

em simple

h_exp_first

inside

↓ below is E step.

- try every permutations between the prior axis and the sigma quadric axis.

log_hammer_obs2

↑ inside

first term:

$$\updownarrow ((\text{obs_gen} - \text{mu_data})' * \text{prec_data} * (\text{obs_gen} - \text{mu_data})) / \text{length}(\text{mu_data});$$
$$\log(P(\zeta_i, z_i | c_i')) \propto (x_i - c_i')' \frac{1}{\sigma} I_3 (x_i - c_i') + \zeta_i^T \frac{1}{\sigma} I_3 \zeta_i \quad (14).$$

second term:

$$\min(10^{15}, -\log(\text{ghm.pdf}(M(2,3)'))));$$

$$\updownarrow \zeta_i^T \frac{1}{\sigma} I_3 \zeta_i \quad (14)$$

$$\text{axes} = (n(1) * \text{sqr}(\text{abs}(P * M(2:3) + \text{mu})));$$

$$\text{axes} = \text{axes}.^{1/2};$$

$$\text{obs_gen} = C * R * \text{axes};$$

$$x_i = G' R i z_i (V \zeta_i + \mu_{ci})$$

back to h_exp_first:

```
[modi, lgP] = gmmcmc(minit, logPfuns, 1000, 'thinchain', 1);
```

this runs the MCMC inference to find the expectation of latent variables $\{\hat{z}_i, \hat{\xi}_i\}$ under the posterior.

Optimize the orientation:

```
obs = C * Rm * l;
```

```
x = lsqnonlin(@(x) cost(x, C, obs, l), init_angle);
```

```
function C = cost(angles, G, C, l)
```

```
R = rot_euler2rot(angles)';
```

```
Rm = [R(1, :).^2; ...];
```

```
C = norm(G * Rm * l - C);
```

```
end.
```

In paper (15): $\hat{\theta} = \arg \min_{\theta} \|\hat{x}_i - c_i\|^2$

$\hat{x}_i = G^T R_i \hat{z}_i (V_i^A + \mu).$

back to em-simple, M step

In M step, use estimate of \hat{u}_i to estimate noise cov. $\hat{\sigma}_i^2$:

$$\hat{C} = \frac{1}{3} \sum_{i=1}^3 \{ \|C_i\|^2 - 2W_i^T G^T C_i + \text{trace}(W_i^T W_i G^T G^T) \} \quad (17)$$

where is the trace term?

in code:

`diagnoise(i) = measure(i,:) * measure(i,:)' - (C(i,:) * Eh * measure(i,:))';`

`diagnoise(i) = diagnoise(i) / n_images3;`