Partial differential equations II

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1 Winter semester addendum

1.0.1 Weak* convergence

Since $L_{\infty}(0,T); L_2(\Omega)$ is not reflexive, we cannot extracting a convergent subsequence; however, we know the predual of $L_{\infty}(0,T); L_2(\Omega)$ is reflexive, i.e.

$$L_{\infty}\Big((0,T);L_{2}(\Omega)\Big)\approx \big(L_{1}\Big((0,T);L_{2}(\Omega)\Big)\big)^{*},$$

which means that balls in $L_{\infty}((0,T);L_2(\Omega))$ are weakly* compact. Moreover, $L_1((0,T);L_2(\Omega))$ is separable, from which it follows $L_{\infty}((0,T);L_2(\Omega))$ with the weak* topology is metrizable and thus there exists s weakly * converging subsequence (from the balls).

Theorem 1. Let the assumptions of the previous theorem hold and $\Omega \in C^{1,1}, \delta \in (0,1)$. Then $u \in L_2(\delta,T); W^{2,2}(\Omega)$.

Proof. Take the weak formulation in $t \in (\delta, T)$. WLOG further assume d = 0. Then

$$\int_{\Omega} \mathbb{A} \nabla u \cdot \nabla \varphi = \int_{\Omega} f \varphi - bu \varphi - \mathbf{c} \cdot \nabla u \varphi - \int_{\Omega} \partial_t u \varphi = \int_{\Omega} (f - bu - \mathbf{c} \cdot \nabla u - \partial_t u) \varphi,$$

and the integrand of the last integral is in $L_2(\Omega)$ for a.e. $t \in (\delta, T)$. We can thus use the elliptic regularity results and write:

$$\|u\|_{\mathbf{W}^{1,2}(\Omega)}^2 \le C(\|f\|_{\mathbf{L}_2(\Omega)}^2 + \|u\|_{\mathbf{W}^{1,2}(\Omega)}^2 + \|\partial_t u\|_{\mathbf{L}_2(\Omega)}^2),$$

integrating both sides $\int_{\delta}^{T} dt$ yields

$$\|u\|_{\mathrm{L}_{2}((\delta,T);\mathrm{L}_{2}(\Omega))}^{2} \leq C(\|f\|_{\mathrm{L}_{2}(\Omega)}^{2} + \|u\|_{\mathrm{L}_{2}((0,T);\mathrm{W}^{1,2}(\Omega))}^{2} + \|u\|_{\mathrm{L}_{2}((\delta,T);\mathrm{L}_{2}(\Omega))}^{2})$$

Theorem 2. If data are smooth and satisfy the compatibility conditions, then the weak solutions to the parabolic equation are smooth.

Proof. no.

Remark (Compatibility condition). : Take the heat equation : $\partial_t u - \triangle u = f$ at time zero: $\triangle u(0) + f(0) = \partial_t u(0) \in W_0^{1,2}(\Omega)$, so we need that $f(0) + \triangle u(0)$ has zero trace \Rightarrow compatibility conditions.

Theorem 3 (Uniqueness of the solution to a hyperbolic equation). Let the assumptions on the data of the hyperbolic equations be standard (i.e. minimal). Further assume that $\mathbf{c} \in W^{1,\infty}(\Omega)$. Then the weak solution to the hyperbolic equation is unique.

Proof. It is enough that if $u_0 = 0$, $u_1 = 0 \Rightarrow u = 0 \in Q_T$. To do that, take the weak equation, multiply it by $\varphi \in V$ fixed and integrate in time and space:

$$<\partial_t u(t), \varphi>+\int_{\Omega}\int_0^t \mathbb{A}(s)\nabla u(s)\nabla\varphi\,\mathrm{d}s+\int_{\Omega}\int_0^t (bu(s)+\mathbf{c}\cdot\nabla u(s))\varphi-\int_{\Omega}\int_0^t u(s)\mathbf{d}(s)\cdot\nabla\varphi=0,$$

next take $\varphi = u(t)$ as a test function and integrate $\int_0^\tau \mathrm{d}t \,, \tau \in (0,T)$. The duality term becomes

$$\int_0^\tau \frac{1}{2} \partial_t \|u(t)\|_{L_2(\Omega)}^2 dt,$$

the remaining terms are (we are using Fubini theorem)

$$\int_0^\tau \int_0^t \int_\Omega \mathbb{A} \nabla u \cdot \nabla u(t) \, \mathrm{d}s \, \mathrm{d}t = \int_\Omega \int_0^\tau \int_s^\tau \nabla u(t) \, \mathrm{d}t \, \mathbb{A}(s) \nabla u(s) \, \mathrm{d}s,$$

denote $\partial_s w(s) = -u(s)$, then

2 Sobolev spaces revisited

Let $\Omega \subset \mathbb{R}^d$ open, $p \in [1, +\infty], k \in \mathbb{N}$. We define

$$\mathbf{W}^{\mathbf{k},\mathbf{p}}(\Omega) = \Big\{ f \in \mathbf{L}_{\mathbf{p}}(\Omega) ; D^{\alpha} f \in \mathbf{L}_{\mathbf{p}}(\Omega), \forall |\alpha| \le k \Big\},\,$$

with the norm

$$||f||_{\mathbf{W}^{k,p}(\Omega)}^p = ||f||_{\mathbf{L}_p(\Omega)}^p + \sum_{0 < |\alpha| \le k} ||D^{\alpha}f||_{\mathbf{L}_p(\Omega)}^p.$$

Recall that:

- $W^{k,p}(\Omega)$ is Banach $\forall p$ and Hilbert for p = 2.
- $W^{k,p}(\Omega)$ is separable if $p < \infty$ and reflexive if $p > 1, p < \infty$.

Our goal will be to prove embedding and trace theorems. We will use the density of smooth functions.

2.1 Tools from functional analysis

Definition 1 (Regularization kernel). The function η is called the regularization kernel supposed:

- $\eta \in \mathcal{D}(\mathbb{R}^d)$
- supp $\eta \in \mathrm{U}(0,1)$
- $\eta \ge 0$
- η is radially symmetric
- $\int_{\mathbb{R}^d} \eta(x) \, \mathrm{d}x = 1$

Definition 2 (Regularization of a function). Let η be a regularization kernel. Set $\eta_{\varepsilon}(x) = \varepsilon^{-d}\eta(x/\varepsilon), \varepsilon > 0$. We define the smoothing of f by

$$f_{\varepsilon}(x) = (f \star \eta_{\varepsilon})(x).$$

Remark (Properties of regularization). The regularization has the following properties:

- $f \in L_p(\Omega) \Rightarrow f_{\varepsilon} \to f \text{ in } L_p(\Omega)$ and also a.e
- $f \in L_{\infty}(\Omega) \Rightarrow f_{\varepsilon} \to f$ a.e and *-weak
- $f_{\varepsilon}(x) = \int_{\mathbb{R}^d} f(y) \eta_{\varepsilon}(x-y) \, dy = \int_{U(x,\varepsilon)} f_y \eta_{\varepsilon}(x-y) \, dy$
- supp $f_{\varepsilon} \subset \overline{U(\Omega, \varepsilon)}, f = 0 \text{ on } U(x, \varepsilon) \Rightarrow f_{\varepsilon}(x) = 0$

Definition 3 $(\Omega' \subset\subset \Omega)$. $O \subset\subset \Omega$ means \overline{O} is compact and $\overline{O} \subset \Omega$.

