# Artificial Intelligence

**CSE 440** 

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## **Biological inspiration**

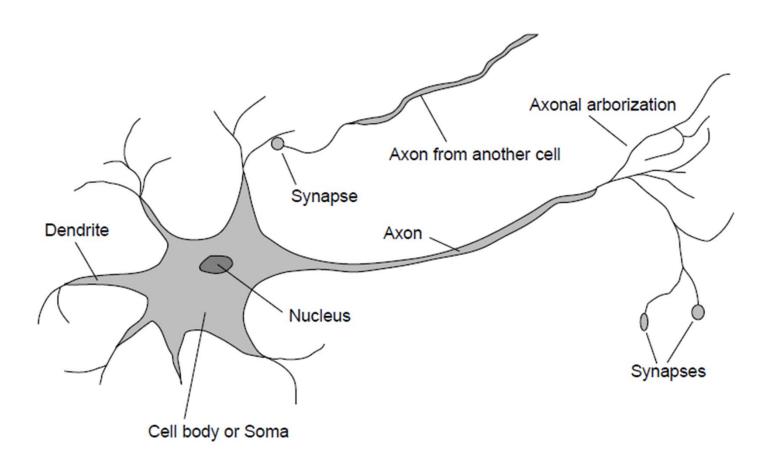
 Animals are able to react adaptively to changes in their external and internal environment, and they use their nervous system to perform these behaviours.

 An appropriate model/simulation of the nervous system should be able to produce similar responses and behaviours in artificial systems.

 The nervous system is build by relatively simple units, the neurons, so copying their behaviour and functionality should be the solution.

### **Biological inspiration**

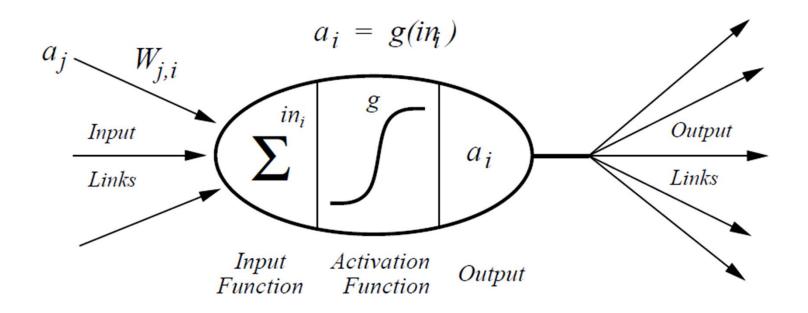
- 10<sup>11</sup> neurons of > 20 types, 1014 synapses, 1ms–10ms cycle time
- Signals are noisy "spike trains" of electrical potential



#### **Neural Networks**

- A neural network consists of a set of nodes (neurons/units) connected by links
  - Each link has a numeric weight
- Each unit has:
  - A set of input links from other units
  - A set of output links to other units
  - A current activation level
  - An activation function to compute the activation level in the next time step

#### **Basic definitions**



 A gross oversimplification of real neurons, but its purpose is to develop understanding of what networks of simple units can do

#### **Basic definitions**

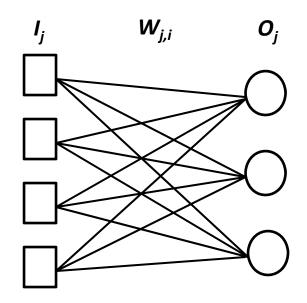
 The total weighted input is the sum of the input activations times their respective weights:

$$in_i = \sum_j W_{j,i} a_j$$

In each step we compute:

$$a_i \leftarrow g(in_i) = g(\sum_j W_{j,i} a_j)$$

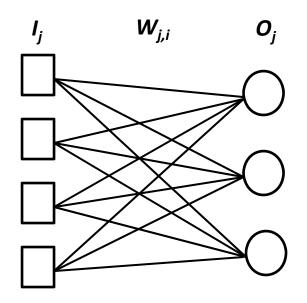
## Learning in single layer network



 If the output for an output unit is O, and the correct output should be T, then the error is given by:

