

# Project\_1

November 4, 2024

```
[1]: import numpy as np
import pandas as pd
from scipy.sparse import csc_matrix

np.random.seed(412) # For reproducibility
from scipy.sparse import csc_matrix, csr_matrix
```

```
[2]: # Install required packages in Jupyter Notebook
!pip install numpy scipy matplotlib scikit-learn
```

```
Requirement already satisfied: numpy in
/home/anis/jupyter_env/lib/python3.12/site-packages (2.1.3)
Requirement already satisfied: scipy in
/home/anis/jupyter_env/lib/python3.12/site-packages (1.14.1)
Requirement already satisfied: matplotlib in
/home/anis/jupyter_env/lib/python3.12/site-packages (3.9.2)
Requirement already satisfied: scikit-learn in
/home/anis/jupyter_env/lib/python3.12/site-packages (1.5.2)
Requirement already satisfied: contourpy>=1.0.1 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (1.3.0)
Requirement already satisfied: cyclor>=0.10 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (0.12.1)
Requirement already satisfied: fonttools>=4.22.0 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (4.54.1)
Requirement already satisfied: kiwisolver>=1.3.1 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (1.4.7)
Requirement already satisfied: packaging>=20.0 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (24.1)
Requirement already satisfied: pillow>=8 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (11.0.0)
Requirement already satisfied: pyparsing>=2.3.1 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib) (3.2.0)
Requirement already satisfied: python-dateutil>=2.7 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from matplotlib)
(2.9.0.post0)
Requirement already satisfied: joblib>=1.2.0 in
/home/anis/jupyter_env/lib/python3.12/site-packages (from scikit-learn) (1.4.2)
Requirement already satisfied: threadpoolctl>=3.1.0 in
```

/home/anis/jupyter\_env/lib/python3.12/site-packages (from scikit-learn) (3.5.0)  
Requirement already satisfied: six>=1.5 in  
/home/anis/jupyter\_env/lib/python3.12/site-packages (from python-  
dateutil>=2.7->matplotlib) (1.16.0)

## 0.1 Exercise 1)

```
[3]: #Loading data

def load_data(file_path):
    """Loads the data matrix X and target vector y from a CSV file"""

    # load data
    csv_data = pd.read_csv(file_path)
    print(f>Data features: \n {csv_data.columns.values} \n")

    # Separate features (X) and target (y)
    X = csv_data.iloc[:, :-1].values
    y = csv_data.iloc[:, -1].values

    print(y[2])

    num_ones_or_zeros_y=len(y[y == 0])+len(y[y==1])

    print(f"The # of ones and zeros: {num_ones_or_zeros_y} is the same as_
↪length of y {y.shape[0]}")

    # Convert y to ±1 (y is in {0, 1})
    y = np.where(y == 0, -1,1)

    return X, y

# Load the dataset
X, y = load_data('data.csv')
print(X.shape)
```

Data features:

```
['android.permission.GET_ACCOUNTS'
'com.sonyericsson.home.permission.BROADCAST_BADGE'
'android.permission.READ_PROFILE' 'android.permission.MANAGE_ACCOUNTS'
'android.permission.WRITE_SYNC_SETTINGS'
'android.permission.READ_EXTERNAL_STORAGE'
'android.permission.RECEIVE_SMS'
'com.android.launcher.permission.READ_SETTINGS'
'android.permission.WRITE_SETTINGS']
```

