401.
$$\begin{cases} \left(\frac{\dot{x}_{1}}{\dot{x}_{1}}\right) = \left(\frac{2}{o} + \frac{3}{4}\right) \left(\frac{x_{1}}{x_{1}}\right) + \left(\frac{2}{o}\right) u(t) \\ y = \left(3 + 4\right) \left(\frac{x_{1}}{x_{2}}\right) \end{cases}$$

(a) Find
$$H(s)$$
. $(A-sI) = \begin{pmatrix} 2-s & 3 \\ 0 & 4-s \end{pmatrix}$, $(A-sI)^{-1} = \frac{1}{(2-s)(4-s)} \begin{pmatrix} 4-s & -3 \\ 0 & 2-s \end{pmatrix}$.

$$H(s) = -(3 + 4) \frac{1}{(2-s)(4-s)} \begin{pmatrix} 4-s & -3 \\ 0 & 2-s \end{pmatrix} \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$= \frac{1}{(2-s)(4-s)} \cdot (-(3 + 4)) \begin{pmatrix} 8-2s \\ 0 \end{pmatrix} = \frac{1}{(2-s)(4-s)} \cdot (6s-24)$$

$$= \frac{-6(4-s)}{(2-s)(4-s)} = \frac{6}{s-2} , s \notin \{2,4\}.$$

$$H(5) = \frac{6}{5^{-2}} = 2 = 9$$
 $y(t) = H(5) e^{5t} = 2e^{5t}$.

402.
$$\begin{cases} \frac{dx}{dt} = \begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix} x(t) + \begin{pmatrix} 0 \\ 1 \end{pmatrix} u(t) \\ y(t) = x_2(t)$$

(i) Finn H(s).
$$A-sI=\begin{pmatrix} -s & 1 \\ 0 & 1-s \end{pmatrix}, \quad (A-sI)^{-1}=\frac{1}{s(s-1)}\begin{pmatrix} 1-s & -1 \\ 0 & -s \end{pmatrix}.$$

$$H(s) = -(0 | 1) \frac{1}{s(s-1)} {\binom{1-s-1}{s-1}} {\binom{0}{s}} = \frac{-1}{s(s-1)} \cdot (-s)$$

$$= \frac{1}{s-1} + s \notin \{0, 1\}.$$

$$H(-1) = \frac{1}{-1-1} = -\frac{1}{2} = y(t) = H(-1)e^{-t} = -\frac{1}{2}e^{-t}$$

411. Let
$$\begin{cases} \dot{x}_1 = x_3 \\ \dot{x}_2 = 2x_1 - x_3 \\ \dot{x}_3 = -x_1 \end{cases}$$

(iii) Er systemið stabilt?

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 2 & 0 & -1 \\ -1 & 0 & 0 \end{bmatrix} \quad \text{hereon eginvirolini} \quad \lambda = 0 \quad \lambda = \pm i \quad \text{fylgi (i), sum of the have}$$

multiplicitetin p=1=q. Per sedning 2.34 er systemið stabilt, tí $Re(\lambda)=0$ fyri all λ og algebraiski multipliciteturin er eins við tann geometriska.

(iv) Er systemið asymptodiskt stabilt?

Setningur 2.36 sigur, at systemid bert er asymptodiskt stabilt, um $Re(\lambda) < 0$ fyri all eginvirðir λ . Vit hava fyri all okkeru λ , at $Re(\lambda) = 0$, so systemid er ikki asymptodiskt stabilt.