Lemma 1 (Approximation of Sobolev functions using regularization). Assume $p \in [1, \infty), \Omega \subset \mathbb{R}^d$ open, $k \in \mathbb{N}, u \in W^{k,p}(\Omega), \Omega' \subset \Omega$. Then it holds

- 1. dist $(\overline{\Omega}', \partial\Omega) = D > 0$
- 2. $D^{\alpha}(f_{\varepsilon}) = (D^{\alpha}f)_{\varepsilon} \text{ in } \Omega', \forall \varepsilon \in (0, D), \forall |\alpha| \leq k$
- 3. $f_{\varepsilon} \to f$ in $W^{k,p}(\Omega), \varepsilon \to 0^+$

Proof. 1. disjoint compact and closed set

2. WLOG $\frac{\partial f_{\varepsilon}}{\partial x^{k}} = \frac{\partial \int_{\mathbb{R}^{d}} f_{y} \eta_{\varepsilon}(x-y) dy}{\partial x^{k}} = \int_{\Omega} f_{y} \frac{\partial \eta_{\varepsilon}}{\partial x^{k}} dy = -\int_{\Omega} f(y) \frac{\partial \eta_{\varepsilon}}{\partial y^{k}} dy = -\int_{\Omega} \frac{\partial f}{\partial y^{k}} \eta_{\varepsilon}(x-y) dy = (D^{\alpha} f)_{\varepsilon}(x).$

3. follows from 2) and the remark above applied to $f, D^{\alpha} f, |\alpha| \leq k$.

Lemma 2 (Partition of unity). Let $E \subset \mathbb{R}^d$, \mathcal{G} opencovering. Then there exists a countable system \mathcal{F} of nonnegative functions $\varphi \in \mathcal{D}(\mathbb{R}^d)$ such that $0 \le \varphi \le 1$ and

- 1. \mathcal{F} is subordinate to $\mathcal{G}: \forall \varphi \exists U \in \mathcal{Q}: \operatorname{supp} \varphi \subset U$
- 2. \mathcal{F} is locally finite: $\forall K \in E$ compact, supp $\varphi \cap K \neq \emptyset$ for at most finitely many $\varphi \in \mathcal{F}$.

3. $\sum_{\varphi \in \mathcal{F}} \varphi(x) = 1, \forall x \in E$.

Proof. (Sketch) Step 1 (E is compact):

E compact $\Rightarrow \exists N \in \mathbb{N}: U_j \in \mathcal{Q}$ $s.t.E \subset \bigcup_{j=1}^m U_j$. Moreover, $\exists K_j \subset U_j$ compact such that $E \subset \bigcup_{j=1}^m K_j$. That follows from the exhaustion argument: for $U \subset \mathbb{R}^d$ open, you can approximate it by a compact set: $K_m = \left\{x \in U, \operatorname{dist}(x, \partial\Omega) \geq \frac{1}{m}, \|x\| \leq m\right\}$. Then clearly $K_1 \subset K_2 \ldots$, and they "converge monotonously to U. Next, find $\phi_j \in C_c(U_j), \phi_j > 0$ on K_j , e.g. $\phi_j = \theta(\operatorname{dist}(x, \partial U_j))$. Then use convolution: $\psi_j = (\phi_j)_{\varepsilon}, \varepsilon > 0$ small and take finally $\varphi_j = \frac{\psi_j}{\sum_j \psi_j}$.

Step 2 (E is open):

Use exhaustion argument, then finite \rightarrow countable.

2.2 Density of smooth functions

Theorem 4 (Density of smooth functions I). Let $\Omega \subset \mathbb{R}^d$ be open, $k \in \mathbb{N}, p \in [1, \infty)$. Then $\{f \in C^{\infty}(\Omega), \operatorname{supp} f \ bounded\} \cap W^{k,p}(\Omega)$ is dense in $W^{k,p}(\Omega)$.

Proof. Let $u \in W^{k,p}(\Omega)$, $\varepsilon > 0$. I want to show $\exists v \in C^{\infty}(\Omega) \cap W^{k,p}(\Omega)$ $s.t \|u - v\|_{W^{k,p}(\Omega)} < \varepsilon$. Using the exhaustion argument, define

$$\Omega_j = \left\{ x \in \Omega, \operatorname{dist}(x, \partial\Omega) > \frac{1}{j} \right\}.$$

Clearly, $\Omega_j \subset \Omega_{j+1}, \cup_{j=1}^{\infty} \Omega_j = \Omega$. Next, set $U_j = \Omega_{j+1}$ $\overline{\Omega_{j-1}}, j = 1, 2, \ldots$, where $\Omega_0 = \Omega_{-1} = \emptyset$. Using the partition of unity lemma, $\exists \{\varphi_j\}$ partition of unity subordinate to $\{U_j\}$. We can write $u = \sum_j u\varphi_j$, where $u\varphi_j \in W^{k,p}(\Omega)$, supp $u\varphi_j \subset U_j \subset \Omega_{j+1} \subset \Omega$. This is ready for convolution with $\varepsilon_j > 0$ sufficiently small: set $v_j = (u\varphi_j)_{\varepsilon_j}$. By the properties of regularization, we now

$$\|u - u\varphi_j\|_{\mathbf{W}^{\mathbf{k},\mathbf{p}}(\Omega)} < \frac{\varepsilon}{2^j},$$

by taking ε_j small enough. Set $v = \sum_j v_j$ and use the following trick:

Fix $N \in \mathbb{N}$ and estimate $||v - u||_{W^{k,p}(\Omega)}$. Observe $u - v = \sum_{j=1}^{\infty} (u\varphi_j - v_j)$, so taking $x \in \Omega_N$ i have $(u - v)(x) = \sum_{j=1}^{N+1} (u\varphi_j - v_j)$. The norm of this is

$$||u-v||_{W^{k,p}(\Omega_N)} \le \sum_{j=1}^{N+1} ||u\varphi_j-v_j||_{W^{k,p}(\Omega)} < \varepsilon.$$

It only remains to let $N \to \infty$ and realize $\|u - v\|_{W^{k,p}(\Omega_N)} \to \|u - v\|_{W^{k,p}(\Omega)}$ by Lévi's theorem: $\int_{\Omega_N} |D^{\alpha} f| \, \mathrm{d}x \to \int_{\Omega} |D^{\alpha}| \, \mathrm{d}x.$

Remark. It is nice that we only require Ω to be open (no boundary regularity required), but on the other hand, we don't have any information about the function's behaviour near it.

Recall $\Omega \in C^0$ means $\exists U_j, j = 1, ..., m$ open, $\exists \alpha, \beta > 0, a_j : \overline{U(0, \alpha)} \to \mathbb{R}, \mathbb{A}_j : \mathbb{R}^d \to \mathbb{R}^d$ aff.orthogonal, such $\bigcup_{j=1}^m U_j, \partial \Omega \cap U_j = \{(x', a(x'), x' \in U(0, \alpha)\}.$ Setting $G_j(x', b) = \mathbb{A}_j(x', a(x') + b)$ we moreover require $G_j(U(0, \alpha) \times (0, \beta)) \subset \Omega, G_j(U(0, \alpha) \times (-\beta, 0)) \subset \overline{\mathbb{R}^d/\Omega}.$

Definition 4 (Shift operator). For $u \in L_p(\Omega)$, $k \in \{1, ..., d\}$, h > 0, we introduce the shift operator

$$\tau_h u(x) = u(x + h\mathbf{e}_k)$$

Lemma 3 (Approximation property of the shift operator). For $u \in L_p(\Omega)$, it holds $\tau_h u \to u$ in $L_p(\Omega)$, $h \to 0^+$.

Theorem 5 (Density of smooth functions II). Let $\Omega \in C^0$ bounded, $k \in \mathbb{N}, p \in [1, \infty)$. Then $C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d)$ is dense in $W^{k,p}(\Omega)$.

