$$\begin{aligned} \det(A - \lambda I) &= -\lambda \cdot ((-1-\lambda)^2 \cdot (-\lambda) + (-1-\lambda)) \\ &\quad + (-1)^4 \cdot (-1-\lambda) \\ &= \lambda^2(\lambda^2 + 2\lambda + 1) - \lambda(-1-\lambda) + 1 + \lambda \\ &= \lambda^4 + 2\lambda^3 + \lambda^2 + \lambda + \lambda^2 + 1 + \lambda \\ &= \lambda^4 + 2\lambda^3 + 2\lambda^2 + 2\lambda + 1 \end{aligned}$$

Positívir koefficientar og

$$\det \begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix} = 1 > 0, \quad \det \begin{pmatrix} 2 & 2 & 0 \\ 1 & 2 & 1 \\ 0 & 2 & 2 \end{pmatrix} = 8 - 4 - 4 = 0. \quad \text{Lat okkum fáa } \lambda \text{ við } \operatorname{Re}(\lambda) = 0,$$

þi korollar 2.42 sigur, at  $\operatorname{Re}(\lambda) < 0$  kann ei staðfestast.

$$\det(A - \lambda I) = (\lambda^2 + 1)^2 (1 + \lambda)^2 \Rightarrow \lambda = \pm i \vee \lambda = -1$$

Systemið er stabbilt per setning 2.34.

507. Lat  $a \in \mathbb{R}$  og  $\dot{x} = \begin{pmatrix} a & 2 \\ a & 1 \end{pmatrix} x$ .

(i) Finn  $a$ , so at systemið er asymptotískt stabbilt.

$$\begin{aligned} \det(A - \lambda I) &= (a - \lambda)(1 - \lambda) - 2a = \lambda^2 + a - \lambda - a\lambda - 2a \\ &= \lambda^2 - (1 + a)\lambda - a = 0 \end{aligned}$$

Per korollar 2.40, so hafa ræturnar bert  $\operatorname{Re}(\lambda) < 0$ , um koefficientarnir

$$a_1 = -(1 + a) > 0 \quad \text{og} \quad a_2 = -a > 0.$$

Hér skal  $a < -1$ , so at  $\operatorname{Re}(\lambda) < 0$ , og tá er systemið asymptotískt stabbilt per setning 2.36.

(ii) Kanna stabbilitet fyrir  $a = -1$ .

$$A = \begin{pmatrix} -1 & 2 \\ -1 & 1 \end{pmatrix} \Rightarrow \det(A - \lambda I) = \lambda^2 + 1 = 0 \Leftrightarrow \lambda = \pm i.$$

Hér er  $\operatorname{Re}(\lambda) = 0$ , men  $p = q = 1$ , so systemið er stabbilt per setning 2.34.

(iii) Kanna stabbilitet fyrir  $a \geq 0$ .

$$\begin{aligned} \det(A - \lambda I) &= \lambda^2 - (1 + a)\lambda - a \quad \text{við } a \geq 0 \text{ gefur koefficientar} \\ a_1 &= -(1 + a) < 0 \quad \text{og} \quad a_2 = -a \leq 0. \end{aligned}$$

Per korollar 2.40, so hefur systemið ekki bert eiginvirði  $\lambda$  við  $\operatorname{Re}(\lambda) < 0$ . Vit kunnu altso votta at systemið ekki er asymptotískt stabbilt við setning 2.36.

Vit vísa, at eitt eiginvirði  $\lambda$  hefur  $\operatorname{Re}(\lambda) > 0$ , so systemið er óstabbilt.

$$\lambda = \frac{1 + a \pm \sqrt{(1 + a)^2 + 4a}}{2} = \frac{1}{2} + \frac{a}{2} \pm \frac{\sqrt{a^2 + 6a + 1}}{2}$$

Av tí at  $a \geq 0$ , so er  $\lambda = \frac{1}{2} + \frac{a}{2} + \frac{\sqrt{a^2 + 6a + 1}}{2} \geq \frac{1}{2}$  fyrir öll  $a \geq 0$ .

Systemið er altso óstabbilt per setning 2.34.