'com.google.android.providers.gsf.permission.READ\_GSERVICES'  
 'android.permission.DOWNLOAD\_WITHOUT\_NOTIFICATION'  
 'android.permission.GET\_TASKS'  
 'android.permission.WRITE\_EXTERNAL\_STORAGE'  
 'android.permission.RECORD\_AUDIO'  
 'com.huawei.android.launcher.permission.CHANGE\_BADGE'  
 'com.oppo.launcher.permission.READ\_SETTINGS'  
 'android.permission.CHANGE\_NETWORK\_STATE'  
 'com.android.launcher.permission.INSTALL\_SHORTCUT'  
 'android.permission.android.permission.READ\_PHONE\_STATE'  
 'android.permission.CALL\_PHONE' 'android.permission.WRITE\_CONTACTS'  
 'android.permission.READ\_PHONE\_STATE'  
 'com.samsung.android.providers.context.permission.WRITE\_USE\_APP\_FEATURE\_SURVEY'  
 'android.permission.MODIFY\_AUDIO\_SETTINGS'  
 'android.permission.ACCESS\_LOCATION\_EXTRA\_COMMANDS'  
 'android.permission.INTERNET'  
 'android.permission.MOUNT\_UNMOUNT\_FILESYSTEMS'  
 'com.majeur.launcher.permission.UPDATE\_BADGE'  
 'android.permission.AUTHENTICATE\_ACCOUNTS'  
 'com.htc.launcher.permission.READ\_SETTINGS'  
 'android.permission.ACCESS\_WIFI\_STATE' 'android.permission.FLASHLIGHT'  
 'android.permission.READ\_APP\_BADGE' 'android.permission.USE\_CREDENTIALS'  
 'android.permission.CHANGE\_CONFIGURATION'  
 'android.permission.READ\_SYNC\_SETTINGS'  
 'android.permission.BROADCAST\_STICKY'  
 'com.anddoes.launcher.permission.UPDATE\_COUNT'  
 'com.android.alarm.permission.SET\_ALARM'  
 'com.google.android.c2dm.permission.RECEIVE'  
 'android.permission.KILL\_BACKGROUND\_PROCESSES'  
 'com.sonymobile.home.permission.PROVIDER\_INSERT\_BADGE'  
 'com.sec.android.provider.badge.permission.READ'  
 'android.permission.WRITE\_CALENDAR' 'android.permission.SEND\_SMS'  
 'com.huawei.android.launcher.permission.WRITE\_SETTINGS'  
 'android.permission.REQUEST\_INSTALL\_PACKAGES'  
 'android.permission.SET\_WALLPAPER\_HINTS'  
 'android.permission.SET\_WALLPAPER'  
 'com.oppo.launcher.permission.WRITE\_SETTINGS'  
 'android.permission.RESTART\_PACKAGES'  
 'me.everything.badger.permission.BADGE\_COUNT\_WRITE'  
 'android.permission.ACCESS\_MOCK\_LOCATION'  
 'android.permission.ACCESS\_COARSE\_LOCATION'  
 'android.permission.READ\_LOGS'  
 'com.google.android.gms.permission.ACTIVITY\_RECOGNITION'  
 'com.amazon.device.messaging.permission.RECEIVE'  
 'android.permission.SYSTEM\_ALERT\_WINDOW'  
 'android.permission.DISABLE\_KEYGUARD'  
 'android.permission.USE\_FINGERPRINT'  
 'me.everything.badger.permission.BADGE\_COUNT\_READ'

```
'android.permission.CHANGE_WIFI_STATE' 'android.permission.READ_CONTACTS'
'com.android.vending.BILLING' 'android.permission.READ_CALENDAR'
'android.permission.RECEIVE_BOOT_COMPLETED'
'android.permission.WAKE_LOCK' 'android.permission.ACCESS_FINE_LOCATION'
'android.permission.BLUETOOTH' 'android.permission.CAMERA'
'com.android.vending.CHECK_LICENSE'
'android.permission.FOREGROUND_SERVICE'
'android.permission.BLUETOOTH_ADMIN' 'android.permission.VIBRATE'
'android.permission.NFC' 'android.permission.RECEIVE_USER_PRESENT'
'android.permission.CLEAR_APP_CACHE'
'com.android.launcher.permission.UNINSTALL_SHORTCUT'
'com.sec.android.iap.permission.BILLING'
'com.htc.launcher.permission.UPDATE_SHORTCUT'
'com.sec.android.provider.badge.permission.WRITE'
'android.permission.ACCESS_NETWORK_STATE'
'com.google.android.finsky.permission.BIND_GET_INSTALL_REFERRER_SERVICE'
'com.huawei.android.launcher.permission.READ_SETTINGS'
'android.permission.READ_SMS' 'android.permission.PROCESS_INCOMING_CALLS'
'Result']
```

0

The # of ones and zeros: 29332 is the same as length of y 29332  
(29332, 86)

```
[4]: # Display data details
print(f"Loaded dataset with {X.shape[0]} samples and {X.shape[1]} features.")
print(f"Number of malicious data points: {np.sum(y == 1)}")
print(f"Number of non-malicious data points: {np.sum(y == -1)}")

sparsity = len(X[X == 0]) / X.size * 100
print(f"{sparsity:.2f}% of X's entries are 0")
```

Loaded dataset with 29332 samples and 86 features.  
Number of malicious data points: 14700  
Number of non-malicious data points: 14632  
89.01% of X's entries are 0

We don't need one-hot encoding since all the data is binary. The data features and many others, are binary features. Each permission is either granted (1) or not granted (0).

