1 Numerical solution of underlying equations of OTIS-R

The numerical solution of the equations underlying OTIS-R is derived analogue to the numerical solution of the equations underlying OTIS proposed by Runkel (1998), with small changes due to the terms added for OTIS-R.

1.1 Differential equations

$$\frac{\partial C}{\partial t} = -\frac{Q}{A}\frac{\partial C}{\partial x} + \frac{1}{A}\frac{\partial}{\partial x}\left(AD\frac{\partial C}{\partial x}\right) + \frac{q_I}{A}(C_I - C) - \lambda C - \frac{k}{d}C + \alpha(C_H - C) + \rho\hat{\lambda}(C_{\text{sed}} - K_d C) \tag{1}$$

$$\frac{dC_H}{dt} = \alpha\frac{A}{A_H}(C - C_H) - \lambda_H C_H + \gamma + \hat{\lambda}_H(\hat{C}_H - C_H) \tag{2}$$

$$\frac{dC_{\text{sed}}}{dt} = \hat{\lambda}(K_d C - C_{\text{sed}}) \tag{3}$$

1.2 Steady-state equations

condition: $\frac{\partial C}{\partial t} = 0$, $\frac{dC_H}{dt} = 0$, $\frac{dC_{\text{sed}}}{dt} = 0$

equation (1) becomes:

$$0 = -\frac{Q}{A}\frac{\partial C}{\partial x} + \frac{1}{A}\frac{\partial}{\partial x}\left(AD\frac{\partial C}{\partial x}\right) + \frac{q_I}{A}(C_I - C) - \lambda C - \frac{k}{d}C + \alpha(C_H - C) + \rho\hat{\lambda}(C_{\text{sed}} - K_d C) \tag{4}$$

equation (2) becomes:

$$0 = \alpha\frac{A}{A_H}(C - C_H) - \lambda_H C_H + \hat{\lambda}_H(\hat{C}_H - C_H) \tag{5}$$

$$0 = \alpha\frac{A}{A_H}C - \alpha\frac{A}{A_H}C_H - \lambda_H C_H + \gamma + \hat{\lambda}_H\hat{C}_H - \hat{\lambda}_H C_H$$

$$0 = \alpha\frac{A}{A_H}C + \gamma + \hat{\lambda}_H\hat{C}_H - \left(\alpha\frac{A}{A_H} + \lambda_H + \hat{\lambda}_H\right)C_H$$

$$\left(\alpha\frac{A}{A_H} + \lambda_H + \hat{\lambda}_H\right)C_H = \alpha\frac{A}{A_H}C + \gamma + \hat{\lambda}_H\hat{C}_H$$

$$C_H = \frac{\alpha\frac{A}{A_H}C + \gamma + \hat{\lambda}_H\hat{C}_H}{\alpha\frac{A}{A_H} + \lambda_H + \hat{\lambda}_H}$$

$$\boxed{C_H = \frac{\alpha AC + \gamma A_H + \hat{\lambda}_H\hat{C}_H A_H}{\alpha A + \lambda_H A_H + \hat{\lambda}_H A_H}} \tag{6}$$

equation (3) becomes:

$$
\begin{aligned}
0 &= \hat{\lambda}(K_d C - C_{\text{sed}}) && (7)\\
0 &= \hat{\lambda} K_d C - \hat{\lambda} C_{\text{sed}}\\
\boxed{C_{\text{sed}} = K_d C} & && (8)
\end{aligned}
$$

