

Computer Networks: Link Layer and LANs

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Link Layer

5.1 Introduction and services

5.2 Error detection and
correction

5.3 Multiple access protocols

WiFi

5.4 Link-layer Addressing

5.5 Ethernet

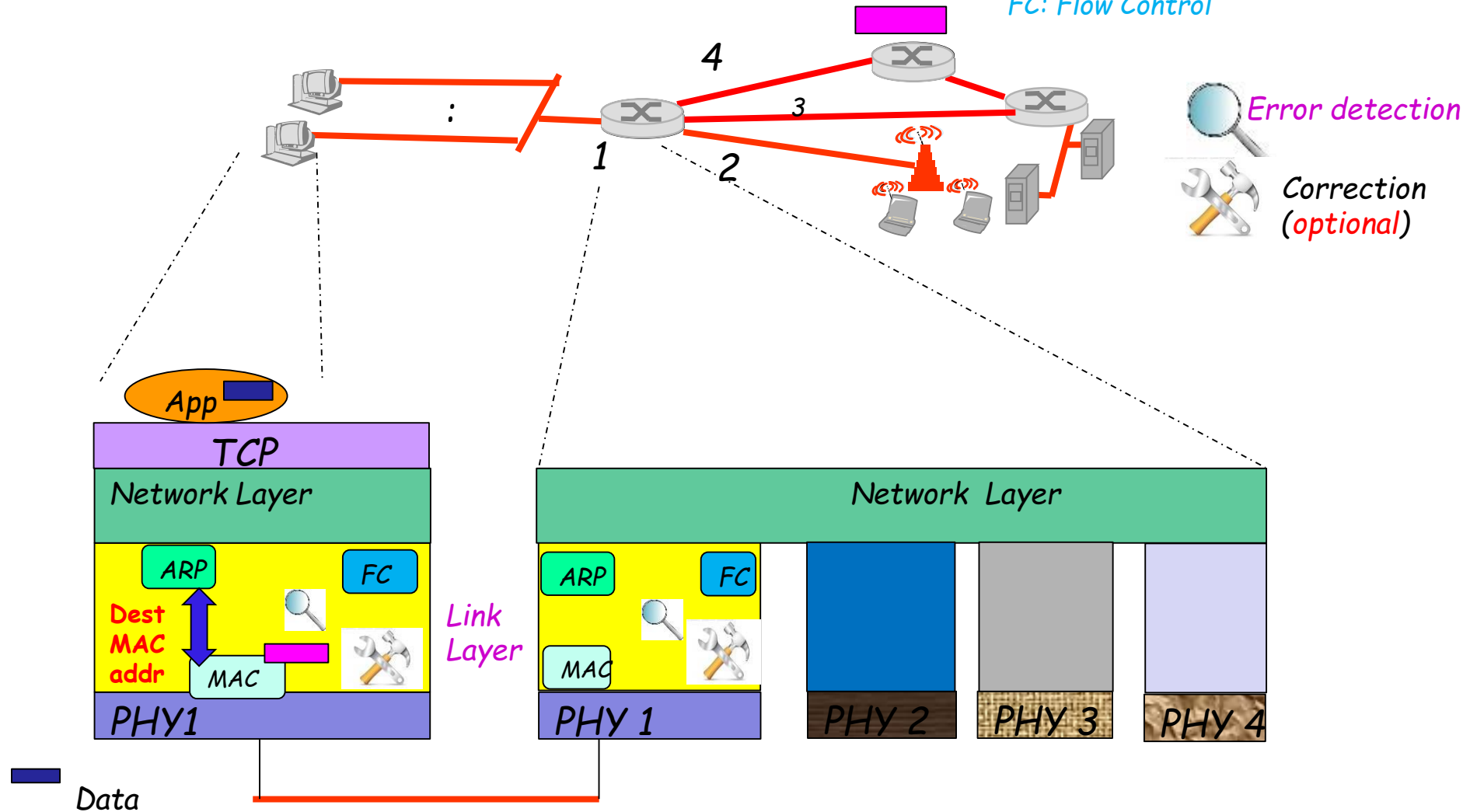
5.6 Link-layer switches

3.4 Reliable data transfer +
flow control

Link layer: context

MAC: Medium Access Control

FC: Flow Control



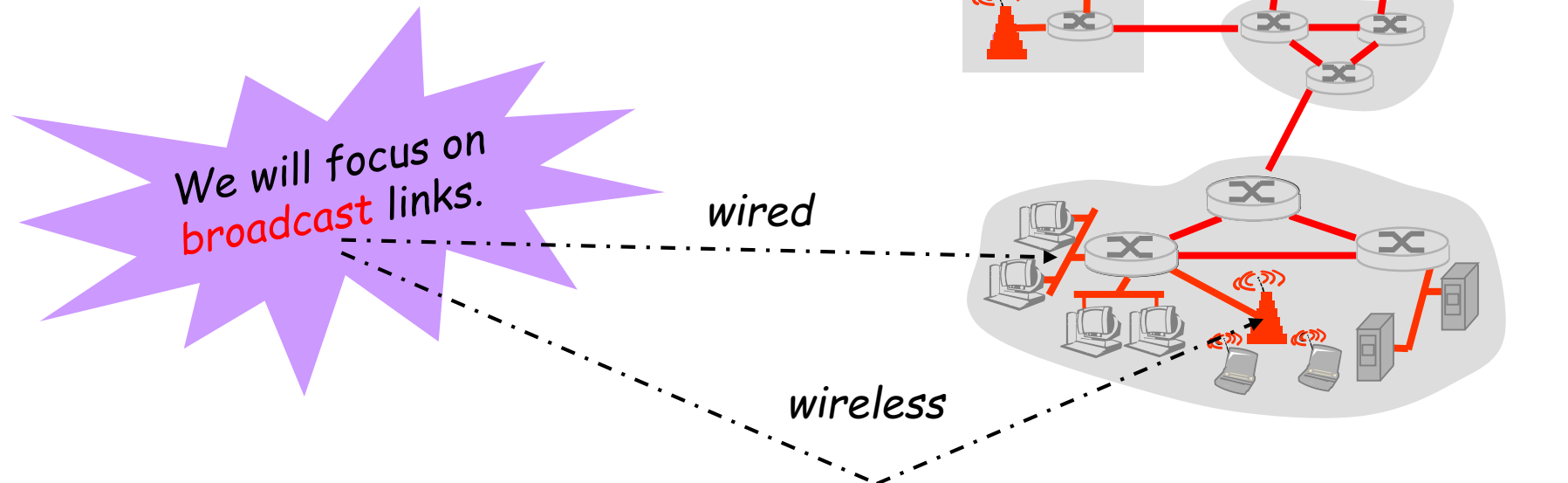
ARP (Address Resolution Protocol): IP address → MAC address
(%ipconfig /all ← for MAC addresses.)

PHY: Physical layer ← hardware

Link Layer: Introduction

Terminology:

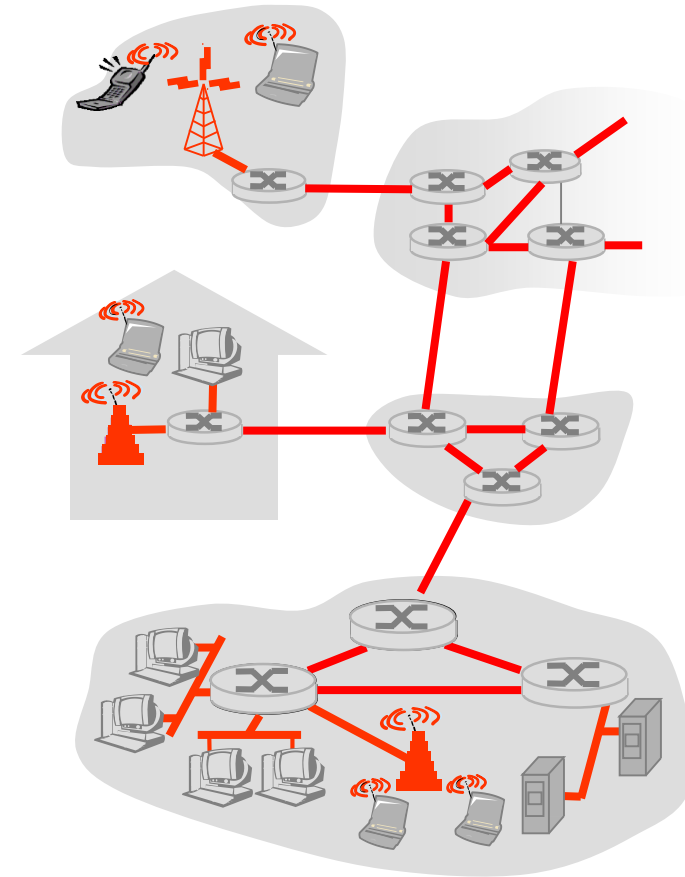
- ❖ hosts and routers are **nodes**
- ❖ **communication channels** that connect adjacent nodes are **links**
 - wired links
 - wireless links



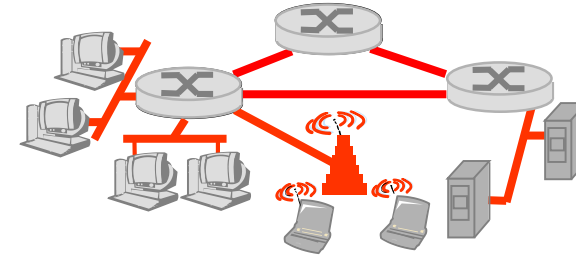
Our goals:

- ❖ understand principles behind **data link layer services:**

- 1 **link access by sharing a broadcast channel:** multiple access
 - Instruct the hardware (PHY layer) **when** to transmit (... MAC protocols)
- 2 link layer **addressing**



Link Layer Services (more)



❖ *error detection:*

3

- errors **caused by** signal attenuation and noise
- receiver **detects** presence of errors

❖ *error correction:*

- receiver **identifies and corrects** bit error(s) without resorting to **retransmission**
- receiver **signals sender** for **retransmission**

4

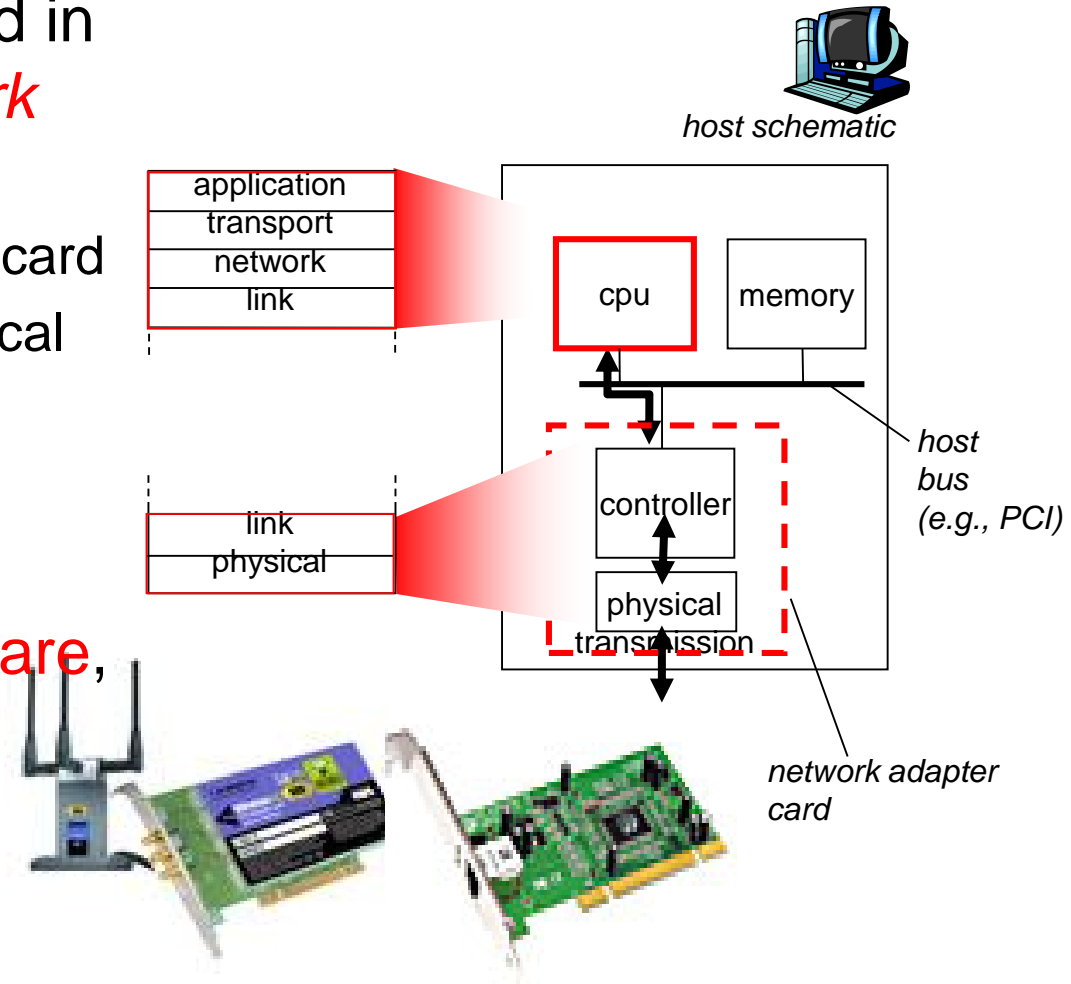
❖ *flow control:*

- pacing between (adjacent) sending and receiving nodes

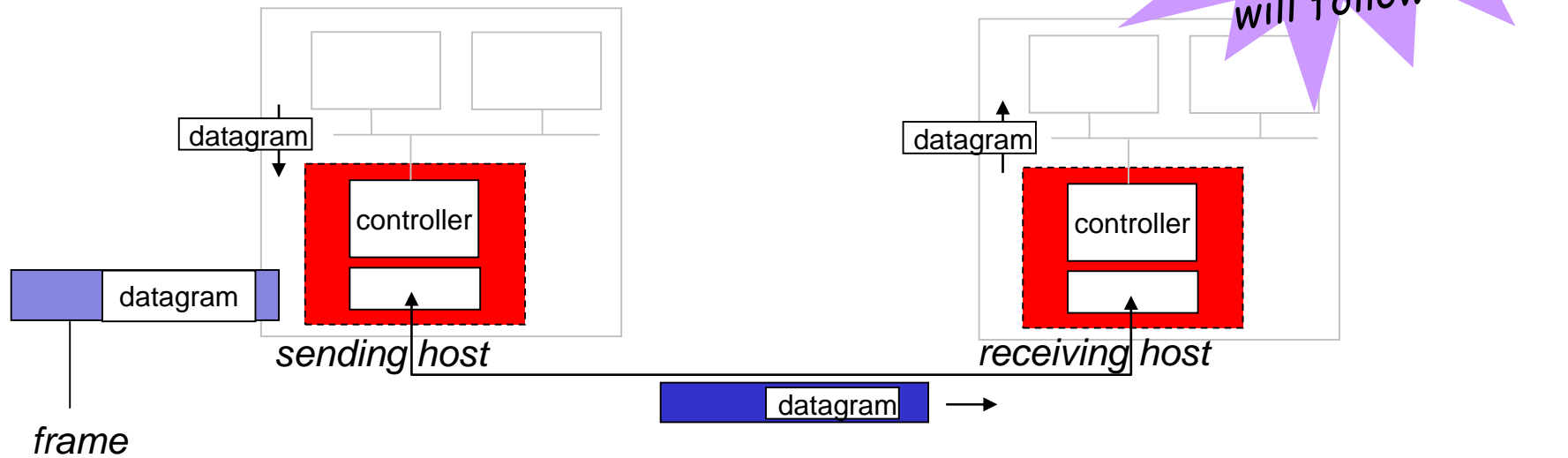


Where is the link layer implemented?

- ❖ in each and every host
- ❖ link layer implemented in “adaptor” (aka **network interface card** NIC)
 - Ethernet card, 802.11 card
 - implements link, physical layer
- ❖ attaches into host's system buses
- ❖ combination of **hardware**, **software**, **firmware**



Adaptors Communicating



❖ sending side:

- encapsulates datagram in frame
- adds **error checking bits**, and sequence # for flow control

❖ receiving side

- looks for errors
- extracts datagram, passes to upper layer at receiving side

Link Layer

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5.7 PPP

3.4 Reliable data transfer



Bit errors in frame (packet) transmissions

Transmitted: 1 0 1 1 1 0 0 1

Received: 1 0 0 1 1 0 1 1

Bit error is generally **bursty**

Tx: 1 0 1 1 0 1 0 0 1 1 1 0 0 1 1 1

Rx: 1 0 0 0 1 0 0 0 1 1 1 0 0 1 1 1

Metric used to represent transmission media

BER: Bit Error Rate

Example: $4/16 = 0.25$

BER = # of bit errors / Total # of bits transmitted

BER (copper): 10^{-8}

BER (wireless): 10^{-5}

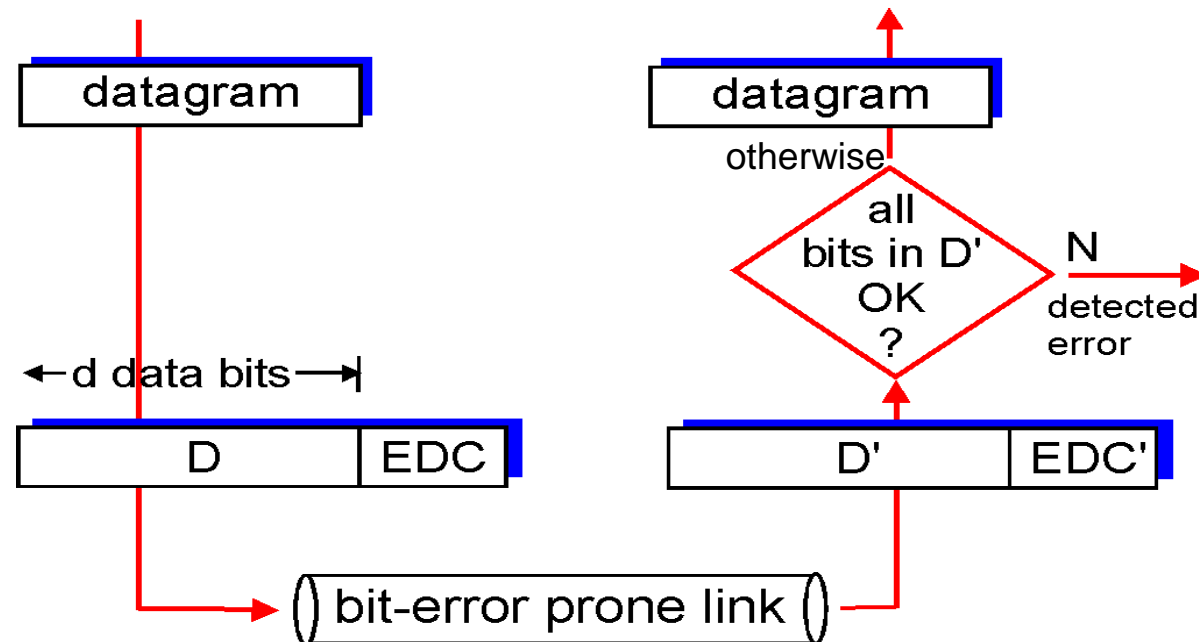
BER (fibre optics): 10^{-12}

Error Detection

EDC = Error Detection and Correction bits (redundancy)

D = Data protected by error checking, may include header fields

- Error detection **not** 100% reliable!
 - protocol may miss some errors, but rarely
 - **larger** EDC field yields **better** detection and correction



What are all the **error detection mechanisms** that I will learn



Parity bits (today ...)

You will learn ...



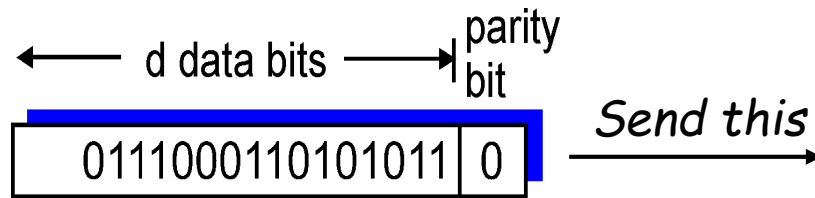
CRC:
Cyclic Redundancy Check (Link layer)

Internet Checksum
(Network Layer, Transport Layer)

Parity Checking

Single Bit Parity:

Detect single bit errors

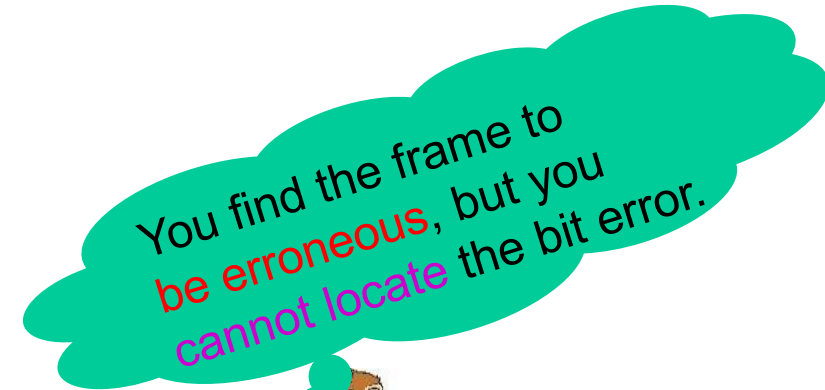


(Example of **odd** parity)

Two kinds of parity:

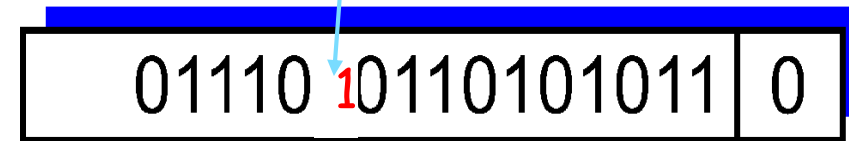
* **Odd parity:** Set the parity bit to 1 or 0 to make the total # of 1's an odd number.

* **Even parity:** Set the parity bit to 1 or 0 to make the total # of 1's an even number



You find the frame to be **erroneous**, but you cannot locate the bit error.

..... But, this is received



When you compute the parity bit, you know that it should be a '1'.

Use two-dimensional bit parity to detect and correct single bit errors

Parity Checking (Two dimensional)

				row parity →
	$d_{1,1}$...	$d_{1,j}$	$d_{1,j+1}$
	$d_{2,1}$...	$d_{2,j}$	$d_{2,j+1}$

	$d_{i,1}$...	$d_{i,j}$	$d_{i,j+1}$
column parity ↓	$d_{i+1,1}$...	$d_{i+1,j}$	$d_{i+1,j+1}$

Detect and correct single bit errors

1	0	1	0	1	1
1	1	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

Even parity

Send this

... but this is
what you
receive

1	0	1	0	1	1
1	0	1	1	0	0
0	1	1	1	0	1
0	0	1	0	1	0

Inconsistent
Row....

Inconsistent
column....

Fix this error
 $0 \rightarrow 1$.

Applications of Parity Checking

Where is parity checking used?
Not generally in network protocols
these days...



RAID: Redundant Array of Inexpensive Drives

DES: Data Encryption Standard for
symmetric-key cryptography



But, it is used
here and here
and here



Media access is a **noisy process**.....
because of **imperfect fabrication**
and **hardware aging**.

What kinds of questions
can be asked on the exams?



ECE358
Mid-term S'12



For the following **four bytes**
of data, compute the
two dimensional **odd** parity bits.