 $\textit{Proof.} \ \, \text{Let} \,\, u \in \mathcal{W}^{k,p}(\Omega) \,, \varepsilon > 0 \quad \textit{given}, \, \text{i am looking for} \,\, v \in C_c^{\infty}(\mathbb{R}^d) \quad \textit{suchthat} \| u - v \|_{\mathcal{W}^{k,p}(\Omega)} < \varepsilon.$

The sketch is simple: covering of $\overline{\Omega}$, partition of unity. Clearly, $\Omega \subset \bigcup_{j=0}^m U_j$, where $U_0 = \Omega, U_j$ are from the definition of C^0 boundary. Take $\{\varphi_j\}$ to be the partition of unity on $\overline{\Omega}$, subordinate to this cover. Observe that $u\varphi_j \in W^{k,p}(\Omega)$, supp $u\varphi_j \subset U_j$. Find

$$v_j \in \mathcal{D}(\mathbb{R}^d)$$
 $s.t. \|v_j - u\varphi_j\|_{W^{k,p}(\Omega)} < \frac{\varepsilon}{m+1}.$

If i am able to do this, i am finished: just take

$$v = \sum_{j=0}^{m} v_j$$

Case j=0. We have supp $u\varphi_0 \subset \Omega$, take $v_0=(u\varphi_0)_{\varepsilon}$, so if we take $\varepsilon>0$ small enough, i can use the previous lemma.

Case $j \in \{1, ..., m\}$. Set $w_j = u\varphi_j, \tau_\delta w_j(x', x_d) = w(x', x_d + \delta)$ (ignore $\mathbb{A}_{\tilde{j}}$), observe $t_\delta u_j \in \mathbb{W}^{k,p}(U_j^\delta), U_j \subset U_j^\delta$. Finally, set $v_j = (t_\delta w_j)_{\varepsilon_j}, \varepsilon_j > 0$ small enough. From the properties of the shift $\tau_\delta w_j$ is close to w_j in $L_p(U_j \cap \Omega)$ and $D^\alpha \tau_\delta w_j = \tau_\delta(D^\alpha w_j)$ close to $D^\alpha w_j$ in $L_p(U_j \cap \Omega)$. Finally, set $v_j = (t_\delta w_j)_{\varepsilon_j}, \varepsilon_j > 0$ small enough $\Rightarrow v_j \in \mathcal{D}(\mathbb{R}^d)$, supp $v_j \subset U_j$ by the previous lemma $\|v_j - \tau_\delta w_j\|_{W^{k,p}(\Omega)}$ small.

Remark. Recall $C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d) = \{u|_{\overline{\Omega}}, u \in C^{\infty}(\mathbb{R}^d)\}.$

2.3 Extension of Sobolev functions

Problem of extension: For $u \in W^{k,p}(\Omega)$, does there exist $\overline{u} \in W^{k,p}(\mathbb{R}^d)$, $s.t.\overline{u}|_{\Omega} = u$, $\|\overline{u}\|_{W^{k,p}(\mathbb{R}^d)} \le C(\Omega)\|u\|_{W^{k,p}(\Omega)}$?

The answer is **yes**, if Ω is nice enough.

Lemma 4. Let $\alpha, \beta > 0, K \subset U(0, \alpha) \times [\alpha, \beta]$ be compact. Then

$$\exists C>0, \exists E: C^1(\overline{U(0,\alpha)}\times [0,\beta]) \to C^1(\overline{U(0,\alpha)}\times [-\beta,\beta]), \exists \tilde{K} \subset U(0,\alpha)\times [-\beta,b) \ compact$$

such that:

- 1. $||Eu||_{W^{1,p}(U(0,\alpha)\times(-\beta,\beta))} \le ||u||_{W^{1,p}(U(0,\alpha)\times(-\beta,\beta))}$
- 2. if supp $u \subset K \Rightarrow \text{supp}\, Eu \subset \tilde{K}$

Proof. Use the following trick:

$$\overline{u}(x) = \begin{cases} u(x), & x_d > 0 \\ -3u(x_1, \dots, x_{d-1}, -x_d) + 4u(x_1, \dots, x_{d-1}, -\frac{x_d}{2}), & x_d < 0. \end{cases}$$

Is this extension C^1 ? Take some $a = (x_1, \ldots, x_{d-1}, 0)$. Then

$$u(x \to a) = \begin{cases} u(a), & x_d > 0 \\ -3u(a) + 4u(a) = u(a), & x_d < 0, \end{cases}$$

so \overline{u} is continuous. Its derivative

 $\partial_k \overline{u}, k = 1, \dots, d-1$ is the same as for u, where as

$$\partial_d \overline{u} = \begin{cases} \partial_d u, & x_d > 0 \\ -3\partial_d u(x_1, \dots, x_{d-1}, -x_d)(-1) + 4\partial_d u(x_1, \dots, x_{d-1}, -\frac{x_d}{2})(\frac{-1}{2}) = 3\partial_d u - 2\partial_d u, & x_d < 0, \end{cases}$$

so the the derivative is also continuous. Thus, we have $Eu = \overline{u} \in C^1 \subset W^{1,p}(U(0,\alpha) \times (-\beta,\beta))$ and estimate of the norm $||Eu||_{W^{1,p}(U(0,\alpha)\times(-\beta,\beta))}$ is clear, as the wanted term is just some linear combination.

Mr. Prazak is not sure how this should be correctly finished and i am not also.

Lemma 5 (Change of variables under C^1 diffeomorphisms). Let $U, V \subset \mathbb{R}^d$ be open, $\phi : U \to V$ be C^1 diffeomorphism. Let $\tilde{U} \subset U$. Then

$$\phi(\tilde{U}) \subset\subset V, \ and \ \exists C>0: \forall u\in C^1(V): \|u\circ\phi\|_{W^{1,p}(\tilde{U})}\leq C\|u\|_{W^{1,p}(\phi(\tilde{U}))}$$

 $\begin{aligned} & Proof. \ \|u \circ \phi\|_{\mathrm{L}_{\mathbf{p}}(\tilde{U})}^p = \int_{\tilde{U}} (u \circ \phi)^p |\det \nabla \phi| \, \mathrm{d}x \leq C_0^{-1} \int_{\tilde{U}} |u \circ \phi|^p |\det \nabla \phi| \, \mathrm{d}x, \text{ where } \det \nabla \phi > 0 \text{ in } U, \text{ so } \det \nabla \phi \geq C_0 > 0 \text{ in } \tilde{U}. \text{ Together } \|u \circ \phi\|_{\mathrm{L}_{\mathbf{p}}(\tilde{U})}^p = C_0^{-1} \int_{\phi(\tilde{U})} |u|^p \, \mathrm{d}x = C_0^{-1} \|u\|_{\mathrm{L}_{\mathbf{p}}(\phi(\tilde{U}))} \end{aligned} \qquad \qquad \Box$

Lemma 6. Let $\alpha, \beta > 0, K \subset U(0, \alpha) \times [0, \beta), K$ compact. Then there is $C > 0, E : C^1(\overline{U(0, \alpha)} \times [0, \beta)) \to C^1(\overline{U(0, \alpha)} \times [-\beta, \beta]), \tilde{K} \subset U(0, \alpha) \times [-\beta, \beta)$ compact such that

- $||E||_{\mathcal{L}(W^{1,p}(U(0,\alpha)\times(0,\beta)),W^{1,p}(U(0,\alpha)\times(-\beta,\beta))} \le C$
- $u \in C^1(\overline{U(0,\alpha)} \times [0,\beta])$, supp $u \subset K \Rightarrow \text{supp } Eu \subset \tilde{K}$

Proof. No proof.

Lemma 7. Let $U, V \subset \mathbb{R}^d$ open, $\Phi: U \to V, C^1$ diffeomorphism, $\tilde{U} \subset\subset U$ compact. Then $\Phi(\tilde{U}) \subset\subset V$ and

$$\exists C > 0: \forall u \in C^{1}(V): \|u \circ \Phi\|_{W^{1,p}(\tilde{U})} \le C \|u\|_{W^{1,p}(\Phi(\tilde{U}))}.$$

Proof. No proof.