1.3 Numerical solution - nonequilibrium

Finite differences

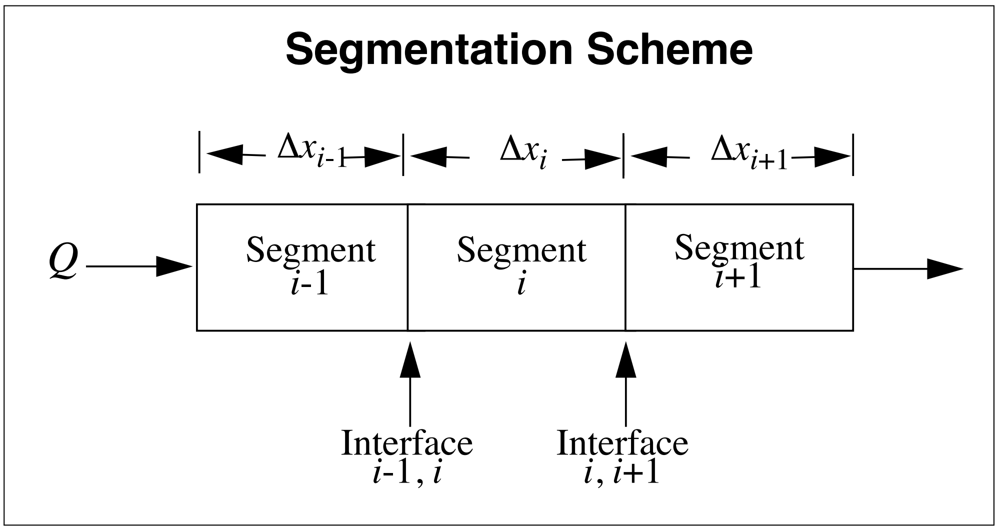

Figure 1: Segmentation scheme for the finite differences method. Image from Runkel (1998).

Using the finite differences approximation illustrated in Figure 1 Runkel (1998), equation (1) becomes:

$$
\begin{aligned}
\frac{dC}{dt} = &-\left(\frac{Q}{A}\right)_i \left(\frac{C_{i+1} - C_{i-1}}{2\Delta x}\right) + \frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1} - C_i) - (AD)_{i-1,i}(C_i - C_{i-1})}{\Delta x^2}\right)\\
&+ \frac{q_I}{A_i}(C_I - C_i) - \lambda C_i - \frac{k}{d_i} C_i + \alpha(C_H - C_i) + \rho\hat{\lambda}(C_{\text{sed}} - K_d C_i) \qquad (9)
\end{aligned}
$$

The Crank-Nicolson method for the main channel concentration

Applying the Crank-Nicolson method, the time derivative of C becomes:

$$\frac{dC}{dt} = \frac{C_i^{j+1} - C_i^j}{\Delta t} \tag{10}$$

where j is the current time and $j+1$ a future time. equation (9) then becomes:

$$\frac{C_i^{j+1} - C_i^j}{\Delta t} = \frac{G[C, C_H, C_{\text{sed}}]^{j+1} + G[C, C_H, C_{\text{sed}}]^j}{2} \tag{11}$$

where:

$$G[C, C_H, C_{\text{sed}}] = -\left(\frac{Q}{A}\right)_i \left(\frac{C_{i+1} - C_{i-1}}{2\Delta x}\right) + \frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1} - C_i) - (AD)_{i-1,i}(C_i - C_{i-1})}{\Delta x^2}\right) + \frac{q_I}{A_i}(C_I - C_i) - \lambda C_i - \frac{k}{d_i}C_i + \alpha(C_H - C_i) + \rho\hat{\lambda}(C_{\text{sed}} - K_d C_i)$$

then:

$$\begin{aligned}\frac{C_i^{j+1} - C_i^j}{\Delta t} =& \frac{1}{2}\Bigg[-\left(\frac{Q}{A}\right)_i^{j+1}\left(\frac{C_{i+1}^{j+1} - C_{i-1}^{j+1}}{2\Delta x}\right) \\ &+ \frac{1}{A_i^{j+1}}\left(\frac{(AD)_{i,i+1}^{j+1}(C_{i+1}^{j+1} - C_i^{j+1}) - (AD)_{i-1,i}^{j+1}(C_i^{j+1} - C_{i-1}^{j+1})}{\Delta x^2}\right) \\ &+ \frac{q_I^{j+1}}{A_i^{j+1}}(C_I^{j+1} - C_i^{j+1}) - \lambda C_i^{j+1} - \frac{k}{d_i^{j+1}}C_i^{j+1} + \alpha(C_H^{j+1} - C_i^{j+1}) \\ &+ \rho\hat{\lambda}(C_{\text{sed}}^{j+1} - K_d C_i^{j+1}) + G[C, C_H, C_{\text{sed}}]^j\Bigg]\end{aligned} \tag{12}$$