1	1	0	0	1	1	0	1	
1	0	1	1	1	0	1	1	
0	1	1	0	1	0	1	1	
1	0	0	0	0	1	0	1	

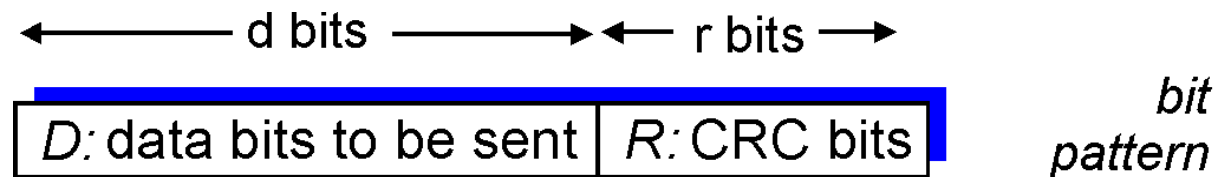
For the data and parity bits
generated above, **introduce four bit
errors** that the **receiver** will not be
able to detect...

ECE358
Mid-term F'12



Checksumming: Cyclic Redundancy Check

- ❖ view **data bits**, **D**, as a binary number
- ❖ **choose** $r+1$ bit pattern (generator), **G**
- ❖ **goal**: compute r CRC bits, **R**, such that
 - $\langle D, R \rangle$ is exactly divisible by **G** (modulo 2)  **← zero remainder**
 - receiver knows **G**:
Divides $\langle D, R \rangle$ by **G**. If **non-zero remainder**: error detected!
- ❖ can detect all burst errors less than $r+1$ bits
- ❖ widely used in practice (Ethernet LAN, 802.11 WiFi, ...)



$$D * 2^r \text{ XOR } R$$

mathematical formula

CRC Example:

Want:

$$D \cdot 2^r \text{ XOR } R = nG$$

equivalently:

$$D \cdot 2^r = nG \text{ XOR } R$$

equivalently:

if we **divide** $D \cdot 2^r$ by G ,
we get remainder R

$$R = \text{remainder} \left[\frac{D \cdot 2^r}{G} \right]$$

Properties of XOR:

$$A \text{ XOR } A = 0$$

$$A \text{ XOR } 0 = A$$

$$(A \text{ XOR } B) \text{ XOR } C = A \text{ XOR } (B \text{ XOR } C)$$

Process: Calculation of CRC

If the **input** bit **above** the **leftmost divisor** bit is **1**,
the divisor is **XORed** into the input.

Else (the **input** bit **above** the **leftmost divisor** bit is **0**) do nothing.

The **divisor** is then **shifted one bit** to the right (\rightarrow)

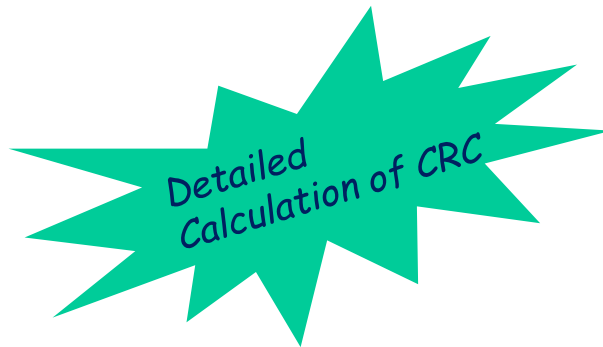
The process is **repeated until**

the **divisor reaches** the **right-hand end** of the input row.

Input: $D \cdot 2^r$ \longrightarrow 1 0 1 1 1 0 0 0 0

Divisor: G \longrightarrow 1 0 0 1

Align input and divisor on MSB



0 0 1 0 1 0 0 0 0
1 0 0 1

0 0 1 0 1 0 0 0 0
1 0 0 1

0 0 0 0 1 1 0 0 0
1 0 0 1

0 0 0 0 1 1 0 0 0
1 0 0 1

0 0 0 0 0 1 0 1 0
1 0 0 1

0 0 0 0 0 0 0 1 1

R

$D = 101110$

$G = 1001$

Transmit $\langle D, R \rangle$: 101110011



What questions
can be asked on the exams?

For the data bits $D = 11001101$ and
generator bits $G = 1011$,
compute the CRC bits.

ECE358
Mid-term S'12



What is the *disadvantage* of making
the CRC field as long as the data portion of a frame?



D: 11001101 000?
G: 1011

What is the length
of the CRC field?



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5.9 A day in the life of a web
request

Multiple Access Links and Protocols

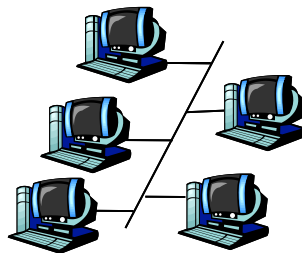
Two types of “links”:

❖ **point-to-point**

- PPP for dial-up access

❖ **broadcast** (shared wire or medium)

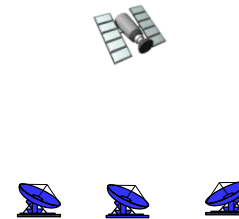
- old-fashioned Ethernet
- 802.11 wireless LAN



shared wire (e.g.,
cabled Ethernet)



shared RF
(e.g., 802.11 WiFi)



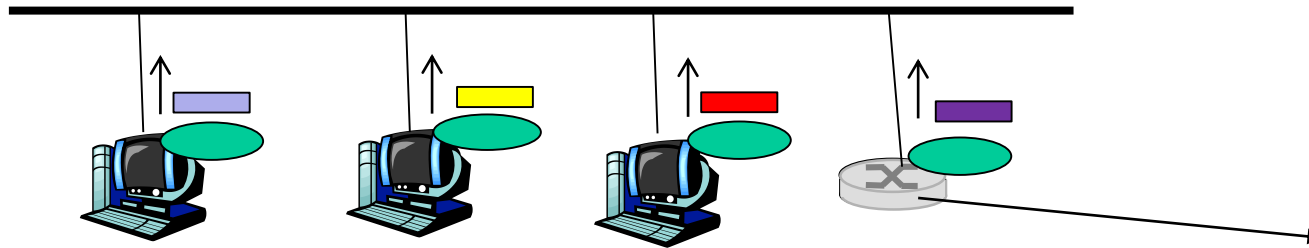
shared RF
(satellite)



humans at a
cocktail party
(shared air, acoustical)

Multiple Access protocols

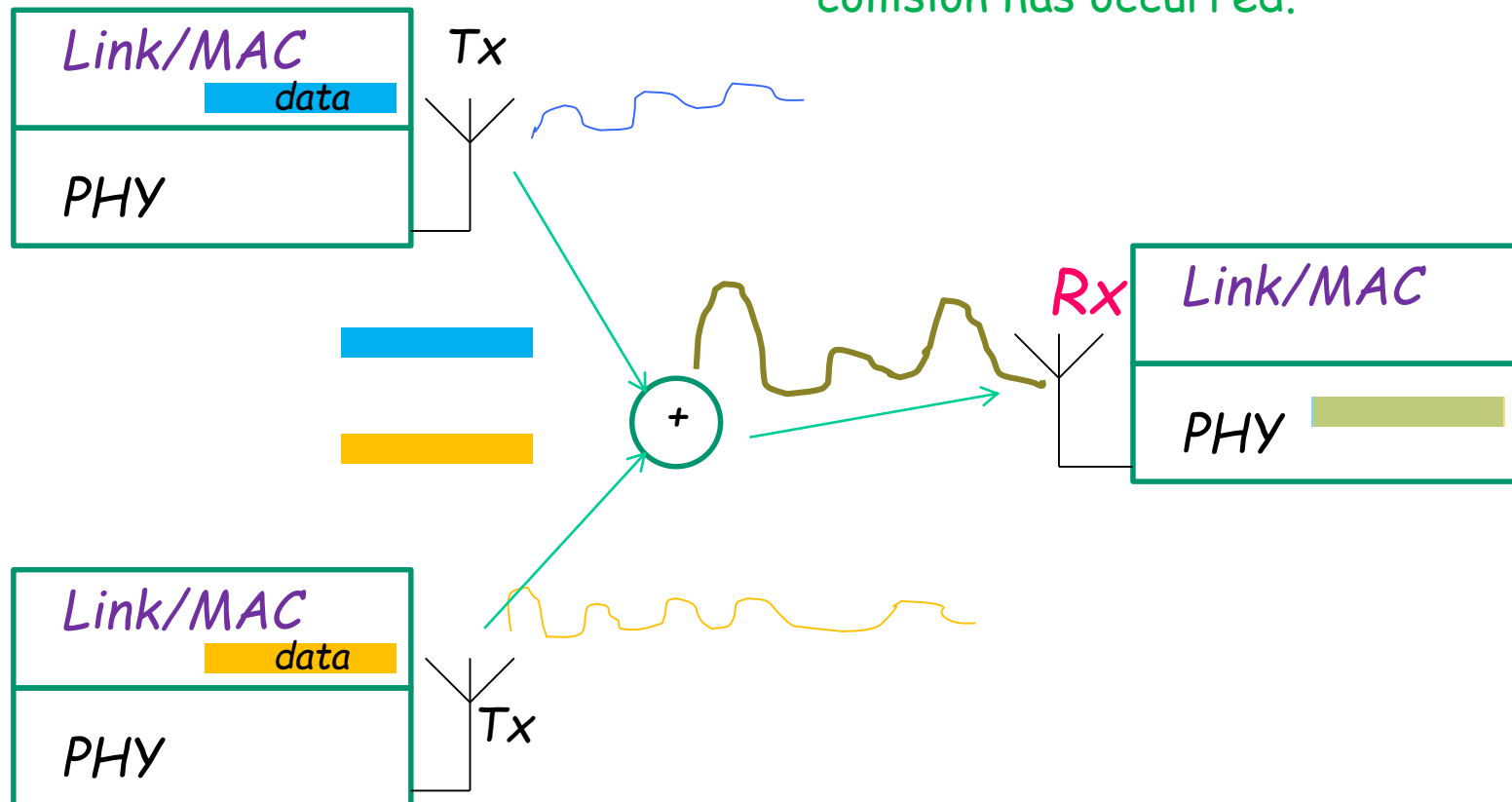
- ❖ single shared broadcast channel
- ❖ two or more simultaneous transmissions cause collision
- ❖ multiple access protocol
 - distributed algorithm that determines when a node can transmit



Packet Collision

Note

Packet collision occurs at the receiver, but transmitters must know that collision has occurred.



Ideal Multiple Access Protocol

Broadcast channel of rate R bps

1. when one node wants to transmit, it can send at rate R .
2. when M nodes want to transmit, each can send at average rate R/M
3. fully decentralized:
 - no special node to coordinate transmissions
 - no synchronization of clocks, slots
4. simple (plug-and-play, no complex hardware, ...)

MAC Protocols: a taxonomy

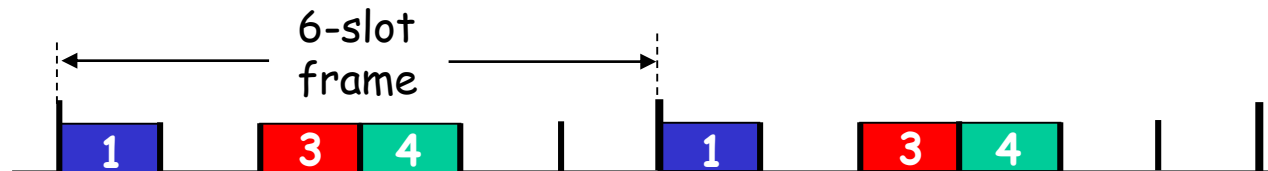
Three broad classes:

- ❖ **Channel Partitioning** (Commonly done in cellular networks)
 - divide channel into smaller “pieces” (time slots, frequency)
 - allocate piece to node for **exclusive use**
- ❖ **Random Access**
 - channel not divided, allow collisions
 - “recover” from collisions OR do not let collision happen
- ❖ **“Taking turns”**
 - nodes take turns

Channel Partitioning MAC protocols: TDMA

TDMA: time division multiple access

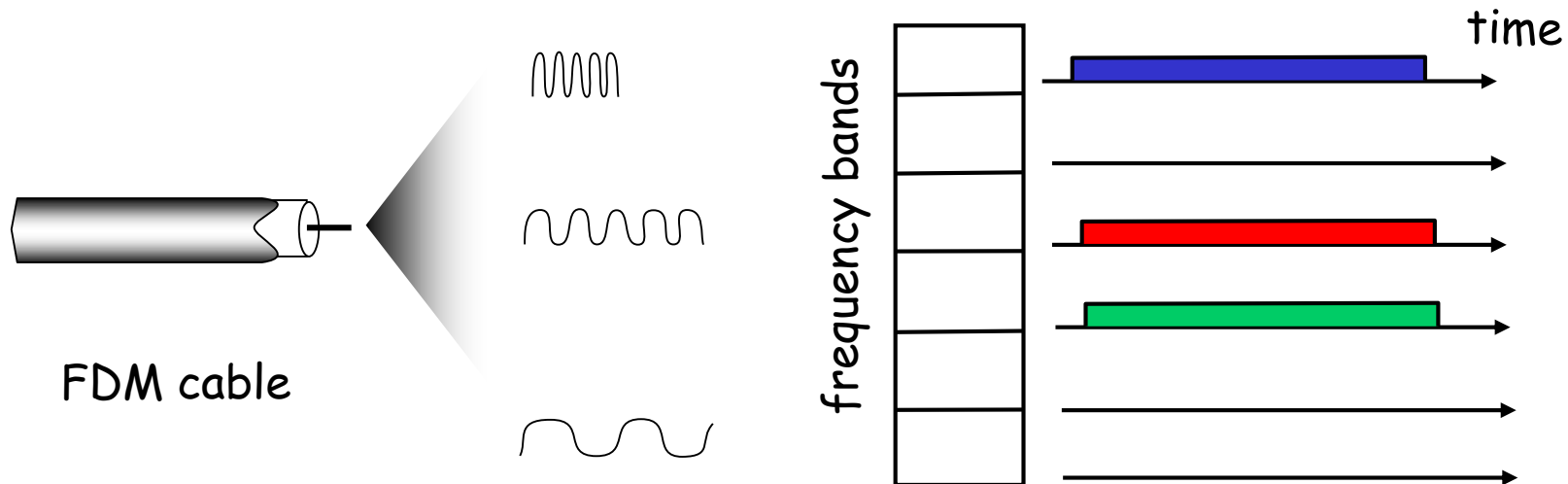
- ❖ access to channel in "rounds"
- ❖ each station gets fixed length slot (length = pkt trans time) in each round
- ❖ unused slots go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, slots 2,5,6 idle



Channel Partitioning MAC protocols: FDMA

FDMA: frequency division multiple access

- ❖ channel spectrum divided into frequency bands
- ❖ each station assigned fixed frequency band
- ❖ unused transmission time in frequency bands go idle
- ❖ example: 6-station LAN, 1,3,4 have pkt, frequency bands 2,5,6 idle



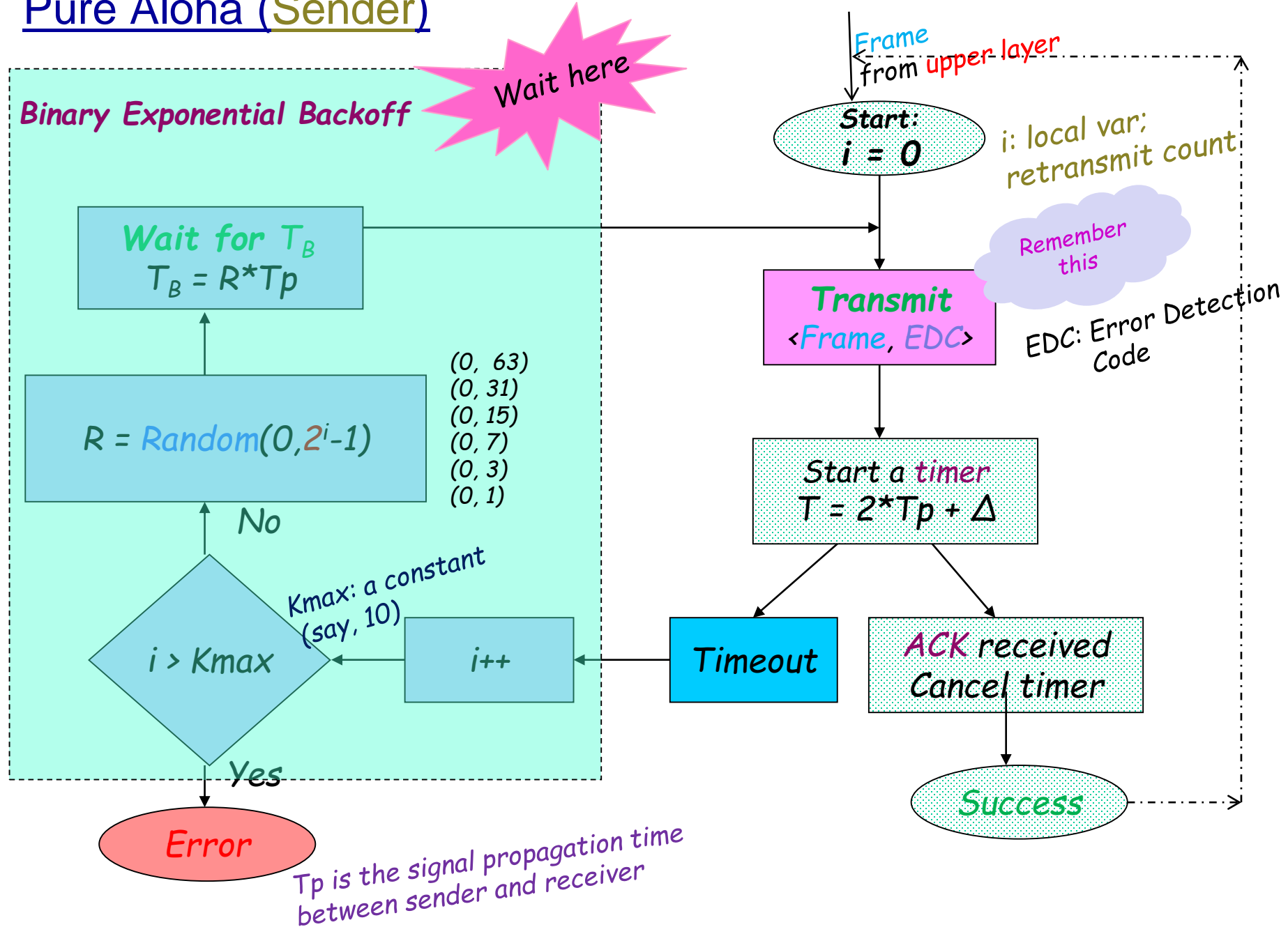
Random Access Protocols

- ❖ When node has packet to send
 - transmit at full channel data rate R .
 - no *a priori* coordination among nodes (...partial exception in WiFi)
- ❖ two or more transmitting nodes → “collision”,
- ❖ random access MAC protocol specifies:
 - how to detect collisions
 - how to recover from collisions (or, even avoid collision)
- ❖ Examples of random access MAC protocols:
 - ALOHA and slotted ALOHA
 - CSMA/CD, CSMA/CA CSMA: Carrier Sense Multiple Access
 - CD: Collision Detection ← Reactive scheme
 - CA: Collision Avoidance ← Preventive scheme

Aloha Protocol

- ❖ Developed in the 1970s at U of Hawaii
- ❖ To interconnect **terminals** with **mainframes**
- ❖ LAN/ WLAN: **Possible**, but not used
- ❖ **GSM**: Cell phones use this protocol to **request a channel** from the base stations
- ❖ Two types
 - **Pure** Aloha (**Continuous** time)
 - **Slotted** Aloha

Pure Aloha (Sender)



Pure Aloha



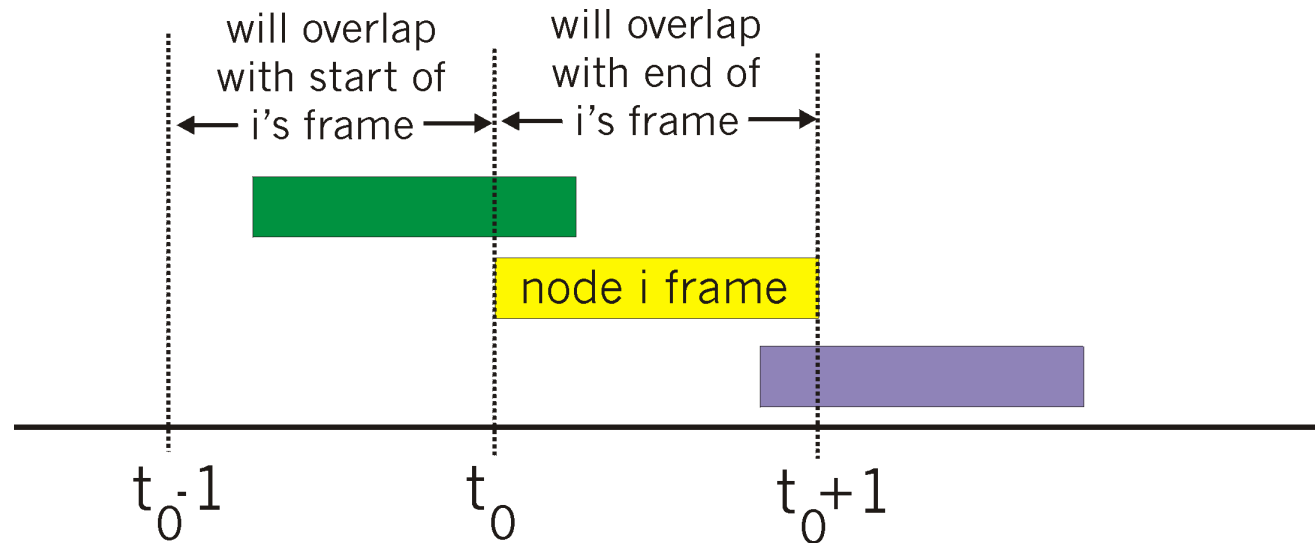
What does
the **receiver**
do?



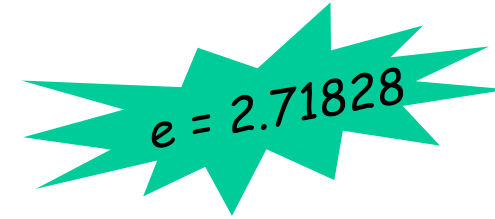
OK...
This is my
homework...

Pure (unslotted) ALOHA

- ❖ unslotted Aloha: simpler, no synchronization
- ❖ when frame first arrives
 - transmit immediately
- ❖ **collision probability increases:**
 - frame sent at t_0 collides with other frames sent in $[t_0-1, t_0+1]$



Pure Aloha efficiency


$$e = 2.71828$$

Throughput of Pure Aloha =

Total input rate (G) * Prob. of successful Packet Trans.

$$= G * e^{-2G}$$

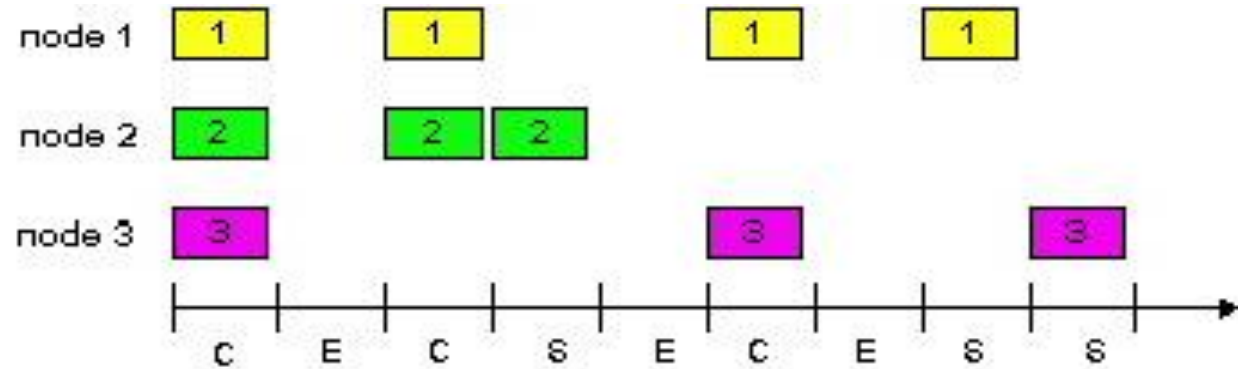
G: Number of packets in X sec.

