Question 1

Let A be a matrix composed of the column vectors, such that $A = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \\ -1 & -2 & 3 \\ 0 & -1 & 2 \end{pmatrix}$. We first

note that the system contains no solution:

$$\operatorname{rref}\left(A \mid \overrightarrow{\mathbf{b}}\right) = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Using A\b, we find that the least-squares solution is $\vec{\mathbf{x}}^* = A \setminus b = \begin{pmatrix} 1/4 \\ 0 \\ 1/4 \end{pmatrix}$. Hence, the closest

point from
$$\vec{\mathbf{b}}$$
 is $A\vec{\mathbf{x}}^* = \mathbf{A} * (\mathbf{A} \setminus \mathbf{b}) = \begin{pmatrix} 1/2 \\ 1/2 \\ 1/2 \\ 1/2 \end{pmatrix}$.

Question 2

Refer to section %% Question 2 in the math425hw5.m file for the relevant code.

Method one

This method involves using the QR decomposition. Where $A = QR = \begin{pmatrix} 1 & 2 & 1 \\ 2 & 1 & 0 \\ -1 & -2 & 3 \\ 0 & -1 & 2 \end{pmatrix}$, we

have that

$$A\vec{\mathbf{x}} = \vec{\mathbf{b}}$$

$$QR\vec{\mathbf{x}} = \vec{\mathbf{b}}$$

$$Q^{\top}QR\vec{\mathbf{x}} = Q^{\top}\vec{\mathbf{b}}$$

$$R\vec{\mathbf{x}} = Q^{\top}\vec{\mathbf{b}}.$$

Since Q is orthogonal, $Q^{\top}Q = I$. And since R is upper triangular, we can simply solve for $\vec{\mathbf{x}}$ by performing backward substitution. With our ol' reliable myBackwardSubstitution and the QR factorization of A, the least-squares solution is given by

$$\overrightarrow{\mathbf{x}} = \text{myBackwardSubstitution(R, Q'*b)} = \begin{pmatrix} -1 \\ 2 \\ 3 \end{pmatrix}$$
.

MATH 425

This method involves using the Cholesky decomposition. Since $A^{T}A$ is symmetric, Using

This method involves using the Cholesky decomposition. Since $A^{T}A$ is symmetric, Using MATLAB, we can find the Cholesky factorization using chol(A'A). Where R is an upper triangular matrix such that $R^{T}R = A^{T}A$, we have that

$$A^{\top} A \overrightarrow{\mathbf{x}} = A^{\top} \overrightarrow{\mathbf{b}} \iff R^{\top} R \overrightarrow{\mathbf{x}} = A^{\top} \overrightarrow{\mathbf{b}}$$
$$\iff R^{\top} \overrightarrow{\mathbf{y}} = A^{\top} \overrightarrow{\mathbf{b}}$$

where $\vec{\mathbf{y}} = R\vec{\mathbf{x}}$.

As such, we can compute the least-squares solution in two steps. First, solve the lower triangular system for \vec{y} :

$$\vec{y} = \texttt{fixed.forwardSubstitute(R', A'*b)} = \begin{pmatrix} -5.4272... \\ 6.0554... \\ 7.6731... \end{pmatrix}$$

Then, solve the upper triangular system, giving us the least-squares solution

$$\vec{\mathbf{x}} = \texttt{fixed.backwardSubstitute(R, y)} = \begin{pmatrix} -1 \\ 2 \\ 3 \end{pmatrix}$$
.

Question 3

Refer to section %% Question 3 in the math425hw5.m file for the relevant code.