Shifting all known quantities in equation (12) on the right side and all unknown quantities on the left side leads to:

$$\begin{aligned}C_i^{j+1} - \frac{\Delta t}{2}\Bigg[&-\left(\frac{Q}{A}\right)_i^{j+1}\left(\frac{C_{i+1}^{j+1} - C_{i-1}^{j+1}}{2\Delta x}\right) \\ &+ \frac{1}{A_i^{j+1}}\left(\frac{(AD)_{i,i+1}^{j+1}(C_{i+1}^{j+1} - C_i^{j+1}) - (AD)_{i-1,i}^{j+1}(C_i^{j+1} - C_{i-1}^{j+1})}{\Delta x^2}\right) \\ &- \frac{q_I^{j+1}}{A_i^{j+1}}C_i^{j+1} - \lambda C_i^{j+1} - \frac{k}{d_i^{j+1}}C_i^{j+1} - \alpha C_i^{j+1} - \rho\hat{\lambda}K_d C_i^{j+1}\Bigg] \\ &= C_i^j + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}}C_I^{j+1} + \alpha C_H^{j+1} + \rho\hat{\lambda}C_{\text{sed}}^{j+1} + G[C, C_H, C_{\text{sed}}]^j\right]\end{aligned}$$

$$\begin{aligned}&\left(1+\frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha + \rho\hat{\lambda}K_d\right]\right)C_i^{j+1} - \frac{\Delta t}{2}\Bigg[-\left(\frac{Q}{A}\right)_i^{j+1}\left(\frac{C_{i+1}^{j+1} - C_{i-1}^{j+1}}{2\Delta x}\right) \\ &\quad + \frac{1}{A_i^{j+1}}\left(\frac{(AD)_{i,i+1}^{j+1}(C_{i+1}^{j+1} - C_i^{j+1}) - (AD)_{i-1,i}^{j+1}(C_i^{j+1} - C_{i-1}^{j+1})}{\Delta x^2}\right)\Bigg] \\ &\quad = C_i^j + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}}C_I^{j+1} + \alpha C_H^{j+1} + \rho\hat{\lambda}C_{\text{sed}}^{j+1} + G[C, C_H, C_{\text{sed}}]^j\right]\end{aligned} \tag{13}$$

Grouping equation (13) leads to:

$$\boxed{E_i C_{i-1}^{j+1} + F_i C_i^{j+1} + G_i C_{i+1}^{j+1} = R_i} \tag{14}$$

where:

$$E_i C_{i-1}^{j+1} = -\frac{\Delta t}{2}\left[-\left(\frac{Q}{A}\right)_i^{j+1}\left(\frac{-C_{i-1}^{j+1}}{2\Delta x}\right) + \frac{1}{A_i^{j+1}}\left(\frac{-(AD)_{i-1,i}^{j+1}(-C_{i-1}^{j+1})}{\Delta x^2}\right)\right]$$

$$E_i C_{i-1}^{j+1} = -\frac{\Delta t}{2A_i^{j+1}\Delta x}\left(\frac{Q_i^{j+1}C_i^{j+1}}{2} + \frac{(AD)_{i-1,i}^{j+1}C_{i-1}^{j+1}}{\Delta x}\right)$$

$$\boxed{E_i = -\frac{\Delta t}{2A_i^{j+1}\Delta x}\left(\frac{Q_i^{j+1}}{2} + \frac{(AD)_{i-1,i}^{j+1}}{\Delta x}\right)} \tag{15}$$

$$\begin{aligned} F_i C_i^{j+1} =& \left(1 + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha + \rho\hat{\lambda}K_d\right]\right)C_i^{j+1} \\ &- \frac{\Delta t}{2}\left[\frac{1}{A_i^{j+1}}\frac{(AD)_{i,i+1}^{j+1}(-C_i^{j+1}) - (AD)_{i-1,i}^{j+1}C_i^{j+1}}{\Delta x^2}\right] \\ F_i C_i^{j+1} =& \left(1 + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha + \rho\hat{\lambda}K_d\right]\right)C_i^{j+1} \\ &+ \frac{\Delta t}{2}\left[\frac{(AD)_{i,i+1}^{j+1} + (AD)_{i-1,i}^{j+1}}{A_i^{j+1}\Delta x^2}\right]C_i^{j+1} \\ F_i =& 1 + \frac{\Delta t}{2}\left(\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha + \rho\hat{\lambda}K_d + \frac{(AD)_{i,i+1}^{j+1} + (AD)_{i-1,i}^{j+1}}{A_i^{j+1}\Delta x^2}\right) \end{aligned} \tag{16}$$