Max throughput occurs at G = 0.5.

where X is the packet Tx time.

$$\text{Max Throughput} = 1/(2e) = .18$$

Slotted ALOHA



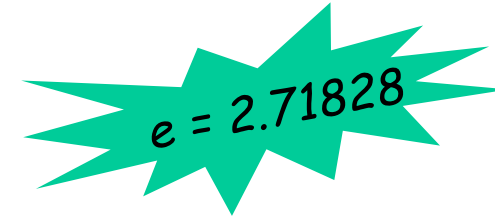
Assumptions:

- ❖ all frames are **same size**
- ❖ time divided into **equal size slots** (time to transmit 1 frame)
- ❖ nodes start to **transmit only at slot beginning**
- ❖ nodes are **synchronized**

Operation:

- ❖ when node obtains fresh frame, **transmit in next slot**
- ❖ if **Tx is not successful**, retransmit in following slots after some wait..

Slotted Aloha efficiency


$$e = 2.71828$$

Throughput of Slotted Aloha =

Total input rate (G) * Prob. of successful Packet Trans.

$$= G * e^{-G}$$

G: Number of packets in X sec.

Max throughput occurs at G = 1.

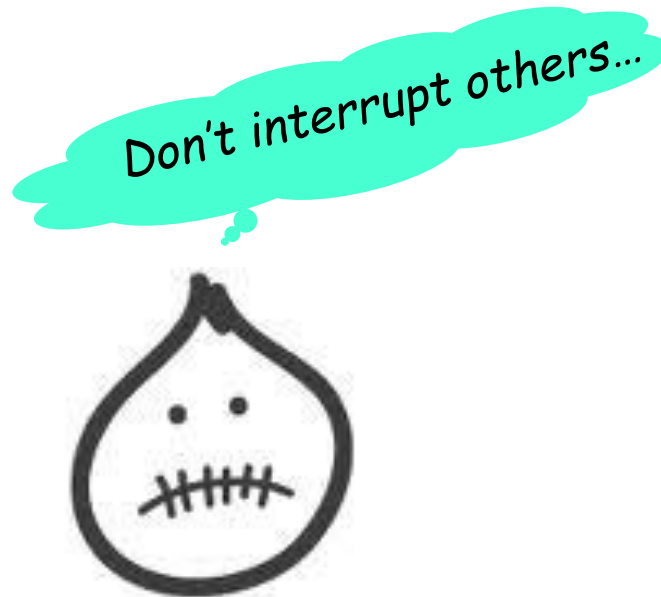
where X is the packet Tx time.

$$\text{Max Throughput} = 1/e = .37$$

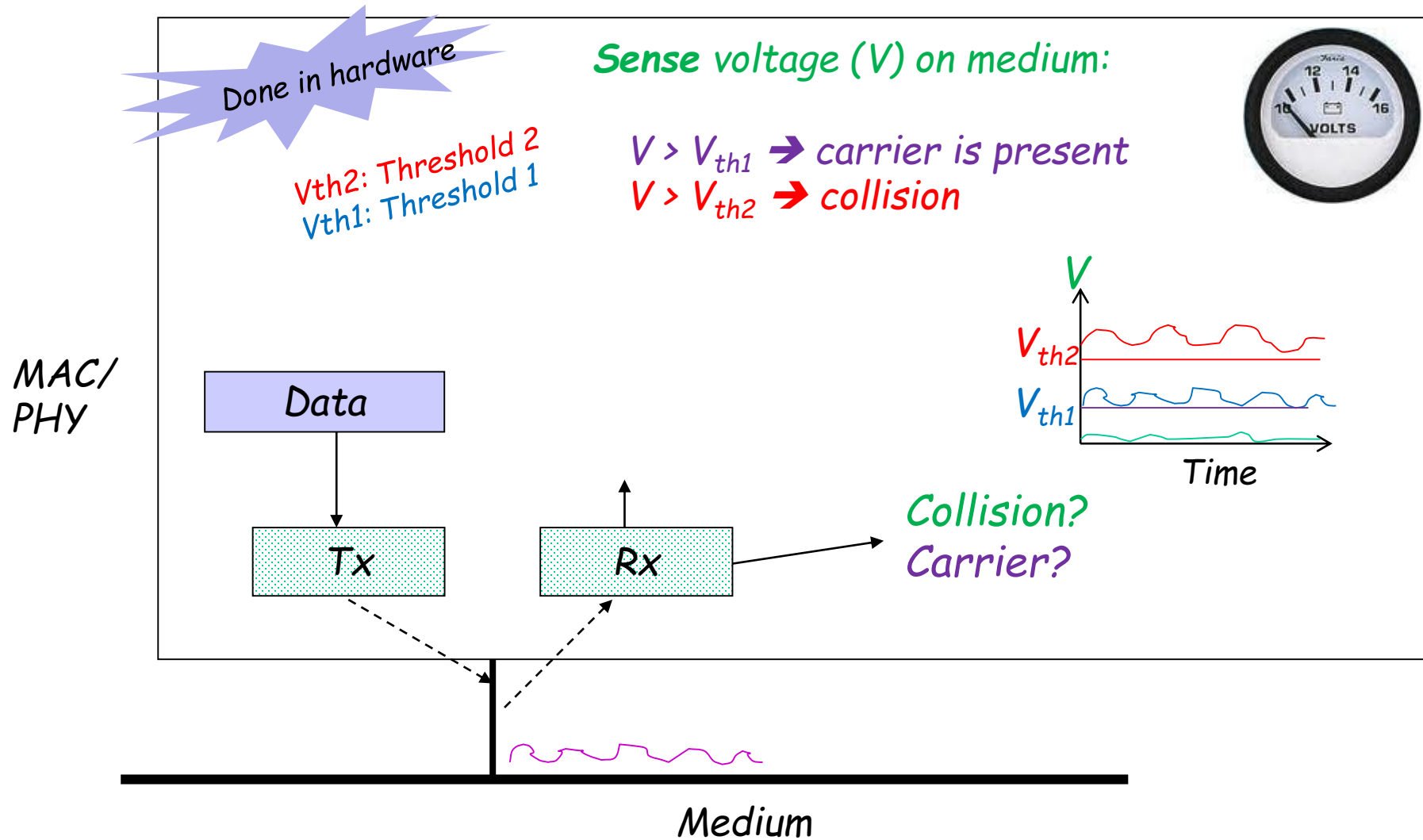
CSMA (Carrier Sense Multiple Access)

CSMA: listen before you transmit:

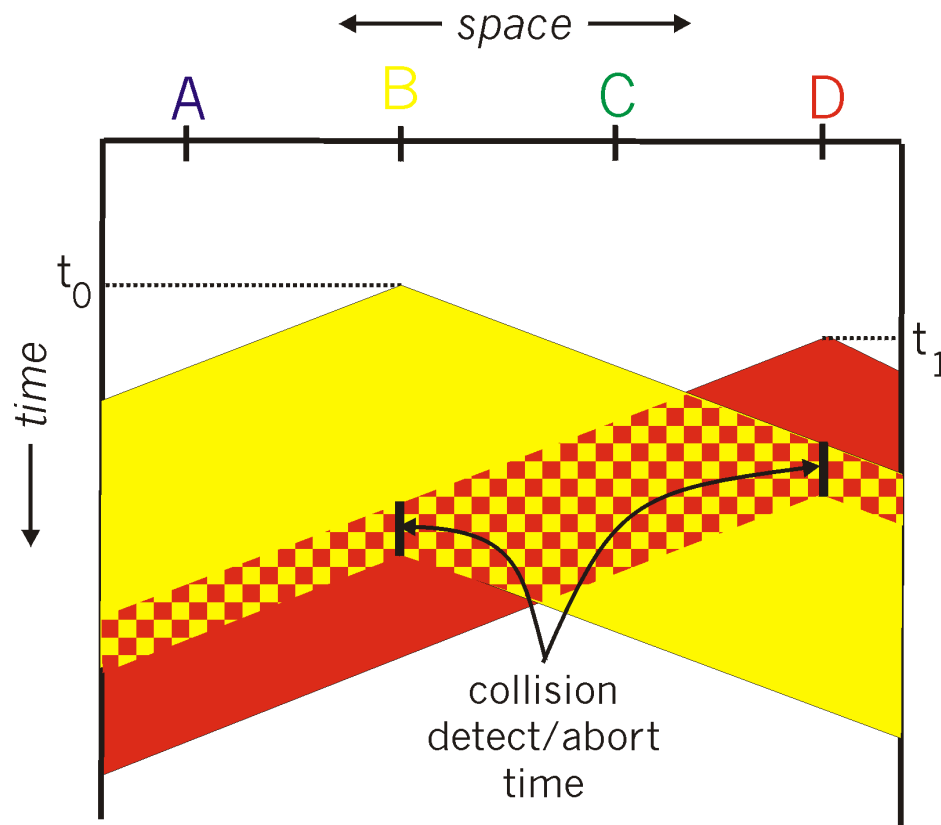
- ❖ If channel is sensed idle: transmit entire frame
- ❖ If channel is sensed busy, defer transmission



CSMA/CD Concepts of Carrier Sense and Collision Detection



CSMA/CD collision detection



Signal from all nodes must reach all others

Remember this



Therefore, collision occurring at a receiving node is detected by the frame's sender.... after some delay..

CSMA/CD (Collision Detection)

CSMA/CD: **C**arrier **S**ense **M**ultiple **A**ccess with CD

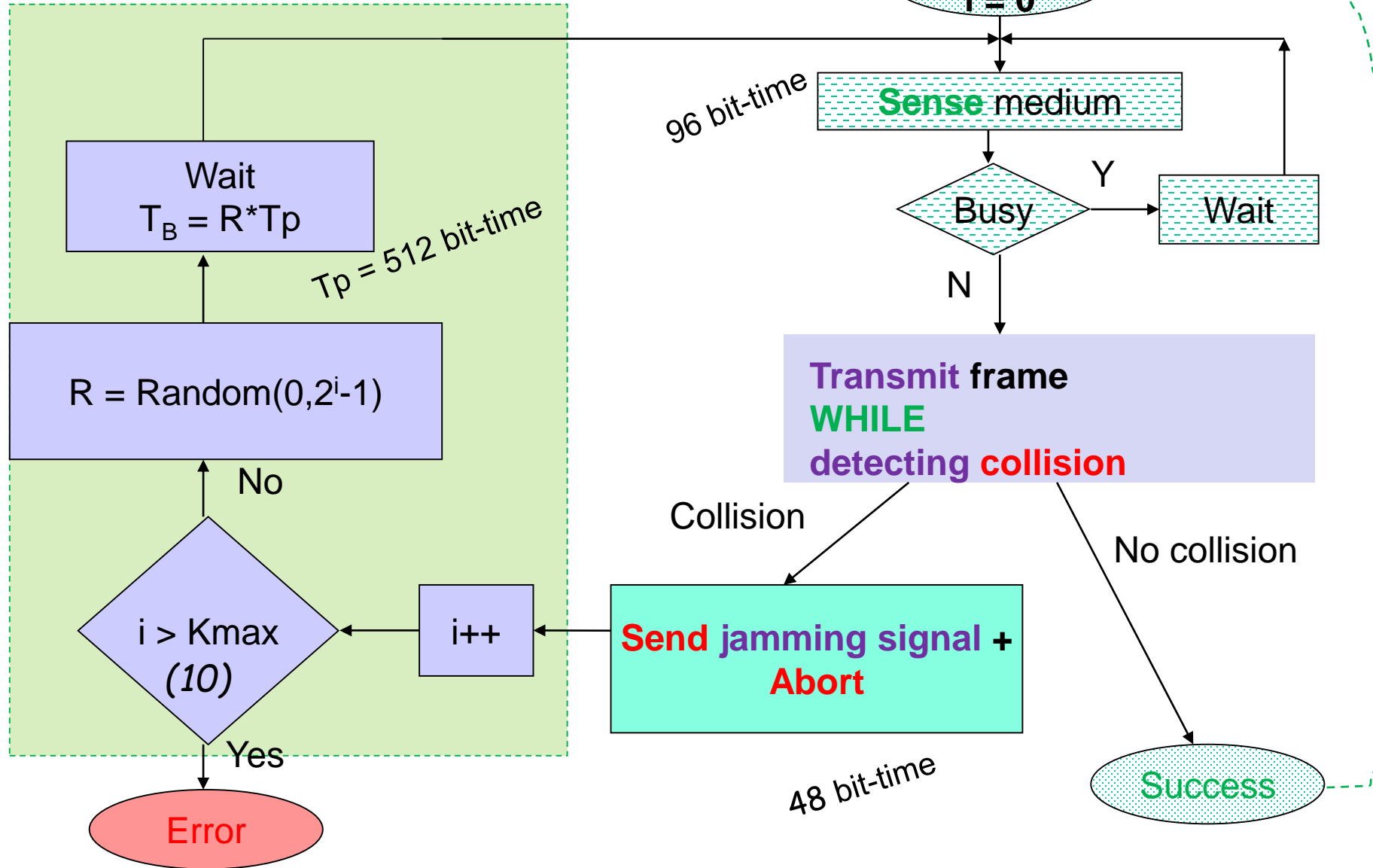
- Tx attempts multiple times (multiple access)
- Collisions are *detected* within short time
- A colliding transmission is aborted ← don't keep wasting channel resource

❖ Collision detection:

- Easy in wired LANs: explained before ...
- Not possible in wireless LANs: will be explained ...

CSMA/CD

Exponential backoff



CSMA/CD

- Medium sensing is done for 96 bit-times.
- Jamming signal length is 48 bits. Jamming signal creates enough energy on the medium for collision detection.
- T_p is equated with 512 bit-times.
- “i” saturates at 10.



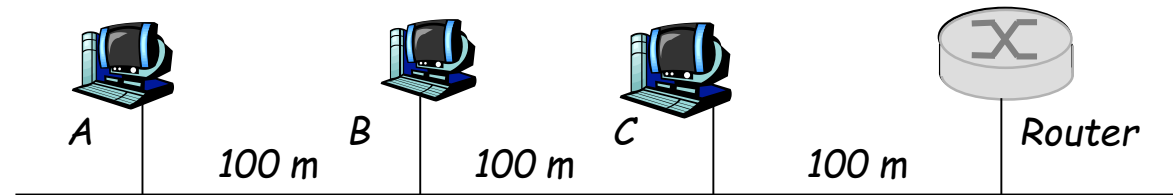
I have learned CSMA/CD...
What kinds of questions should I
expect on the exams

F12 Mid-term



Computers A, B, and C and one router are connected
to an Ethernet bus 100 metres apart
to make a LAN using the CSMA/CD protocol.

Assume that signal propagates on the Ethernet bus at a
speed of 2×10^8 m/sec, and all nodes can transmit data
at the rate of 100 Mbps.



- After finding the bus to be idle for a little while, A and the router start transmitting their frames exactly at the same time. How many bits of data can node A transmit before detecting collision?
- What is the maximum time gap between the start of transmission and detection of collision by A?
- What is the length of the smallest frame that A can transmit while knowing whether or not it collided with a transmission from the router?

“Taking Turns” MAC protocols

channel partitioning MAC protocols:

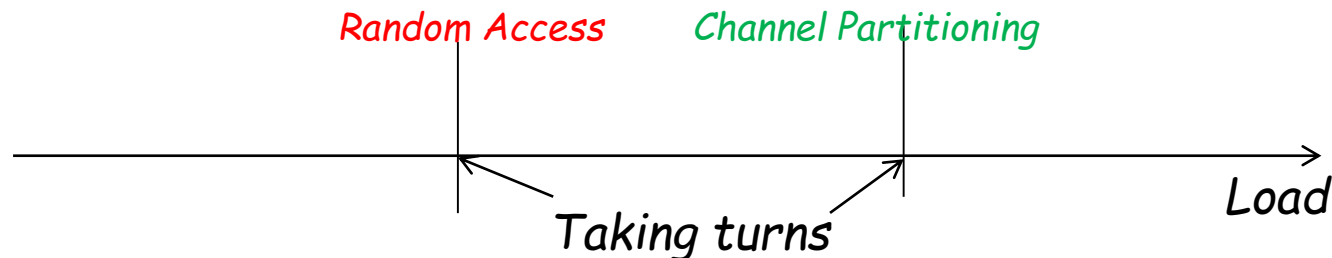
- share channel *efficiently and fairly* at high load
- **inefficient** at low load: $1/N$ bandwidth allocated even if only 1 active node!

random access MAC protocols:

- **efficient** at low load: single node can fully utilize channel
- Much **collision overhead** at high load

“taking turns” protocols

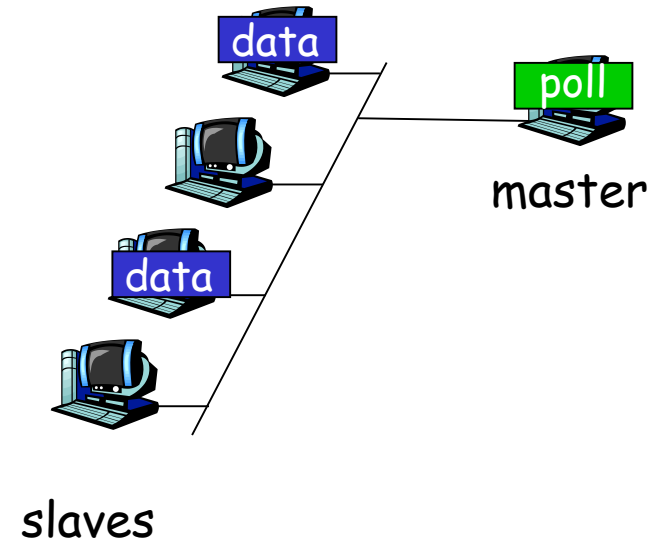
look for best of both worlds!



“Taking Turns” MAC protocols

Polling:

- ❖ **master node** “invites” slave nodes to transmit in turn
- ❖ typically used with “dumb” slave devices
- ❖ **concerns:**
 - polling overhead
 - latency
 - single point of failure (master)

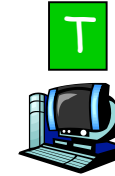
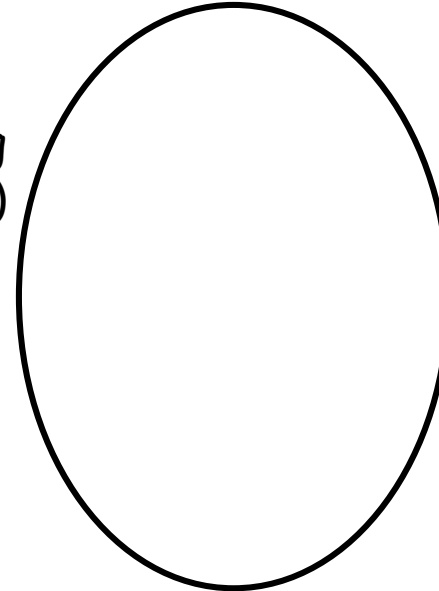


“Taking Turns” MAC protocols

Token passing:

- ❖ control **token** passed from one node to next sequentially.
- ❖ token message
- ❖ **concerns:**
 - token overhead
 - latency
 - single point of failure (token)

(nothing
to send)



data

IBM Token Ring
was developed at
IBM Zurich to compete
against CSMA/CD.

Where are all those
different kinds of MAC
protocols used



Ch. Partitioning MAC

- Cellphone networks
- Bluetooth

Random access MAC

- LAN (Local Area Network)
- WLAN (Wireless LAN)

Taking turns

- Bluetooth

Link Layer

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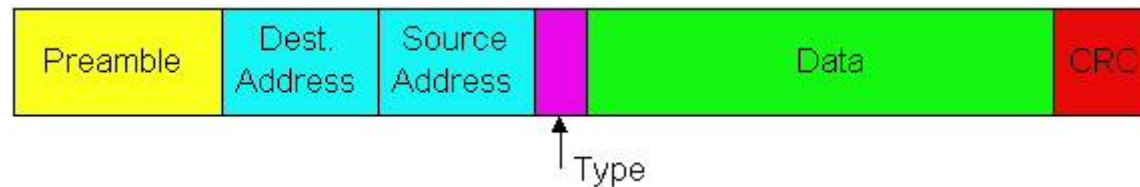
5.8 Link virtualization: MPLS

5.9 A day in the life of a web request

3.4 Reliable data transfer

Ethernet Frame Structure (example)

Sending adapter encapsulates IP datagram (or other network layer protocol packet) in **Ethernet frame**

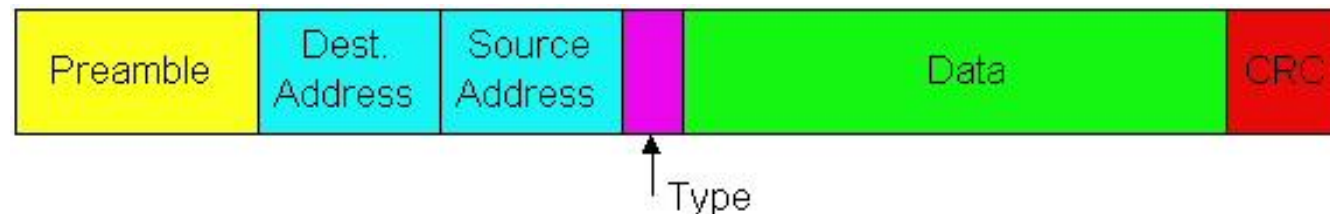


Preamble:

- ❖ 7 bytes with pattern 10101010 followed by one byte with pattern 10101011
- ❖ used to synchronize receiver, sender clock rates

Ethernet Frame Structure (more)

- ❖ **Addresses:** 6 bytes
 - if adapter receives frame with **matching destination address**, or with **broadcast address** (e.g. ARP packet), it **passes data** in frame to **upper layer protocol**
 - otherwise, adapter **discards** frame
- ❖ **Type:** indicates higher layer protocol (mostly IP but others possible, e.g., Novell IPX, AppleTalk)
- ❖ **CRC:** checked at receiver;
 - if **error is detected**, frame is **dropped**.

