Vector Spaces

- Ex1. State the zero vector and dimension of the following vector spaces
 - 1. \mathbb{R}^4 has $\underline{o} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ and $\dim(\mathbb{R}^4) = 4$.
 - 2. C^4 has $C = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ and $dim(C^4) = 4$.
 - 3. $C^{\circ}([0,1])$ has f(x) = 0 for all $x \in [0,1]$ and din $\left(C^{\circ}([0,1])\right) = \infty$.
 - 4. $R^{4\times2}$ has $c = \begin{bmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$ and $dim(R^{4\times2}) = 8$.
 - 5. $P_{y}(R)$ has $f_{QY} = 0$ for all $x \in \mathbb{R}$ and $dim(P_{y}(R)) = S$.
- Ex 2. Determine whether the systems are lin. dependent or independent.

 If dependent, then write one as a combination.
 - 1. (1, 2, 1, 0), (2, 7, 3, 1), $(3, 12, 5, 2) \in \mathbb{R}^{4}$. $-\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} + 2\begin{bmatrix} 2 \\ 7 \\ 3 \end{bmatrix} = \begin{bmatrix} 3 \\ 12 \\ 5 \\ 2 \end{bmatrix}$ The set of vectors is lin. dept.
 - 2. (1,i), $(1+i,-1+i) \in \mathbb{C}^2$. $(1+i) \begin{bmatrix} 1 \\ i \end{bmatrix} = \begin{bmatrix} 1+i \\ -1+i \end{bmatrix}$ The set of vectors is lin. dept.

$$\begin{bmatrix} 1 & 2 & 3 & 1 \\ 2 & 5 & -1 & 1 \\ -3 & 2 & -4 & -2 \\ \end{bmatrix} - 2R, \quad \Rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & -7 & -1 \\ 0 & 8 & 5 & 1 \\ \end{bmatrix} - 8R_{2}$$

$$\rightarrow \begin{bmatrix} 1 & 2 & 3 & 1 \\ 0 & 1 & -7 & -1 \\ 0 & 0 & 61 & 9 \end{bmatrix}$$
 The set of vectors is lin. indept.

$$4. \quad \begin{bmatrix} 1 & 2 & 0 \\ 1 & 1 & 1 \end{bmatrix}, \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 1 \end{bmatrix}, \begin{bmatrix} 2 & 5 & -2 \\ 3 & 3 & 2 \end{bmatrix} \in \mathbb{R}^{2\times 3}.$$

$$3\begin{bmatrix}1&2&0\\1&1&1\end{bmatrix}-\begin{bmatrix}1&1&2\\0&0&1\end{bmatrix}=\begin{bmatrix}2&5&-2\\3&3&2\end{bmatrix}$$

The set of vectors is lin. dept.

Ex 3. Given ((1,2,3), (-1,0,2), (1,6,a)), which value of a a) must be avoided in order for the vectors to be a basis for \mathbb{R}^3 ? See method 11.42.

$$\det \left(\begin{bmatrix} 1 & -1 & 1 \\ 2 & 0 & 6 \\ 3 & 2 & \alpha \end{bmatrix} \right) = 0 \iff -18 + 4 - (12 - 2a) = 0$$

$$4 = 13.$$

The value a=13 is to be avoided. For $a \in \mathbb{R} \setminus \{13\}$ the vectors span \mathbb{R}^3 , and there are only 3 of them.

b) Let
$$\underline{a}_1 = (1, -1, 2, 1), \ \underline{a}_2 = (0, 1, 1, 3), \ \underline{a}_3 = (1, -2, 2, -1),$$

 $\underline{a}_4 = (0, 1, -1, 3) \ \text{and} \ \underline{v} = (1, -2, 2, -3).$

Prove that (a1, -, a4) is a basis for R, and compete av.

$$\det \begin{pmatrix} \begin{bmatrix} 1 & 0 & 1 & 0 \\ -1 & 1 & -2 & 1 \\ 2 & 1 & 2 & -1 \\ 3 & -1 & 3 \end{bmatrix} \end{pmatrix} = \det \begin{pmatrix} \begin{bmatrix} 1 & -2 & 1 \\ 1 & -2 & -1 \\ 3 & -1 & 3 \end{bmatrix} \end{pmatrix} + \det \begin{pmatrix} \begin{bmatrix} -1 & 1 & 1 \\ 2 & 1 & -1 \\ 1 & 3 & 3 \end{bmatrix} \end{pmatrix}$$

$$= -6+6-1-(-6+1-6) - 3-1+6-(1+3+6)$$

$$= 10-8=2$$

The vectors are lin. indept. and there are 4 of them corresponding to $din(R^4)$, so they are a boxis.

The linear combination that yields a v is

$$2 \underline{a}_1 - \underline{a}_2 - \underline{a}_3 - \underline{a}_4 = \underline{a} \underline{V} = \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix}$$

Ez 4.

a) We have a basis for $P_2(R)$ given by vectors $P_1(x) = 1 + x^2$, $P_2(x) = -1 - x - 3x^2$, $P_3(x) = 6 + x + 5x^2$.