Theorem 6 (Extension of Sobolev functions). Let $\Omega \in C^{k-1,1}, k \in \mathbb{N}, p \in [1, \infty], V \subset \mathbb{R}^d$ open such that $\Omega \subset V$. Then there is $E: W^{k,p}(\Omega) \to W^{k,p}(\mathbb{R}^d)$ bounded linear operator such that

- 1. $\forall u \in W^{k,p}(\Omega) : Eu = u \text{ a.e. } in \Omega$
- 2. $\forall u \in W^{k,p}(\Omega) : \operatorname{supp} Eu \subset V$,
- 3. $||E|| \le C, C = C(p, \Omega, V)$.

Proof. Only for $k = 1, \Omega \in C^1, p < \infty$. We know $C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d)$ is dense in $W^{1,p}(\Omega)$, we show existence of E for $u \in C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d)$ with properties 1),2),3) and then extend E to $W^{1,p}(\Omega)$ by density. Covering of Ω :

$$\overline{\Omega} \subset \Omega \cup \bigcup_{j=1}^m U_j$$

with $U_j, a_j, \mathbb{A}_j, \alpha, \beta$ as in the definition of a C^1 domain. In particular, $a_j \in C^1(\mathrm{U}(0,\alpha))$. Construction of E: We denote $\{\varphi_j\}_{j=0}^m$ partition of unity subordinate to $\{U_j\}_{j=1}^m$. For $j \in \{1, \ldots, n\}$ we define $\phi_j : \mathrm{U}(0,\alpha) \times (-\beta,\beta) \to U_j$ by

$$\phi_i(y', y_d) = \mathbb{A}_i(y', a_i(y') + y_d), y' \in \mathbb{R}^{d-1}, y_d \in \mathbb{R}.$$

Trivially ϕ_j is C^1 diffemorphism. Let us denote by \tilde{E} the extension operator from the previous lemma. Then we have for $u \in C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d)$: $u = \sum_{j=1}^m \varphi_j u$. We define

$$Eu = \varphi_0 u + \sum_{j=1}^m \left(\eta \tilde{E}((\varphi_j u) \circ \phi_j) \right) \circ \phi_j^{-1},$$

where η is a cut-off function $\eta = 1$ on $y_d \ge 0$, $\in (0,1)$ else, = 0 on $y_d \le -h$, for some parameter h > 0 which will be defined later. We also take $\eta \in C^{\infty}$. Due to our construction,

$$\phi_j^{-1}(\mathrm{U}(0,\alpha)\times[-2h,\beta))\subset\mathrm{U}(\Omega,\varepsilon)\subset\mathrm{U}(\Omega,2\varepsilon)\subset V,$$

for some $\varepsilon > 0$.

Properties of E: It is clear that

- \bullet E is linear from its definition
- 1) holds, as ϕ_j and ϕ_j^{-1} cancel somewhere
- 2) holds for $h < \frac{\beta}{2}$
- 3) we use the previous lemma:

$$\left\|\underbrace{\left(\eta \tilde{E}(\varphi_{j}u\circ\phi_{j})\right)}_{\text{supp}()\in\mathcal{U}(0,\alpha)\times(-\beta,\beta)}\circ\phi_{j}^{-1}\right\|_{\mathcal{W}^{1,p}(\mathbb{R}^{d})}\leq C\left\|\eta \tilde{E}(\varphi_{j}u\circ\phi_{j})\right\|_{\mathcal{W}^{1,p}(\mathcal{U}(0,\alpha)\times(-\beta,\beta))}$$

$$\leq C\left\|\varphi_{j}u\circ\phi_{j}\right\|_{\mathcal{W}^{1,p}(\mathcal{U}(0,\alpha)\times(0,\beta))}$$

$$\leq C\left\|\varphi_{j}u\circ\phi_{j}\right\|_{\mathcal{W}^{1,p}(\mathcal{U}(0,\alpha)\times(0,\beta))}$$
previous lemma
$$\leq C\left\|\varphi_{j}u\right\|_{\mathcal{W}^{1,p}(\mathcal{U}_{j}\cap\Omega)}\leq \left\|u\right\|_{\mathcal{W}^{1,p}(\Omega)}\Rightarrow \left\|E\right\|\leq C.$$
previous lemma

So all the properties hold for $u \in C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d)$. We need to show them also for $u \in W^{1,p}(\Omega)$. Pick an arbitrary $u \in W^{1,p}(\Omega)$, find $\{u_k\} \subset C^{\infty}_{\overline{\Omega}}(\mathbb{R}^d) : u_k \to u \text{ in } W^{1,p}(\Omega)$.

Ad 1): Since E is continuous, then $Eu_k \to Eu$ in $W^{1,p}(\mathbb{R}^d)$. Since $\Omega \subset \mathbb{R}^d \Rightarrow Eu = u$ in $W^{1,p}(\Omega)$.

Ad 2): supp
$$Eu_k \subset U(\Omega, \varepsilon) \Rightarrow \text{supp } Eu \subset \overline{U(\Omega, \varepsilon)} \subset V$$
.

Remark ($\Omega \in C^{0,1}$ suffices). The theorem is still valid if we assume only $C^{0,1}$ and $p \in (1, \infty), k > 1$.

2.4 Embedding theorems

Example. Let $u \in \mathcal{D}(\mathbb{R}^2)$. Then

$$u(x_1, x_2) = \int_{-\infty}^{x_1} \partial_1 u(s, x_2) ds = \int_{-\infty}^{x_2} \partial_2 u(x_1, s) ds,$$

so

$$\int_{\mathbb{R}^2} \int_{\mathbb{R}^2} |u(x_1, x_2)|^2 dx_1 dx_2 \le \int_{\mathbb{R}} |\partial_1 u(s, x_2)| ds \int_{\mathbb{R}} |\partial_2 u(x_1, s)| ds dx_1 dx_2 \le \left(\int_{\mathbb{R}^2} |\nabla u|^2 d\lambda^2\right)^2,$$

SC

$$||u||_{L_2(\mathbb{R}^2)} \le ||\nabla u||_{L_1(\mathbb{R}^2)}.$$

Lemma 8. Let $d \ge 2$. Let $\hat{u}_i : \mathbb{R}^{d-1} \to \mathbb{R}$ be nonnegative and measurable for $j \in \{1, \dots, d\}$. We define

$$\hat{x}_j = (x_1, \dots, x_{j-1}, x_{j+1}, \dots, x_d), \hat{dx}_j = dx_1 \dots dx_{j-1} dx_{j+1} \dots dx_d$$

Consider the functions $u_j: \mathbb{R}^d \to \mathbb{R}, u_j(x) = \hat{u_j}(\hat{x_j})$. Then

$$\int_{\mathbb{R}^d} \prod_{j=1}^d u_j(x) \, \mathrm{d}x \le \prod_{j=1}^d \left(\int_{\mathbb{R}^{d-1}} \left(\hat{u}_j(\hat{x}_j) \right)^{d-1} \, \hat{\mathrm{dx}}_{ij} \right)^{\frac{1}{d-1}}. \tag{1}$$

Proof. Induction by d.