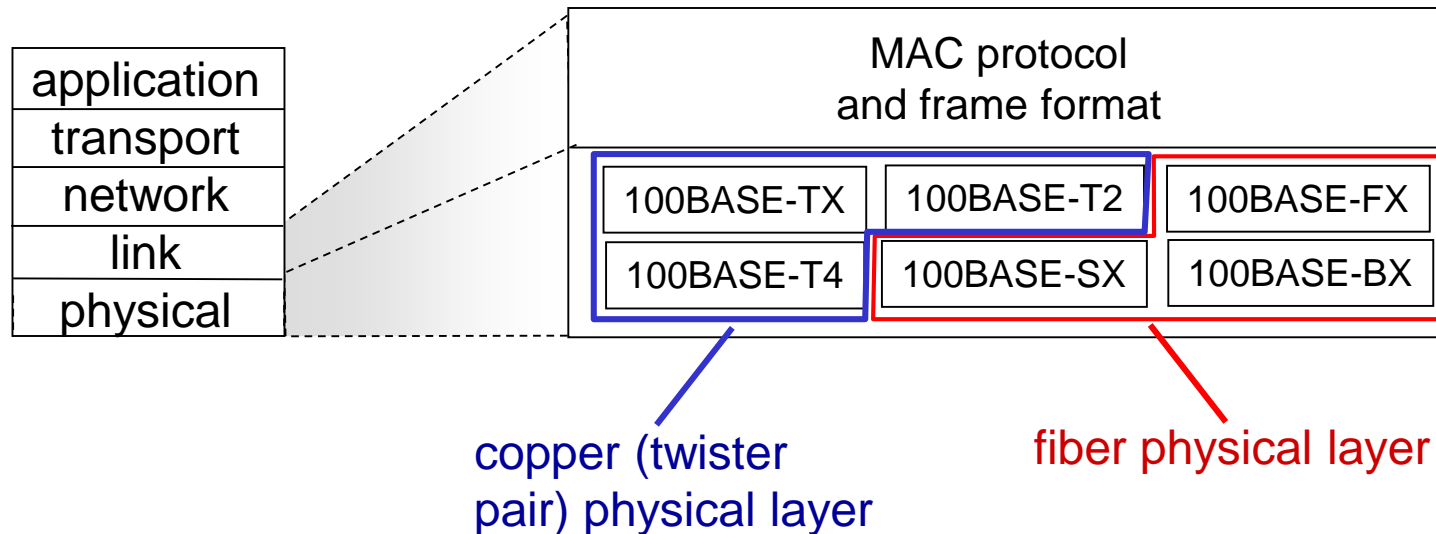


Ethernet: unreliable, connectionless

- ❖ *connectionless*: no handshaking between sending and receiving NICs
- ❖ *unreliable*: receiving NIC doesn't send acks or nacks to sending NIC
 - data in dropped frames recovered only if initial sender uses higher layer rdt (e.g., TCP), otherwise dropped data lost
- ❖ Ethernet's MAC protocol: unslotted *CSMA/CD with binary backoff*

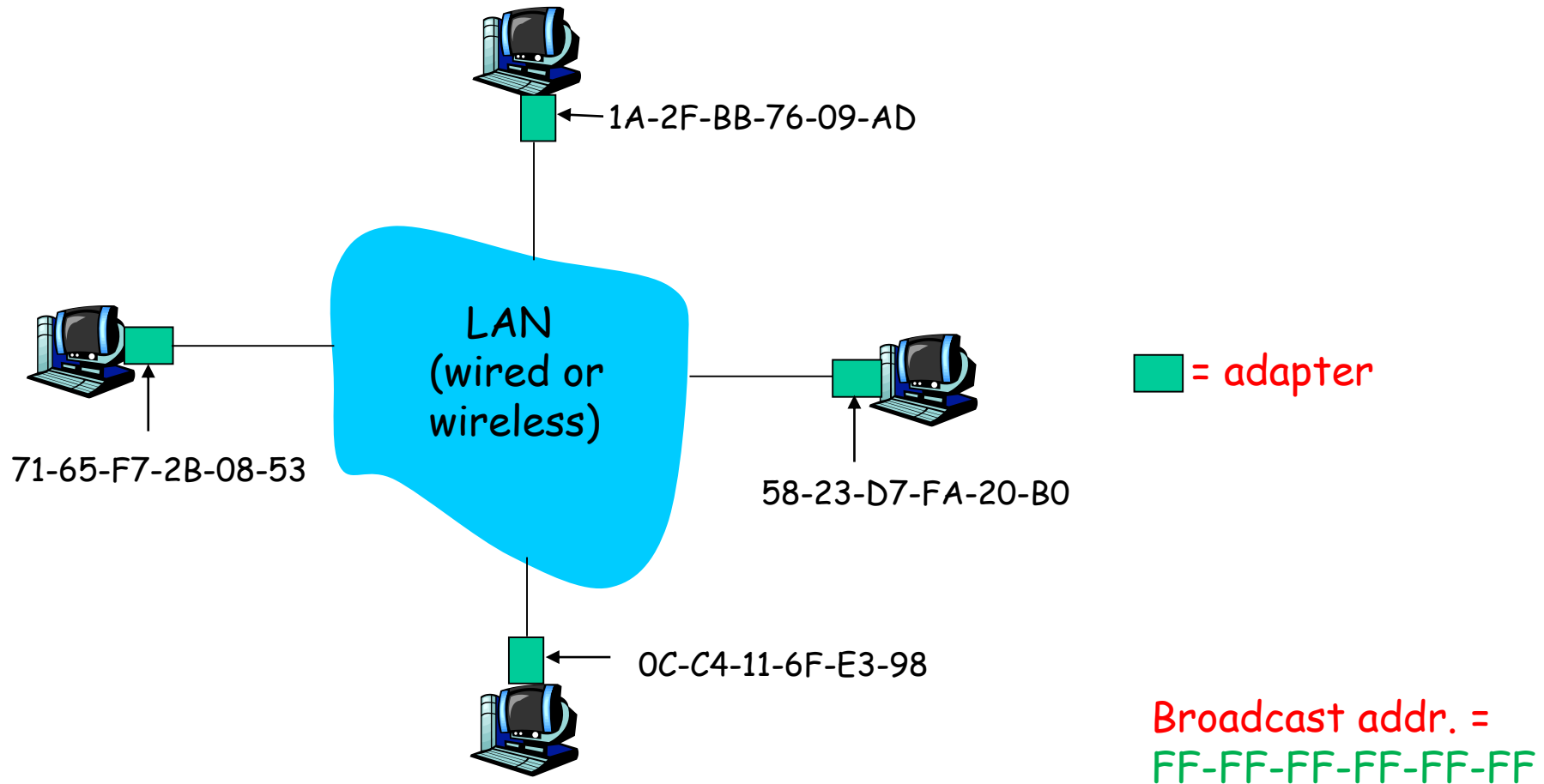
802.3 Ethernet standards: link & physical layers

- ❖ *many* different Ethernet standards
 - common MAC protocol and frame format
 - different speeds: 2 Mbps, 10 Mbps, 100 Mbps, 1Gbps, 10G bps
 - different physical layer media: fiber, cable



LAN Addresses and ARP

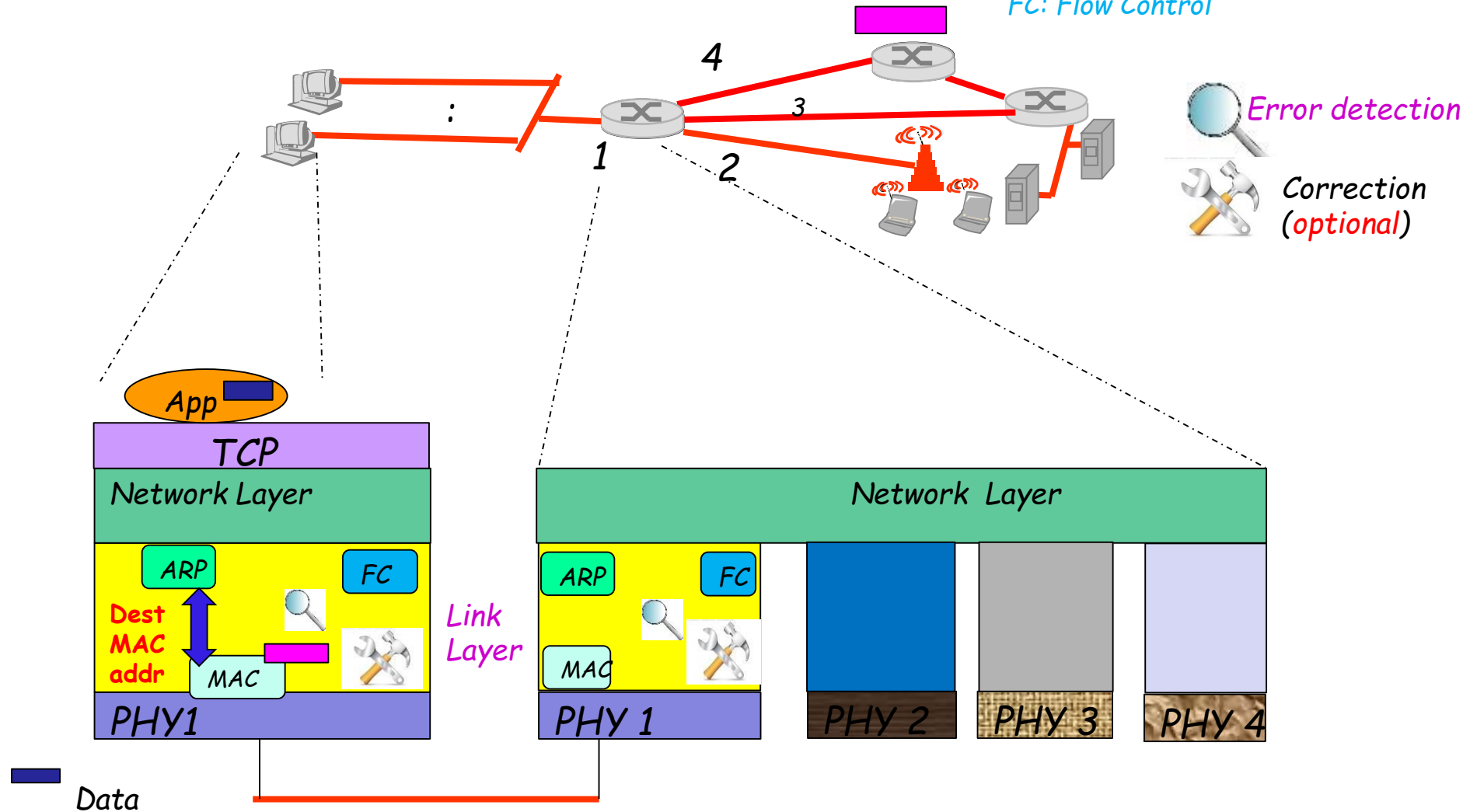
Each adapter on LAN has unique LAN address



ARP context

MAC: Medium Access Control

FC: Flow Control



ARP (Address Resolution Protocol): IP address → MAC address
(%ipconfig /all ← for MAC addresses.)

PHY: Physical layer ← hardware

ARP: Address Resolution Protocol

Question:

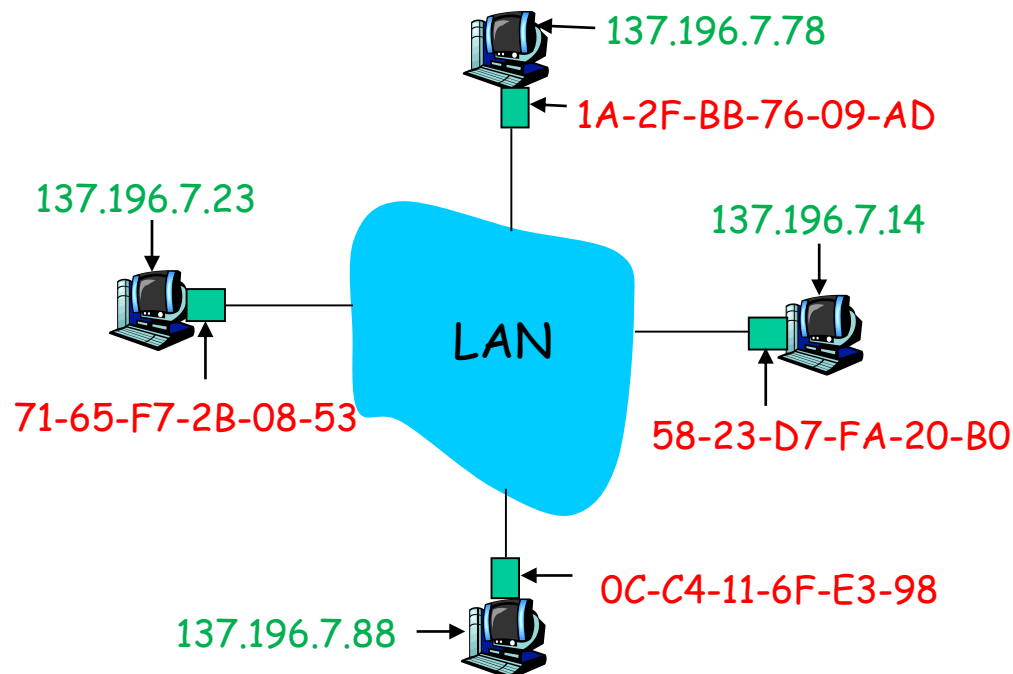
How to determine B's **MAC address** knowing B's **IP address**?

- ❖ Each IP node (host, router) on LAN has **ARP** table

- ❖ **ARP table: IP/MAC addr. mappings for LAN nodes**

< **IP address**; **MAC address**; **TTL** >

- **TTL (Time To Live):** time after which address mapping will be forgotten (typically 20 min)

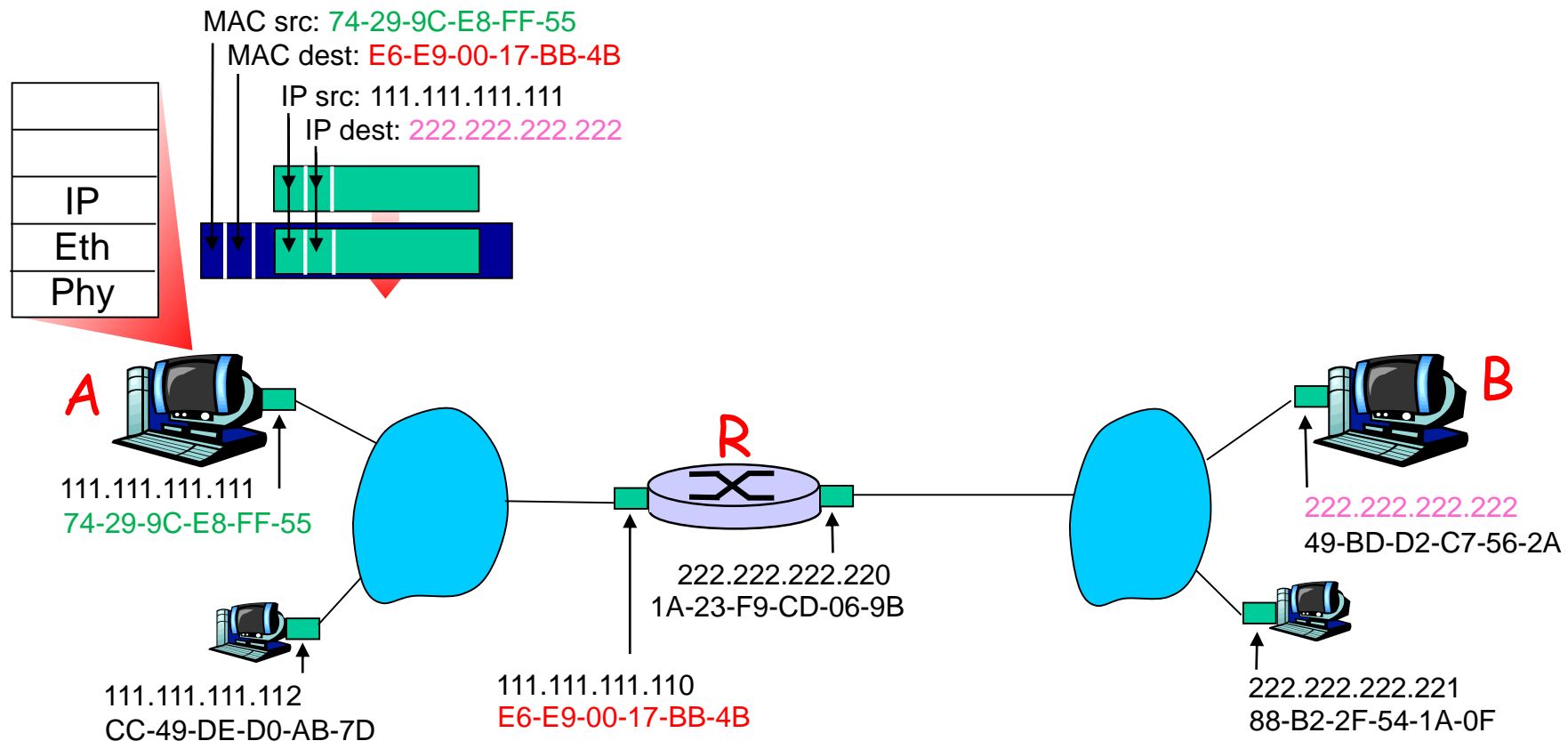


ARP protocol: Same LAN (network)

- ❖ A wants to send datagram to B, and B's MAC address not in A's ARP table.
- ❖ A broadcasts ARP query pkt containing B's IP addr
 - dest MAC address = FF-FF-FF-FF-FF-FF
 - all machines on LAN receive ARP query
- ❖ B receives ARP query, replies to A with its (B's) MAC addr
 - frame sent to A's MAC address (unicast)
- ❖ A caches (saves) IP-to-MAC addr pair in its ARP table until this becomes old
- ❖ ARP is "plug-and-play":
 - nodes create their ARP tables without intervention from net administrator

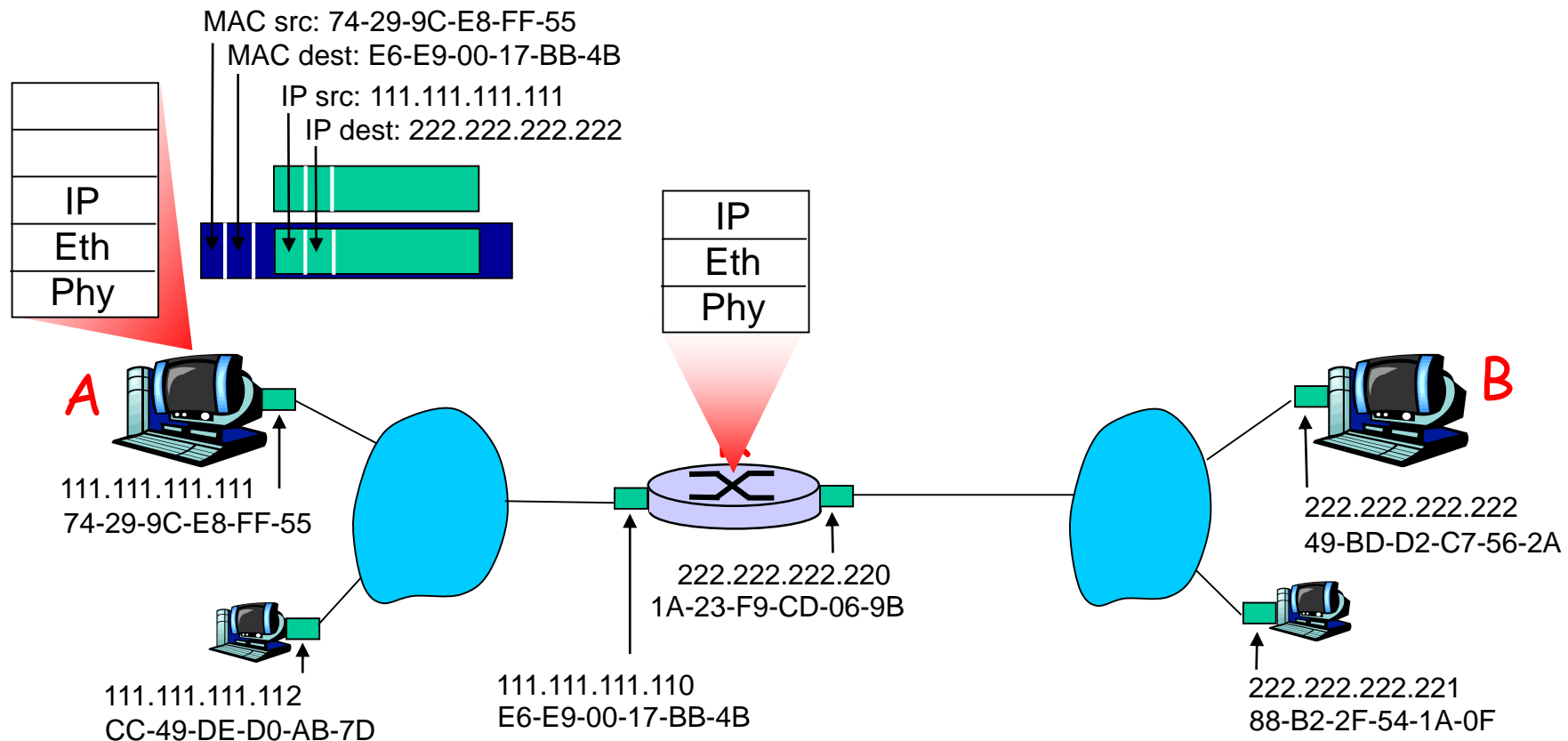
Addressing: routing to another LAN

- ❖ A creates IP datagram with IP source A, destination B
- ❖ A creates link-layer frame with R's MAC address as dest, frame contains A-to-B IP datagram



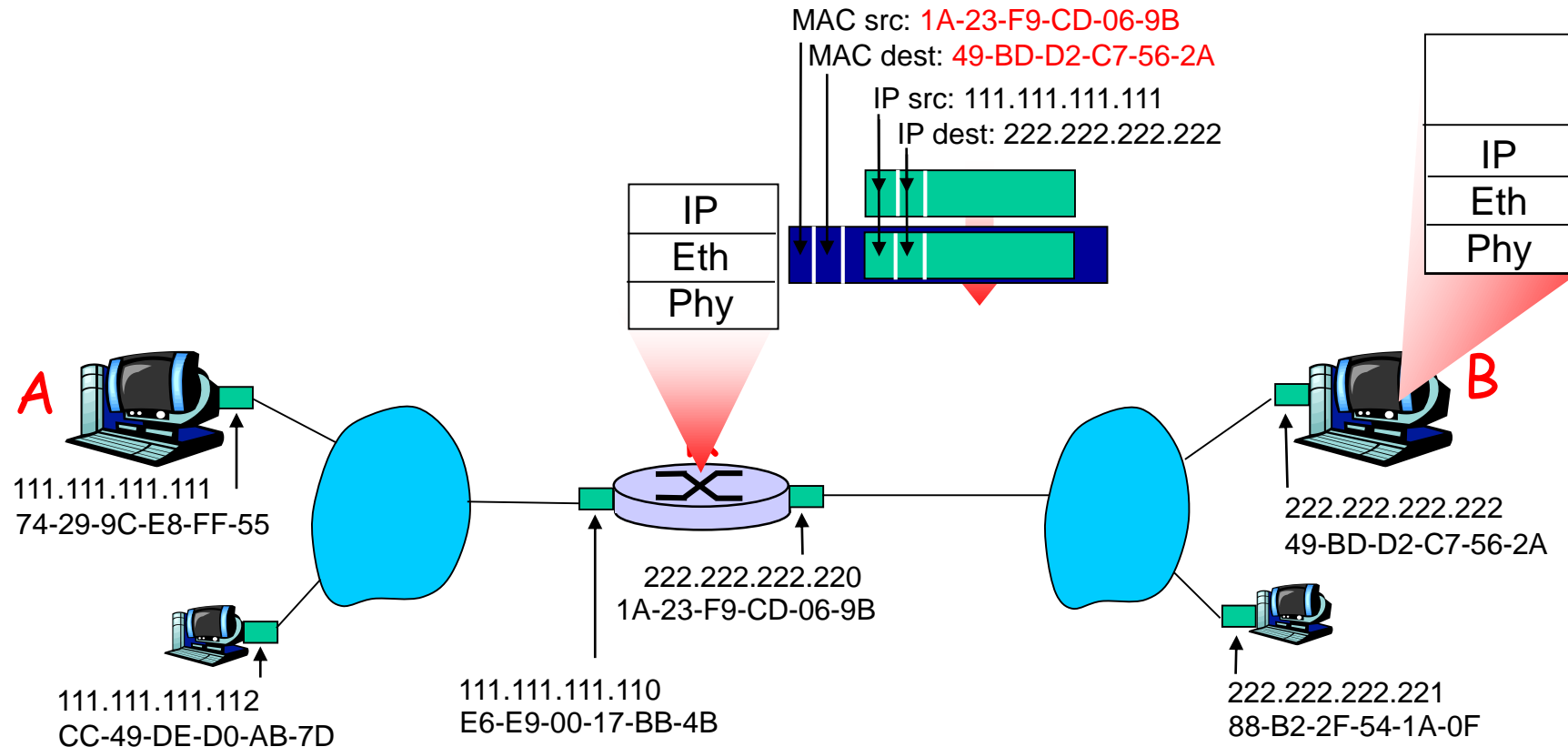
Addressing: routing to another LAN

- ❖ frame sent from A to R
- ❖ frame received at R, datagram removed, passed up to IP



