

Basic Data Structures: Dynamic Arrays and Amortized Analysis

Data Structures

Data Structures and Algorithms

Outline

- 1 Dynamic Arrays
- 2 Amortized Analysis-Aggregate Method

Problem: static arrays are static!

```
int my_array[100];
```

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Semi-solution: dynamically-allocated arrays:

```
int *my_array = new int[size];
```

Problem: might not know max size when allocating an array

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All problems in computer science can be solved by another level of indirection.

Solution: *dynamic arrays* (also known as *resizable arrays*)

Idea: store a pointer to a dynamically allocated array, and replace it with a newly-allocated array as needed.

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Abstract data type with the following operations (at a minimum):

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Dynamic Array:

Abstract data type with the following operations (at a minimum):

- $\text{Get}(i)$: returns element at location i^*
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- $\text{PushBack}(val)$: Adds val to the end

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- $\text{Get}(i)$: returns element at location i^*
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- $\text{PushBack}(val)$: Adds val to the end
- $\text{Remove}(i)$: Removes element at location i
- $\text{Size}()$: the number of elements

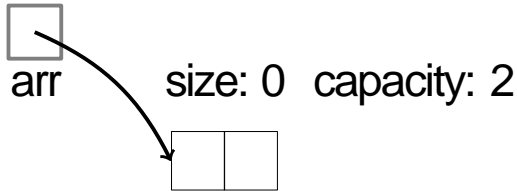
*must be constant time

Implementation

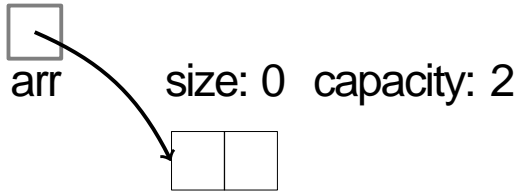
Store:

- `arr`: dynamically-allocated array
- `capacity`: size of the dynamically-allocated array
- `size`: number of elements currently in the array

Dynamic Array Resizing

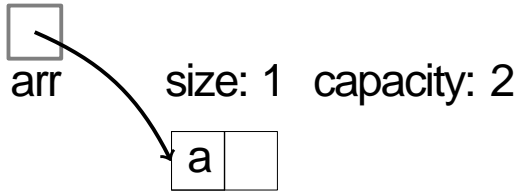


Dynamic Array Resizing



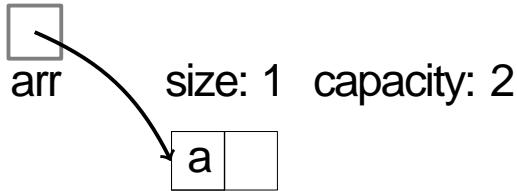
PushBack (a)

Dynamic Array Resizing

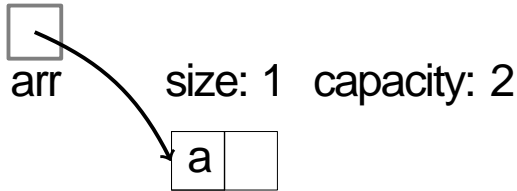


`PushBack (a)`

Dynamic Array Resizing

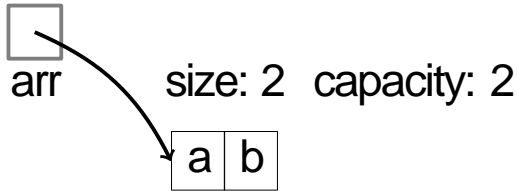


Dynamic Array Resizing



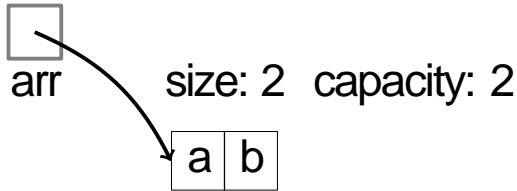
PushBack (b)

Dynamic Array Resizing

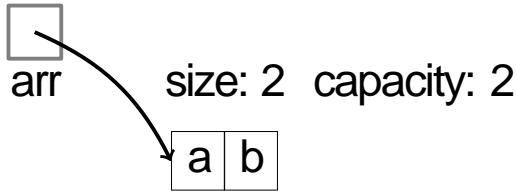


PushBack (b)