$$G_i C_{i+1}^{j+1} = -\frac{\Delta t}{2}\left(-\left(\frac{Q}{A}\right)_i^{j+1}\frac{C_{i+1}^{j+1}}{2\Delta x} + \frac{1}{A_i^{j+1}}\frac{(AD)_{i,i+1}^{j+1}C_{i+1}^{j+1}}{\Delta x^2}\right)$$

$$\boxed{G_i = \frac{\Delta t}{2A_i^{j+1}\Delta x}\left(\frac{Q_i^{j+1}}{2} - \frac{(AD)_{i,i+1}^{j+1}}{\Delta x}\right)} \tag{17}$$

$$R_i = C_i^j + \frac{\Delta t}{2}\left(\frac{q_I^{j+1}}{A_i^{j+1}}C_I^{j+1} + \alpha C_H^{j+1} + \rho\hat{\lambda}C_{\text{sed}}^{j+1} + G[C, C_H, C_{\text{sed}}]^j\right) \tag{18}$$

The Crank-Nicolson method for the hyporheic zone and streamed sediments

Applying the Crank-Nicolson method to equation (2) leads to:

$$\begin{aligned} \frac{C_H^{j+1} - C_H^j}{\Delta t} =& \frac{\left(\alpha\frac{A}{A_H}(C - C_H) - \lambda_H C_H + \gamma + \hat{\lambda}(\hat{C}_H - C_H)\right)^{j+1}}{2} \\ &+ \frac{\left(\alpha\frac{A}{A_H}(C - C_H) - \lambda_H C_H + \gamma + \hat{\lambda}(\hat{C}_H - C_H)\right)^{j}}{2} \end{aligned} \tag{19}$$

Solving equation (19) for C_H^{j+1} leads to:

$$
\begin{aligned}
C_H^{j+1} - C_H^j =& \frac{\Delta t}{2} \left(\alpha \frac{A}{A_H} C^{j+1} - \alpha \frac{A}{A_H} C_H^{j+1} - \lambda_H C_H^{j+1} + \gamma \right. \\
& + \hat{\lambda}_H \hat{C}_H - \hat{\lambda}_H C_H^{j+1} + \alpha \frac{A}{A_H} C^j - \alpha \frac{A}{A_H} C_H^j \\
& \left. - \lambda_H C_H^j + \gamma + \hat{\lambda}_H \hat{C}_H - \hat{\lambda}_H C_H^j \right) \\
0 =& \frac{\Delta t}{2} \alpha \frac{A}{A_H} C^{j+1} - \frac{\Delta t}{2} \alpha \frac{A}{A_H} C_H^{j+1} - \frac{\Delta t}{2} \lambda_H C_H^{j+1} \\
& + \frac{\Delta t}{2} \gamma + \frac{\Delta t}{2} \hat{\lambda}_H \hat{C}_H - \frac{\Delta t}{2} \hat{\lambda}_H C_H^{j+1} \\
& + \frac{\Delta t}{2} \alpha \frac{A}{A_H} C^j - \frac{\Delta t}{2} \alpha \frac{A}{A_H} C_H^j - \frac{\Delta t}{2} \lambda_H C_H^j \\
& + \frac{\Delta t}{2} \gamma + \frac{\Delta t}{2} \hat{\lambda}_H \hat{C}_H - \frac{\Delta t}{2} \hat{\lambda}_H C_H^j \\
0 =& \frac{\Delta t}{2} \alpha \frac{A}{A_H} C^{j+1} + \frac{\Delta t}{2} \gamma + \frac{\Delta t}{2} \gamma + \frac{\Delta t}{2} \hat{\lambda}_H \hat{C}_H \\
& + \frac{\Delta t}{2} \hat{\lambda}_H \hat{C}_H + \frac{\Delta t}{2} \alpha \frac{A}{A_H} C^j \\
& + \left(-\frac{\Delta t}{2} \alpha \frac{A}{A_H} - \frac{\Delta t}{2} \lambda_H - \frac{\Delta t}{2} \hat{\lambda}_H + 1 \right) C_H^j \\
& - \left(\frac{\Delta t}{2} \alpha \frac{A}{A_H} + \frac{\Delta t}{2} \lambda_H + \frac{\Delta t}{2} \hat{\lambda}_H + 1 \right) C_H^{j+1} \\
\left(\Delta t \alpha \frac{A}{A_H} + \Delta t \lambda_H + \Delta t \hat{\lambda}_H + 2 \right) C_H^{j+1} =& \Delta t \alpha \frac{A}{A_H} C^{j+1} + 2 \Delta t \gamma + 2 \Delta t \hat{\lambda}_H \hat{C}_H + \Delta t \alpha \frac{A}{A_H} C^j \\
& + 2 \left(2 - \Delta t \alpha \frac{A}{A_H} - \Delta t \lambda_H - \Delta t \hat{\lambda}_H \right) C_H^j
\end{aligned}
$$