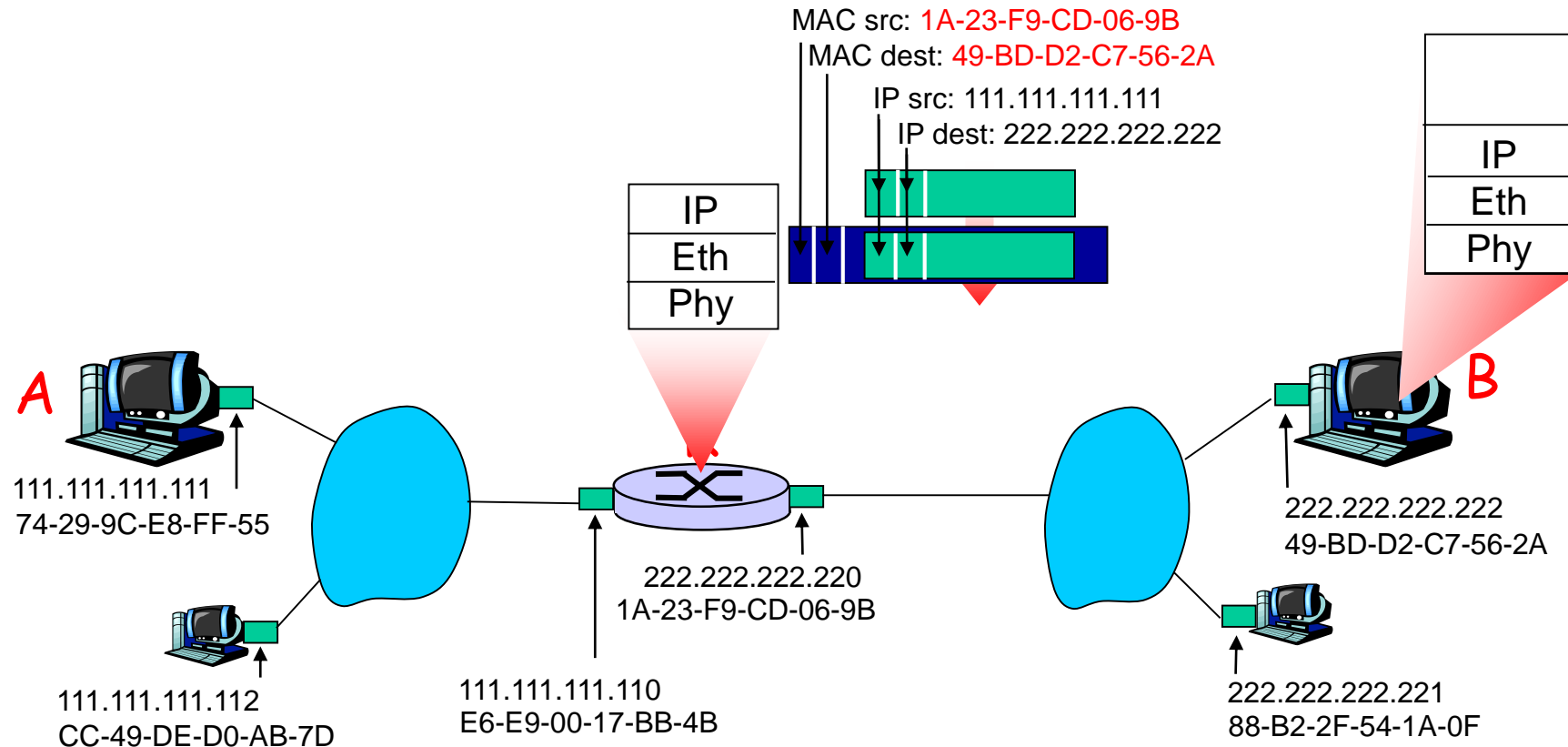
Addressing: routing to another LAN

- ❖ R forwards datagram with IP source A, destination B
- ❖ R creates link-layer frame with B's MAC address as dest, frame contains A-to-B IP datagram



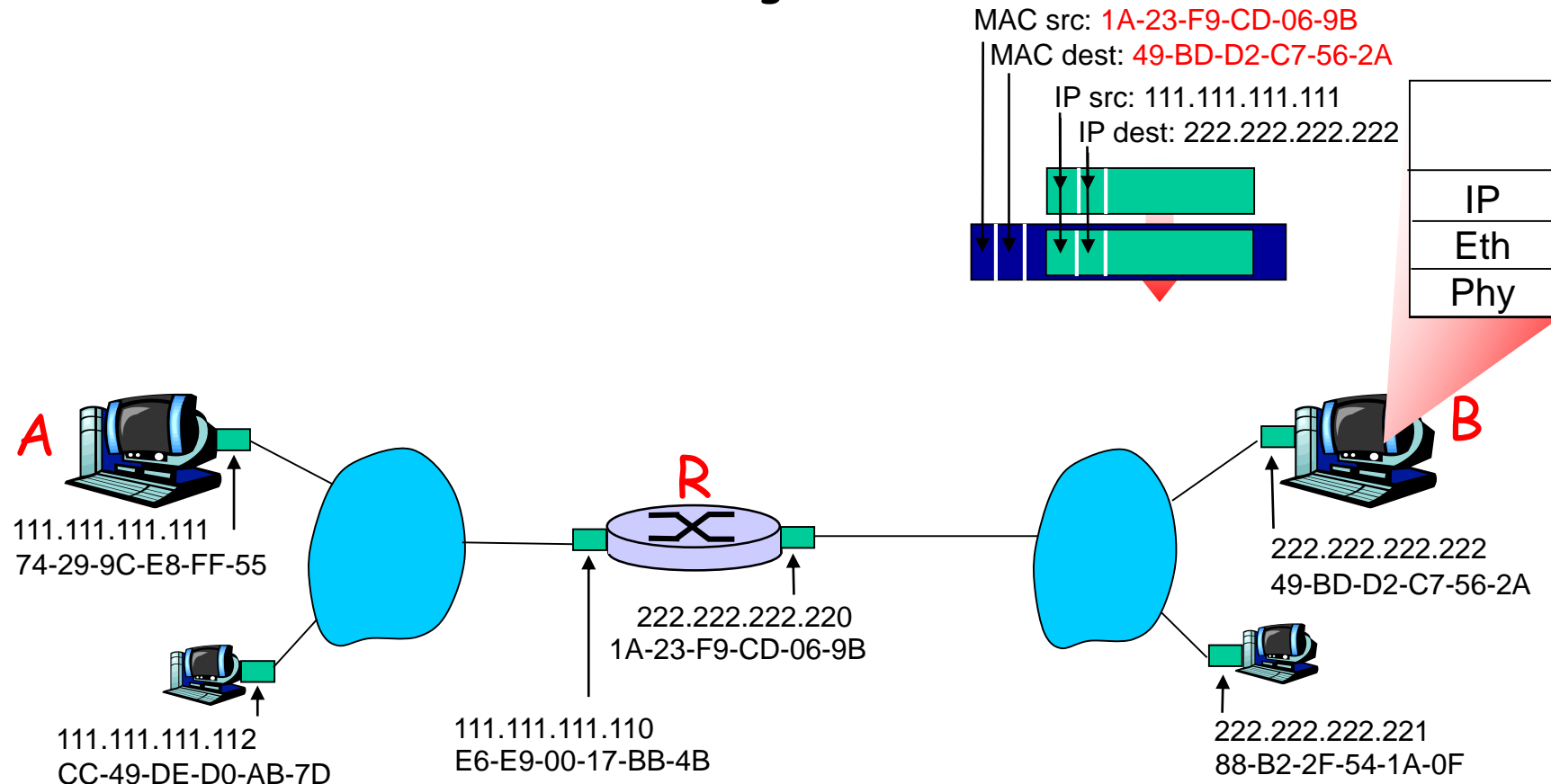
Addressing: routing to another LAN

- ❖ R forwards datagram with IP source A, destination B
- ❖ R creates link-layer frame with B's MAC address as dest, frame contains A-to-B IP datagram



Addressing: routing to another LAN

- ❖ R forwards datagram with IP source A, destination B
- ❖ R creates link-layer frame with B's MAC address as dest, frame contains A-to-B IP datagram



Link Layer

5.1 Introduction and services

5.2 Error detection and correction

5.3 Multiple access protocols

5.4 Link-layer Addressing

5.5 Ethernet

5.6 Link-layer switches,
LANs, VLANs

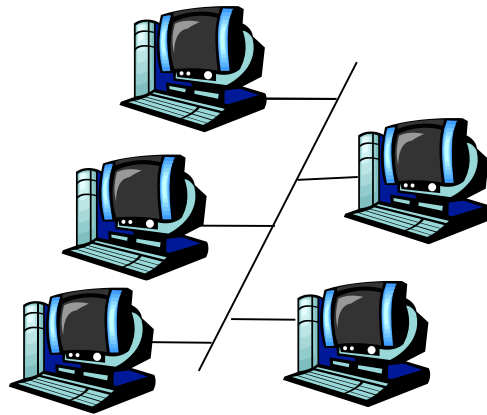
5.7 PPP

5.8 Link virtualization: MPLS

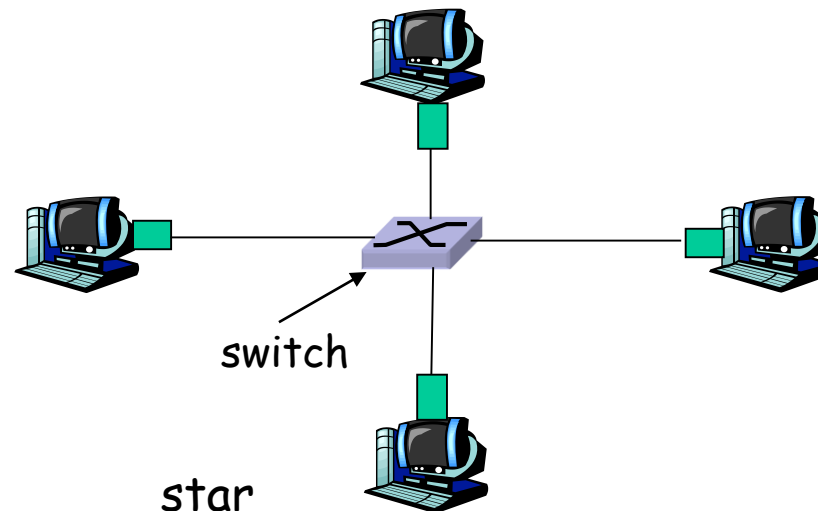
5.9 A day in the life of a web
request

LAN with star topology

- ❖ bus topology popular through mid 90s
- ❖ today: star topology prevails
 - active switch in centre
 - each "spoke" runs a (separate) Ethernet protocol (nodes do not collide with each other)



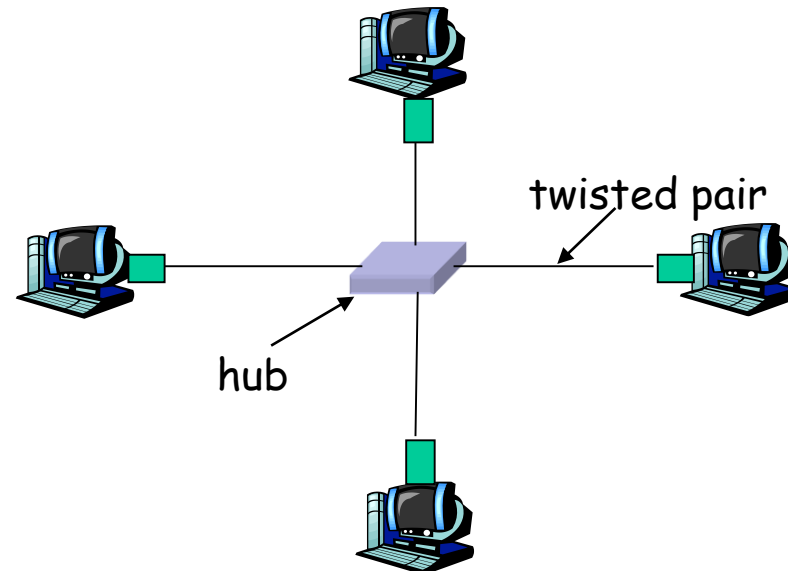
bus: coaxial cable



Hubs

... physical-layer (“dumb”) repeaters:

- bits coming in on one link go out *all* other links at same rate
- all nodes connected to hub can collide with one another
- no frame buffering
- no CSMA/CD at hub: host NICs detect collisions



Switch

❖ smarter than hubs, take *active* role

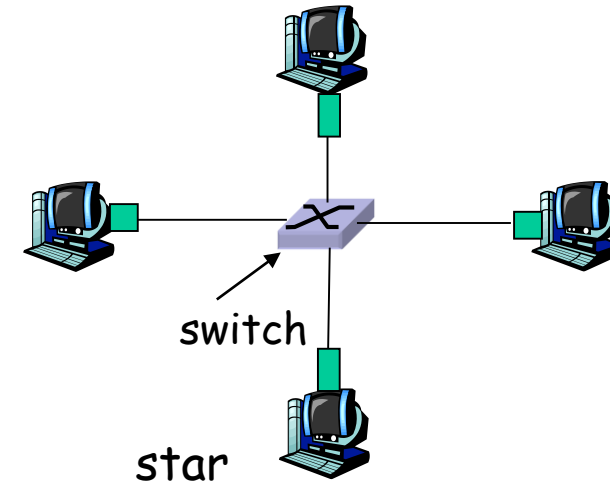
- Store and forward frames
- Examine incoming frame's MAC address, *selectively* forward frame to one-or-more outgoing links when frame is to be forwarded on segment, using CSMA/CD to access segment

❖ *transparent*

hosts are *unaware* of presence of switches

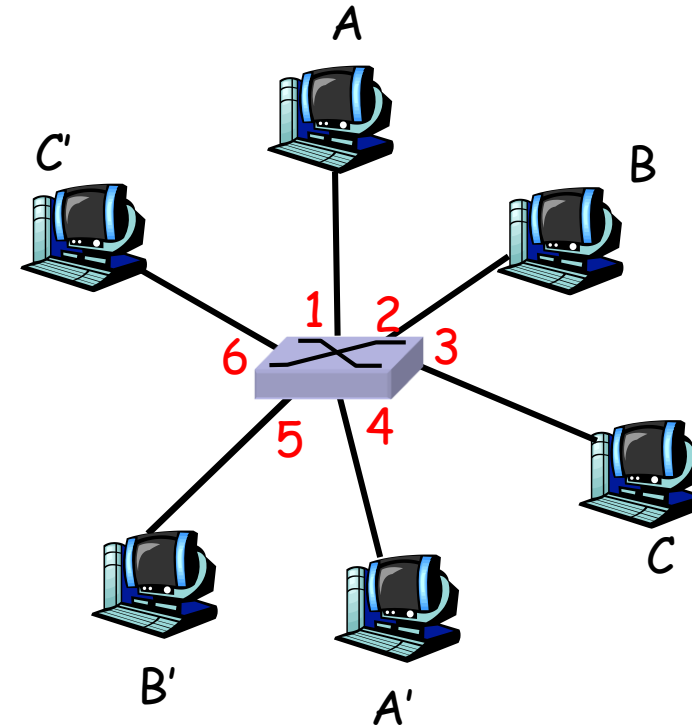
❖ *plug-and-play, self-learning*

switches do not need to be configured



Switch: allows *multiple* simultaneous transmissions

- ❖ hosts have dedicated, direct connection to switch
- ❖ switches buffer packets
- ❖ Ethernet protocol is used on each link
- ❖ *switching*: A-to-A' and B-to-B' simultaneously, without collisions
 - not possible with dumb hub

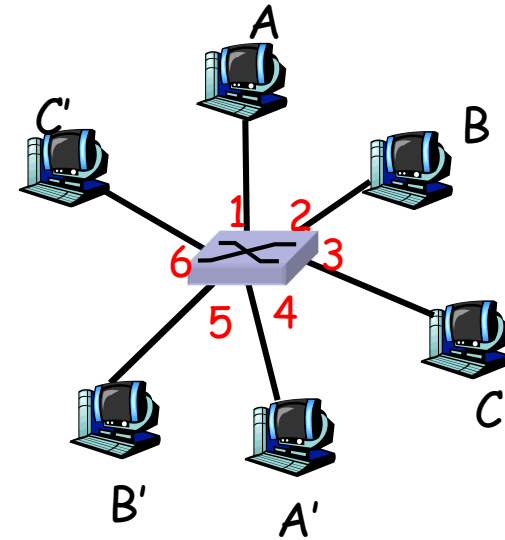


switch with six interfaces
(1,2,3,4,5,6)

Switch Table

- ❖ Q: how does switch know that A' reachable via interface 4, B' reachable via interface 5?
- ❖ A: each switch has a switch table

MAC addr of host	Interface #	Time To Live (TTL)

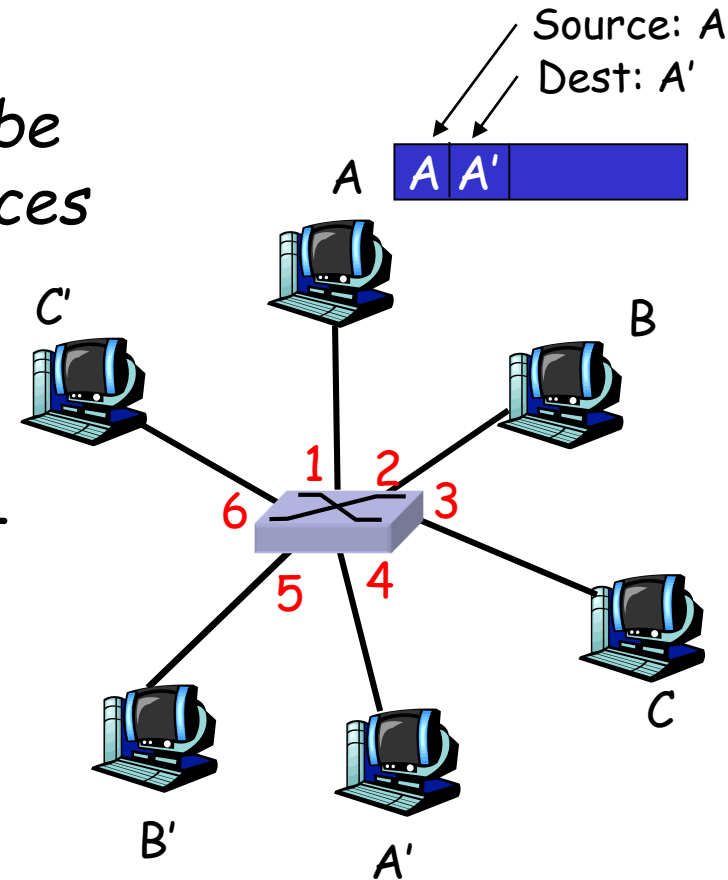


switch with six interfaces
(1,2,3,4,5,6)

- ❖ Q: How are entries created and maintained in switch table?

Switch: self-learning

- ❖ Switch *learns* which hosts can be reached through which interfaces
- ❖ When frame received
 - Switch "learns" location of sender: incoming LAN segment
 - Records sender/location pair in switch table



MAC addr	interface	TTL
A	1	60

Switch table
(initially empty)

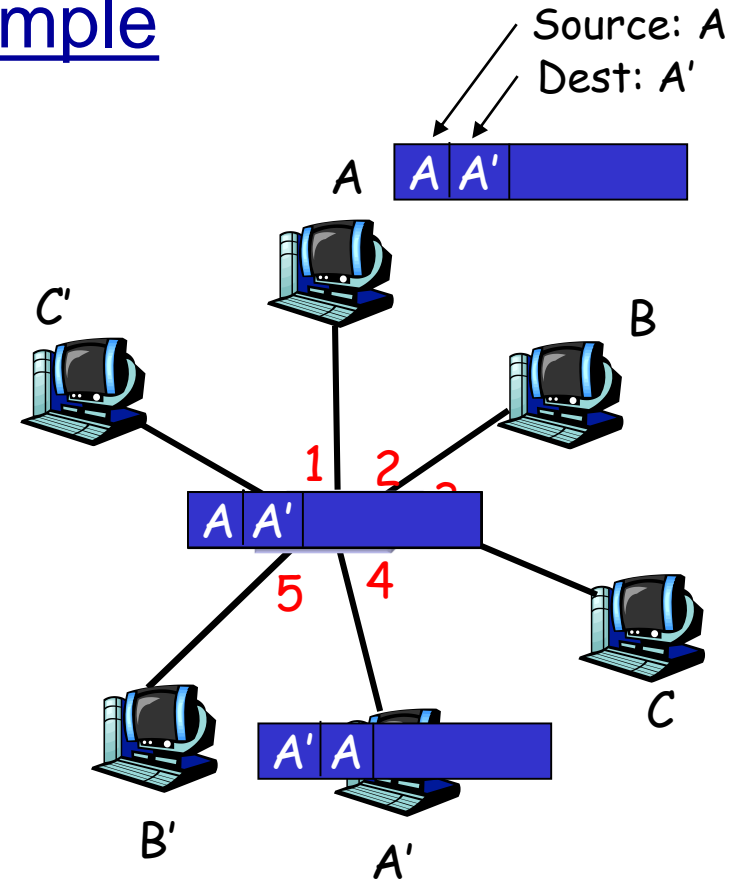
Switch: frame filtering/forwarding

When frame received:

1. record link associated with sending host
 2. index switch table using MAC dest address
 3. if entry found for destination then {
 - if dest on segment from which frame arrived
 - then drop the frame
 - else forward the frame on interface indicated}
 - else flood
- forward on all but the interface
on which the frame arrived

Self-learning, forwarding: example

- ❖ frame destination unknown: *flood*
- ❖ destination A location known: *selective send*

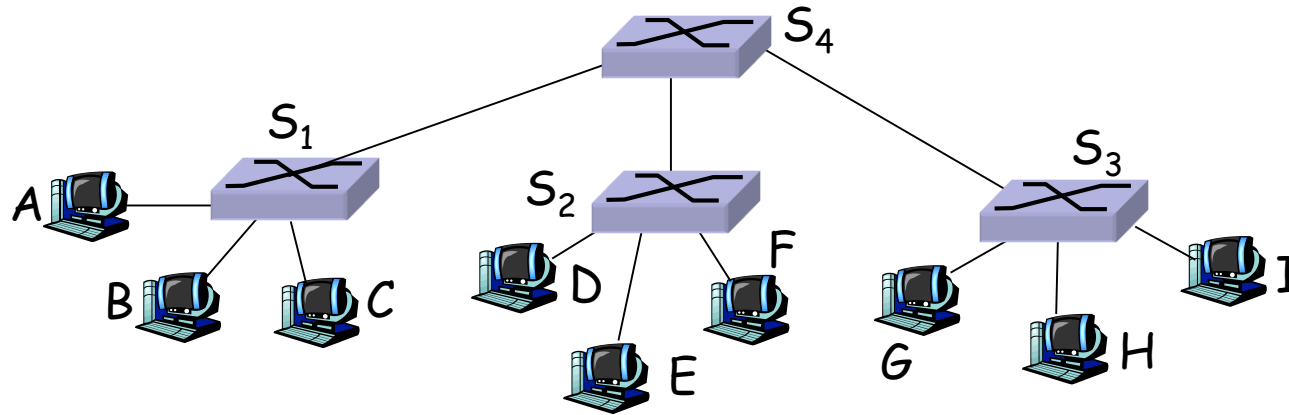


MAC addr	interface	TTL
A	1	60
A'	4	60

Switch table
(initially empty)

Interconnecting switches

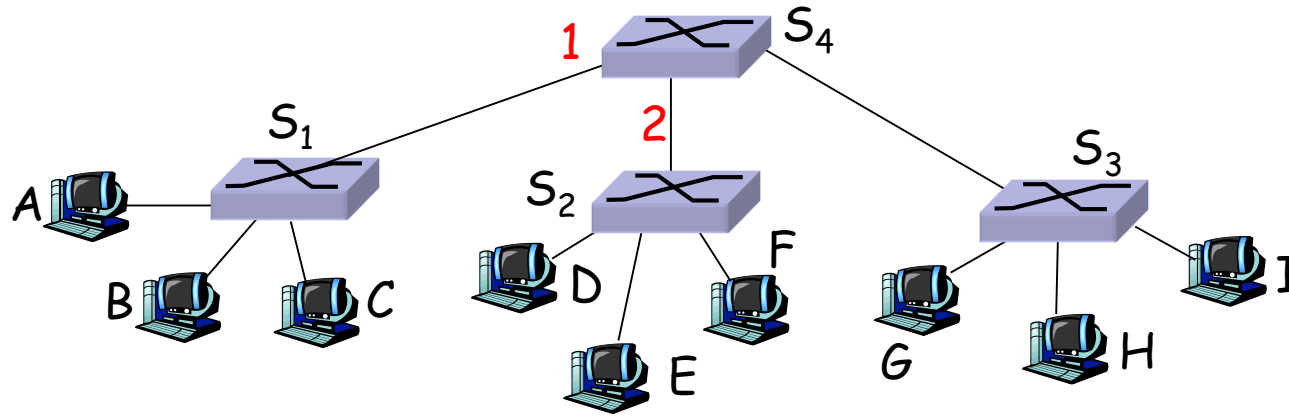
- ❖ switches can be connected together



- ❖ Q: sending from A to G - how does S₁ know to forward frame destined to G via S₄ and S₃?
- ❖ A: self learning! (works exactly the same as in single-switch case!)