1.
$$d = 2 : \int_{\mathbb{R}^d} u_1(x_1, x_2) u_2(x_1, x_2) dx_1 dx_2 = \int_{\mathbb{R}^2} \hat{u}_1(x_2) \hat{u}_2(x_1) dx_1 dx_2 = \int_{\text{Fubini}} \int_{\mathbb{R}} \hat{u}_1(x_2) dx_2 \int_{\mathbb{R}} \hat{u}_2 dx_1.$$

2.

$$d \rightarrow d+1: \int_{\mathbb{R}^{d+1}} \prod_{j=1}^{d+1} u_j(x) \, \mathrm{d}x = \int_{\mathbb{R}^d} \int_{\mathbb{R}} \prod_{j=1}^d u_j(x) \, \mathrm{d}x_{d+1} \, u_{d+1} \, \mathrm{d}x \, \mathrm{d}\hat{\mathbf{x}}_{d+1}$$

$$\overset{\leq}{\underset{\text{Holder}}{=}} \int_{\mathbb{R}^d} \left(\prod_{j=1}^d \int_{\mathbb{R}} \left(u_j(x) \right)^d \, \mathrm{d}x_{d+1} \right)^{\frac{1}{d}} u_{d+1}(x) \, \mathrm{d}\hat{\mathbf{x}}_{d+1}$$

$$\overset{\leq}{\underset{\text{Holder}}{=}} \left(\int_{\mathbb{R}^d} \left(\prod_{j=1}^d \int_{\mathbb{R}} u_j^d(x) \, \mathrm{d}x_{d-1} \right)^{\frac{1}{d-1}} \, \mathrm{d}x \, \hat{\mathbf{d}}_{d+1} \right)^{\frac{d-1}{d}} \left(\int_{\mathbb{R}^d} u_{d+1}^d \, \mathrm{d}x \, \hat{\mathbf{d}}_{d+1} \right)^{\frac{1}{d}}$$

$$\overset{\leq}{\underset{\text{induction step}^1}{=}} \left(\int_{\mathbb{R}^d} u_{d+1}^d \, \mathrm{d}\hat{x}_{d+1} \right)^{\frac{1}{d}} \left(\prod_{j=1}^d \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}} u_j^d(x) \, \mathrm{d}x_{d+1} \, \mathrm{d}\hat{x}_j \, \mathrm{d}\hat{x}_{d+1} \right)^{\frac{d-1}{d}}.$$

Theorem 7 (Gagliardo-Nirenberg). Let $p \in [1, d)$. Then $\forall u \in W^{1,p}(\mathbb{R}^d)$:

$$||u||_{L_{p^*}(\mathbb{R}^d)} \le \frac{p(d-1)}{d-p} ||\nabla u||_{L_p(\mathbb{R}^d)},$$

where $p^* = \frac{dp}{d-p}$.

Proof. Estimate for $u \in \mathcal{D}(\mathbb{R}^d)$:

$$\forall j \in \{1, \dots, d\}, x \in \mathbb{R}^d : u(x) = \int_{-\infty}^{x_j} \partial_j u(x_1, \dots, x_{j-1}, s, x_{j+1}, \dots, x_d) \, ds$$

independet of x_j , so

$$|u(x)| \leq \int_{\mathbb{R}} |\nabla u|(\ldots, s, \ldots) ds.$$

Next, consider $p=1, p^*=\frac{d}{d-1}$ and estimate:

$$|u|^{\frac{d}{d-1}} \le \prod_{j=1}^{d} \underbrace{\left(\int_{\mathbb{R}} |\nabla u|(\ldots, s, \ldots) \,\mathrm{d}s\right)^{\frac{1}{d-1}}}_{u_j \text{ independent of } x_j},$$

so the integral

$$\int_{\mathbb{R}^d} |u|^{\frac{d}{d-1}} \, \mathrm{d}x \le \int_{\mathbb{R}^d} \prod_{j=1}^d u \big) j \, \mathrm{d}x \underset{\text{previous lemma}}{\underbrace{\leq}} \left(\prod_{j=1}^d \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}} |\nabla u|(x) \, \mathrm{d}x_j \, \mathrm{d}\hat{x}_j \right)^{\frac{1}{d-1}} = \left(\int_{\mathbb{R}^d} |\nabla u| \, \mathrm{d}x \right)^{\frac{d}{d-1}}.$$

If $p \in (1, d)$, compute

$$\|u\|_{\mathrm{L}_{\frac{qd}{d-1}}(\mathbb{R}^d)}^q = \||u|^q\|_{\mathrm{L}_{\frac{d}{d-1}}(\mathbb{R}^d)} \leq \|\nabla(|u|^q)\|_{\mathrm{L}_{1}(\mathbb{R}^d)} = \int_{\mathbb{R}^d} q|u|^{q-1} |\nabla u| \, \mathrm{d}x \underbrace{\leq}_{\mathrm{Holder}} \|\nabla u\|_{\mathrm{L}_{p}(\mathbb{R}^d)} \|u\|_{\mathrm{L}_{(q-1)p'}(\mathbb{R}^d)}^{q-1}.$$

We want $\frac{(q-1)p'}{p-1} = \frac{qd}{d-1}$, so

$$q\left(\frac{p}{p-1}-\frac{d}{d-1}\right)=\frac{p}{p-1}, \Leftrightarrow q\frac{pd-p-pd+d}{(p-1)(d-1)}=\frac{d-p}{(p-1)(d-1)}=\frac{p}{p-1} \Leftrightarrow q=\frac{d-1}{d-p}p.$$

Also

$$q\frac{d}{d-1}=p^*.$$

 \Rightarrow statement holds for $u \in \mathcal{D}(\mathbb{R}^d)$. To finish, use density of $\mathcal{D}(\mathbb{R}^d)$ in $W^{1,p}(\mathbb{R}^d)$.

Remark. • It is evident that nonzero constants are not in $W^{1,p}(\mathbb{R}^d)$ and that also the inequality does not hold for them.

• the set \mathbb{R}^d is of course unbounded, so we have no ordering of $L_p(\Omega)$ spaces.

• of course, we require no smoothness of the domain

Theorem 8. Let $\Omega \subset \mathbb{R}^d$ be open. Then $\forall u \in W_0^{1,p}(\Omega), \forall p \in [1,d)$ the statement of the previous theorem holds.

Proof. An immediate corollary of the previous theorem.

Remark. In the proof of theorem we showed that $\forall u \in W^{1,p}(\mathbb{R}^d)$ it holds

$$||u||_{\mathbf{L}_{\frac{qd}{d-1}}(\Omega)}^{q} \le q ||\nabla u||_{\mathbf{L}_{\mathbf{p}}(\Omega)} ||u||_{\mathbf{L}_{\frac{p(q-1)}{2}}(\Omega)}^{q-1},$$

for q such that $\frac{qd}{d-1} \leq p^*$.

Theorem 9 (Embedding theorem). Let $\Omega \subset C^{0,1}$, $p^* = \frac{dp}{1-p}$ If $p \in [1,d)$ then

$$W^{1,p}(\Omega) \subset L_q(\Omega) \ \forall q \in [1, p^*].$$

Moreover, if $q < p^*$, then

$$W^{1,p}(\Omega) \subset\subset L_q(\Omega)$$
.

If p = d, then

$$W^{1,p}(\Omega) \subset L_q(\Omega) \ \forall q < \infty, \ W^{1,p}(\Omega) \subset L_q(\Omega) \ \forall 1 \leq q < \infty.$$

Proof. We would like to use the previous theorem + extension. Ad continuity for $p < d : E : W^{1,p}(\Omega) \to W^{1,p}(\mathbb{R}^d)$ the extension is continuous. We also know

- identity $I_1: W^{1,p}(\mathbb{R}^d) \to L_{p^*}(\mathbb{R}^d)$ is continous,
- restriction $I_2: L_{n^*}(\mathbb{R}^d) \to L_{n^*}(\Omega)$ is continuous,
- identity $I_3: L_{p^*}(\Omega) \to L_q(\Omega)$ is continous.

