# PHY 107 Center of mass and Linear momentum

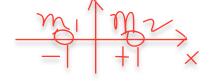
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## **OUTLINE**

- Center of mass
- Newton's second law for a system of particles
- Linear Momentum
- ▶ Linear Momentum of a system of particles
- Collision and Impulse
- Conservation of linear momentum
- Momentum and Kinetic Energy in collisions
- ► Elastic and Inelastic collision in 1D

## Center of mass



The center of mass of a system of particles is the point that moves as though (1) all of the system's mass were concentrated there and (2) all external forces were applied there.  $1 \times 1$ 

## System of particles

n particles are strung out along the x-axism2,  $x_{com} = \frac{m_1x_1 + m_2x_2 + m_3x_3 + \dots + m_nx_n}{m_1 + m_2 + \dots + m_n}$ 

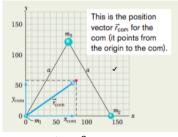
#### Solid bodies

 $x_{com} = \frac{1}{M} \int x \ dm, \ y_{com} = \frac{1}{M} \int y \ dm, \ z_{com} = \frac{1}{M} \int z \ dm$  We look into uniform objects

- 1. Point, line or plane of symmetry
- 2. The center of mass of an object need not lie within the object.

## Center of mass

**EXAMPLE** Three particles of masses  $m_1 = 1.2kg$ ,  $m_2 = 2.5kg$ , and  $m_3 = 3.4kg$  form an equilateral triangle of edge length a 140 cm. Where is the center of mass of this system?



Particle	Mass (kg)	x (cm)	y (cm)
1	1.2	0	0
2	2.5	140	0
3	3.4	70	120

$$x_{com} = \frac{1}{M} \sum_{i=1}^{3} m_i x_i = 83 \text{ cm}$$
  
 $y_{com} = \frac{1}{M} \sum_{i=1}^{3} m_i y_i = 58 \text{ cm}$ 

M = m1 + m2 + m3

m1x1+m2x2+m3x3



# Newton's Second law for a system of particles

The governing equation of the motion of the center of mass of a system of particles is

 $\overrightarrow{F_{net}} = M\overrightarrow{a_{com}}$  (system of particles)

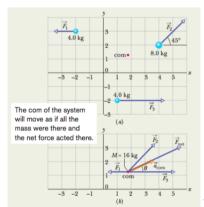
What exactly are these three quantities?





# Newton's second law for a system of particles

**EXAMPLE** Motion of the com of three particles The three particles are initially at rest. Each experiences an external force due to bodies outside the three-particle system. The directions are indicated, and the magnitudes are  $F_1 = 6.0N$ ,  $F_2 = 12N$ , and  $F_3 = 14N$ . What is the acceleration of the center of mass of the system, and in what direction does it move?



# Newton's second law for a system of particles

### Solution

$$a_{com,x} = \frac{F_{1x} + F_{2x} + F_{3x}}{M}$$
  
 $a_{com,y} = \frac{F_{1y} + F_{2y} + F_{3y}}{M}$ 

If you have a in unit vector notation, then you can easily find the magnitude and the angle

## Linear Momentum



The linear momentum of a particle is a vector quantity  $\overrightarrow{p}$  that is defined as:  $\overrightarrow{p} = m\overrightarrow{V}$ 

Newtons' second law:  $\overrightarrow{F_{net}} = \frac{d\overrightarrow{p}}{dt}$ 

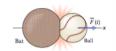
The system as a whole has a total linear momentum  $\overrightarrow{P}$ , which is defined to be the vector sum of the individual particles' linear momenta.

$$\overrightarrow{P} = \overrightarrow{p_1} + \overrightarrow{p_2} + \dots + \overrightarrow{p_n} = m_1 \overrightarrow{v_1} + m_2 \overrightarrow{v_2} + \dots + m_n \overrightarrow{v_n}$$

The linear momentum of a system of particles is equal to the product of the total mass M of the system and the velocity of the center of mass

# Collision and Impulse

Collisions are common in the world and we aim to study collisions where a moving particle like body collides with some other body (a target)



$$\int_{t_i}^{t_f} d\overrightarrow{p} = \int_{t_i}^{t_f} \overrightarrow{F}(t) dt$$

 $\int_{t_i}^{t_f} d\overrightarrow{p} = \int_{t_i}^{t_f} \overrightarrow{F}(t)dt$   $\Delta \overrightarrow{p} = \overrightarrow{J} \text{ (linear momentum-impulse theorem)}$ 

The impulse in the collision is equal to the area under the curve.



## Conservation of linear momentum

The net external force  $\overrightarrow{F_{net}}$  (and thus the net impulse  $\overrightarrow{J}$ ) acting on a system of particles is zero (the system is isolated) and that no particles leave or enter the system (the system is closed)

 $\overrightarrow{P} = constant$  $\overrightarrow{P}_i = \overrightarrow{P}_f$  (closed, isolated system)

If the component of the net external force on a closed system is zero along an axis, then the component of the linear momentum of the system along that axis cannot change.

