

Moses C. Nah

(+1) 617-858-9525 | ✉ mosesnash@mit.com | 📱 [mosesnash-shared](#)

Education

Massachusetts Institute of Technology (MIT)

PH.D. IN MECHANICAL ENGINEERING (MIT MECHE)

Cambridge, MA, USA

May.2020 - Present

Massachusetts Institute of Technology (MIT)

M.S. IN MECHANICAL ENGINEERING (MIT MECHE)

Cambridge, MA, USA

Sep.2018 - May.2020

Seoul National University

B.S. IN MECHANICAL AEROSPACE AND ENGINEERING

- Summa Cum Laude

Seoul, S.Korea

Mar.2011 - Sep.2018

Gyeonggibuk Science High School

EARLY GRADUATION WITH HONORS

Gyeonggi-Do, S.Korea

Mar.2009 - Mar.2011

Publications

Manipulating a Whip in 3D via Dynamic Primitives

MOSES C. NAH, ALEKSEI KROTOV, MARTA RUSSO, DAGMAR STERNAD AND NEVILLE HOGAN

IROS

Prague, Czech Republic, Sep.2021

Online Impedance Adaptation Facilitates Manipulating a Whip

XIAOFENG XIONG, MOSES C. NAH, ALEKSEI KROTOV AND DAGMAR STERNAD

IROS

Prague, Czech Republic, Sep.2021

Dynamic Primitives Facilitate Manipulating a Whip

MOSES C. NAH, ALEKSEI KROTOV, MARTA RUSSO, DAGMAR STERNAD AND NEVILLE HOGAN

- Best Student Paper Award [LINK]

BIOROB

New York, USA, Nov.2020

Motion Planning of Autonomous Personal Transporter Using Model Predictive Control for Minimizing Non-Minimum Phase Behavior

DONGIL CHOI, MINSU KIM, HYEONGKEUN KIM, CHOE JONGHUN AND MOSES C. NAH

International Conference on Ubiquitous Robots (UR)

Honolulu, U.S.A, Jun.2018

Design Analysis of Tuskbot: Universal Stair Climbing 4-Wheel Indoor Robot

JONGHUN CHOE, UKJIN KWON, MOSES C. NAH AND HYEONGKEUN KIM (EQUAL CONTRIBUTIONS)

- 'Tuskbot with Track Mechanism' for Stairs with Large Nose and Stairs without Riser [LINK]
- 'Tuskbot with Length Adjustment Mechanism' for Stairs with Various Height and Depth [LINK]

IROS

Vancouver, Canada, Sep.2017

'Tuskbot': Design of the Mobile Stair Climbing 2 by 2 Wheels Robot Platform with Novel Passive Structure 'Tusk'

JONGHUN CHOE, MOSES C. NAH, HYEONGKEUN KIM AND UKJIN KWON (EQUAL CONTRIBUTIONS)

International Conference on Control, Automation and Robotics (ICCAR)

Nagoya, Japan, Apr.2017

Rocker-Bogie with 'Tusk': Design of the Mobile Robot Platform that can Climb Stairs with Tusk and Rocker-Bogie Mechanism

UKJIN KWON, HYEONGKEUN KIM, MOSES C. NAH AND JONGHUN CHOE (EQUAL CONTRIBUTIONS)

Korea Robotics Society Annual Conference (KROC)

Pyongyang, S.Korea, Feb.2017

Experience

NAVER LABS Robotics Team

Gyeonggi-Do, S.Korea

UNDERGRADUATE INTERNSHIP PROGRAM

Aug.2016 - Feb.2017

- Advisor: Dr. Sang-ok Seok (Leader of NAVER LABS, MIT MECHE, Meshworm and MIT Cheetah)
- Team Project: "Wheel Based Robot which can Climb Stairs"
- Personal Project: "Li-Ion Battery Pack PCB for Universal Usages of NAVER LABS Robots"
- Developed and Patented a Passive Novel Structure 'Tusk'
- Developed and Published Four Successful Stair Climbing Robots

SNU Biorobotics Lab

Seoul, S.Korea

UNDERGRADUATE THESIS

Mar.2017 - Present

- Advisor: Prof. Kyu-Jin Cho (Professor of Seoul National University)
- Stabilized the Underactuation Mechanism of "SNU Exo-Glove Poly"
- Developed Circuitry for Material Stiffness Identification