Together, the mapping $id: W^{1,p}(\Omega): L_q(\Omega), id = I_3 \circ I_2 \circ I_1 \circ E$ identity is continuous. If p=d, then $W^{1,d}(\Omega) \subset W^{1,r}(\Omega) \ \forall r \in [1,d), \ \text{and} \ r^* \to \infty \ \text{as} \ r \to d-. \ \text{For} \ q \in [1,\infty) \ \text{find} \ r \in [1,d) \ \text{s.t.} \ r^* > q. \ \text{Then}$

$$W^{1,d}(\Omega) \subset W^{1,r}(\Omega) \subset L_{r^*}(\Omega) \subset L_q(\Omega)$$
,

using the previous results.

Ad compactness: We show $W^{1,p}(\Omega) \subset L_q(\Omega)$ using Arzela-Ascoli and then it will get technical: show compactness in smooth functions, then show compactness in $L_1(\Omega)$, then approximate the norm of $L_q(\Omega)$ using the obtained quantities.

Consider $B = U_{W^{1,p}(\Omega)}(0,1)$ and extend it to EB. Fix $\delta > 0$ and let η be a regularization kernel. Then $\exists R > 0 : \operatorname{supp}(EB)_{\delta} \subset \overline{\mathrm{U}(0,R)} \subset \mathbb{R}^d$ (i.e. all the functions from EB have the support contained in the ball). Moreover, $(EB)_{\delta} \subset C^1(\overline{\mathrm{U}(0,R)})$. Actually, it is bounded in $C^1(\overline{\mathrm{U}(0,R)})$. $\subset C(\overline{\mathrm{U}(0,R)})$ (uniform equicontinuity comes from uniform boundedness of the gradients, $\nabla(u*\eta_\delta) = u*\nabla\eta_\delta$.) Altogether $(EB)_\delta$ is relatively compact in

$$C(\overline{\mathrm{U}(0,R)}) \underset{\mathrm{the\ space}\ C(\overline{\mathrm{U}(0,R)}) \text{ is complete}}{\Longrightarrow} \text{bounded in}\ C(\overline{\mathrm{U}(0,R)}) \underset{\mathrm{bounded\ domain}}{\Longrightarrow} \text{bounded in}\ \mathrm{L}_1(\mathrm{U}(0,R)).$$

Next, take

$$u \in B : \|u - (Eu)_{\delta}\|_{L_{q}(\Omega)} \le \|Eu - (Eu)_{\delta}\|_{L_{q}(U(0,R))} = \int_{U(0,R)} |v - v_{\delta}| \, \mathrm{d}x = \int_{\mathbb{R}^{d}} |\int_{\mathbb{R}^{d}} v(x+y) - v(x)\eta_{\delta}(y) \, \mathrm{d}y \, \mathrm{d}x \le$$

$$\le \int_{\mathbb{R}^{d}} |\int_{\mathbb{R}^{d}} \frac{|v(x+y) - v(x)|}{|y|} |\eta_{\delta}(y)| |y| \, \mathrm{d}y \, \mathrm{d}x \underset{\mathrm{Eukini}}{\le} \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} \frac{|v(x+y) - v(x)|}{|y|} \, \mathrm{d}x \, |y| \eta_{\delta}(y) \, \mathrm{d}y \, .$$

Estimate the inner integral: assume v is smooth and write

$$\int_{\mathbb{R}^d} \frac{1}{|y|} | \int_0^1 \underbrace{\frac{\mathrm{d}}{\mathrm{d}s} (v(x+sy))}_{\nabla v(x+sy) \cdot y} \, \mathrm{d}s \, | \, \mathrm{d}x \underbrace{\leq}_{\text{Cauchy Schwartz}} \int_{\mathbb{R}^d} \int_0^1 |\nabla v| (x+sy) \, \mathrm{d}s \, \mathrm{d}x \underbrace{\leq}_{\text{Holder}} C(R) \left(\int_{\mathbb{R}^d} |\nabla v|^p \, \mathrm{d}x \right)^{\frac{1}{p}}.$$

Now, take $v \in W_0^{1,p}(\mathrm{U}(0,R))$, then $\exists \{v_k\} \subset \mathcal{D}(\mathrm{U}(0,R)) : v_k \to v \text{ in } W^{1,p}(\mathrm{U}(0,R))$. So

$$\forall y \in \mathbb{R}^d : \int_{\mathbb{R}^d} \frac{|v_k(x+y) - v_k(x)|}{|y|} \, \mathrm{d}x \le C(R) \left(\int_{\mathbb{R}^d} |\nabla v_k|^p \, \mathrm{d}x \right)^{\frac{1}{p}} \to C(R) \left(\int_{\mathbb{R}^d} |\nabla v|^p \, \mathrm{d}x \right)^{\frac{1}{p}}.$$

So finally

$$\|u - (Eu)_{\delta}\|_{\mathcal{L}_{q}(\Omega)} \leq \int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} \frac{|v(x+y) - v(x)|}{|y|} \, \mathrm{d}x \, |y| \eta_{\delta}(y) \, \mathrm{d}y \underset{|y| \leq \delta}{\leq} C(R) \delta \int_{\mathbb{R}^{d}} \left(\int_{\mathbb{R}^{d}} |\nabla u|^{p} \, \mathrm{d}x \right)^{\frac{1}{p}} \, \mathrm{d}x \leq C_{1} \delta.$$

Fix $\varepsilon > 0$, find finite $\frac{\varepsilon}{2}$ -net in $(EB)_{\delta}$ in $L_1(\mathrm{U}(0,R))$ (that is possible since we have total boundedness in $L_1(\mathrm{U}(0,R))$.) Set $\delta > 0$ s.t. $C_1\delta \frac{\varepsilon}{4}$. Denote the $\frac{\varepsilon}{2}$ -net as $\{Eu_k\}_{k=1}^m, m \in \mathbb{N}$. We show $\{u_k\}_{k=1}^m$ is a ε -net in B. Fix $u \in B$, find $j \in \{1,\ldots,m\} : \|(Eu)_{\delta} - (Eu_j)_{\delta}\|_{L_1(\mathrm{U}(0,R))}$. Compute

$$\|u - u_j\|_{L_1(\Omega)} \le \|u - (Eu)_{\delta}\|_{L_1(\Omega)} + \|(Eu)_{\delta} - (Eu_j)_{\delta}\|_{L_1(\Omega)} + \|(Eu_j)_{\delta} - u_j\|_{L_1(\Omega)} \le 2C_1\delta + \frac{\varepsilon}{2} \le \varepsilon.$$

Thus, we have shown

$$W^{1,p}(\Omega) \subset L_1(\Omega)$$
.

It remains to show the validity for a general q. Let $q \in [1, p^*) : \|v\|_{L_q(\Omega)} \le \|v\|_{L_1(\Omega)}^{\alpha} \|v\|_{L_{p^*}(\Omega)}^{1-\alpha}$, for $\frac{1}{q} = \alpha + \frac{1-\alpha}{p^*}$, $\alpha \in (0, 1]$. Is B totally bounded in $L_q(\Omega)$? Let us compute

$$\|u-u_j\|_{\mathrm{L}_q(\Omega)} \leq \|u-u_j\|_{\mathrm{L}_1(\Omega)}^{\alpha} \underbrace{\|u-u_j\|_{\mathrm{L}_{p^*}(\Omega)}^{1-\alpha}}_{\leq C,\mathrm{W}^{1,p}(\Omega) \subset \mathrm{L}_{p^*}(\Omega)} \leq C\varepsilon^{\alpha}.$$

²The order of the choices is not precise...

