COGS260 Image Recognition Instructor: Prof. Zhuowen Tu

A spatiotemporal model with visual attention for video classification

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Outline

Motivation

Proposed model

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Motivation

Video classification

- Semantic understanding of sequential visual input is important for robots in localization and object detection.
- ▶ Eg, search for a cat in a living room, instead of in a gym.



Source: Harvey M., Five video classification methods

Motivation

Rotation and scale

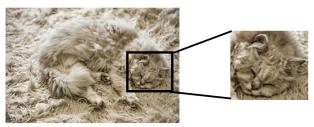
- Existing benchmark contains videos of daily scenes.
- Objects in real world could be rotated and scaled.



Motivation

Visual attention

Attention mechanism reduces complexity and avoids cluttering. This makes it easier to deal with rotated and scaled images.

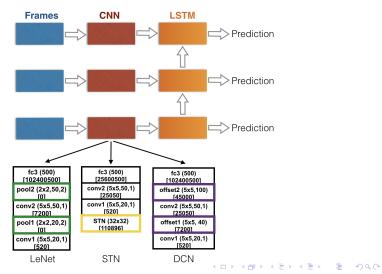


Source: cs231n, Stanford

Proposed model

Architecture

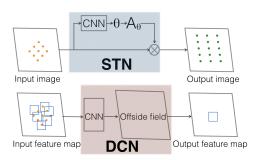
- The proposed model concatenates CNN to RNN.
- ► The CNN stage is augmented with attention modules.



Proposed model

Attention modules

- ► Spatial transformer network learns a global affine transformation.
- Deformable convolutional networks learns offsets locally and densely.



Experiment

Dataset

Moving MNIST is augmented with rotation and scaling.

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Experiment

Quantitative analysis

▶ DCN-LSTM consistently performs the best in all cases.

TABLE I: Comparison of cross entropy loss and test accuracy for the proposed model and baseline.

Moving MNIST	-	LeNet-LSTM	STN-LSTM	DCN-LSTM
Normal	Ī	1.39, 98.2%	2.07, 84.9%	1.27, 99.7%
Rotation		1.32,99.3%	1.85, 92.2%	1.15,99.8%
Scaling	1	1.51, 97.5%	1.96, 89.8%	1.23,99.2%
Rotation+Scaling	Ī	1.64,95.8%	2.04, 88.2%	1.23,99.2%

Experiment

Qualitative analysis

STN could not attend to each digits individually.



Conclusion

Key insights

- ▶ DCN-LSTM achieves high accuracy compared to baseline.
- Attention modules are useful to deal with rotation and scale changes.
- ► STN-LSTM does not perform well due to global transformation.
- How to train the entire model end to end remains a future work.