417.
$$\begin{cases} \frac{d\varkappa}{dt} = \begin{pmatrix} 2 & -1 \\ 3 & 1 \end{pmatrix} \varkappa(t) + \begin{pmatrix} 0 \\ -1 \end{pmatrix} \varkappa(t) \\ y(t) = 2 \varkappa(t) - \varkappa_z(t) \end{cases}$$

(i) Finn H(s).
$$(A-sI) = \begin{pmatrix} 2-s & -1 \\ 3 & 1-s \end{pmatrix}, \quad (A-sI)^{-1} = \frac{1}{(2-s)(1-s)+5} \begin{pmatrix} 1-s & 1 \\ -3 & 2-s \end{pmatrix}.$$

$$H(s) = \frac{1}{s^2-3s+5} \quad (-2-1) \begin{pmatrix} 1-s & 1 \\ -3 & 2-s \end{pmatrix} \begin{pmatrix} 0 \\ -1 \end{pmatrix} \qquad det(A-sI) = 0 c \Rightarrow s = \frac{3\pm\sqrt{9-20}}{2} = \frac{3}{2} \cdot \frac{100}{2};$$

$$= \frac{1}{s^2-3s+5} \quad \left(2+(s-2)\right) = \frac{s}{s^2-3s+5} \quad 1 \leq 4\left\{\frac{3}{2} + \frac{111}{2}i\right\}.$$

$$H(i) = \frac{i}{i^2 - 3i + 5} = \frac{i}{-3i + 4} = \frac{i}{9 + 16} = -\frac{3}{25} + \frac{4}{25};$$

Vit fáa nú | Hú) | = $\sqrt{\frac{9}{25^2} + \frac{16}{25^2}} = \sqrt{\frac{25}{25^2}} = \frac{1}{5}$, arg (Hú) = arctan (- $\frac{4}{3}$ + π).

..
$$y(t) = \frac{1}{5} \cos\left(t + \arctan\left(-\frac{4}{3} + \pi\right)\right)$$

Anners við Re(H₀) e^{it}) = Re(
$$(-\frac{3}{25} + \frac{4}{25}i)$$
(cost) + i sint))
= $-\frac{3}{25}$ cos(t) - $\frac{4}{25}$ sint).

422. Kuma um systemið er stabilt ella asymptodiskt stabilt. Vit minna á, at eitt asymptodiskt stabilt system er stabilt.

(i)
$$\dot{z} = \begin{pmatrix} 1 & 3 \\ 3 & -2 \end{pmatrix} \times \det \left(A - \lambda I \right) = \left(1 - \lambda \right) \left(-2 - \lambda \right) - \lambda I = \lambda^{2} + \lambda - \lambda 3 = 0$$

$$c = \lambda = \frac{-1 \pm \sqrt{1 - 4(-23)}}{\lambda} = -\frac{1}{2} \pm \frac{\sqrt{93}}{2}.$$

Av tí at Re(2) > 0, so er systemið óstabilt per setning 2.34.

(ii)
$$\dot{x} = \begin{pmatrix} -1 & 1 & 0 \\ -\zeta & -1 & 1 \\ -\gamma & 0 & 1 \end{pmatrix} x$$

$$\det (A - \lambda I) = (-1 - \lambda)^{2} (1 - \lambda) - \frac{1}{4} + \frac{5}{5} (1 - \lambda) = 0$$

$$\angle = \lambda (\lambda^{2} + 2\lambda + 1)(1 - \lambda) - \frac{5}{5} \lambda - 2 = 0$$

$$\angle = \lambda - \lambda^{3} - \lambda^{2} + \lambda + 1 - \frac{5}{5} \lambda - 2 = 0$$

$$\angle = \lambda^{3} - \lambda^{2} - \frac{1}{4} \lambda - 1 = 0$$

$$\angle = \lambda^{3} + \lambda^{2} + \frac{1}{4} \lambda + 1 = 0$$

Koefficientornir ern allir meiri enn 0 og det $\binom{1}{4} = 3 > 0$, so per kerrollar 2.41 hava allar roturnar $\text{Re}(\lambda) < 0$.

Av ti at $\text{Re}(\lambda) < 0$ fyri oll eginvirði λ , so gevur setningur 2.36, at systemið er asymptodiskt stabilt.