Dynamic Array Resizing

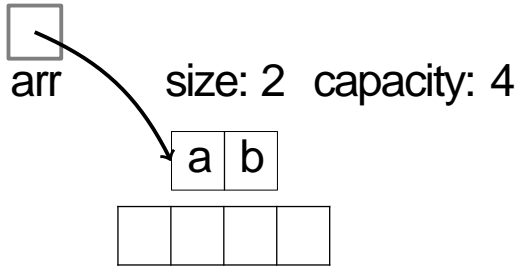


Dynamic Array Resizing



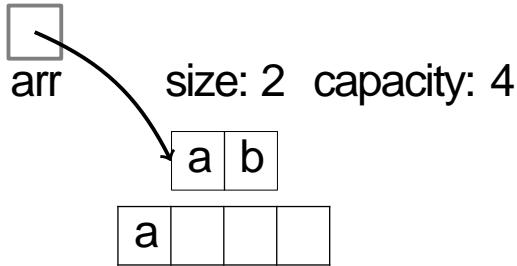
`PushBack (c)`

Dynamic Array Resizing



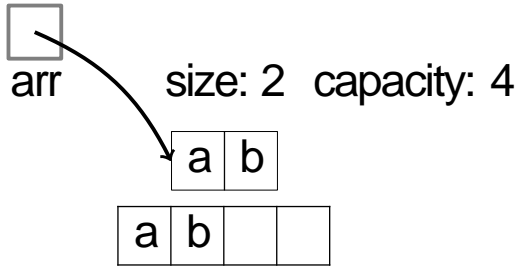
PushBack (c)

Dynamic Array Resizing



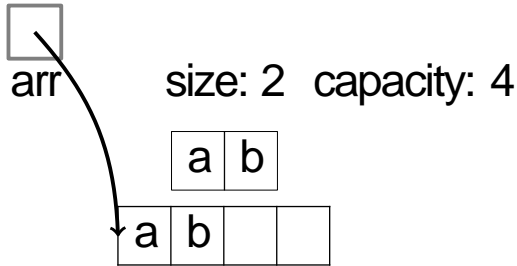
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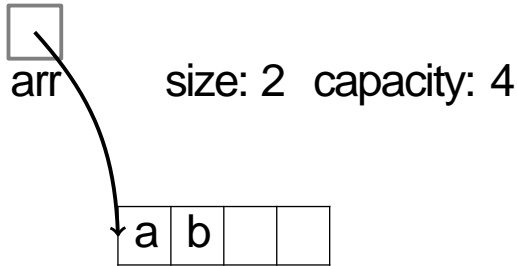
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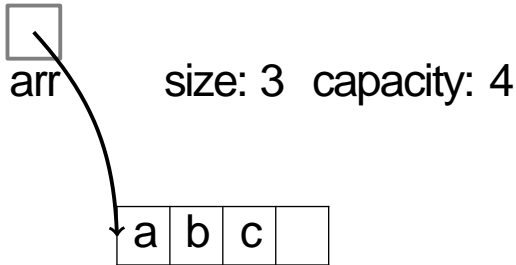
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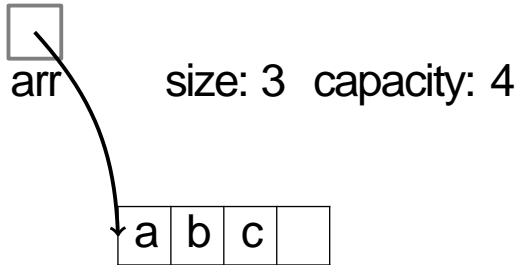
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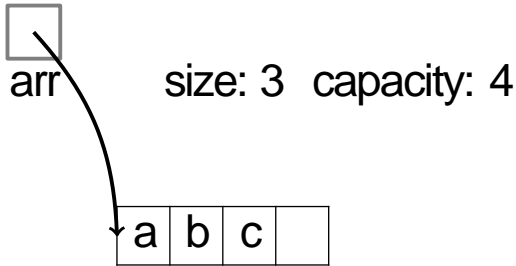


PushBack (c)

Dynamic Array Resizing

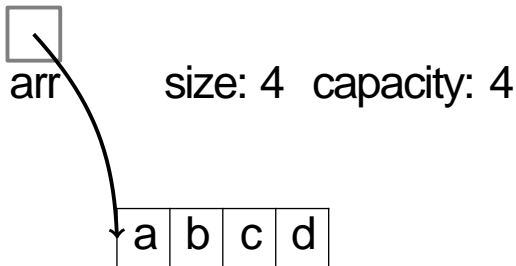


Dynamic Array Resizing



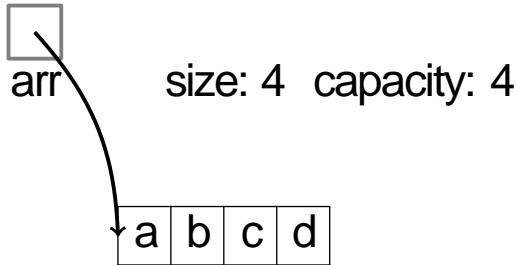
PushBack (d)