$$
C_H^{j+1} = \frac{\left(2 - \Delta t \alpha \frac{A}{A_H} - \Delta t \lambda_H - \Delta t \hat{\lambda}_H \right) C_H^j + \Delta t \alpha \frac{A}{A_H} C^{j+1} + \Delta t \alpha \frac{A}{A_H} C^j + 2 \Delta t \hat{\lambda}_H \hat{C}_H + 2 \Delta t \gamma}{2 + \Delta t \alpha \frac{A}{A_H} + \Delta t \lambda_H + \Delta t \hat{\lambda}_H} \tag{20}
$$

With $\mathrm{GAM} = \frac{\alpha \Delta t A}{A_H}$, equation (20) becomes:

$$
\boxed{C_H^{j+1} = \frac{\left(2 - \mathrm{GAM}^j - \Delta t \lambda_H - \Delta t \hat{\lambda}_H \right) C_H^j + \mathrm{GAM}^{j+1} C^{j+1} + \mathrm{GAM}^j C^j + 2 \Delta t \hat{\lambda}_H \hat{C}_H + 2 \Delta t \gamma}{2 + \mathrm{GAM}^{j+1} + \Delta t \lambda_H + \Delta t \hat{\lambda}_H}} \tag{21}
$$

Applying the Crank-Nicolson method to equation (3) leads to:

$$\frac{C_{\text{sed}}^{j+1} - C_{\text{sed}}^{j}}{\Delta t} = \frac{\left(\hat{\lambda}(K_d C - C_{\text{sed}})\right)^{j+1} \left(\hat{\lambda}(K_d C - C_{\text{sed}})\right)^{j}}{2}$$

$$\boxed{C_{\text{sed}}^{j+1} = \frac{(2 - \Delta t\hat{\lambda})C_{\text{sed}} + \Delta t\hat{\lambda}K_d(C^j + C^{j+1})}{2 + \Delta t\hat{\lambda}}} \tag{22}$$

Decoupling the main channel, hyporheic zone and streambed sediment equations

Substituting equation (21) and equation (20) into equation (18):

$$\begin{aligned} R_i' =& C_i^j + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}}C_I^{j+1}\right. \\ &+ \alpha\frac{\left(2 - \text{GAM}^j - \Delta t\lambda_H - \Delta t\hat{\lambda}_H\right)C_H^j + \text{GAM}^{j+1}C^{j+1} + \text{GAM}^jC^j + 2\Delta t\hat{\lambda}_H\hat{C}_H + 2\Delta t\gamma}{2 + \text{GAM}^{j+1} + \Delta t\lambda_H + \Delta t\hat{\lambda}_H} \\ &\left. + \rho\hat{\lambda}\frac{(2 - \Delta t\hat{\lambda})C_{\text{sed}^j} + \Delta t\hat{\lambda}K_d(C^j + C^{j+1})}{2 + \Delta t\hat{\lambda}} + G[C, C_H, C_{\text{sed}}]^j\right] \end{aligned} \tag{23}$$