Self-learning multi-switch example

Suppose C sends frame to I, I responds to C



- ❖ Q: show switch tables and packet forwarding in S₁, S₂, S₃, S₄

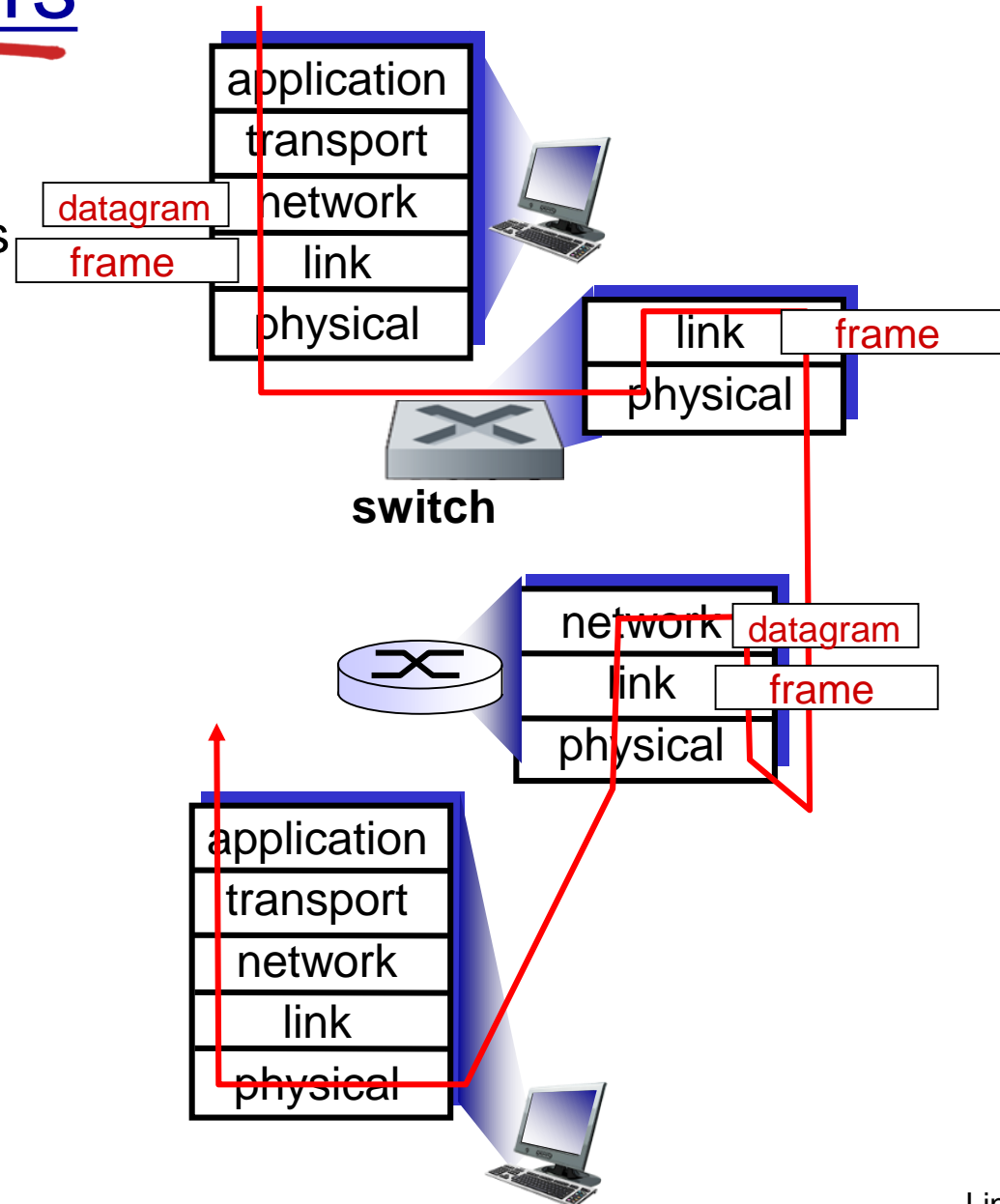
Switches vs. routers

both are store-and-forward:

- **routers:** network-layer devices (examine network-layer headers)
- **switches:** link-layer devices (examine link-layer headers)

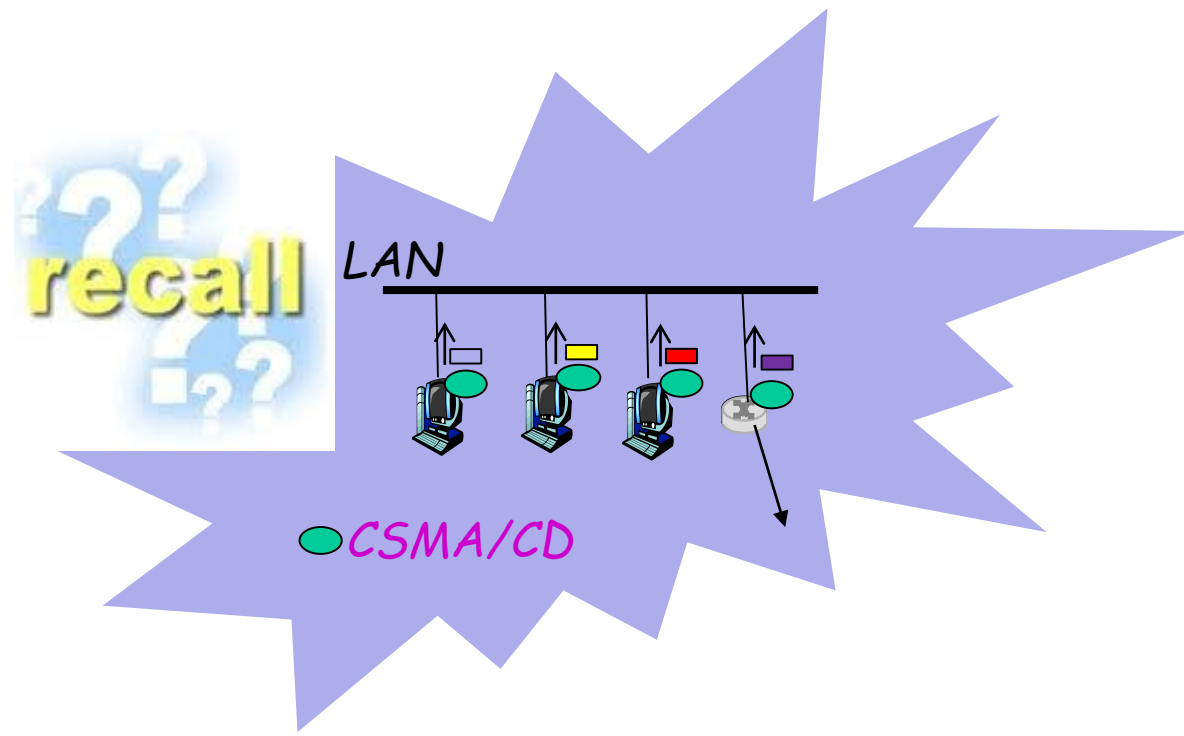
both have forwarding tables:

- **routers:** compute tables using routing algorithms, IP addresses
- **switches:** learn forwarding table using flooding, learning, MAC addresses



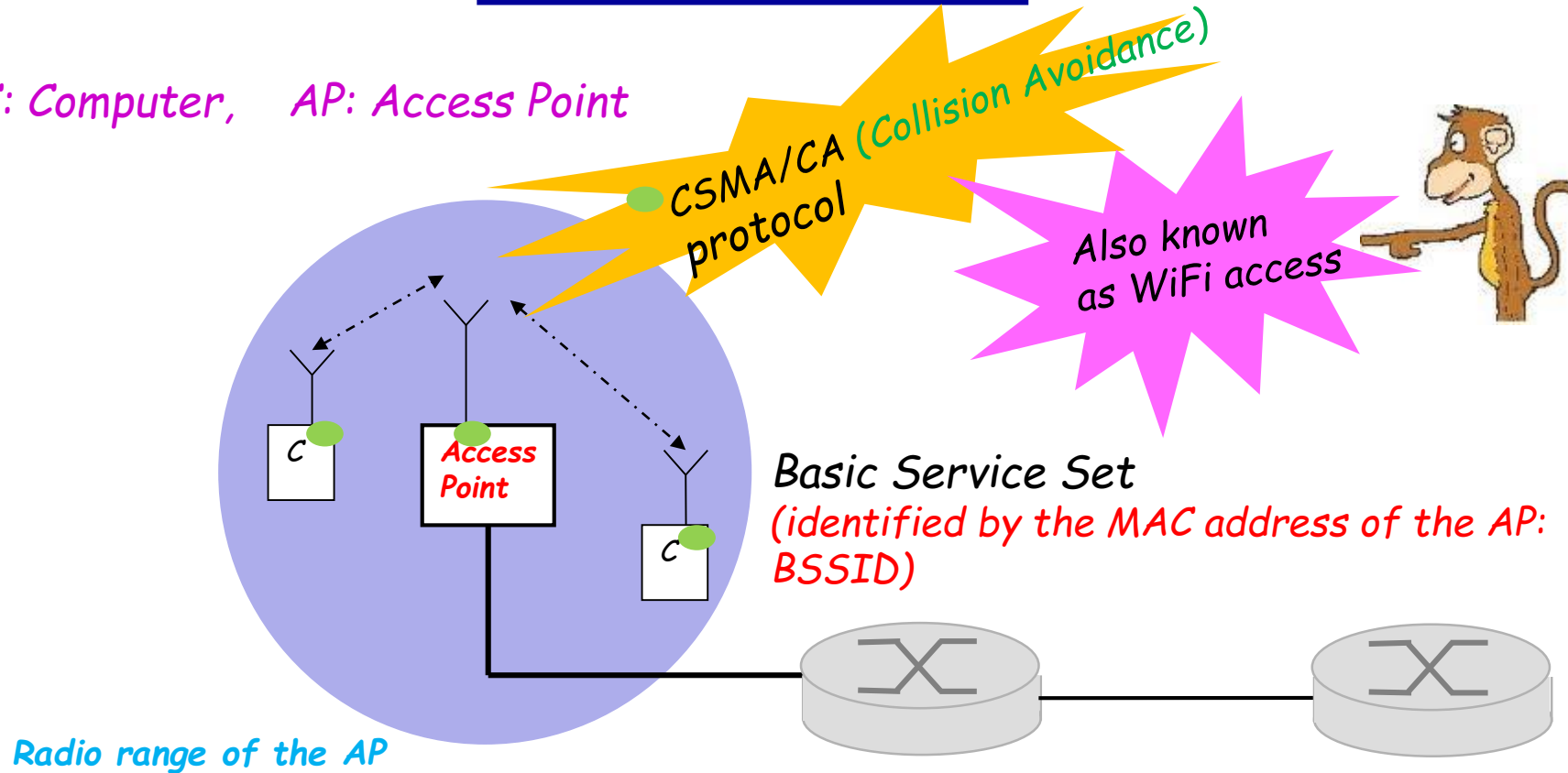
Wireless LAN

Standards: IEEE 802.11/a/b/g/n



WLAN: Basic idea

C: Computer, AP: Access Point



Independent BSS (IBSS)= BSS - AP

*Extended Service Set (ESS): A collection of BSS
connected by a Distribution System*

Example: The NSU WiFi network is one ESS.

IEEE 802.11/a/b/g/n Family

IEEE	Signal Transmission	Frequency Band	Rate (Mbps)
802.11	DSSS FHSS	2.4 GHz 2.4 GHz	1 and 2 1 and 2
802.11b	DSSS	2.4 GHz	5.5 and 11
802.11a	OFDM	5 GHz	6--54
802.11g 802.11n	OFDM OFDM	2.4 GHz 2.4/5 GHz	22 and 54 72 and <u>150</u>
802.11ac	OFDM	5 GHz	<u>6.9 Gbps</u>

DSSS: Direct Sequence Spread Spectrum

FHSS: Frequency Hopping Spread Spectrum

OFDM: Orthogonal Frequency Division Multiplexing



Are there
different **MAC** protocols in
IEEE 802.11/a/b/g/n standards

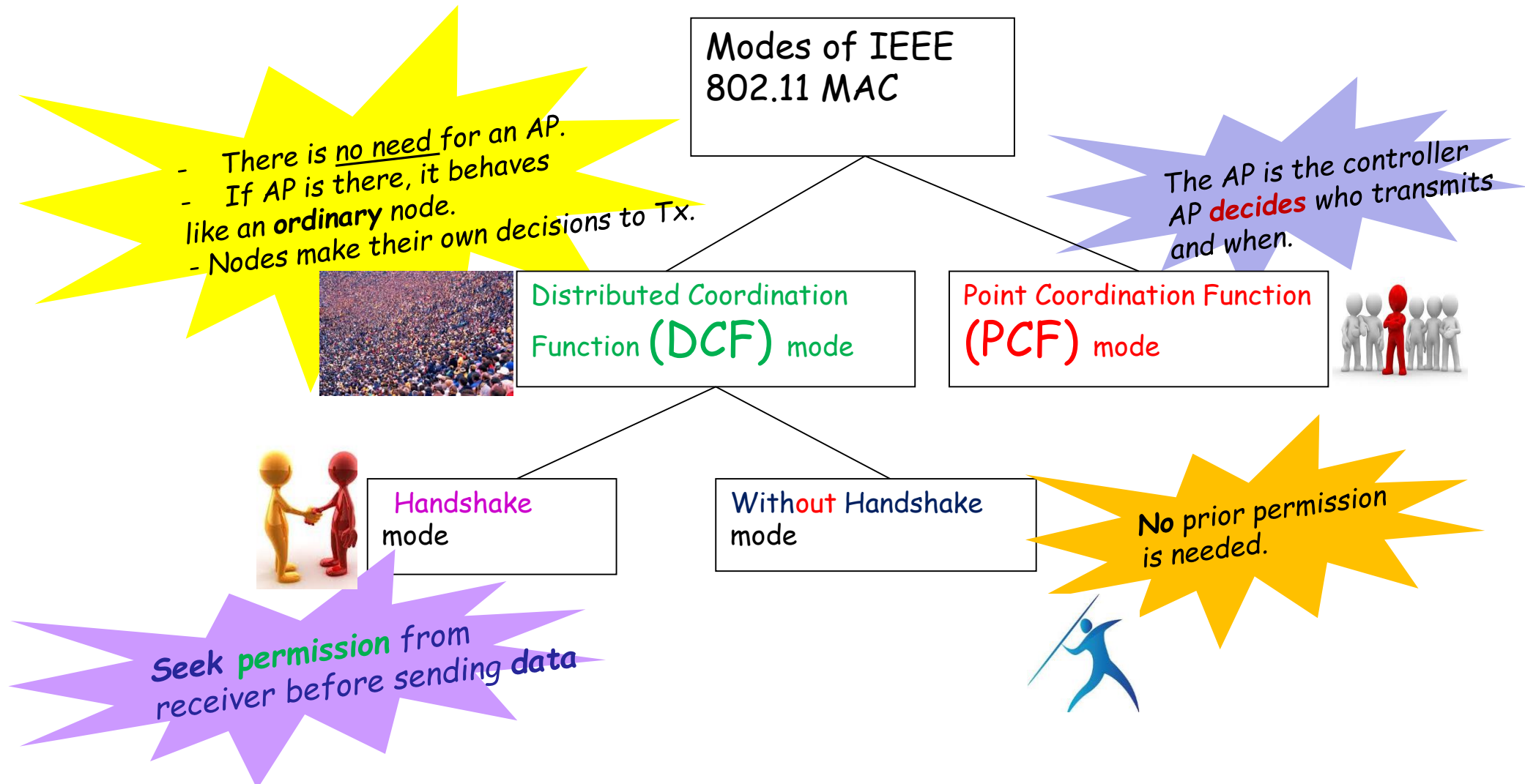


They have all different
PHY layers

But, all of them have the
same MAC protocol

First

Different Modes of Operation of MAC in IEEE 802.11





PCF Mode



❖ The AP

- Operates as the **central controller** in the BSS.
- Decides who transmits and when.
- There is no contention for medium access
- Can follow a round-robin policy to allocate slots.

❖ This mode

- Leads to waste of bandwidth if a scheduled node has no traffic.
- Is based on the idea of polling ← Recall “taking-turns” MAC

DCF Mode



❖ An AP

- Need not be used.
 - Computers can directly communicate among themselves <= Ad hoc.
- Is used to provide connectivity to the Internet.

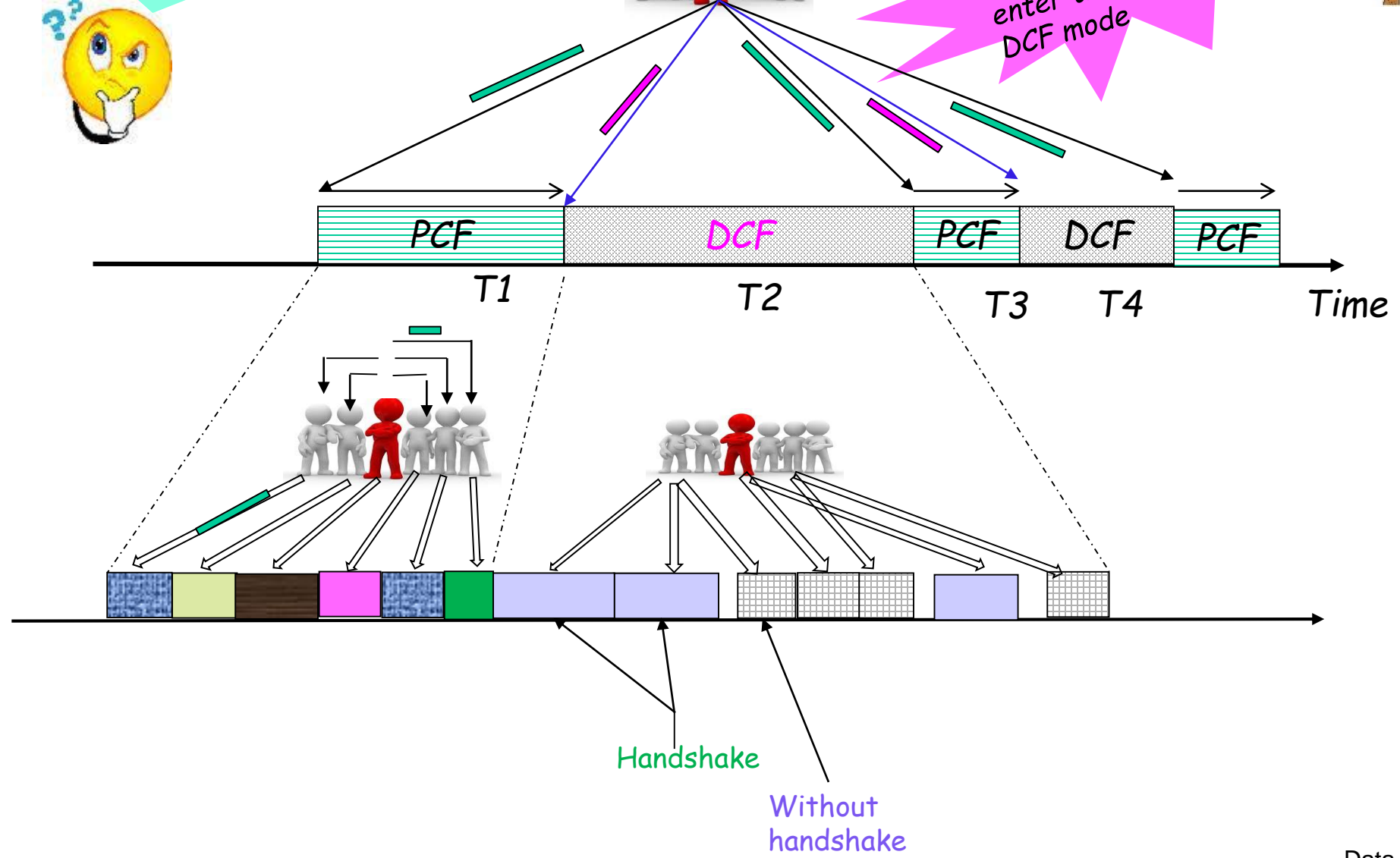
❖ In DCF

- All nodes, including the AP, compete for medium access.
- The AP does not operate as a central controller.

How are all those modes related?