Dynamic Array Resizing

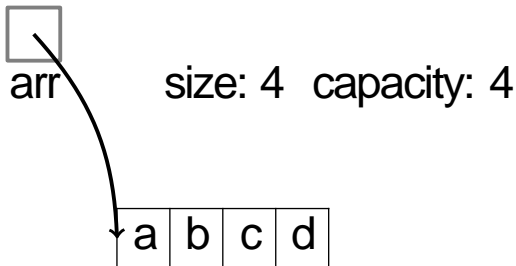


PushBack (d)

Dynamic Array Resizing

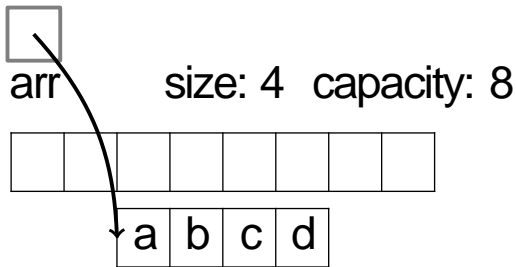


Dynamic Array Resizing



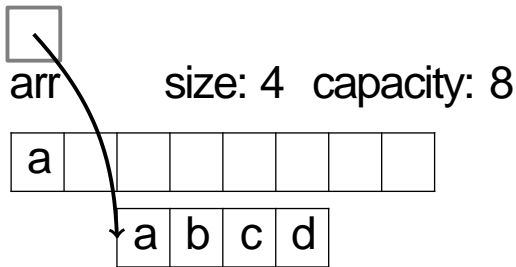
PushBack (e)

Dynamic Array Resizing



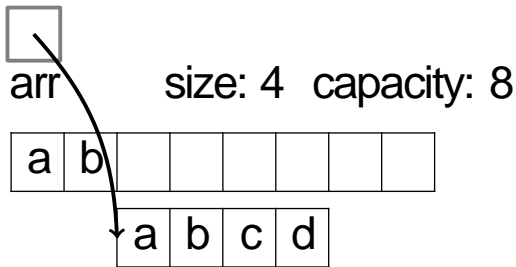
PushBack (e)

Dynamic Array Resizing



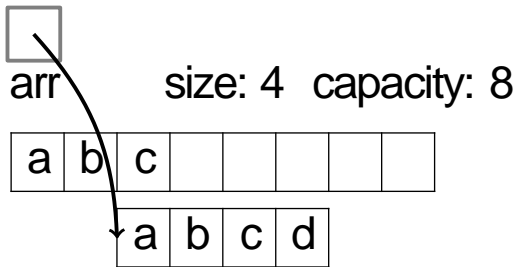
PushBack (e)

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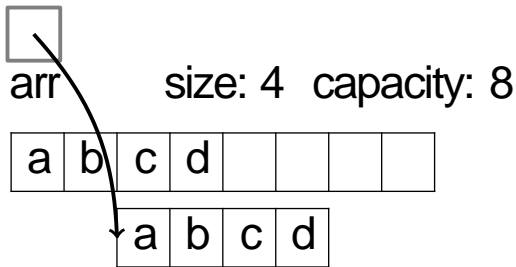
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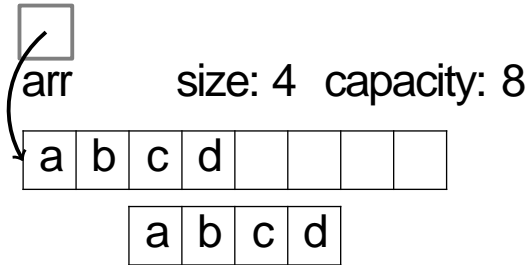
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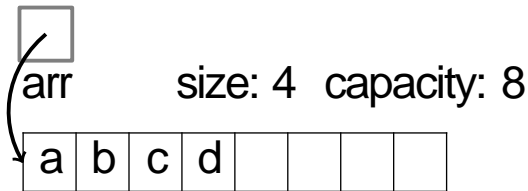
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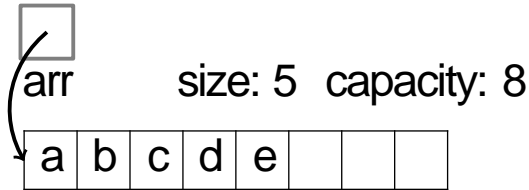
PushBack (e)

Dynamic Array Resizing



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Dynamic Array Resizing



PushBack (e)

Get(*i*)

if $i < 0$ or $i \geq \text{size}$:

 ERROR: index out of range

return *arr*[*i*]

Set(i , val)

if $i < 0$ or $i \geq size$:

 ERROR: index out of
 range

$arr[i] = val$

PushBack(*val*)

if *size* = *capacity*:

 allocate *new_arr*[$2 \times \text{capacity}$]

 for *i* from 0 to *size* - 1:

new_arr[*i*] \leftarrow *arr*[*i*]

 free *arr*

arr \leftarrow *new_arr*; *capacity* $\leftarrow 2 \times \text{capacity}$

arr[*size*] \leftarrow *val*

size \leftarrow *size* + 1

Remove(*i*)

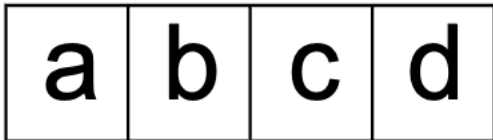
if $i < 0$ or $i \geq \text{size}$:

 ERROR: index out of range

for j from i to size :

$\text{arr}[j] \leftarrow \text{arr}[j + 1]$

$\text{size} \leftarrow \text{size} - 1$



```
Size()
```

```
return size
```

Common Implementations

- **C++:** `vector`
- **Java:** `ArrayList`
- **Python:** `list` (the only kind of array)

Runtimes

Get(*i*) | $O(1)$

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<code>Get(<i>i</i>)</code>	$O(1)$
<code>Set(<i>i</i>, <i>val</i>)</code>	$O(1)$

Runtimes

Get(<i>i</i>)	$O(1)$
Set(<i>i</i> , <i>val</i>)	$O(1)$
PushBack(<i>val</i>)	$O(n)$

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Get(i)	$O(1)$
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Remove(i)	$O(n)$
Size()	$O(1)$

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- Appending a new element to a dynamic array is often constant time, but can take $O(n)$.
- Some space is wasted-at most half.

Outline

- ① Dynamic Arrays
- ② Amortized Analysis-Aggregate Method
- ③ Amortized Analysis-Banker's Method
- ④ Amortized Analysis-Physicist's Method

Sometimes, looking at the individual worst-case may be too severe. We may want to know the total worst-case cost for a sequence of operations.

Dynamic Array

We only resize every so often.

Many $O(1)$ operations are followed by an

$O(n)$ operations.

What is the total cost of inserting many elements?

Definition

Amortized cost: Given a sequence of n operations, the amortized cost is:

$$\frac{\text{Cost}(n \text{ operations})}{n}$$

Aggregate Method

Dynamic array: n calls to `PushBack`

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Let $c_i =$ cost of i 'th insertion.

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Dynamic array: n calls to `PushBack`

Let c_i = cost of i 'th insertion.

$$c_i = 1 + \begin{cases} i - 1 & \text{if } i - 1 \text{ is a power of 2} \\ 0 & \text{otherwise} \end{cases}$$

$$\frac{\sum_{i=1}^n c_i}{n} = \frac{n + \sum_{j=1}^{\lfloor \log_2(n-1) \rfloor} 2^j}{n} = \frac{O(n)}{n}$$

$$\sum_{j=1}^{\lfloor \log_2(n-1) \rfloor} 2^j = 2^{\lfloor \log_2(n-1) \rfloor + 1} - 2.$$

Note that $2^{\lfloor \log_2(n-1) \rfloor + 1} = 2 \cdot 2^{\lfloor \log_2(n-1) \rfloor} \leq 2 \cdot (n-1)$, so the total sum is at most $2(n-1) - 2 = O(n)$.

Question

Which of the following is the tightest correct upper bound on the value of the sum. $\sum_{j=1}^{\lfloor \log_2(n-1) \rfloor} 2^j$? Recall that $\lfloor x \rfloor$ is the floor function

of x - the largest integer that is not greater than x . Also recall that

$$2^{\log_2(x)} = x.$$

. You may want to read about the [geometric series](#).

$$O(n)$$

$$O(1)$$

$$O(\log n)$$

$$O(n^2).$$

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Alternatives to Doubling the Array Size

We could use some different growth factor (1.5, 2.5, etc.).

Could we use a constant amount?

Cannot Use Constant Amount

If we expand by 10 each time, then:

Let c_i = cost of i 'th insertion.

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$$c_i = 1 + \begin{cases} i - 1 & \text{if } i - 1 \text{ is a multiple of } 10 \\ 0 & \text{otherwise} \end{cases}$$

$$\begin{aligned} \frac{\sum_{i=1}^n c_i}{n} &= \frac{n + \sum_{j=1}^{(n-1)/10} 10j}{n} = \frac{n + 10 \sum_{j=1}^{(n-1)/10} j}{n} \\ &= \frac{n + 10O(n^2)}{n} = \frac{O(n^2)}{n} = O(n) \end{aligned}$$

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Summary

- Calculate amortized cost of an operation in the context of a sequence of operations.
- Three ways to do analysis:
 - Aggregate method (brute-force sum)
 - Banker's method (tokens)
 - Physicist's method (potential function, Φ)
- Nothing changes in the code: runtime analysis only.