Honors & Awards

2020	Best Student Paper Award , 2020 BIOROB	New York, NY, USA
2020	First Place Presenter, \$500 Award , 2020 MIT MERE	Cambridge, MA, USA
2018	₩1,500,000 Start-Up Investment , SNU Start-Up Camp	Seoul, S.Korea
2017	Excellence Award with ₩1,500,000 , SNU Smart Social Contribution Contest	Seoul, S.Korea
2017	Excellent Paper Award with ₩500,000 Prize , SNU CTL 26th Best Report Contest	Seoul, S.Korea
2017	Young Talent Support Scholarship , NAVER LABS	Seoul, S.Korea
2017	Gwanak Special Intention Scholarship , Hanil Corporation	Seoul, S.Korea
2013	Grand Prize Award , Design, Manufacturing Process and Laboratory Contest	Seoul, S.Korea
2011	First Runner-Up Prize Award , Creative Engineering and Design Contest	Seoul, S.Korea
2009	International Physics Olympiad Candidate , Winter and Summer School Completion	Seoul, S.Korea
2009	Gold Medal Prize , 12 th Korea Physics Olympiad High School Session	Seoul, S.Korea
2009	First Place , Task Assignment Test before High-School Admission	Seoul, S.Korea
2008	Silver Medal Prize , 11 th Korea Physics Olympiad Middle School Session	Seoul, S.Korea

Presentations and Invited Talks

Conference Presentations

- 2021 **ICRA (Virtual)**
- 2020 **Neural Control of Movement** Blitz Talk
- 2020 **BIOROB** Best Student Paper Award, [LINK]
- 2020 **Neuromatch Conference 3.0** [LINK]

Poster Presentations

- 2022 **MIT De Florez Competition**
- 2022 **MIT MERE**
- 2021 **DO-Sim at RSS (Robotics: Science and Systems)**
- 2021 **Neural Control of Movement**
- 2020 **MIT MERE** First Place Presenter, \$500 Award
- 2020 **IROS Workshop** Impedance Learning, [LINK 1] [LINK 2]
- 2019 **MIT MERE**
- 2019 **MIT Embodied Intelligence Research Mixer**

Invited Talks

- 2017 **TEDx SNU Salon** Presenter for TED Session: People who make Something

Patents

- 2017 **KR10-2017-0037517**, Assistive Device for Stair Climbing Robot Seoul, S.Korea

Teaching Experience

Teaching Assistant

Cambridge, MA, USA

2.151 ADVANCED SYSTEM DYNAMICS & CONTROL

- Overall Rating: 6.8/7.0

Group and Personal Tutor

Seoul, S.Korea

COURSES FROM SNU LIBERAL EDUCATION

- Tutor of Science and Technology Writing Class - 2017 Autumn, 2018 Spring Semester
- Tutor of Basic Physics Class Students - 2012 Autumn, 2013 Spring Semester
- Tutor of Basic Calculus Class Students - 2012 Spring, 2012 Autumn, 2013 Spring, 2018 Spring Semester

Group Tutor

Seoul, S.Korea

SNU SOCIAL RESPONSIBILITY (SNUSR)

- Group Tutor of Arduino Class

Extracurricular Activity

Voluntary TA for Quas - Dynamics

Cambridge, MA, USA

MIT MECHE

2021 - Present

Seongnam City Bundang Borough Office

Gyeonggi-Do, S.Korea

SOCIAL SERVICE AGENT

Jun.2014 - Jun.2016

- Bureaucratic Book Binder

SNU in Washington D.C

Washington D.C, U.S.A.

MEMBER

Oct.2013 - Jan.2014

- 'SNU in Series' Global Visiting Program
- Seoul National University Special Talent Training Program

SNU NGO Dream Consultant

Chungju, S.Korea

MEMBER

Aug.2013 - Sep.2013

- Mentor of Chungju High School

Media

MIT News

[LINK]

Nov.2020

Yonhap News

[LINK]

Oct.2017

Hankyung Economics

[LINK]

Jun.2017

Skills

PROGRAMMING LANGUAGES

- C/C++, Python, R, Bash

MARKUP LANGUAGES

- LaTeX, HTML, XML, RMarkdown

VERSION CONTROL

- GIT

OTHERS

- Matlab, MuJoCo, ROS, Docker, LabVIEW

CADs

- KiCAD, Solidworks

LANGUAGE

- English, Korean