Moving the terms containing C_i^{j+1} in equation (23) to equation (16), leads to the new F_i' and R_i'':

$$\begin{aligned} F_i' =& 1 + \frac{\Delta t}{2}\left(\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha + \rho\hat{\lambda}K_d + \frac{(AD)_{i,i+1}^{j+1} + (AD)_{i-1,i}^{j+1}}{A_i^{j+1}\Delta x^2}\right) \\ &- \alpha\frac{\Delta t}{2}\left(\frac{\text{GAM}^{j+1}}{2 + \text{GAM}^{j+1} + \Delta t\lambda_H + \Delta t\hat{\lambda}_H}\right) - \frac{\Delta t}{2}\rho\hat{\lambda}\left(\frac{\Delta t\hat{\lambda}K_d}{2 + \Delta t\hat{\lambda}}\right) \end{aligned}$$

$$\boxed{\begin{aligned} F_i' =& 1 + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}} + \lambda + \frac{k}{d_i^{j+1}} + \alpha\left(1 - \frac{\text{GAM}^{j+1}}{2 + \text{GAM}^{j+1} + \Delta t\lambda_H + \Delta t\hat{\lambda}_H}\right)\right. \\ &\left. + \rho\hat{\lambda}K_d\left(1 - \frac{\Delta t\hat{\lambda}}{2 + \Delta t\hat{\lambda}}\right) + \frac{(AD)_{i,i+1}^{j+1} + (AD)_{i-1,i}^{j+1}}{A_i^{j+1}\Delta x^2}\right] \end{aligned}} \tag{24}$$

$$\boxed{\begin{aligned} R_i'' =& C_i^j + \frac{\Delta t}{2}\left[\frac{q_I^{j+1}}{A_i^{j+1}}C_I^{j+1}\right. \\ &+ \alpha\frac{\left(2 - \text{GAM}^j - \Delta t\lambda_H - \Delta t\hat{\lambda}_H\right)C_H^j + \text{GAM}^jC^j + 2\Delta t\hat{\lambda}_H\hat{C}_H + 2\Delta t\gamma}{2 + \text{GAM}^{j+1} + \Delta t\lambda_H + \Delta t\hat{\lambda}_H} \\ &\left. + \rho\hat{\lambda}\frac{(2 - \Delta t\hat{\lambda})C_{\text{sed}^j} + \Delta t\hat{\lambda}K_dC^j}{2 + \Delta t\hat{\lambda}} + G[C, C_H, C_{\text{sed}}]^j\right] \end{aligned}} \tag{25}$$

1.4 Numerical solution - Steady-state

Finite differences

Using the finite differences approximation shown above (Figure 1), equation (4) becomes:

$$
\begin{aligned}
0 =& -\left(\frac{Q}{A}\right)_i\left(\frac{C_{i+1}-C_{i-1}}{2\Delta x}\right)+\frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1}-C_i)-(AD)_{i-1,i}(C_i-C_{i-1})}{\Delta x^2}\right)\\
&+\frac{q_I}{A_i}(C_I-C_i)-\lambda C_i-\frac{k}{d_i}C_i+\alpha(C_H-C_i)+\rho\hat{\lambda}(C_{\text{sed}}-K_dC_i)
\end{aligned}
\tag{26}
$$

Substituting equation (6) and equation (8) into equation (26) leads to:

$$
\begin{aligned}
0 =& -\left(\frac{Q}{A}\right)_i\left(\frac{C_{i+1}-C_{i-1}}{2\Delta x}\right)+\frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1}-C_i)-(AD)_{i-1,i}(C_i-C_{i-1})}{\Delta x^2}\right)\\
&+\frac{q_I}{A_i}(C_I-C_i)-\lambda C_i-\frac{k}{d_i}C_i+\alpha\left(\frac{\alpha A_iC_i+\gamma A_H+\hat{\lambda}_H\hat{C}_HA_H}{\alpha A_i+\lambda_HA_H+\hat{\lambda}_HA_H}-C_i\right)\\
&+\rho\hat{\lambda}(K_dC_i-K_dC_i)\\
0 =& -\left(\frac{Q}{A}\right)_i\left(\frac{C_{i+1}-C_{i-1}}{2\Delta x}\right)+\frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1}-C_i)-(AD)_{i-1,i}(C_i-C_{i-1})}{\Delta x^2}\right)\\
&+\frac{q_I}{A_i}(C_I-C_i)-\lambda C_i-\frac{k}{d_i}C_i\\
&+\frac{\alpha^2A_iC_i+\alpha\gamma A_H+\alpha\hat{\lambda}_H\hat{C}_HA_H-\alpha^2A_iC_i-\alpha\lambda_HA_HC_i-\alpha\hat{\lambda}_HA_HC_i}{\alpha A_i+\lambda A_H+\hat{\lambda}_HA_H}\\
0 =& -\left(\frac{Q}{A}\right)_i\left(\frac{C_{i+1}-C_{i-1}}{2\Delta x}\right)+\frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(C_{i+1}-C_i)-(AD)_{i-1,i}(C_i-C_{i-1})}{\Delta x^2}\right)\\
&+\frac{q_I}{A_i}(C_I-C_i)-\lambda C_i-\frac{k}{d_i}C_i+\frac{\alpha A_H(\gamma+\hat{\lambda}_H\hat{C}_H-\lambda_HC_i-\hat{\lambda}_HC_i)}{\alpha A_i+\lambda A_H+\hat{\lambda}_HA_H}
\end{aligned}
\tag{27}
$$