(iii)
$$\dot{x} = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & -1 & -1 & -1 \\ -1 & 0 & -1 & -1 \\ 0 & 0 & 1 & 0 \end{pmatrix} x$$
, vit útvikla í fyrsta rað.

$$A - \lambda I = \begin{pmatrix} -\lambda & 0 & 0 & 1 \\ 0 & -1 - \lambda & -1 & -1 \\ -1 & 0 & -1 - \lambda & -1 \\ 0 & 0 & 1 & -\lambda \end{pmatrix}$$

$$dd(A - \lambda I) = -\lambda \cdot (c -1 - \lambda)^{2} \cdot (-\lambda) + (-1 - \lambda)$$

$$+(-1)^{2-1} (c -1 - \lambda)$$

$$= \lambda^{2} (\lambda^{2} + \lambda^{2} + \lambda + 1) - \lambda (-1 - \lambda)$$

Positivir koefficientar og

$$dd(\lambda - \lambda I) = -\lambda \cdot \left((-1 - \lambda)^2 \cdot (-\lambda) + (-1 - \lambda) \right)$$

$$+ (-1)^{2+4} \left(-1 - \lambda \right)$$

$$= \lambda^2 \left(\lambda^2 + 2\lambda + 1 \right) - \lambda \left(-1 - \lambda \right) + 1 + \lambda$$

$$= \lambda^4 + 2\lambda^3 + \lambda^2 + \lambda + \lambda^2 + 1 + \lambda$$

$$= \lambda^4 + 2\lambda^3 + \lambda^2 + \lambda + 1 + \lambda + 1$$

 $\det\begin{pmatrix} 2 & 2 \\ 1 & 2 \end{pmatrix} = 1 > 0 , \det\begin{pmatrix} 2 & 2 & 0 \\ 1 & 2 & 1 \\ 0 & 2 & 2 \end{pmatrix} = 8 - 4 - 4 = 0. \text{ Lat oblime } faa \quad \lambda \text{ vid } R_{e}(\lambda) = 0,$

tí korollar 2.42 sigur, at $Re(\lambda) < 0$ kann ei stadfestast.

$$det(A-\lambda T) = (\lambda^2+1)^2(1+\lambda)^2 \implies \lambda = \pm i \quad \forall \quad \lambda = -1$$

Systemið er stabilt per setning 2.34.

507. Lat
$$a \in \mathbb{R}$$
 og $\dot{z} = \begin{pmatrix} a & z \\ a & 1 \end{pmatrix} z$.

(i) Finn a, so at systemid er asymptodisket stabilt

$$\det (A - \lambda I) = (a - \lambda)(1 - \lambda) - 2a = \lambda^2 + a - \lambda - a\lambda - 2a$$
$$= \lambda^2 - (1 + a)\lambda - a = 0$$

Per korollar 2.40, so have returned best $Re(\lambda) < 0$, um koefficientaris

 $a_1 = -(1+\alpha) > 0$ og $a_2 = -\alpha > 0$. Her skal $\alpha < -1$, so at Re(α) < 0, og tå er systemið asymptodiskt stabilt per setning 2.36.

(ii) Kanna stabilitet fyri a=-1.

$$A = \begin{pmatrix} -1 & 2 \\ -1 & 1 \end{pmatrix} = \lambda \quad dct(A - \lambda 1) = \lambda^{2} + 1 = 0 \quad c = \lambda = \pm i.$$

Her er $Re(\lambda)=0$, men p=q=1, so systemit er stabilt per setning 2.34.

(iii) Kanna stabilitet fyri azo.

$$\det(A-\Omega I) = \lambda - (1+a)\lambda - a \quad \text{vid} \quad a \neq 0 \quad \text{genur} \quad \text{koefficienter}$$

$$a_1 = -(1+a) < 0 \quad \text{og} \quad a_2 = -a \neq 0.$$

Per lecrollar 2.40, so herur systemið ikki bert eginvirðir λ við Re(2)<0. Vit kunnn altso vátta at systemið ikki er asymptodiskt stabilt við setning 2.36. Vit vísa, at eitt eginvirði λ herur Re(λ)>0, so systemið er östabilt.

$$\lambda = \frac{1 + a^{-\frac{1}{2}} \sqrt{(1+a)^2 + 4a^2}}{2} = \frac{1}{2} + \frac{a}{2} + \frac{\sqrt{a^2 + 6a + 1}}{2}$$

Av tí at $a \ge 0$, so er $\lambda = \frac{1}{2} + \frac{a}{2} + \frac{\sqrt{a^2 + ba + 1}}{2} \ge \frac{1}{2}$ fyri all $a \ge 0$. Systemid er altso éstabill per setning 2.34.