## 0.2 Exercise 2)

```
[5]: ## Create test and training sets
```

```
def split_data(X, y, r=0.5):
    """
```

```

Splits the data into training and test sets.
X should be in CSC (Compressed Sparse Column) format.
y will be returned as a dense vector.
r: Test size ratio (0 < r < 1).
"""

# Convert X to sparse CSC matrix (if not already sparse)
if not isinstance(X, csc_matrix):
    X_sparse = csc_matrix(X)
else:
    X_sparse = X

# y is now expected to be a dense array, so no need to convert it to sparse
y_dense = np.array(y)

# Shuffle and split data
indices = np.random.permutation(X_sparse.shape[0])
split_index = int(X_sparse.shape[0] * (1 - r))

# Splitting X
X_train = X_sparse[indices[:split_index], :]
X_test = X_sparse[indices[split_index:], :]

# Splitting y (kept as dense)
y_train = y_dense[indices[:split_index]]
y_test = y_dense[indices[split_index:]]

return X_train, X_test, y_train, y_test

# Split the dataset (50/50 split)
X_train, X_test, y_train, y_test = split_data(X, y, r=0.5)

```

### 0.3 Exercise 3)

```

[6]: import numpy as np

def classify(X, y, w):
    """Returns the number of correctly classified points using the weight_
    ↪vector w."""
    # Perform matrix-vector multiplication (X.dot(w)) and predict using the_
    ↪sign function
    predictions = np.sign(X.dot(w))

    # Convert sparse vector y to dense for comparison
    if isinstance(y, np.ndarray): # If y is already dense
        y_dense = y

```

```

    else:
        y_dense = y.toarray().flatten() # Convert sparse matrix to dense and
        ↪flatten it

        # Compare predictions with true labels and count correct classifications
        correct = np.sum(predictions == y_dense)
        accuracy = correct / len(y_dense)

    return correct, accuracy

# Example: Try random weight vector
w_random = np.random.randn(X_train.shape[1]) # Random weight vector of
        ↪appropriate size
correct, accuracy = classify(X_test, y_test, w_random)
print(f"Random classification accuracy: {accuracy * 100:.2f}%")

```

Random classification accuracy: 69.68%

We can verify that the output makes sense for random weight vectors by calculating the mean over N trials:

```

[7]: avg_arr=[]
    for i in range(0,100):
        w_random = np.random.randn(X_train.shape[1]) # Random weight vector of
        ↪appropriate size
        correct,accuracy=classify(X_test,y_test,w_random)
        avg_arr.append(accuracy)

    print(f"average accuracy is: {np.mean(avg_arr)}")

```

average accuracy is: 0.5088715396154371

As expected, we get a value around 50%

## 0.4 Exercise 4

Let

$$X \in \mathbb{R}^{n \times d}$$

be a data matrix,

$$\underline{\omega} \in \mathbb{R}^{d \times 1}$$

be the parameter vector, and

$$\underline{y} \in \mathbb{R}^{n \times 1}$$

be the vector of target labels.

Let  $\sigma(z)$  denote the **sigmoid function**, defined as:

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

We define the following cost function for logistic regression with  $L_2$  regularization:

$$J(\underline{\omega}) = \sum_{i=1}^n L(y_i x_i^T \underline{\omega}) + \frac{\lambda}{2} \|\underline{\omega}\|^2$$

where

$$L(s) = \log(1 + e^{-s})$$

is the logistic loss function.