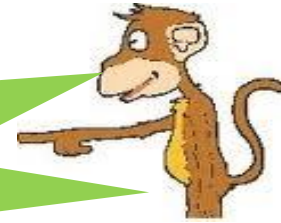
The AP tells all when to enter the PCF mode and DCF mode



How do I know when to use
handshake and when to use
without-handshake



The MAC management database
holds a variable: **dotRTSThreshold**
(integer in bytes)



Handshake mode

Frame length \geq dotRTSThreshold

Without-Handshake mode

Frame length $<$ dotRTSThreshold

For "long" frames, you want
to reduce the prob. of collision...
with some overhead

DCF with *handshake*

How is **handshake** implemented



Under a **certain condition**
(to be explained soon)

Control Frames:

RTS: Request To Send
CTS: Clear To Send

Sender

Receiver

handshake

RTS

CTS

DATA

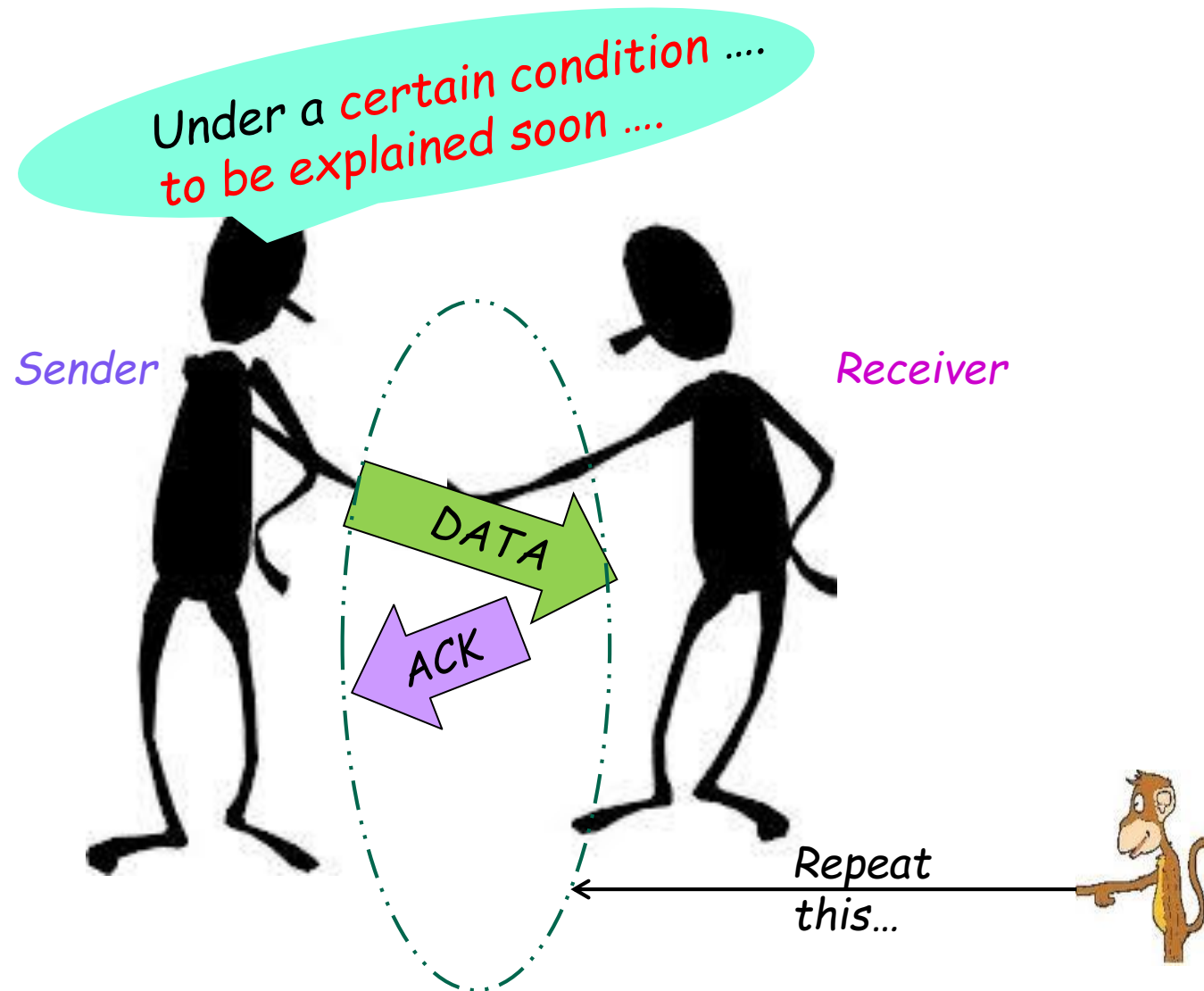
ACK

Receiver is
under no
obligation
to send CTS.

Note: There is
strict timing
relationship
between successive
frames

Repeat this...

DCF without *handshake*

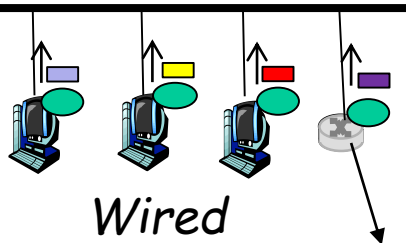


What is the big deal in a WLAN?
What happens to my RTS, CTS, DATA, ACK,.....
Do they **collide** with Tx from other nodes

Note the diff. between
a **wired** medium & a **wireless** medium



Signal from all nodes
must reach all others

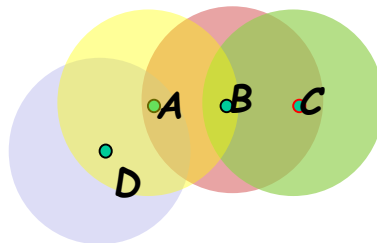


Wired



Remember this diff...

Wireless



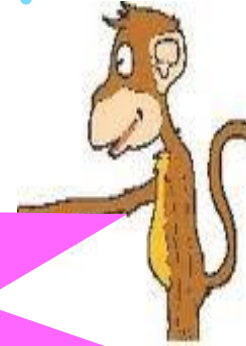
Signal from some nodes
may not reach all others

This diff. leads
to some problems

What problems can arise
in a wireless net



Collision detection is not always
possible in a wireless LAN.



You do not receive
the **signal** received by
the intended receiver of
your frame.



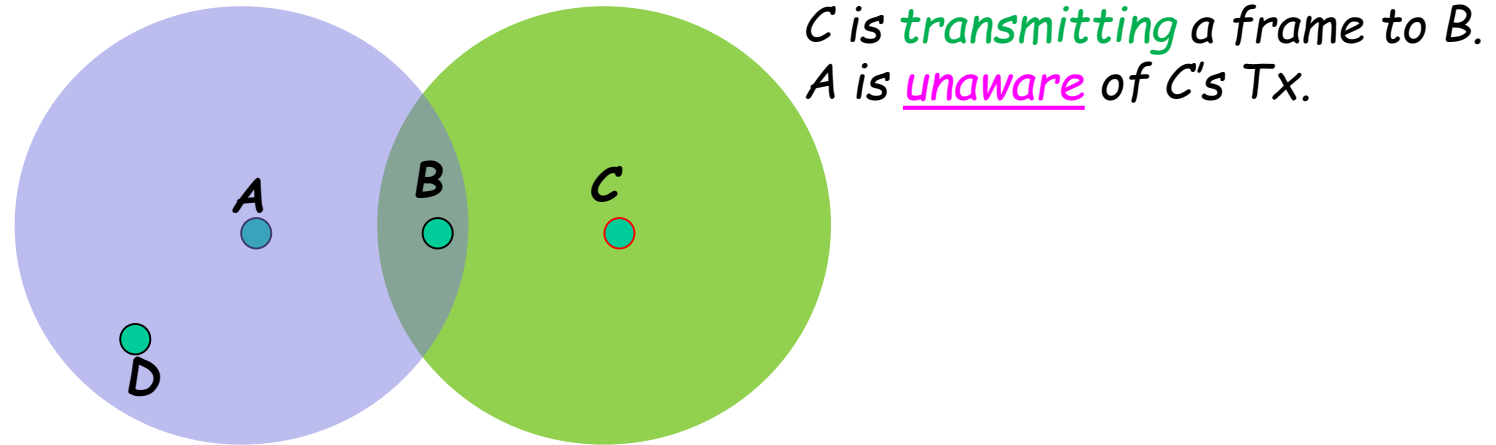
As a result, if your frame
encountered collision at the
receiver, you are **NOT** aware
of that.

Two Problems in WLAN

- ❖ Hidden Terminal Problem
- ❖ Exposed Terminal Problem



Hidden Terminal Problem



Now, *if A transmits*, A's frame will *collide* with C's at B

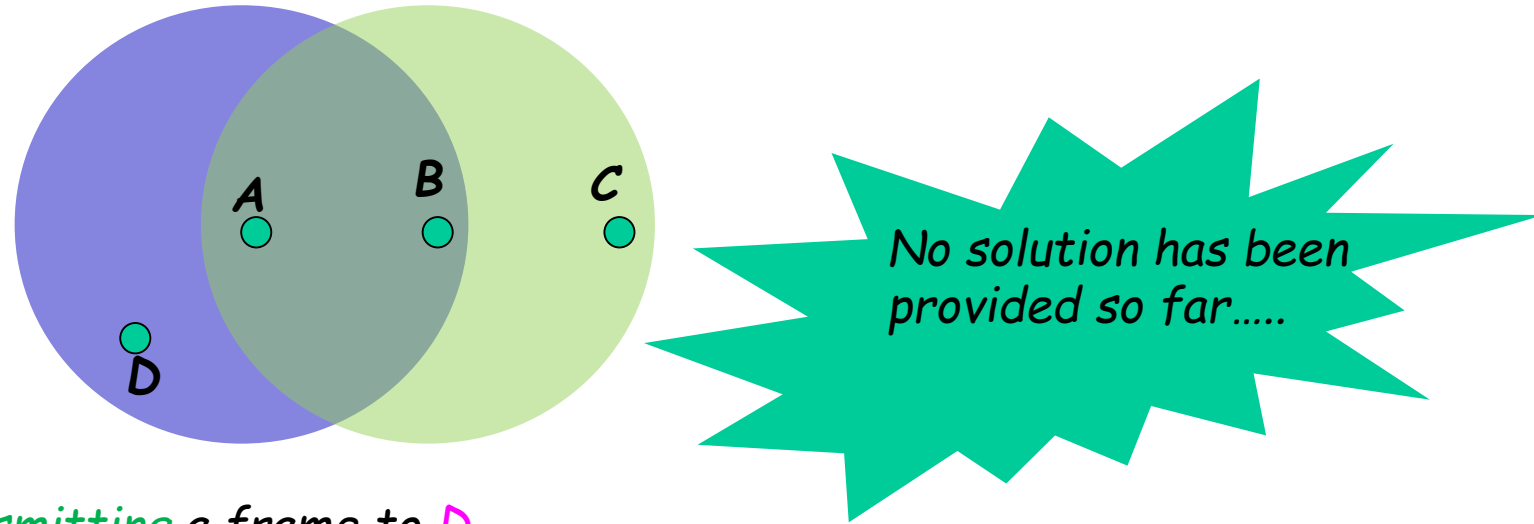
- This problem is due to C being **hidden** from A.
 - Hidden means being "far away" ...



Collision occurs at B,
but A cannot detect it...

Solution exists:
CSMA/CA
(Collision Avoidance)

Exposed Terminal Problem



A is transmitting a frame to D.

B knows that someone is transmitting.

If B transmits a frame to C, it does not collide with A's at D.

However, B does not transmit because B is unaware of D's location.

Problem: Loss of opportunity to transmit → Loss of bandwidth

The above problem is due to B being exposed to A's Tx.

WLAN MAC: CSMA/CA (basic idea)

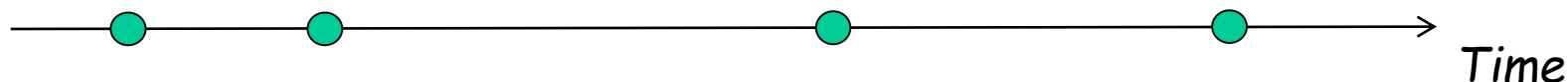


❖ Collision is avoided by using two techniques

- **PHY-level carrier sensing:** Done in receiver hardware
- **Virtual carrier sensing:**
 - An **integer variable** in each node - called **NAV** (Network Allocation Vector) -- indicates whether or not a nearby node is likely to be transmitting now.
 - **NAV > 0** → Most likely another node is transmitting.
 - **NAV = 0** → No one nearby is transmitting.
 - ~~NAV < 0: This condition does not occur.~~

❖ **Transmit condition:** *Medium is idle at the receiver.*

(Carrier is absent) AND (NAV = 0)



CSMA/CA: NAV in detail

- Recall the *handshake* mechanism with *RTS* and *CTS*
- A *duration* field in frame header indicates the length of time the sender of the frame may use the medium.
- *All nodes* which receive *RTS* and *CTS* (and *DATA*) update their *NAV* as follows

Events that update NAV: Initially NAV = 0

With each passing μs (micro second)

If ($NAV > 0$) $NAV = NAV - 1$

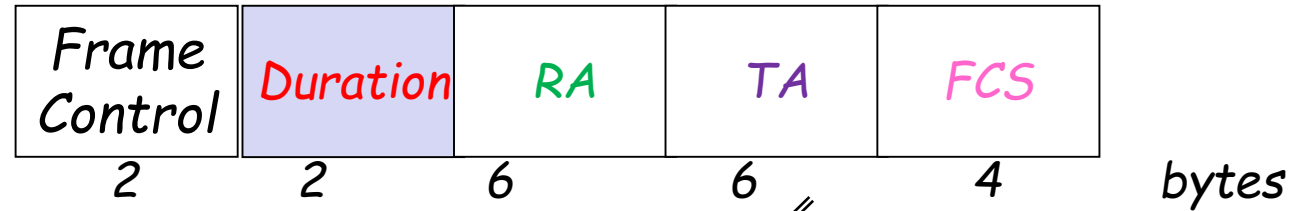
Else stop decrementing *NAV*

If a *frame* (e.g. *RTS*, *CTS*) with *duration* field is received

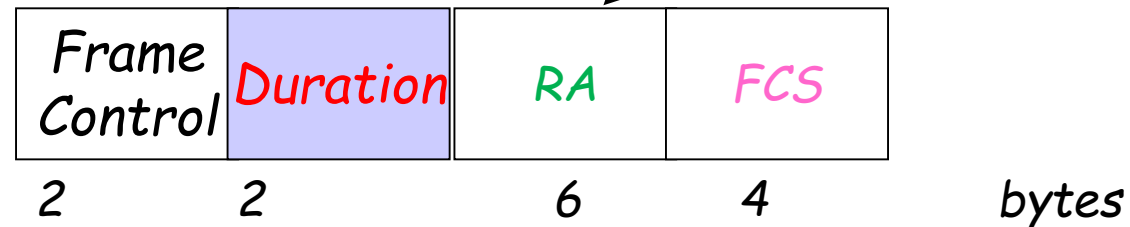
$NAV = \text{Max}(NAV, \text{duration})$

RTS and CTS Frames

RTS

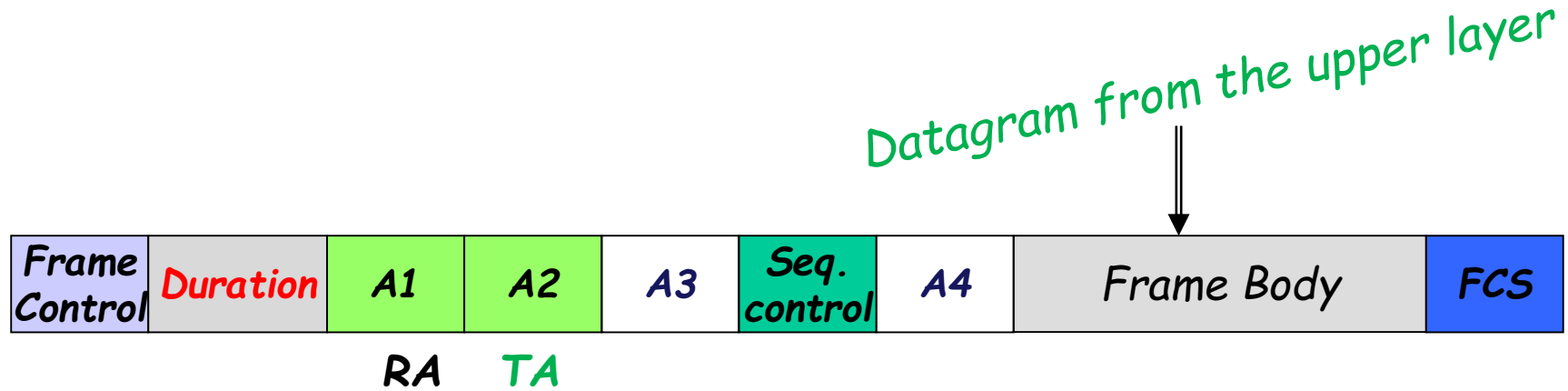


CTS/
ACK

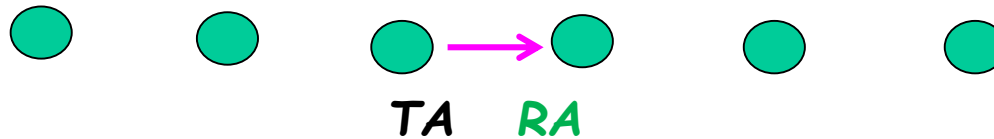


FCS: Frame Check Sequence ← **CRC**
RA: Receiver Address
TA: Transmitter Address

DATA Frame



TA: Physically transmitting the frame.



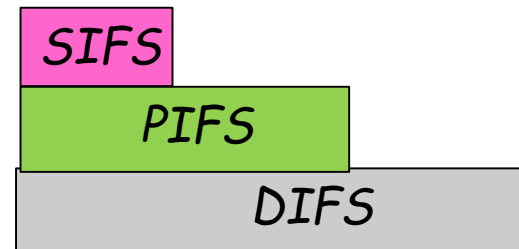
Timing Intervals

- ❖ The IEEE 802.11 MAC defines 4 timing intervals
 - 2 at the PHY level
 - *SIFS*: Short Inter-Frame Space (10 micro-sec) between successive frames (RTS, CTS, DATA, ACK, ...)
 - *aSlot* (20 micro-sec)
 - 2 at the MAC level
 - *PIFS*: Priority (in PCF) IFS (*SIFS* + *aSlot*)
 - *DIFS*: Distributed IFS (*PIFS* + *aSlot*)

aSlot is chosen s.t. a node can determine if another node initiated a Tx *aSlot* time before
(= propagation time + some hardware delay)



Timing intervals are used to control priority



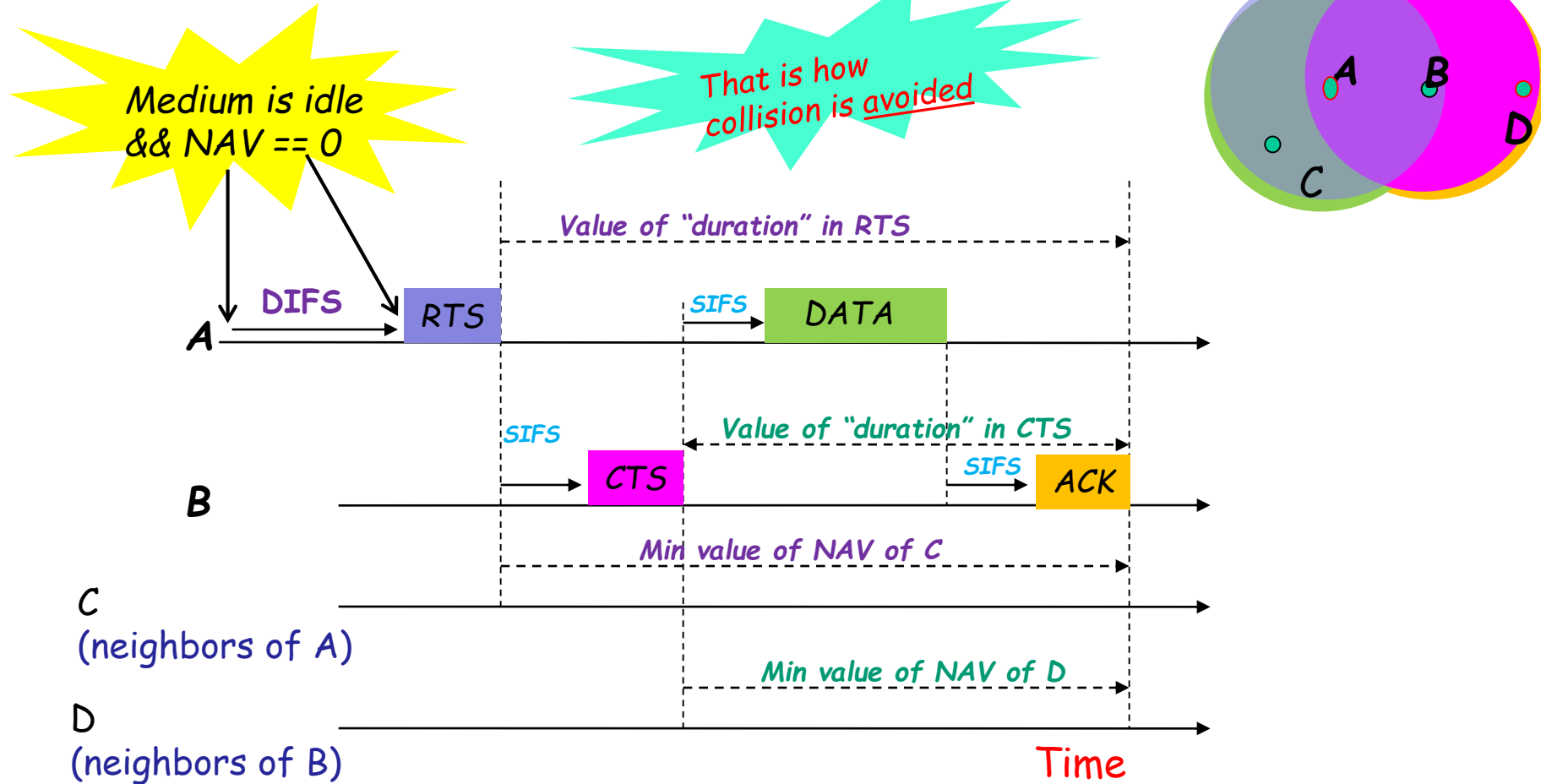
By keeping SIFS shortest, it is ensured that an ongoing cycle of Tx (with handshake or without handshake) is not disturbed

No one else can Tx between RTS, CTS, DATA, ACK.

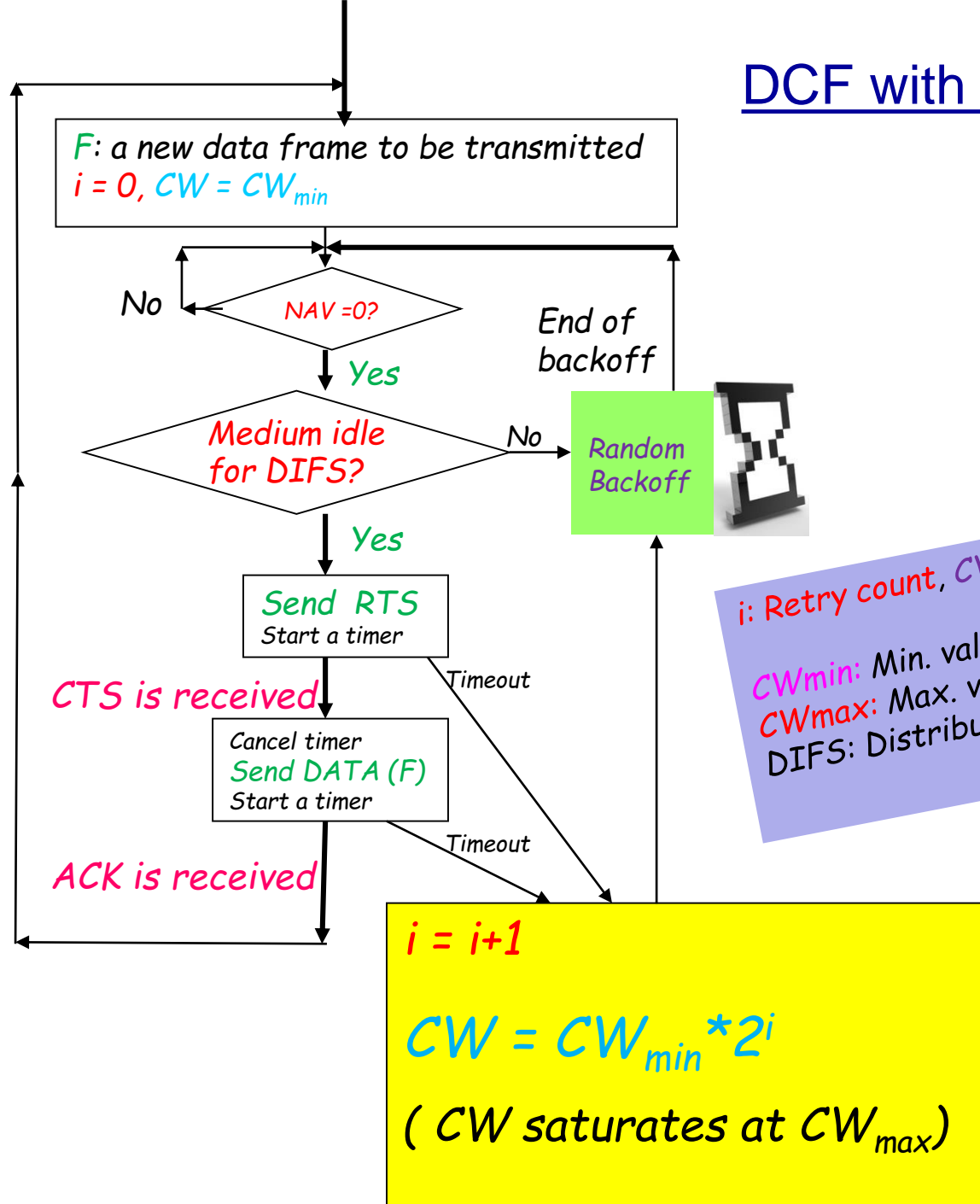
PIFS < DIFS enables an AP to become the controller of a BSS ...

