

Eiginvörðir og eiginvektorar Vit sön, at tá ein línear afmyndan \underline{A} hefur rætningar, sum eru varðveittir upp til ein konstant λ ,

$$\underline{A}\underline{r} = \lambda \underline{r},$$

so er λ eiginvörðir og \underline{r} eiginvektorur hjá \underline{A} . Vit kunnu ikki altíð finna hesi, t.d. broytir ein rotation ella spegling allar rætningar hjá øllum vektorunum.

Tá eiginvörðir eru at finna, so eru hesi loysn hjá karakterlikningini

$$\det(\underline{A} - \lambda \underline{I}) = 0,$$

ella ekvivalent, at λ er rót í karakteristiska polynomid

$$p(\lambda) = \det(\underline{A} - \lambda \underline{I}).$$

Dømi Lat $\underline{A} = \begin{bmatrix} 2 & 3 \\ 2 & 1 \end{bmatrix}$, so er $p(\lambda) = \det(\underline{A} - \lambda \underline{I}) = \begin{vmatrix} 2-\lambda & 3 \\ 2 & 1-\lambda \end{vmatrix} = (2-\lambda)(1-\lambda) - 6 = \lambda^2 - 3\lambda - 4$

$$\lambda = \frac{-(-3) \pm \sqrt{(-3)^2 - 4 \cdot 1 \cdot (-4)}}{2} = \frac{3 \pm \sqrt{25}}{2} = \frac{3 \pm 5}{2} = \begin{cases} 4 \\ -1 \end{cases}$$

Vit seta altso $\lambda_1 = 4$ og $\lambda_2 = -1$. Nú er \underline{r} ein eiginvektorur, um hesin er loysn hjá

$$(\underline{A} - \lambda \underline{I}) \underline{r} = \underline{0}.$$

Set inn í tveimum umførum. $\lambda_1 = 4$:

$$\begin{bmatrix} 2-4 & 3 \\ 2 & 1-4 \end{bmatrix} \underline{r} = \begin{bmatrix} -2 & 3 \\ 2 & -3 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Leftrightarrow \underline{r} = c_1 \begin{bmatrix} 1 \\ \frac{2}{3} \end{bmatrix}, c_1 \in \mathbb{R}.$$

$\lambda_2 = -1$:

$$\begin{bmatrix} 2-(-1) & 3 \\ 2 & 1-(-1) \end{bmatrix} \underline{r} = \begin{bmatrix} 3 & 3 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} r_1 \\ r_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Leftrightarrow \underline{r} = c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}, c_2 \in \mathbb{R}.$$

Dømi 7.2 Lat $\underline{A} = \begin{bmatrix} 1 & 2 \\ 0 & 2 \end{bmatrix}$ $p(\lambda) = (1-\lambda)(2-\lambda) = 0 \Leftrightarrow \lambda_1 = 2$ ella $\lambda_2 = 1$.

$$\lambda_1 = 2: \begin{bmatrix} -1 & 2 \\ 0 & 0 \end{bmatrix} \underline{r}_1 = \underline{0} \Leftrightarrow \underline{r}_1 = c_1 \begin{bmatrix} 2 \\ 1 \end{bmatrix}, c_1 \in \mathbb{R}.$$

$$\lambda_2 = 1: \begin{bmatrix} 0 & 2 \\ 0 & 1 \end{bmatrix} \underline{r}_2 = \underline{0} \Leftrightarrow \underline{r}_2 = c_2 \begin{bmatrix} 1 \\ 0 \end{bmatrix}, c_2 \in \mathbb{R}.$$

Dæmi

Lat $A = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix}$, so er $p(\lambda) = \lambda^2 + 1 \neq 0$, um $\lambda \in \mathbb{R}$.

Lat nú $A = \begin{bmatrix} 1 & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$, so er $p(\lambda) = (1-\lambda)^2 = 0 \Leftrightarrow \lambda = 1$.

Vit siga, at $\lambda_1 = \lambda_2 = 1$ er dupultrót í $p(\lambda)$, ella at rötin hefur ein algebraískan multiplicitet á 2.

$$(A - I) \underline{r} = \underline{0} \Leftrightarrow \begin{bmatrix} 0 & \frac{1}{2} \\ 0 & 0 \end{bmatrix} \underline{r} = \underline{0} \Leftrightarrow \underline{r} = c \begin{bmatrix} 1 \\ 0 \end{bmatrix}, c \in \mathbb{R}.$$