Determine wrt. p the vectors

$$Q_{1}(x) = P_{1}(x) - 2P_{2}(x) = \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} \qquad P_{1} \qquad P_{2} \qquad P_{3} \qquad Q$$

$$Q_{2}(x) = P_{1}(x) - P_{2}(x) = \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix} \qquad Q_{3} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} + b \cdot \begin{bmatrix} -1 \\ -1 \\ -3 \end{bmatrix} + c \cdot \begin{bmatrix} 6 \\ 1 \\ 5 \end{bmatrix} = \begin{bmatrix} q_{1} \\ q_{2} \\ q_{3} \end{bmatrix}$$

$$Q_3(x) = P_2(x) + P_3(x) = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$$

Given

with coordinates wrt. p

determine the basis vectors.

We have

$$\begin{bmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ -2 & -1 & 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} + 2R, \rightarrow \begin{bmatrix} 1 & 1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & 2 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix} - R_{3}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & 0 & | & -1 & -1 & 1 \\ 0 & 1 & 0 & | & 2 & 1 & -1 \\ 0 & 0 & 1 & | & 0 & 0 & 1 \end{bmatrix}$$

$$= \left\{ \begin{array}{cccc} P_{1} & P_{2} & P_{3} \end{array} \right\} = \left[\begin{array}{cccc} 3 & 2 & 5 \\ 2 & 1 & 0 \\ 7 & 4 & 2 \end{array} \right] \left[\begin{array}{ccccc} -1 & -1 & 1 \\ 2 & 1 & -1 \\ 0 & 0 & 1 \end{array} \right] = \left[\begin{array}{ccccc} 1 & -1 & 6 \\ 0 & -1 & 1 \\ 1 & -3 & 5 \end{array} \right]$$

Thus $P_1(z) = 1 + x^2$, $P_2(x) = -1 - x - 3x^2$ and $P_3(x) = 6 + x + 5x^2$.

Er S. W. Consider G.3. Do subspaces with dimension 6,1,2,3 or 4 exist?

The zero vector is a 0 dimensional subspace of G3.

One dimensional subspaces are any vector on the same line.

Vectors one the same plane represent a 2 dimensional subspace.

G3 is a 3 dimensional subspace of itself. No 4 dimensional subspace.

(b) In {a cers(x) + b sin(x) | $a,b \in \mathbb{R}$ } a subspace of $C(\mathbb{R})$? We use proposition 11.47. Clearly a cers(x) + b sin(x) $\in C(\mathbb{R})$. Let $f_1(x)$ and $f_2(x)$ be function of the above nature, then $f_1(x) + f_2(x) = (a_1 + a_2) \cos(x) + (b_1 + b_2) \sin(x) \in C(\mathbb{R})$

and $c \cdot f(x) = ca_1 \cos(x_1 + ca_2 \sin(x_2)) \in C^0(\mathbb{R}).$

Since the stability requirements are met, then we indeed have a subspace of C(R).

- c) Is $\left\{ \left(x_{1}, x_{2}, x_{3}, x_{4} \right) \middle| x_{1}, x_{2}, x_{3}, x_{4} = 0 \right\}$ a subspace of \mathbb{R}^{4} ?

 No, just observe $\begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \notin \left\{ \left(x_{1}, x_{2}, x_{3}, x_{4} \right) \middle| x_{1}, x_{2}, x_{3}, x_{4} = 0 \right\}.$
- Subset of Pr(R) with the root 1 in Pr(R). If a subspace, then determine a basis.

For f,g with 1 as a root, then $f+g \in P_2(R)$, and $(\alpha\cdot f+g)(1)=\alpha\cdot f(1)+g(1)=0$, so 11.47 is satisfied.

A basis for the subspace is the vectors $1-2^2$ and $x-x^2$.

e) Subset of P2(R) with double in P2(R).

No this isn't closed under addition.

Ex6. Explain why the solution is a subspace of R. State as dimension and besis.

$$\begin{bmatrix}
1 & 1 & -1 & 2 & -1 & 0 \\
0 & 1 & 3 & -1 & 2 & 0 \\
2 & 3 & 1 & 3 & 6 & 6
\end{bmatrix}
\rightarrow
\begin{bmatrix}
1 & 1 & -1 & 2 & -1 & 0 \\
0 & 1 & 3 & -1 & 2 & 0 \\
0 & 1 & 3 & -1 & 2 & 6
\end{bmatrix}
-R_{2}$$

$$\Rightarrow \begin{bmatrix} 1 & 0 & -4 & 3 & -3 & 0 \\ 0 & 1 & 3 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

$$\mathbf{z} = \mathbf{t}_{1} \begin{bmatrix} \mathbf{q} \\ -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \mathbf{t}_{2} \begin{bmatrix} -3 \\ 1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \mathbf{t}_{3} \begin{bmatrix} 3 \\ -2 \\ 0 \\ 0 \\ 1 \end{bmatrix} , \quad \mathbf{t}_{1}, \mathbf{t}_{2}, \mathbf{t}_{3} \in \mathbb{R}.$$

$$V = \begin{pmatrix} V_1 & V_2 & V_3 \end{pmatrix}$$

The set v is line indept. set of vectors in \mathbb{R}^5 . Linear combinations are solutions, hence v spans a subspace. It follows that $\dim(v) = 3$ and as defined v is a basis.