Rearrangement of equation (27) yields:

$$
\boxed{E_iC_{i-1}^{j+1}+F_iC_i^{j+1}+G_iC_{i+1}^{j+1}=R_i}
\tag{28}
$$

where:

$$
\begin{aligned}
E_iC_{i-1} &= \left(\frac{Q}{A}\right)_i\left(\frac{-C_{i-1}}{2\Delta x}\right)-\frac{1}{A_i}\left(\frac{-(AD)_{i-1,i}(-C_{i-1})}{\Delta x^2}\right)\\
&\boxed{E_i=-\frac{1}{A_i\Delta x}\left(\frac{Q_i}{2}+\frac{(AD)_{i-1,i}}{\Delta x}\right)}
\end{aligned}
\tag{29}
$$

$$
\begin{aligned}
F_iC_i =& -\frac{1}{A_i}\left(\frac{(AD)_{i,i+1}(-C_i)-(AD)_{i-1,i}C_i}{\Delta x^2}\right)+\frac{q_I}{A_i}+\lambda C_i+\frac{k}{d_i}C_i\\
&-\frac{\alpha A_H{-}\lambda_HC_i-\hat{\lambda}_HC_i}{\alpha A_i+\lambda A_H+\hat{\lambda}_HA_H}\\
&\boxed{F_i=\frac{(AD)_{i,i+1}+(AD)_{i-1,i}}{A_i\Delta x^2}+\frac{q_I}{A_i}+\lambda+\frac{k}{d_i}+\alpha A_H\frac{\lambda_H+\hat{\lambda}_H}{\alpha A_i+\lambda A_H+\hat{\lambda}_HA_H}}
\end{aligned}
\tag{30}
$$

$$G_iC_{i+1} = \left(\frac{Q}{A}\right)_i \frac{C_{i+1}}{2\Delta x} - \frac{1}{A_i}\left(\frac{(AD)_{i,i+1}C_{i+1}}{\Delta x^2}\right)$$
$$\boxed{G_i = \frac{1}{A_i\Delta x}\left(\frac{Q_i}{2} - \frac{(AD)_{i,i+1}}{\Delta x}\right)} \tag{31}$$

$$\boxed{R_i = \frac{q_I}{A_i}C_I + \frac{\alpha A_H(\gamma + \hat{\lambda}_H\hat{C}_H)}{\alpha A_i + \lambda_H A_H + \hat{\lambda}_H A_H}} \tag{32}$$

1.5 Solving the numerical equations

equation (14) and equation (28) can be solved as:

$$\begin{bmatrix} F_1^{(\prime)} & G_1 & & & \\ E_2 & F_2^{(\prime)} & G_2 & & \\ & & ... & & \\ & & E_{N-1} & F_{N-1}^{(\prime)} & G_{N-1} \\ & & & E_N & F_N^{(\prime)} \end{bmatrix} \begin{bmatrix} C_1^{j+1} \\ C_2^{j+1} \\ ... \\ C_{N-1}^{j+1} \\ C_N^{j+1} \end{bmatrix} = \begin{bmatrix} R_1^{(\prime\prime)} \\ R_2^{(\prime\prime)} \\ ... \\ R_{N-1}^{(\prime\prime)} \\ R_N^{(\prime\prime)} \end{bmatrix} \tag{33}$$

where N is the number of segments.

Bibliography

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