430.

$$\begin{cases} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -4 & 2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 2 \\ -1 \end{pmatrix} u \\ y = x_1 \end{cases}$$

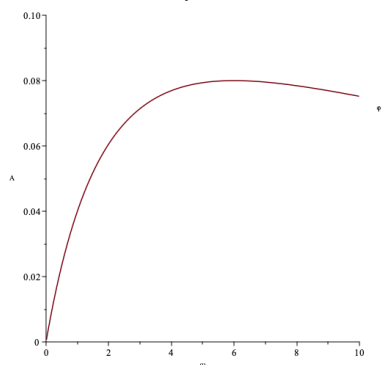
(a) Finn  $H(s)$ .  $(A - sI)^{-1} = \frac{1}{(-4-s)(-1-s)+2} \begin{pmatrix} -1-s & -2 \\ 1 & -4-s \end{pmatrix}$

$$\begin{aligned} H(s) &= \frac{-1}{(s+4)(s+1)+2} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} -1-s & -2 \\ 1 & -4-s \end{pmatrix} \begin{pmatrix} 2 \\ -1 \end{pmatrix} \\ &= \frac{-1}{s^2 + 5s + 6} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} -2s \\ 6+s \end{pmatrix}, \quad \frac{-5 \pm 1}{2} = \begin{Bmatrix} -2 \\ -3 \end{Bmatrix} \\ &= \frac{-1}{(s+2)(s+3)} (-2s) = \frac{2s}{(s+2)(s+3)}, \quad s \notin \{-3, -2\}. \end{aligned}$$

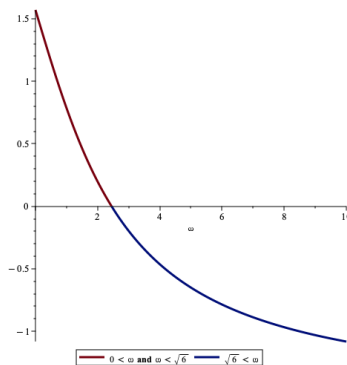
(b) Finn  $A(\omega)$ .  $A(\omega) = |H(i\omega)|$

$$\begin{aligned} H(i\omega) &= \frac{2i\omega}{(2+i\omega)(3+i\omega)} = \frac{2i\omega}{(6-\omega^2) + 5i\omega} \\ |H(i\omega)| &= \frac{\sqrt{(2\omega)^2}}{\sqrt{(6-\omega^2)^2 + (5\omega)^2}} = \frac{2\omega}{\omega^2 + 13\omega + 36}, \quad \omega > 0. \end{aligned}$$

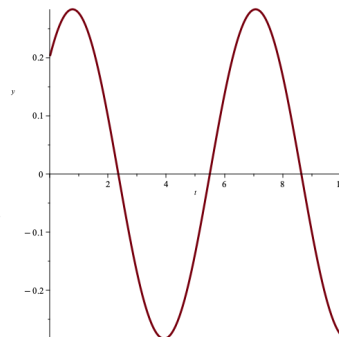
(c) Plots:  $A(\omega)$



$\varphi(\omega)$



$y(t)$  vid  $u(t) = \sin(t)$ .



(d) Finn og plott  $\varphi(\omega)$ .

$$\varphi(\omega) = \arg(H(i\omega))$$

$$H(i\omega) = \frac{2i\omega}{(6-\omega^2) + 5i\omega}$$

$$\arg(H(i\omega)) = \arg(2i\omega) - \arg((6-\omega^2) + 5i\omega) = \begin{cases} \frac{\pi}{2} - \arctan\left(\frac{5\omega}{6-\omega^2}\right), & 0 < \omega < \sqrt{6} \\ -\frac{\pi}{2} - \arctan\left(\frac{5\omega}{6-\omega^2}\right), & \omega > \sqrt{6} \end{cases}$$

(e) Finn og plott  $y$  til  $u(t) = \sin(t)$ .

$$\begin{aligned} y(t) &= \operatorname{Im}(H(i) e^{it}) = \operatorname{Im}\left(\frac{2i}{5+i} (\cos(t) + i \sin(t))\right) = \operatorname{Im}\left(\left(\frac{1}{5} + \frac{1}{5}i\right) (\cos(t) + i \sin(t))\right) \\ &= \frac{1}{5} \sin(t) + \frac{1}{5} \cos(t). \end{aligned}$$

$$\begin{aligned} \text{ella } y(t) &= A \sin(t + \varphi(i)) = \frac{1}{5} \sin\left(t + \frac{\pi}{2} - \arctan(1)\right) = \frac{1}{5} \sin\left(t + \frac{\pi}{2} - \frac{\pi}{4}\right) \\ &= \frac{1}{5} \sin\left(t + \frac{\pi}{4}\right). \end{aligned}$$