#### 0.4.1 Gradient of the Logistic Regression Cost Function

Using the chain rule, we find the expression for the gradient of  $J(\underline{\omega})$  with respect to  $\omega_j$ . The gradient of the cost function  $J(\underline{\omega})$  with respect to  $\underline{\omega}$  is given by:

$$\frac{\partial J(\underline{\omega})}{\partial \omega_j} = \lambda \omega_j - \left( \sum_{i=1}^n \frac{\exp(-y_i x_i^T \underline{\omega})}{1 + \exp(-y_i x_i^T \underline{\omega})} y_i x_i^T \right) e_j$$

Let  $z^T$  represent the row vector in the summation above:

$$z^T = \sum_{i=1}^n \frac{\exp(-y_i x_i^T \underline{\omega})}{1 + \exp(-y_i x_i^T \underline{\omega})} y_i x_i^T$$

Then, the gradient can be rewritten as:

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - \begin{bmatrix} z^T e_1 \\ z^T e_2 \\ \vdots \\ z^T e_d \end{bmatrix} = \lambda \underline{\omega} - \begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_d \end{bmatrix} = \lambda \underline{\omega} - \underline{z}$$

By transposing  $z^T$  to obtain  $\underline{z}$ , we get:

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - \sum_{i=1}^n \frac{\exp(-y_i x_i^T \underline{\omega})}{1 + \exp(-y_i x_i^T \underline{\omega})} y_i x_i$$

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - \sum_{i=1}^n \frac{1}{1 + \exp(y_i x_i^T \underline{\omega})} y_i x_i$$

Since  $\frac{1}{1 + \exp(y_i x_i^T \underline{\omega})} = \sigma(-y_i x_i^T \underline{\omega})$ , this simplifies to:

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - \sum_{i=1}^n \sigma(-y_i x_i^T \underline{\omega}) y_i x_i$$

Let  $u_i = \sigma(-y_i x_i^T \underline{\omega}) y_i$ , which essentially rescales  $y$  by the sigmoid function. Defining a new vector  $\underline{u}$  with entries  $u_i$ , we can rewrite the gradient as:

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - \sum_{i=1}^n u_i x_i$$

Since  $x_i^T$  represents a row of the matrix  $X$ , the vector  $\underline{x}_i$  is, consequently, a column of the transposed matrix  $X^T$ . With this observation, we can see that the sum above simplifies to a matrix-vector product:

$$\nabla J(\underline{\omega}) = \lambda \underline{\omega} - X^T \underline{u}$$

where the components of  $\underline{u}$  are given by  $u_i = \sigma(-y_i x_i^T \underline{\omega}) y_i$ .

## 0.5 Exercise 5

```
[8]: import numpy as np
from scipy.special import expit # Efficient sigmoid for sparse

def sigmoid(z):
    """Using Scipy's own Sigmoid function optimized for sparse matrices."""
    return expit(z)

def logistic_regression(X, y, alpha=0.001, reg_lambda=10, K=100):
    """
    Logistic regression using gradient descent with L2 regularization.
    Arguments:
    X -- sparse data matrix (CSC format)
    y -- labels
    alpha -- learning rate
    reg_lambda -- regularization constant
    K -- number of gradient descent steps

    Returns:
    w -- weight vector
    """
    # Initialize weights
    w = np.zeros(X.shape[1])

    # Gradient descent
    for step in range(K):
        # Prediction and gradient calculation
        scale_vector = sigmoid(-X.dot(w) * y)
        y_rescaled = scale_vector * y
        grad = -X.T.dot(y_rescaled) + reg_lambda * w
        # Update weights
        w -= alpha * grad

    return w

# Hyperparameters
alpha = 0.001
reg_lambda = 10
K = 100
```



```

# Train model
w = logistic_regression(X_train, y_train, alpha, reg_lambda, K)

# Evaluate on test set
correct, accuracy = classify(X_test, y_test, w)
print(f"Test set classification accuracy: {accuracy * 100:.2f}%")

# Calculate cost on training set
weights_vector = sigmoid(-X_train.dot(w) * y_train)
cost = -np.sum(np.log(weights_vector)) + 0.5 * reg_lambda * w.dot(w)
print(f"Cost: {cost / len(y_train):.4f}")