- 2.5 Trace theorems
- 2.6 Composition of sobolev functions
- 2.7 Difference quotients

3 Nonlinear elliptic equations as compact perturbations

Theorem 10 (Nemytskii). Let $f: \Omega \times \mathbb{R}^N \to \mathbb{R}, N \in N, \Omega \subset \mathbb{R}^d$ measurable, f Caratheodory. Then

- 1. if $u: \Omega \to \mathbb{R}^N$ is measurable then $f(\cdot, u)$ is also measurable
- 2. If there is $p_i \in [1, +\infty)$, $i \in \{1, \dots, N\}$, $q \in [1, \infty)$, $g \in L_q(\Omega)$, C > 0 such that for almost all

$$x \in \Omega, \forall y \in \mathbb{R}^N : |f(x,y)| \le g(x) + c \sum_{i=1}^N |y_i|^{p_i/q}$$

, then $u \mapsto f(\cdot, u)$ is continuous from $L_{p_i}(\Omega) \times \cdots \times L_{p_N}(\Omega)$ to $L_q(\Omega)$. Moreover, it maps bounded sets to bounded sets.

Proof. No proof \Box

Definition 5 (Compact operator — Drábek, Milota: Methods of Nonlinear Analysis, Def 5.2.2). Let X, Y be normed linear spaces, $M \subset X$. The mapping $F: M \to Y$ is called a compact operator on M into Y if F is continuous and $F(M \cap K)$ is relatively compact in Y for any bounded $K \subset X$.

Remark. We have no linearity of F! So continuity cannot follow from compactness (we have compactness \Rightarrow boundedness \neq continuity for nonlinear operators)

Theorem 11 (Brouwer fixed point theorem). Let $K \subset \mathbb{R}^N$, $N \in \mathbb{N}$ be a nonempty convex closed bounded. Assume that $F: K \to K$ is continuous. Then F has a fixed point in K, i.e.,

$$\exists x_0 \in K : F(x_0) = x_0.$$

Proof. No proof

Theorem 12 (Schauder fixed point theorem). Let $K \subset X$ be a nonempty convex closed bonded subset of a linear normed space X. Assume that F is compact on K into K and $F(K) \subset K$. Then there is fixed point of F in K.

Proof. No proof \Box

- for Brouwer, $K \subset \mathbb{R}^N$ so since it is closed and bouded, it is automatically compact, and since $F: K \to K$ is continuous, F is compact. For Schauder, we have to assume this extra.
- proof of Brouwer with N=1 is easy, based on Darboux property.

3.0.1 Problem protypes

In this chapter some nonlinear elliptic equations are discussed.

Example. Suppose the following problem:

$$\begin{cases} -\triangle u + g(u) = f & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega, \end{cases}$$

where

$$g: \mathbb{R} \to \mathbb{R}, f \in (W_0^{1,2}(\Omega))^*$$
, continuous, $\exists \alpha \in [0,1): \forall s \in \mathbb{R}: |g(s)| \le C(1+|s|^{\alpha})$.

Theorem 13 (Existence). Let $\Omega \in C^{1,1}$, $f \in (W_0^{1,2}(\Omega))^*$, g is as above. Then there is a weak solution to the above problem, i.e., it holds:

$$\forall \varphi \in W_0^{1,2}(\Omega) : \int_{\Omega} \nabla u \cdot \nabla \varphi \, \mathrm{d}x = \langle f, \varphi \rangle_{(W_0^{1,2}(\Omega))^*}.$$

If $f \in L_2(\Omega)$, then the solution $u \in W^{2,2}(\Omega)$.

Proof. We define $S: L_2(\Omega) \to L_2(\Omega)$ such that

$$Sw = u \Leftrightarrow \forall \varphi \in W_0^{1,2}(\Omega) : \int_{\Omega} \nabla u \cdot \nabla \varphi \, \mathrm{d}x = \langle f, \varphi \rangle - \int_{\Omega} g(w) \varphi \, \mathrm{d}x.$$

S is well defined:

$$|\operatorname{RHS}| \le ||f||_{(W_0^{1,2}(\Omega))^*} ||\varphi||_{W^{1,2}(\Omega)} + ||\varphi||_{L_2(\Omega)} ||g(w)||_{L_2(\Omega)},$$

and

$$\int_{\Omega} |g(w)|^2 dx \le \int_{\Omega} C(1+|w|^{\alpha})^2 dx \le \int_{\Omega} C(1+|w|^{2\alpha}) dx \le \int_{\Omega} C(1+|w|^2) dx \le \infty,$$

where we used the Young inequality and $\alpha \leq 1$. We have thus shown the mapping $w \mapsto g(w)$ is continuous from $L_2(\Omega)$ to $L_2(\Omega)$ by Nemytskii. Next, S is continuous:

- $w \mapsto g(w)$ is continuous from $L_2(\Omega)$ to $L_2(\Omega)$
- $w \mapsto \left(\varphi W_0^{1,2}(\Omega) \to \langle f, \varphi \rangle \int_{\Omega} g(w)\varphi \, dx\right)$ is continuous from $L_2(\Omega)$ to $\left(W_0^{1,2}(\Omega)\right)^*$
- $F \to u$, where u is the weak solution of $\begin{cases} -\triangle u = F & in\Omega \\ u = 0 & on\partial\Omega, \end{cases}$, is linear and continuous from $(W_0^{1,2}(\Omega))^*$ to $W_0^{1,2}(\Omega)$.

In total, the composition is continuous and yields S. Next, we would like to show S is compact. We start with showing S maps bounded sets in $L_2(\Omega)$ to bounded sets in $W_0^{1,2}(\Omega)$; for that we need apriori estimates: test the weak formulation with u:

$$\|\nabla u\|_{\mathrm{L}_{2}(\Omega)}^{2} \leq \varepsilon \|u\|_{\mathrm{W}^{1,2}(\Omega)}^{2} + C\Big(\|f\|_{(\mathrm{W}^{1,2}(\Omega))^{*}}^{2} + \|g(w)\|_{\mathrm{L}_{2}(\Omega)}^{2}\Big) \underbrace{\leq}_{\text{Younge}} C\Big(\|f\|_{(\mathrm{W}_{0}^{1,2}(\Omega))^{*}}) + 1 + \|w\|_{\mathrm{L}_{2}(\Omega)}^{2}\Big),$$

from which follows S is compact from $L_2(\Omega)$ to $L_2(\Omega)$ by compact embedding. Now we need to show $S(U(0,R)) \subset U(0,R)$ for some R > 0. From the previous we know:

$$\frac{C}{2} \|u\|_{\mathbf{W}^{1,2}(\Omega)}^2 \le \tilde{C} \Big(\|f\|_{\left(\mathbf{W}_0^{1,2}(\Omega)\right)^*} + \|g\|_{\mathbf{L}_2(\Omega)}^2 \Big),$$

so since

$$\tilde{C} \int_{\Omega} |g(w)|^2 dx \le \int_{\Omega} C(1 + |w|^{2\alpha}) dx \le \int_{\text{Younge}} \int_{\Omega} \left(C + \frac{c}{4}|w|^2\right) dx$$

we know

$$\frac{c}{2}\|u\|_{\mathrm{L}_2(\Omega)}^2 \leq \frac{c}{2}\|u\|_{\mathrm{W}^{1,2}(\Omega)}^2 \leq \tilde{C}\|f\|_{(\mathrm{W}_0^{1,2}(\Omega))^*}^2 + C\lambda(\Omega) + \frac{c}{4}\|w\|_{\mathrm{L}_2(\Omega)}^2,$$

and thus

$$\|u\|_{\mathrm{L}_{2}(\Omega)}^{2} \leq \underbrace{\frac{2\tilde{C}}{c} \|f\|_{(\mathrm{W}_{0}^{1,2}(\Omega))^{*}}^{2} + 2\frac{C}{c}}_{C} + \frac{1}{2} \|w\|_{\mathrm{L}_{2}(\Omega)}^{2}.$$

so if $\overline{C} + \frac{1}{2}R^2 < R^2$, we are done ³. But such an R of course exists (says doc. Kaplicky) \Rightarrow the image of a ball is in a ball for some $R \Rightarrow S$ is compact and using Schauder we get the solution exists.