$$Err = T - O$$

## Learning in single layer network



The weight adjustment rule is:

$$W_j \leftarrow W_j + \alpha X I_j X Err$$

where  $\alpha$  is a constant called the learning rate

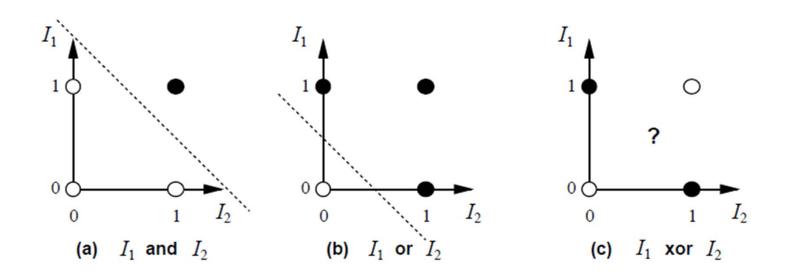
### **Learning Network Structures**

- Different functions are implemented by different network topologies and unit weights.
- The lure of NNs is that a network need not be explicitly programmed to compute a certain function *f*.
- Given enough nodes and links, a NN can learn the function by itself.
- It does so by looking at a training set of input/output pairs for f and modifying its topology and weights so that its own input/output behavior agrees with the training pairs.
- In other words, NNs too learn by induction.

### **Computing with NNs**

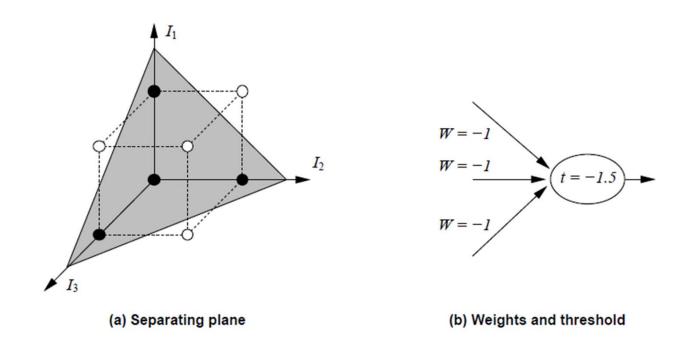
- The structure of a NN is given by its nodes and links.
- The type of function a network can represent depends on the network structure.
- Fixing the network structure in advance can make the task of learning a certain function impossible.
- On the other hand, using a large network is also potentially problematic.
- If a network has too many parameters (ie, weights), it will simply learn the examples by memorizing them in its weights (overfitting).

#### Linearly Separable Functions on a 2-dimensional Space



 A black dot corresponds to an output value of 1. An empty dot corresponds to an output value of 0.

#### Linearly Separable Functions on a 3-dimensional Space



 The minority function: Return 1 if the input vector contains less ones than zeros. Return 0 otherwise.

### **Learning Steps**

Learn by adjusting weights to reduce error on training set

The squared error for an example with input x and true output y is

$$E = \frac{1}{2}Err^2 \equiv \frac{1}{2}(y - h_{\mathbf{W}}(\mathbf{x}))^2 ,$$

Perform optimization search by gradient descent:

$$\frac{\partial E}{\partial W_j} = Err \times \frac{\partial Err}{\partial W_j} = Err \times \frac{\partial}{\partial W_j} \left( y - g(\sum_{j=0}^n W_j x_j) \right)$$
$$= -Err \times g'(in) \times x_j$$

Simple weight update rule:

$$W_j \leftarrow W_j + \alpha \times Err \times g'(in) \times x_j$$

E.g., +ve error  $\Rightarrow$  increase network output  $\Rightarrow$  increase weights on +ve inputs, decrease on -ve inputs