```

Test set classification accuracy: 94.86%  
Cost: 5.1566

```

[9]: # Gathering Data to plot the accuracy of logistic gradient descent
# for different values of reg_lambda and alpha
num_lambdas = 100
num_alphas = 100
reg_lambdas = np.linspace(1, 100, num_lambdas)
alphas = np.linspace(0.001, 0.01, num_alphas)

accuracies = np.zeros((num_lambdas, num_alphas))
for p1, reg_lambda in enumerate(reg_lambdas):
    for p2, alpha in enumerate(alphas):
        w = logistic_regression(X_train, y_train, alpha, reg_lambda, K)
        _, accuracies[p1, p2] = classify(X_test, y_test, w)

```

```

[10]: # Heatmap plot of accuracy
import matplotlib.pyplot as plt
fig, ax = plt.subplots()
plt.xlabel("Regularization Lambda")
plt.ylabel("Learning Rate")
plt.imshow(accuracies)
plt.colorbar()
plt.title("Accuracy for Different Regularization Lambda and Learning Rate_↵
↵Values")

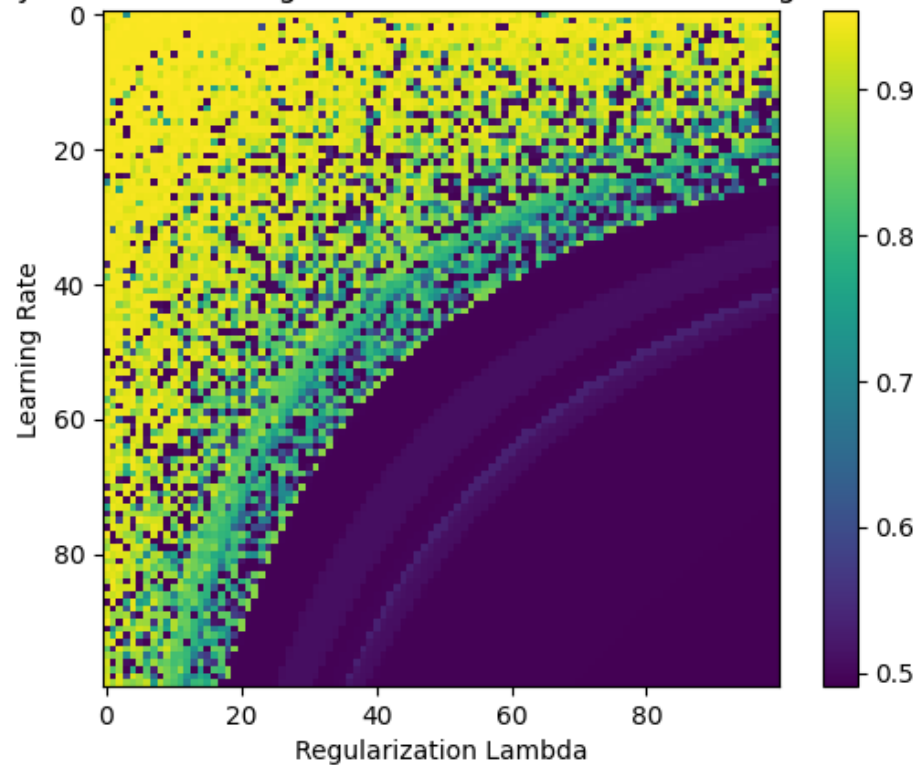
```

```

[10]: Text(0.5, 1.0, 'Accuracy for Different Regularization Lambda and Learning Rate
Values')

```

Accuracy for Different Regularization Lambda and Learning Rate Values



### 0.5.1 Exercise 6)

```
[11]: from sklearn.decomposition import PCA
import numpy as np
import pandas as pd

# Load the dataset with fake points.
csv_data = pd.read_csv("data2.csv")
X = csv_data.iloc[:, :-1].values

# Use PCA with the number of PCA axes the same as our number of features.
# Additionally whiten the data, meaning dividing each column by its standard
# deviation.
pca = PCA(whiten=True)
pca.fit(X)
X_pca = pca.transform(X)

# Affirming that each column has a standard deviation of 1.
epsilon = 0.01
assert np.all(np.abs(np.std(X_pca, axis=0) - 1) <= epsilon)
```

```

# Calculate the norm of points in the whitened PCA basis.
# Points with a large norm can be identified as potential outliers (refer to Lecture 8).
norm = np.linalg.norm(X_pca, axis=1)

# Assuming we know that 2000 fake datapoints were added,
# find the norm threshold that is less than exactly 2000 datapoints
sorted_norm = np.sort(norm)
threshold = sorted_norm[-2000]
print(threshold)
outliers = norm > threshold
# print(len(outliers[outliers==1]))