Handshake using RTS/CTS (A wants to send data to B)

(Note: "duration" info in DATA will not be shown.)



DCF with Hand-shake: Tx



i : Retry count, CW : Contention Window
 CW_{min} : Min. value of CW (typical: 32)
 CW_{max} : Max. value of CW (typical: 256)
DIFS: Distributed Interframe Space

Backoff Mechanism

- ❖ **Initialize** a counter: Backoff Time Counter (BTC)
 - $BTC = \text{Random}(0, CW-1)$ time unit of BTC is **aSlot**

- ❖ *As time passes, BTC is decremented as follows*

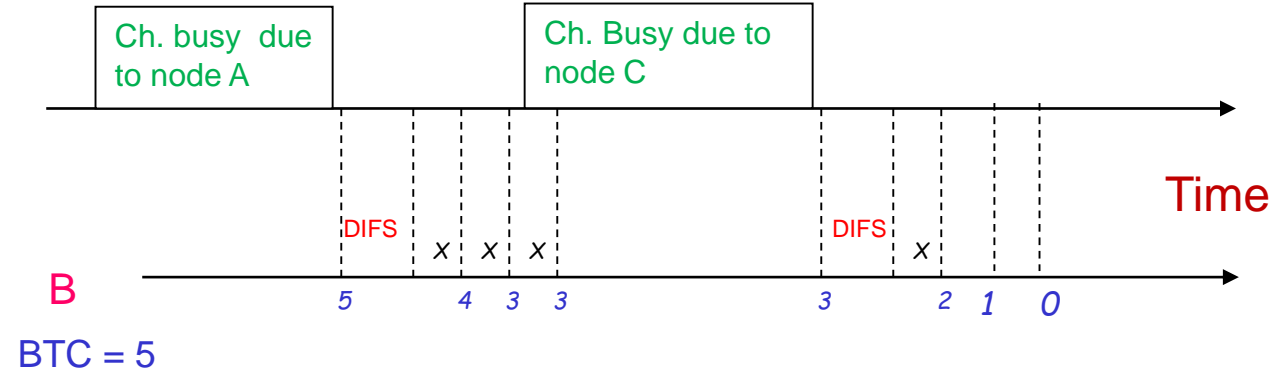
At the start, let ch. remain idle for DIFS.

 *Next, if ch. is idle for aSlot: $BTC = BTC - 1$ ← Repeat this*

Anytime the medium is busy: Freeze BTC

- ❖ $BTC == 0 \rightarrow$ *End of backoff*

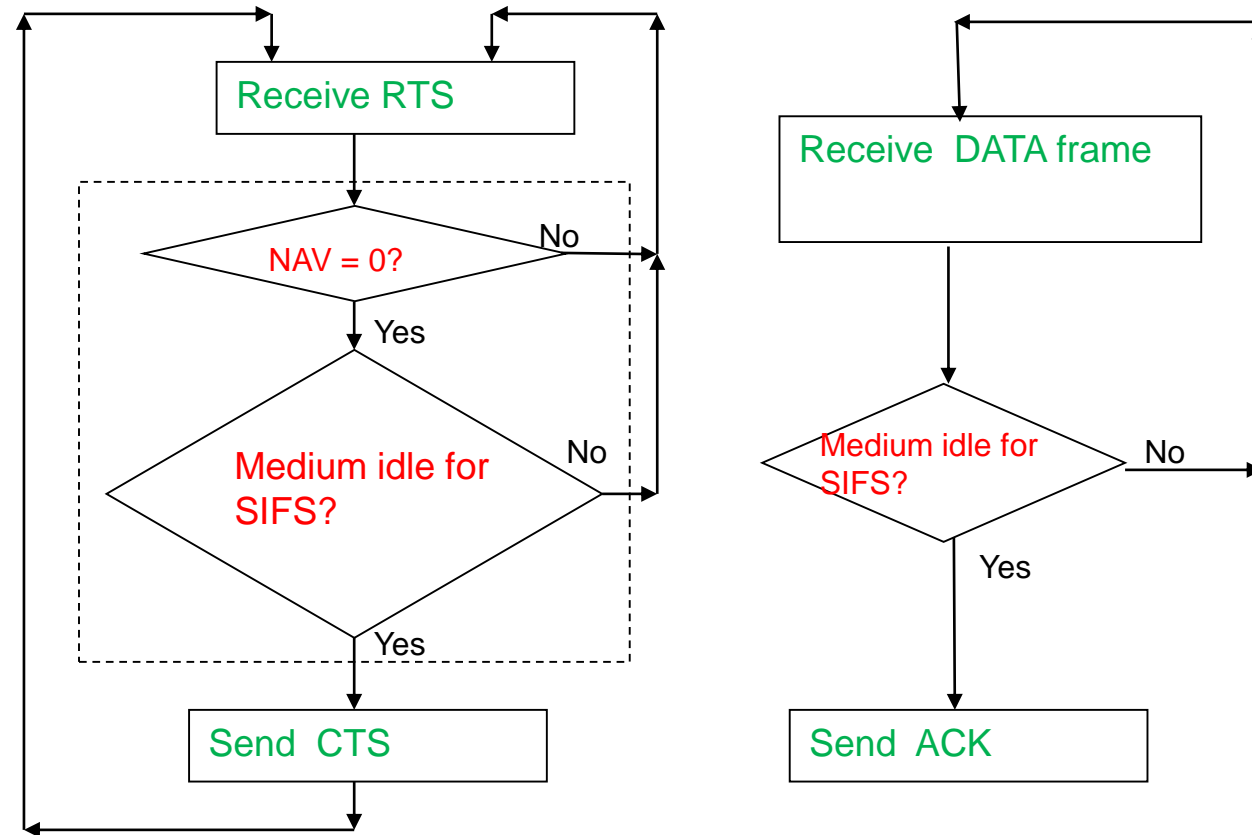
Backoff Mechanism



B is executing **backoff**

$X = \text{aSlotTime}$

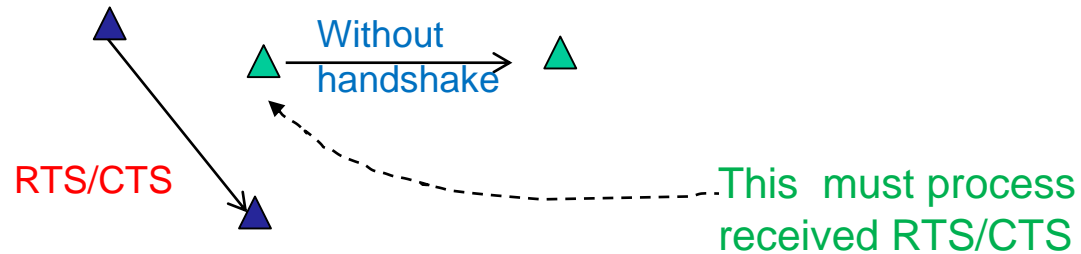
DCF with Handshake: Rx



Note: The above two fragments of flow-charts can be easily merged.

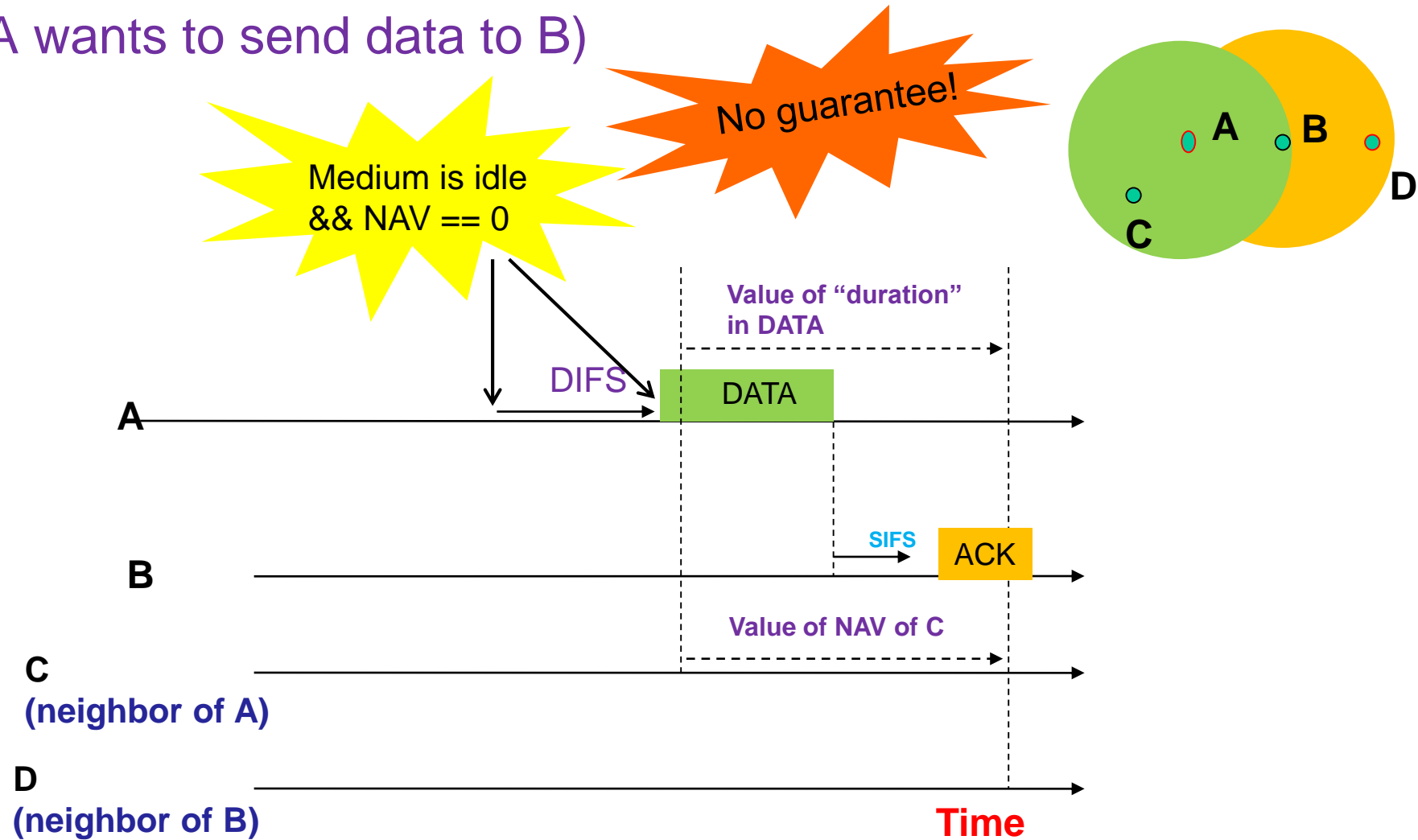
DCF Mode **without** Handshake

- ❖ A special case of DCF without handshake
 - **RTS/CTS** frames are **not** exchanged.
- ❖ The idea of **NAV** is still used in this mode
 - **Recall:** All nodes process the received **RTS/CTS** of others



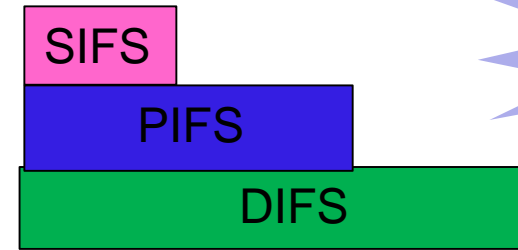
Data transmission without handshake

(A wants to send data to B)



PCF Mode: AP becomes the controller: How?

- ❖ AP **alternates** between **PCF** and **DCF** modes



- ❖ AP operates as the **controller** as follows

If AP finds medium to be **idle** (**no carrier && NAV == 0**) for **PIFS**, it transmits a **beacon** frame.

Beacon contains a **CFPMaxDuration** field (CFP: Contention Free Period)

Nodes receiving a **beacon** update their **NAV** to **CFPMaxDuration**

These nodes perceive **the medium to be busy** for **CFPMaxDuration**

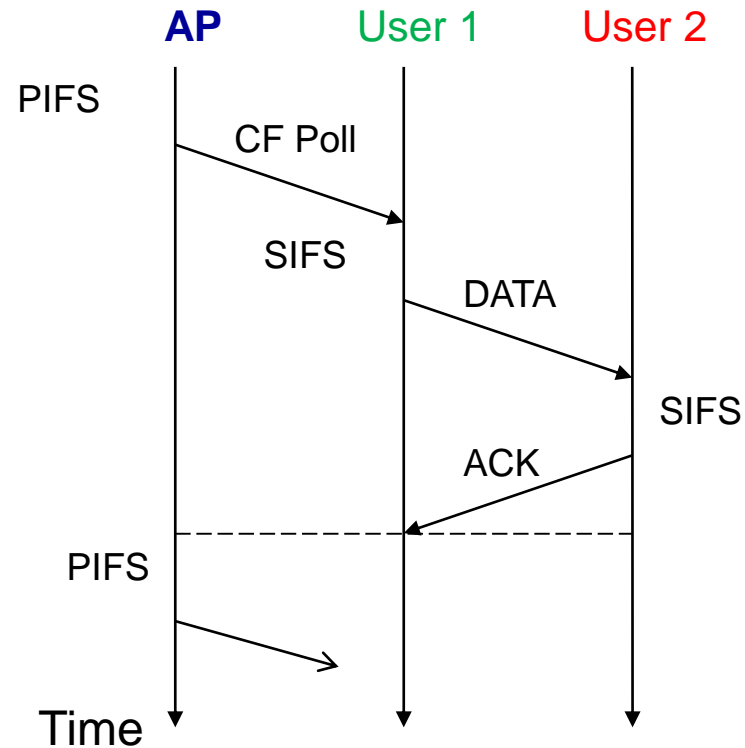
They do not transmit unless asked to do so by the AP.

PCF Mode of Operation (Contd.)

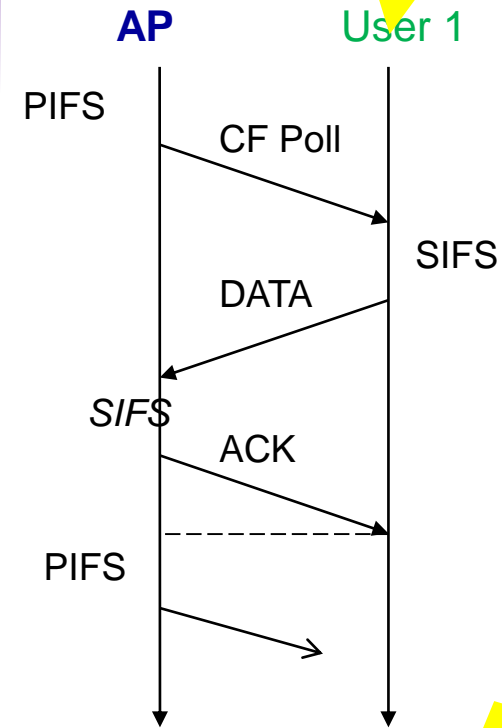
- After **transmitting a beacon**, AP waits for PIFS before transmitting one of the following
 - DATA frame
 - CF Poll frame (CF: Contention Free)
 - DATA+CF Poll frame
 - ACK frame
 - CF End frame

PCF Mode of Operation (Contd.)

CF Poll frame



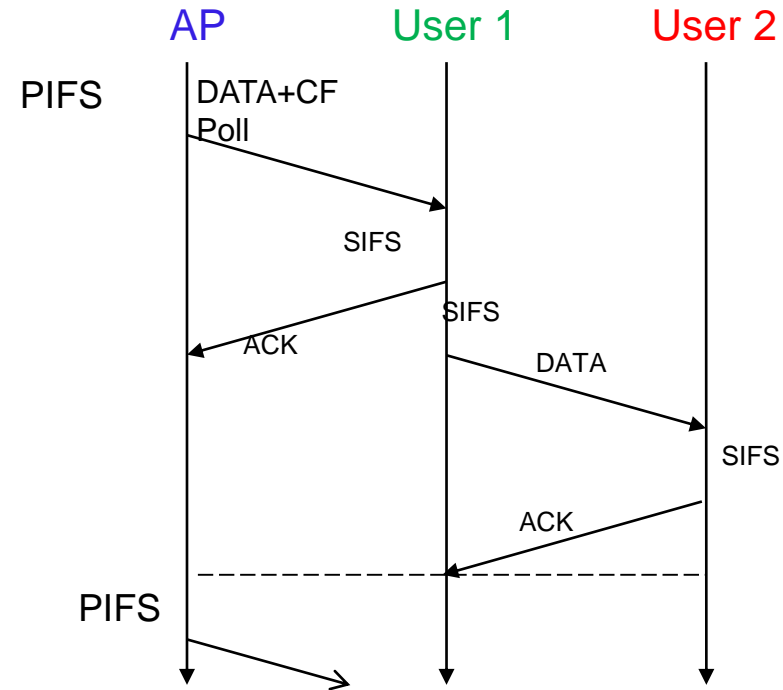
If a user does **not** have data, it sends a **null** DATA frame (A DATA frame with no actual data)



If ACK is not received, user 1 waits until it is polled again.

PCF Mode of Operation (Contd.)

DATA + CF Poll frame



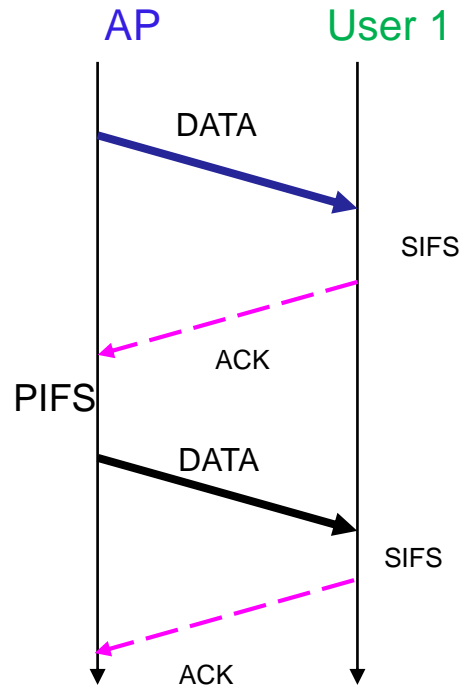
Note 1: If AP does **not** receive an ACK, it **retransmits** data after PIFS.

Note 2: If User 1 does not receive ACK, it does **not retransmit** data.

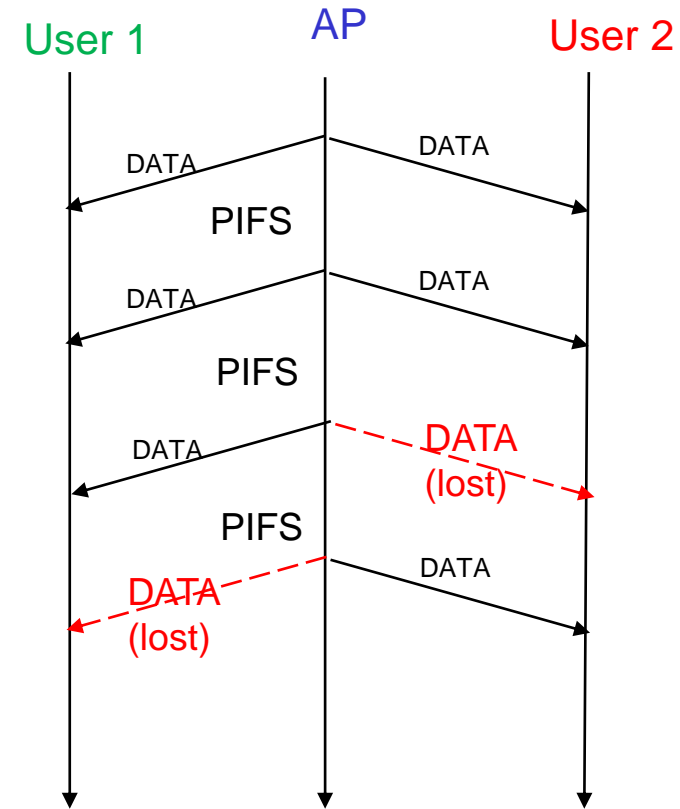
The polled user receives data from the AP and sends data to another user.

PCF Mode of Operation (Contd.)

DATA from AP (unicast): 1 → 1



DATA from AP (broadcast): 1 → all



No ACK....

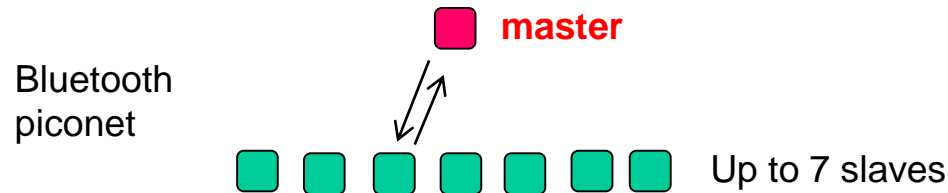
PCF Mode of Operation (Contd.)

❖ CF End frame

- Identifies the end of CF period
 - Receiving nodes set $NAV = 0$.

Summary of MAC protocols

- ❖ **channel partitioning** by time, frequency or code
 - Time Division, Frequency Division, Code Division
- ❖ **random access** (dynamic),
 - ALOHA, S-ALOHA, CSMA/CD, CSMA/CA
 - carrier sensing: easy in some technologies (wire), hard in wireless
 - CSMA/CD used in Ethernet based LAN
 - CSMA/CA used in WiFi (802.11) based WLAN
- ❖ **taking turns**
 - polling from central site, token passing
 - Examples: **Bluetooth**, **IBM Token Ring**



More past exam questions ...

F'12 Mid-term



Clearly explain why collision detection is not possible in wireless local area networks.

Clearly explain why the timing intervals SIFS, PIFS, and DIFS have been ordered as $SIFS < PIFS < DIFS$ in the CSMA/CA protocol.

Clearly explain the hidden terminal problem.

S'12 Mid-term

Summary

- ❖ principles behind data link layer services:
 - error detection, correction
 - sharing a broadcast channel: multiple access
 - link layer addressing
- ❖ instantiation and implementation of various link layer technologies
 - Ethernet
 - switched LANS, WLANs
- ❖ could stop here but *lots* of interesting topics!