4 30.
$$\begin{cases} \begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = \begin{pmatrix} -4 & 2 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 2 \\ -1 \end{pmatrix} u \\ y = x_1 \end{cases}$$

(a) Finn H(s).
$$(A-sI)^{-1} = \frac{1}{(-4-s)(-1-s)+2} \begin{pmatrix} -1-s & -2 \\ 1 & -4-s \end{pmatrix}$$

$$H(5) = \frac{-1}{(5+4)(s+1)+2} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} -1-s & -2 \\ 1 & -4-s \end{pmatrix} \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

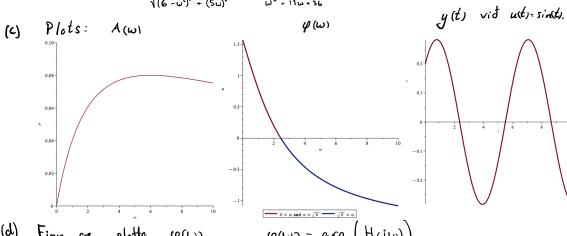
$$= \frac{-1}{s^2+5s+6} \begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} -2s \\ 6+s \end{pmatrix} \qquad 1 \qquad \frac{-5+1}{2} = \begin{cases} -2 \\ -3 \end{pmatrix}$$

$$= \frac{-1}{(5+2)(s+3)} \begin{pmatrix} -2s \end{pmatrix} = \frac{2s}{(5+2)(s+3)} \qquad s \notin \{-3,-2\}.$$

(b) Finn
$$A(\omega)$$
. $A(\omega) = |H(i\omega)|$

$$H(i\omega) = \frac{2i\omega}{(2+i\omega)(3+i\omega)} = \frac{2i\omega}{(6-\omega^{2})+5i\omega}$$

$$|H(i\omega)| = \frac{\sqrt{(2\omega)^{2}}}{\sqrt{(6-\omega^{2})^{2}+(5\omega)^{2}}} = \frac{2\omega}{\omega^{2}+13\omega+36} , \quad \omega > 0.$$



(d) Finn of plotta
$$\varphi(\omega)$$
. $\varphi(\omega) = arg(H(i\omega))$

$$H(i\omega) = \frac{2i\omega}{(6-\omega^2) + 5i\omega}$$

$$arg(H(i\omega)) = arg(\lambda i\omega) - arg((6-\omega^2) + 5i\omega) = \begin{cases} \frac{\pi}{2} - arctan(\frac{5\omega}{6-\omega^2}), & 0 < \omega < \sqrt{6} \\ -\frac{\pi}{2} - arctan(\frac{5\omega}{6-\omega^2}), & \omega > \sqrt{6} \end{cases}$$

$$y(t) = I_{m} \left(H(i) e^{it} \right) = I_{m} \left(\frac{2i}{5+5i} \left(\cos(t) + i \sin(t) \right) \right) = I_{m} \left(\left(\frac{1}{5} + \frac{1}{5} i \right) \left(\cos(t) + i \sin(t) \right) \right)$$

$$= \frac{1}{5} \sin(t) + \frac{1}{5} \cos(t).$$

$$y(t) = A(i) \sin(t + \varphi(i)) = \frac{1}{5} \sin(t + \frac{\pi}{2} - \arctan(1)) = \frac{1}{5} \sin(t + \frac{\pi}{2} - \frac{\pi}{4})$$

$$= \frac{1}{5} \sin(t + \frac{\pi}{4}).$$