```

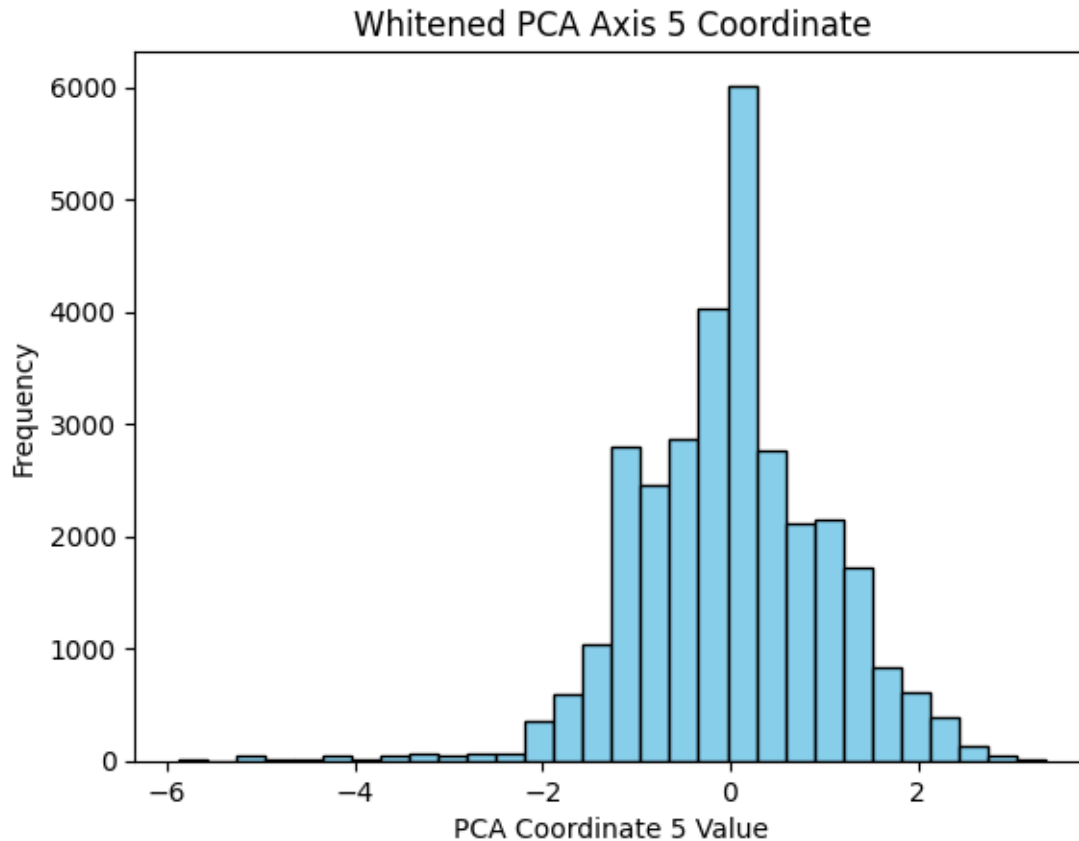
18.703055600592254

```

[12]: import matplotlib.pyplot as plt

# One assumption we made is that the PCA coordinates
# should be normally distributed and in fact we can see this is the case.
plt.hist(X_pca[:, 5], bins=30, color='skyblue', edgecolor='black')
plt.title('Whitened PCA Axis 5 Coordinate')
plt.xlabel('PCA Coordinate 5 Value')
plt.ylabel('Frequency')
plt.show()