# Momentum and Kinetic Energy in collisions

# Inelastic:COLM,COE Elastic:COLM,COKE,COE

**Elastic Collision**Total kinetic energy of a system of two colliding bodies remains the same.

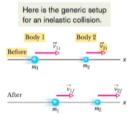
**Inelastic collision** Total kinetic energy of the system is not conserved.

What happens when we drop a ball on a surface?

TKE\_(i) = 
$$10 J$$
  
TKE\_(f) =  $8 J$ 

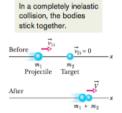
## Inelastic collision in 1D

#### 1D inelastic collision



$$m_1v_{1i} + m_2v_{2i} = m_1v_{1f} + m_2v_{2f}$$

## 1D completely inelastic collision



$$m_1 v_{1i} = (m_1 + m_2)V$$



#### **EXAMPLE** Ballistic Pendulum

The ballistic pendulum was used to measure the speeds of bullets before electronic timing devices were developed. The version below consists of a large block of wood of mass M=5.4~kg, hanging from two long cords. A bullet of mass m=9.5~g is fired into the block, coming quickly to rest. The block bullet then swing upward, their center of mass rising a vertical distance h=6.3~cm before the pendulum comes momentarily to rest at the end of its arc. What is the speed of the bullet just prior to the collision?



# **EXAMPLE** Ballistic Pendulum

### Solution:

Total momentum before collision =Total momentum after collision The mechanical energy of the bullet-block-Earth system is conserved: Mechanical energy at bottom= mechanical energy at top:

$$0.5(m+M)V^2 = (m+M)gh$$

The ballistic pendulum is a kind of 'transformer' exchanging the high speed of a light object (the bullet) for the low and thus more easily measurable speed of a massive object (the block).

## Elastic Collisions in 1D

In an elastic collision, the kinetic energy of each colliding body may change, but the total kinetic energy of the system does not change.

#### Two cases:

- 1. Stationary target
- 2. Moving target

Stationary target:

A projectile body of mass  $m_1$  and initial velocity  $v_{1i}$  moves toward a target body of mass  $m_2$  that is initially at rest  $v_{2i} = 0$ .

$$m_1 v_{1i} = m_1 v_{1f} + m_2 v_{2f}$$
 (linear momentum).  $0.5 m_1 v_{1i}^2 = 0.5 m_1 v_{1f}^2 + 0.5 m_2 v_{2f}^2$   $v_{1f} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i}$   $v_{2f} = \frac{2m_1}{m_1 + m_2} v_{1i}$ 

## Stationary target continued....

A few special situations:

- 1. Equal masses:  $v_{1f} = 0, v_{2f} = v_{1i}$
- 2. A massive target:  $v_{1f} = -v_{1i}, v_{2f} \approx \left(\frac{2m_1}{m_2}\right)v_{1i}$
- 3. A massive projectile:  $v_{1f} \approx v_{1i}, v_{2f} \approx 2v_{1i}$

## Moving target

$$m_1 v_{1i} + m_2 v_{2i} = m_1 v_{1f} + m_2 v_{2f}$$

$$0.5 m_1 v_{1i}^2 + 0.5 m_2 v_{2i}^2 = 0.5 m_1 v_{1f}^2 + 0.5 m_2 v_{2f}^2$$

$$v_{1f} = \frac{m_1 - m_2}{m_1 + m_2} v_{1i} + \frac{2m_2}{m_1 + m_2} v_{2i}$$

$$v_{2f} = \frac{2m_1}{m_1 + m_2} v_{1i} + \frac{m_2 - m_1}{m_1 + m_2} v_{2i}$$

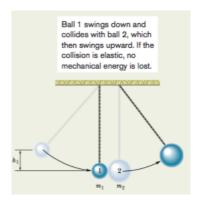
Given, m1,m2 v\_(1i) v (2i)

v\_(1f) and v\_(2f)?

## Elastic collision

**EXAMPLE** Elastic Collision, Two pendulums

Two metal spheres, suspended by vertical cords, initially just touch. Sphere 1, with mass  $m_1=30g$ , is pulled to the left to height  $h_1=8.0cm$ , and then released from rest. After swinging down, it undergoes an elastic collision with sphere 2, whose mass  $m_2=75g$ . What is the velocity  $v_{1f}$  of sphere 1 just after the collision?



## Elastic collision

#### Solution

Apply COE for the descent of sphere 1 Think about conservation of momentum for the two sphere collision

$$0.5m_1v_{1i}^2 = m_1gh_1 \ v_{1f} = rac{m_1-m_2}{m_1+m_2}v_{1i} pprox -0.54 \ \mathrm{m/s}$$

## Problems of importance:

Check the book (Edition: Extended 9th)

Center of mass: 1

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Collision and impulse: 25

Conservation of Linear Momentum: 39

Inelastic collisions in 1D: 49, 51 Elastic collisions in 1D: 61, 63, 65

## Reference

Fundamentals of Physics by Halliday and Resnik