For the regularity part of the assertion, realize that u_0 solves $\begin{cases} -\Delta u_0 = f - g(u_0) \in L_2(\Omega) & \text{in } \Omega \\ u_0 = 0 & \text{on } \partial\Omega. \end{cases}$

So from the regularity theory for elliptic equations we get

$$u \in W^{2,2}(\Omega)$$
.

Theorem 14 (Uniqueness). Let $u_1, u_2 \in W_0^{1,2}(\Omega)$ be weak solutions to the above problem. Let $f \in (W_0^{1,2}(\Omega))^*, g$ be continuous. Let either

1. g is nondecreasing

2.
$$g \in C^1(\mathbb{R}), \|g'\|_{\infty} \text{ small.}$$

Then $u_1 = u_2$.

Proof. We subtract the equations for u_1, u_2 and test with $u_1 - u_2$.:

$$\int_{\Omega} |\nabla (u_1 - u_2)|^2 + (g(u_1) - g(u_2))(u_1 - u_2) dx = 0.$$

In the first case, the second term is nonnegative and so

$$0 = \|\nabla(u_1 - u_2)\|_{L_2(\Omega)} \ge C\|u_1 - u_2\|_{W^{1,2}(\Omega)}^2 \Rightarrow u_1 - u_2 = 0.$$

$$|\int_{\Omega} (g(u_1) - g(u_2)(u_1 - u_2)) dx| \le \int_{\Omega} ||g'||_{\infty} |u_1 - u_2|^2 dx \le ||g'||_{\infty} C_P ||\nabla (u_1 - u_2)||^2_{L_2(\Omega)} = 0 \Rightarrow u_1 = u_2.$$
whenever $C||g'||_{\infty} < 1$.

³The constants are most probably messed up.

Example. Suppose the following problem

$$\begin{cases} -\triangle u + b(\nabla u) = f & \text{in } \Omega \\ u = 0 & \text{on } \partial \Omega. \end{cases}$$

where $f \in (W_0^{1,2}(\Omega))^*, b$ is continuous and bounded. The weak formulation is

$$u \in W_0^{1,2}(\Omega) \land \forall \varphi \in W_0^{1,2}(\Omega) : \int_{\Omega} \nabla u \cdot \nabla \varphi + b(\nabla u) \varphi \, dx = \langle f, \varphi \rangle,$$

and the first apriori estimates (test with u)

$$\|\nabla u\|_{\mathrm{L}_2(\Omega)} \leq \|f\|_{(\mathrm{W}_0^{1,2}(\Omega))^*} \|u\|_{\mathrm{W}_0^{1,2}(\Omega)} + \int_{\Omega} |u| \, \mathrm{d}x \, \|b\|_{\mathrm{L}_\infty(\Omega)}.$$

Theorem 15. Let $f \in (W_0^{1,2}(\Omega))^*$, $\Omega \in C^{0,1}$, $b : \mathbb{R}^d \to \mathbb{R}$ continuous and bounded. Then there is a weak solution to the above problem.

Proof. $S: W_0^{1,2}(\Omega) \to W_0^{1,2}(\Omega), Sw = u$ iff u solves

$$\begin{cases}
-\triangle u = f - b(\nabla w) & \text{in } \Omega \\
u = 0 & \text{on } \partial \Omega.
\end{cases}$$
, i.e.

it holds

$$\forall \varphi \in W_0^{1,2}(\Omega) : \int_{\Omega} \nabla u \cdot \nabla \varphi \, \mathrm{d}x = \langle f, \varphi \rangle - \int_{\Omega} b(\nabla w) \varphi \, \mathrm{d}x.$$

Clearly, S is well defined and

$$||Sw||_{W_0^{1,2}(\Omega)} \le \underbrace{C(||f||_{(W_0^{1,2}(\Omega))^*} + ||b||_{L_{\infty}(\Omega)})}_{:=R},$$

meaning $S(\overline{\mathrm{U}(0,R)}) \subset \overline{\mathrm{U}(0,R)}$. Moreover, S]s continuous, as S is the composiiton of a Nemytskii operator and the solution operator of the Laplace equation. It remains to show S is compact: we already have continuity, consider $\{w_k\}_{k\in\mathbb{N}}\subset \mathrm{W}_0^{1,2}(\Omega)$ bounded. Then $\exists\{u_k\}\subset \mathrm{W}_0^{1,2}(\Omega)$ bounded: $u_k\to u$ in $\mathrm{L}_1(\Omega)$ by embedding up to a subsequence. Next, uss the following trick: substitue equation for u_k from equation for u_l and test with u_l-u_k

$$C\|u_{l}-u_{k}\|_{W_{0}^{1,2}(\Omega)}^{2} \leq \|\nabla(u_{l}-u_{k})\|_{L_{2}(\Omega)}^{2} \leq \int_{\Omega} |b(\nabla u_{l})-b(\nabla u_{k})| \|u_{l}-u_{k}\|_{dx} \leq 2\|b\|_{L_{\infty}(\Omega)} \|u_{l}-u_{k}\|_{L_{1}(\Omega)}.$$

All in all, S has a fixed point by Schauder, which is of course the weak solution.

But this says $\{u_k\}$ is Cauchy in $W_0^{1,2}(\Omega)$.

4 Nonlinear elliptic equations - monotone operator theory

Lemma 9. Let $g: B(0,R) \subset \mathbb{R}^n \to \mathbb{R}^N$ be continuous, $N \in \mathbb{N}, R > 0$, and $\forall c \in S(0,R): g(c) \cdot c \geq 0$. Then, there is $c_0 \in B(0,R): g(c_0) = 0$.

Proof. By contradiction. Let $g \neq 0$ in U(0,R). Let us define

$$h(x) = -R \frac{g(x)}{|g(x)|}.$$

Then $h \in C(\mathrm{B}(0,R)), h(\mathrm{B}(0,R)) \subset \mathrm{S}(0,R)$, so by Brouwer there $\exists x_0 \in \mathrm{B}(0,R) : h(x_{0=}x_0 \Rightarrow -R\frac{g(x_0)}{|g(x_0)|} = x_0$. Take the dot product with x_0 and write

$$\underbrace{-R\frac{g(x_0)\cdot x_0}{|g(x_0)|}}_{\leq 0} = \underbrace{|x_0|^2}_{=R^2} \land x_0 \in S(0,R),$$

so that is a contradiction.

5 Exercises

$5.1 \quad 4.3.2025$

Example (Coefficients for smooth extension). Define

$$Eu(x', x_d) = u(x', x_d), x \ge 0, = \sum_{j=1}^{k+1} u(x', -\frac{x_d}{j})c_j, x_d < 0.$$

for $u \in \mathcal{D}(\mathbb{R}^d)$. Find $\{c_j\}_{j=1}^{k=1}$ in such a way that $Eu \in C^k(\mathbb{R}^d)$. Moreover, take d = 1.

Proof. For k = 0, j = 1 we take $c_1 = 1, c_j = 0, j \neq 1$. For k = 1, compute the derivative:

$$\partial_{d^n} Eu(x', x_d) = \partial_{d^n} u(x', x_d), x_d \ge 0, = \sum_{j=1}^{k=1} (-1)^n \frac{\partial_{d^n} u(x', \frac{x_d}{j})}{j^n} c_j, x_d < 0.$$

If we take $x_d = 0$ in particular:

$$\partial_{d^n} u(x',0) = \sum_{j=1}^{k+1} \partial_{d^n} u(x',0) \left(-\frac{1}{j}\right)^n c_j \Leftrightarrow 1 = \sum_{j=1}^{k+1} c_j \left(-\frac{1}{j}\right)^n, \forall n \in \{0,\dots,k\}.$$

That is a linear system of k + 1 equations. Is it solvable?