```

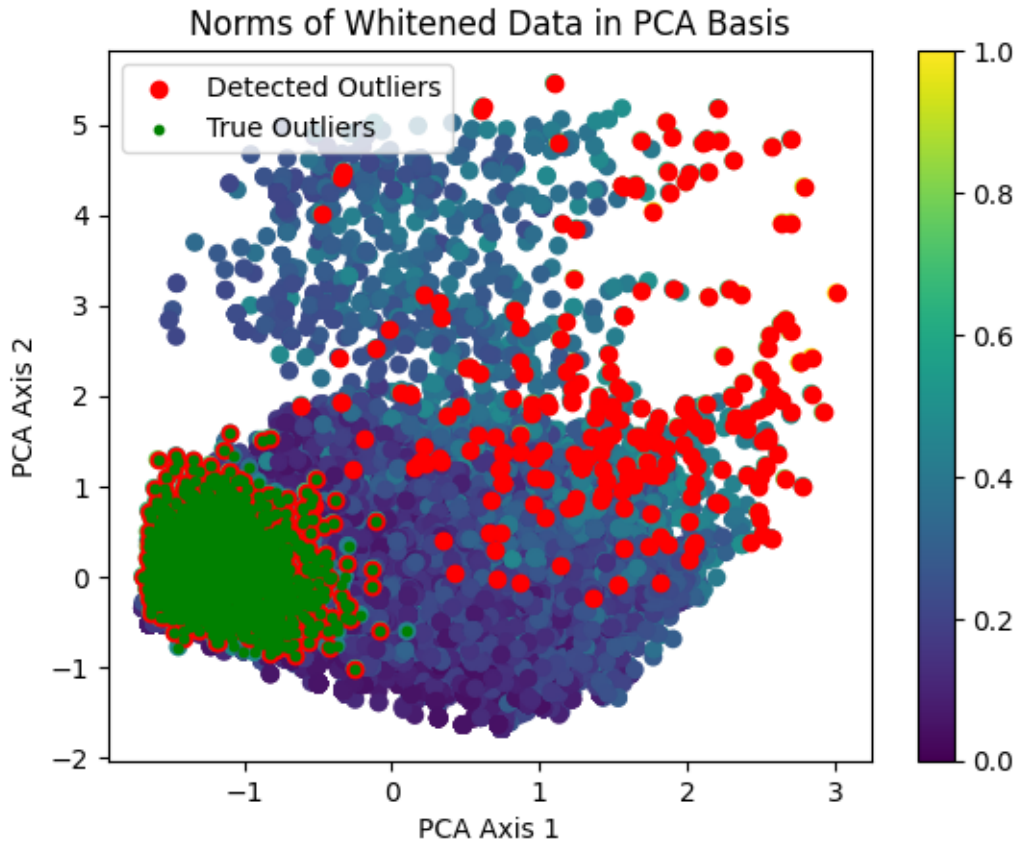


```
[13]: # This visualization shows the outlier points detected by thresholding the
      ↪ norms
      # of the whitened data, compared to the actual fake points that were added.
      # Most of the true fake points are clustered around (-1, 0) in the
      # PCA-1 vs. PCA-2 coordinate space. We can also see that most of fake points
      ↪ were identified.
      # Note: We found that the true outliers were the last 2000 points of X in data2.
      ↪ csv.

      ax1 = 0
      ax2 = 1
      plt.scatter(X_pca[:,ax1], X_pca[:,ax2], c=norm)
      plt.scatter(X_pca[outliers,ax1], X_pca[outliers,ax2], c="red", label="Detected
      ↪ Outliers")
      plt.scatter(X_pca[-2000:,ax1], X_pca[-2000:,ax2],10, c="green", label="True
      ↪ Outliers")
      plt.xlabel("PCA Axis 1")
      plt.ylabel("PCA Axis 2")
      plt.title("Norms of Whitened Data in PCA Basis")
```

```
plt.legend()
plt.colorbar()
```

[13]: <matplotlib.colorbar.Colorbar at 0x73e3ba9b3890>



[14]: *# Fake points detected vs false positive statistics.*

```
outlier_indices = np.array(np.where(outliers)).T
number_fake_detected = np.sum(outlier_indices > X.shape[0]-2000)
print(f"Number of fake points detected: {number_fake_detected}")
print(f"Number of real points falsely detected as fake: {2000 - \
↪number_fake_detected}")
```

Number of fake points detected: 1741

Number of real points falsely detected as fake: 259