b) Show that $\underline{a}_{i} = (1,0,1,0,1,0)$ and $\underline{a}_{i} = (0,1,1,1,-1)$ span the same subspace of R^{6} as $\underline{b}_{i} = (4,-5,-1,-5,-1,5)$ and $\underline{b}_{2} = (-3,2,-1,2,-1,-2)$.

 $b_1 = 49, -59_2$ and $b_2 = -39, +29_2$ Also 9, and 9, are clearly lin. indept. by observing entry 1 and 2.

- Ex 7.

 a) "Meditation" about: A matrix is a vector is a vector is a matrix.

 Sure a matrix is a vectox, see example 11.26 for basis vectors of $\mathbb{R}^{2\times3}$.
 - b) Show linear independence of vectors.

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix} , \begin{bmatrix} 0 & -3 & 0 \\ 0 & 2 & 0 \\ 0 & -1 & 0 \end{bmatrix} , \begin{bmatrix} 0 & 0 & 1 \\ 0 & -2 & 0 \\ 3 & 0 & 0 \end{bmatrix} , \begin{bmatrix} 0 & 0 & 0 \\ -1 & 2 & -3 \\ 0 & 0 & 0 \end{bmatrix} .$$

Just follow example 11.39 and write out as traditional vectors. v1:=<1,0,0,0,-2,0,0,0,3>: v2:=<0,-3,0,0,2,0,0,-1,0>: v3:=<0,0,1,0,-2,0,3,0,0>: v4:=<0,0,0,1,2,-3,0,0,0>: A:=<v1|v2|v3|v4>: GaussianElimination(A):

c) We consider the subspace $U \subseteq \mathbb{R}^{3\times 3}$ spanned by the above vectors.

Show $\begin{bmatrix} 2 & -3 & 2 \\ -3 & 8 & -9 \\ -6 & -1 & 6 \end{bmatrix} \in U$ for some bosis and determine coords.

Let $u = (\underline{u}_1, \underline{u}_2, \underline{u}_3, \underline{u}_4)$ be the above basis in its respective order. $2\underline{u}_1 + \underline{u}_2 - 2\underline{u}_2 + 3\underline{u}_3 = \begin{bmatrix} 2\\1\\-2\\3 \end{bmatrix}$ yields $\begin{bmatrix} 2 & -3 & 2\\-3 & 8 & -9\\1 & -1 & 4 \end{bmatrix}$ in u.

d) Find $\underline{v} \in \mathbb{R}^{3 \times 3}$ such that $\underline{v} \notin U$.

One such choice is $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$.

- Ex8. In $P_2(R)$ we're given $P_1(x) = 1 3x + 2x^2, P_2(x) = 1 + x + 4x^2, P_3(x) = 1 7x.$
- Show $(P_{(\alpha)}, P_{2}(\alpha))$ is a besis for spon $\{P_{(\alpha)}, P_{3}(\alpha), P_{3}(\alpha)\}$. $P_{1} \neq c \cdot P_{2}$ so these are lin. indept. Further $P_{3}(\alpha) = 2P_{1}(\alpha) - P_{2}(\alpha)$ So $(P_{1}(\alpha), P_{2}(\alpha))$ indeed is a basis for spon $\{P_{1}(\alpha), P_{3}(\alpha)\}$.
- (b) Check if $Q_1 \alpha_1 = 1 + 5x + 9x^2$ and $Q_2(x) = 3 x + 10x^2$ belong to span $\{P_1(x), P_2(x), P_3(x)\}_1$ and if so determine coordinates in $(P_1(x), P_2(x))$.

$$\begin{bmatrix}
1 & 1 & 1 & 1 \\
-3 & 1 & 5 \\
2 & 4 & 9
\end{bmatrix}
\xrightarrow{3}
\begin{bmatrix}
1 & 1 & 1 \\
0 & 1 & 2 \\
0 & 2 & 4
\end{bmatrix}$$

 $Q_{2}(x) = P_{1}(x) + 2P_{2}(x) \quad \text{So in coords} \quad pQ_{2}(x) = \begin{bmatrix} 1 \\ 2 \end{bmatrix}.$ c) State the simplest besis for span $\{P_{1}(x), P_{2}(x), P_{3}(x), Q_{1}(x)\}$.
This is the monomial besis $(1, x, x^{2})$.