Dæmi 7.3 Lat $A = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix}$, so er $p(\lambda) = (\frac{1}{2} - \lambda)^2 - \frac{1}{4} = \lambda^2 - \lambda = \lambda(\lambda - 1)$

$$p(\lambda) = 0 \Leftrightarrow \lambda_1 = 1 \vee \lambda_2 = 0.$$

$$\lambda_1 = 1: \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix} \underline{r}_1 = \underline{0} \Leftrightarrow \underline{r}_1 = c_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}, c_1 \in \mathbb{R}.$$

$$\lambda_2 = 0: A \underline{r}_2 = \underline{0} \Leftrightarrow \underline{r}_2 = c_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix}, c_2 \in \mathbb{R}.$$

Symmetriskar Gividd, at $A = A^T$, so finna vit tvey reel eginvirdi og vit matricur fúa gjørt eigendekomposition av A :

$$A = R \Lambda R^{-1}.$$

Vit hava

$$(a - \lambda)(d - \lambda) - c^2 = 0$$

$$\Leftrightarrow (a - \lambda)(d - \lambda) - c^2 = 0$$

$$\Leftrightarrow \lambda - (a + d)\lambda + (ad - c^2) = 0$$

$$\Leftrightarrow \lambda = \frac{a + d \pm \sqrt{(a + d)^2 - 4 \cdot (ad - c^2)}}{2}$$

$$A = \begin{bmatrix} a & c \\ c & d \end{bmatrix}$$

$$\begin{aligned} & a^2 + 2ad + d^2 - 4ad + 4c^2 \\ &= a^2 + d^2 - 2ad + 4c^2 \\ &= (a - d)^2 + 4c^2 > 0 \end{aligned}$$

So eginvirdini eru reel!

Givst

$$\underline{A} \underline{r}_1 = \lambda_1 \underline{r}_1$$

$$\underline{A} \underline{r}_2 = \lambda_2 \underline{r}_2$$

har \underline{A} er symmetrisk, so er

$$(\underline{A} \underline{r}_1)^T = (\lambda_1 \underline{r}_1)^T$$

$$\Leftrightarrow \underline{r}_1^T \underline{A}^T = \lambda_1 \underline{r}_1^T$$

$$\Leftrightarrow \underline{r}_1^T \underline{A} = \lambda_1 \underline{r}_1^T$$

$$\Leftrightarrow \underline{r}_1^T \underline{A} \underline{r}_2 = \lambda_1 \underline{r}_1^T \underline{r}_2$$

og sama við seinni líkningina

$$\underline{r}_1^T \underline{A} \underline{r}_2 = \lambda_2 \underline{r}_1^T \underline{r}_2$$

Nú er

$$\lambda_1 \underline{r}_1^T \underline{r}_2 = \lambda_2 \underline{r}_1^T \underline{r}_2$$

$$(\lambda_1 - \lambda_2) \underline{r}_1^T \underline{r}_2 = 0 \quad \rightarrow \quad \underline{r}_1^T \underline{r}_2 = 0$$

$$\text{Let } \underline{R} = \begin{bmatrix} \underline{r}_{11} & \underline{r}_{21} \\ \underline{r}_{21} & \underline{r}_{22} \end{bmatrix}, \text{ so er}$$

$$\underline{A} \underline{R} = [\lambda_1 \underline{r}_1, \lambda_2 \underline{r}_2]$$

$$\text{Við } \underline{R} = [\underline{r}_1, \underline{r}_2] \text{ og } \underline{\Lambda} = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}, \text{ so er}$$

$$\underline{A} \underline{R} = \underline{R} \underline{\Lambda} \Leftrightarrow \underline{A} = \underline{R} \underline{\Lambda} \underline{R}^{-1}$$

Vit normalisera altíð \underline{r}_1 og \underline{r}_2 , so

$$\underline{r}_1^T \underline{r}_1 = 1 \quad \text{og} \quad \underline{r}_2^T \underline{r}_2 = 1,$$

$$\underline{r}_1^T \underline{r}_2 = 0 \quad \text{og} \quad \underline{r}_2^T \underline{r}_1 = 0$$

$$\text{So vit fáa } \underline{R}^T \underline{R} = \underline{I} \quad \text{og} \quad \underline{R}^{-1} = \underline{R}^T.$$

$$\text{Eisini er } \underline{\Lambda} = \underline{R}^{-1} \underline{A} \underline{R}.$$

2D \rightarrow 3D Vit seta $e_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ og $e_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$ at vera standardbasis hjó \mathbb{R}^3 .

Longd \bar{a} $\underline{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

Krossprodukt \wedge

$$v = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix} \quad \text{og} \quad w = \begin{bmatrix} 0 \\ 3 \\ 4 \end{bmatrix}$$