

Bundle adjustment:

$$\arg \min_{q, p, f} \sum_{i=1}^m \sum_{j=1}^n \| \pi(q_{wci}, p_{wci}, f_j) - z_{f_j}^{c_i} \|_{\Sigma_{ij}}$$

\uparrow
特征点3D坐标.

最小=乘问题求解:

定义 $x^* \in \mathbb{R}^n$, 使 $F(x)$ 局部最小.

$$F(x) = \frac{1}{2} \sum_{i=1}^m (f_i(x))^2$$

局部最小指 对任意, $\|x - x^*\| < \delta$ 有 $F(x^*) \leq F(x)$

二阶泰勒展开:

$$F(x + \Delta x) = F(x) + J\Delta x + \frac{1}{2}\Delta x^T H \Delta x + o(\|\Delta x\|^3) \quad (2)$$

迭代法 1. 找到下降方向的单位向量 d .

2. 确定下降步长 α .

对 $F(x)$ 进行一阶泰勒展开:

$$F(x + \alpha d) \approx F(x) + \alpha Jd$$

下降方向满足 $Jd < 0$.

通过 line search 找到下降步长:

$$\alpha^* = \arg \min_{\alpha > 0} \{ F(x + \alpha d) \}$$

最速下降法寻找单位向量 d :

$$Jd = \|J\| \cos \theta, \theta \text{ 表示下降方向和梯度夹角.}$$

$$\theta = \pi \rightarrow d = -J^T$$

\therefore 梯度的负方向为最速下降方向.

牛顿法: 在局部最优 x^* 附近, 如果 $x + \Delta x$ 最优, 则损失函数对 Δx 的导数为 0, 对 (2) 求一阶导:

$$\frac{\partial}{\partial \Delta x} \left(F(x) + J\Delta x + \frac{1}{2} \Delta x^T H \Delta x \right)$$

$$= J^T + H\Delta x = 0 \rightarrow \Delta x = -H^{-1} J^T.$$

\uparrow
二阶导矩阵计算复杂.

阻尼牛顿法: 二阶泰勒展开:

$$F(x + \Delta x) \approx L(\Delta x) \equiv F(x) + J\Delta x + \frac{1}{2} \Delta x^T H \Delta x$$

$$\Delta x \equiv \arg \min_{\Delta x} \left\{ L(\Delta x) + \frac{1}{2} \mu \Delta x^T \Delta x \right\}.$$

\uparrow
 $\mu > 0$ 为阻尼因子.

$$\frac{1}{2} \mu \Delta x^T \Delta x = \frac{1}{2} \mu \|\Delta x\|^2 \text{ 是惩罚项. 限制 } \Delta x \text{ 不要走太远}$$

求一阶导并令其为 0:

$$L'(\Delta x) + \mu \Delta x = 0$$

$$\Rightarrow (H + \mu I) \Delta x = -J^T$$

非线性最小二乘:

$$f(x) = \begin{bmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{bmatrix}$$

$$\therefore f^T(x) f(x) = \sum_{i=1}^M (f_i(x))^2$$

令 $J_i(x) = \frac{\partial f_i(x)}{\partial x}$, 则有

$$\frac{\partial f(x)}{\partial x} = J = \begin{bmatrix} J_1(x) \\ \vdots \\ J_m(x) \end{bmatrix}$$

残差 $f(x)$ 为非线性, 一阶泰勒展开:

$$f(x + \Delta x) \approx l(\Delta x) \equiv f(x) + J \Delta x$$

J 是残差函数 f 的雅可比矩阵.

代入损失函数:

$$F(x + \Delta x) \approx L(\Delta x) \equiv \frac{1}{2} l(\Delta x)^T l(\Delta x)$$

$$= \frac{1}{2} f^T f + \Delta x^T J^T f + \frac{1}{2} \Delta x^T J^T J \Delta x$$

$$= F(x) + \Delta x^T J^T f + \frac{1}{2} \Delta x^T J^T J \Delta x \quad (7)$$

\therefore 损失函数近似成二次函数, 并且如果雅可比满秩, $J^T J$ 正定,

损失函数有最小值.

$Jx=0$ 等价于 $x=0$.

令 (7) 导数为 0:

$$J^T f + J^T J \Delta x = 0$$

$$\therefore (J^T J) \Delta x_{gn} = -J^T f.$$

$$\text{用 } J^T J \text{ 近似 } H: H \Delta x_{gn} = b.$$

Normal equation.

$$\therefore F(x + \Delta x) \approx F(x) + \Delta x^T J^T f, \therefore F'(x) = (J^T f)^T$$

$$F(x + \Delta x) \approx F(x) + \Delta x^T J^T f + \frac{1}{2} \Delta x^T J^T J \Delta x. \therefore F''(x) = J^T J.$$

LM: 对高斯牛顿法加入阻尼, 限制 Δx 不要跑太远.

$$(J^T J + \mu I) \Delta x_{lm} = -J^T f, \mu \geq 0.$$

$\mu > 0$ 保证 $(J^T J + \mu I)$ 正定, 迭代朝下降方向进行.

$\mu \gg 0$, $\Delta x_{lm} = -\frac{1}{\mu} J^T f$. 接近最速下降.

$\mu \ll 0$, $\Delta x_{lm} \approx \Delta x_{gn}$, 接近高斯牛顿.

阻尼因子更新策略通过比例因子确定:

$$\rho = \frac{F(x) - F(x + \Delta x_{lm})}{L(0) - L(\Delta x_{lm})}$$

$$\begin{aligned}
 L(0) - L(\Delta x_{lm}) &= -\Delta x_{lm}^T J^T f - \frac{1}{2} \Delta x_{lm}^T J^T J \Delta x_{lm} \\
 &= -\frac{1}{2} \Delta x_{lm}^T (-2b + (J^T J + \mu I - \mu I) \Delta x_{lm}) \\
 &= \frac{1}{2} \Delta x_{lm}^T (\mu \Delta x_{lm} + b) > 0.
 \end{aligned}$$

$$\therefore \rho = \frac{F(x) - F(x + \Delta x_{lm})}{\frac{1}{2} \Delta x_{lm}^T (\mu \Delta x_{lm} + b)}$$

$\rho < 0$, 则 $F(x) \uparrow$, 应 $\mu \uparrow \rightarrow \Delta x \downarrow$, 增大阻尼减小步长.

$\rho \gg 0$, 减小 μ , 让 LM 接近 GN, 使收敛加快.

$\rho > 0$ 但 ρ 较小, 则增大 μ , 减小步长.

鲁棒核函数.

$$\min_x \frac{1}{2} \sum_k \rho(\|f_k(x)\|^2).$$

误差平方项记为 $S_k = \|f_k(x)\|^2$, 则鲁棒核函数 = 泰勒展开:

$$\frac{1}{2} \rho(s) = \frac{1}{2} (\text{const} + \rho' \Delta s + \frac{1}{2} \rho'' \Delta^2 s)$$

对变量 Δx 求导, 令其为 0:

$$\sum_k J_k^T (\rho' I + 2\rho'' f_k f_k^T) J_k \Delta x = - \sum_k \rho' f_k^T J_k.$$

$$\sum_k J_k^T W J_k \Delta x = - \sum_k \rho' f_k^T J_k.$$

$$\text{令 } W = \rho' I: J^T J \Delta x = - J^T f$$

