

Course Name : Physics – I Course # PHY 107

Notes-5: Newton's laws - Part One

Abu Mohammad Khan Department of Mathematics and Physics North South University https://abukhan.weebly.com

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# Topics to be studied

- ► What is dynamics?
- ► Cause of motion Concept of Force
- ► Newton's 1<sup>st</sup> law and its equivalent statements
- ► Newton's 2<sup>nd</sup> law
- ► Newton's 3<sup>rd</sup> law
- Examples

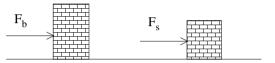
## Dynamics:

- ► The main objective of dynamics is to explain the observed motion. Mainly how and why an object is accelerated or not?
- ► This is done in two steps:
  - ightharpoonup Firstly, how to understand that there is an external cause acting on the object. The answer to this question is known as the Newton's  $1^{\rm st}$  law.
  - ightharpoonup Secondly, if there is an external cause, how to quantitatively express the effect. The answer to this question is known as the Newton's  $2^{\rm nd}$  law.
- ▶ The 1<sup>st</sup> law defines what is known as the 'Inertia' of an object.
- ▶ The 2<sup>nd</sup> law provides a way to measure the amount of inertia.
- ▶ The 3<sup>rd</sup> law explains how two objects interact with each other.

#### Cause of Motion: Force

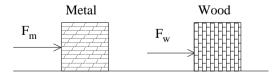
- ▶ Let's consider some observation. An object is at rest implies that it's position does not change with respect to time (*i.e.* zero velocity). If we apply a 'Push', it's position changes. So it acquired the velocity. Here 'Push' is the cause of motion, and the change in velocity (from zero to some nonzero value) is the effect.
- The 'Push' is called the 'Force' and is denoted by  $\vec{F}$  because it is a vector quantity ( has both magnitude and direction).
- ➤ To understand the factor that determine the amount of change in velocity under a force, let's consider some phenomena.
- ▶ We apply the same Force on two objects that are of same material, but different size, to produce same change in velocity on both.
- ▶ We also apply Force on two different objects that are of equal size, but different material to produce the same change in velocity.

- ► Here we assume that the surface is 'perfectly smooth' (i.e. ideal slippery) so that it does not apply any 'influence' on the objects.
- ► Case-I: Force required to change velocity



The blocks are of same material, but different size

► Case-II: Force required to change velocity



The blocks are of same size, but different material.

- ► Here it is clear from the observation that  $\vec{F}_h > \vec{F}_s$ .
- Bigger size object has more 'inertness', or simply it has more 'inertia'.

- Here it is clear from the observation that  $\vec{F}_m > \vec{F}_w$ .
- Metallic (or heavier) object has more 'inertness', or simply it has more 'inertia'.

#### Newton's 1st law:

- ► The previous two observations imply that 'inertia' is an inherent property of all objects. It does not depend on the size.
- Higher inertia requires more force to change the velocity.
- ▶ Because of the inertia, the object resist to change and hence requires the external 'Cause', called the Force, to change it's motion.
- ▶ 1<sup>st</sup> law: If no force acts on an object, the velocity of the object cannot change; that is, the body cannot accelerate.
- ▶ In other words, if the object is at rest, it stays at rest. If it is moving, it continues to move with the same velocity (same magnitude and same direction).
- ▶ But what about if more than one force acts on an object? In this case, the net force needs to be considered, because a given object CAN NOT have different changes in velocities simultaneously. The object must respond to the net force.
- ▶ If no net force acts on an object  $(\vec{F}_{net} = \sum \vec{F} = 0)$ , the object's velocity cannot change; that is, the body cannot accelerate.



- ▶ Finally, the Newton's 1<sup>st</sup> law can be expressed as
  - The object is in equilibrium.
  - 2)  $\vec{v} = \text{constant}$ .
  - 3)  $\vec{a} = 0$ .
  - 4)  $\sum \vec{F} \equiv \vec{F}_{\rm tot} = 0$ .
- It is very important to understand that these four statements are equivalent.
- ► This means that if any of these four is correct, then automatically all four statements are correct.
- ▶ In any frame where Newton's laws hold is called an 'Inertial Reference Frame'.
- ▶ A rotating frame is not an Inertial Reference Frame, because of rotation there is a sideway force due to rotation of the frame.
- ▶ This is why the Earth is not an Inertial Reference Frame in the strict sense.

### Newton's 2<sup>nd</sup> law:

- Let's now understand how to measure the 'Inertia'.
- ▶ Suppose an object with fixed 'Inertia' is moving with a constant velocity  $\vec{v_i}$ . When a force  $\vec{F}$  acts on it for a time interval of  $\Delta t$ . it's velocity changes to  $\vec{v_f}$ .
- ▶ So, the acceleration under this force is  $\vec{a} = \frac{\vec{v_f} \vec{v_i}}{\Delta t} = \frac{\Delta \vec{v}}{\Delta t}$ .
- ▶ It is found from observation that, if the applied force is increased, the observed acceleration also increases proportionally.
- ▶ That is,  $\vec{a} \propto \vec{F}$ .
- ▶ If more than one force is applied, then the acceleration to proportional to the net force, *i.e.*,  $\vec{a} \propto \sum \vec{F}$ .
- ► Therefore, mathematically, we can write,  $\vec{a} = \frac{1}{m} \sum \vec{F}$ . More rigorously this is written as,

$$\sum \vec{F} = m\vec{a}$$
.

- ► The proportionality constant *m* is called the mass of the object, and it is the measure of the 'Inertia' of the object.
- ▶ The mass is a scalar quantity, and in SI unit it is measured in 'Kilogram'.
- ► The previous analysis also clearly indicates that any object must follow either the 1<sup>st</sup> law or the 2<sup>nd</sup> law.
- ► These two laws explain the phenomena what happens when a force acts on a single object. These does not explain the interaction phenomena.

# Newton's 3<sup>rd</sup> law

- ▶ This law explains the interaction between the objects.
- ▶ If two object's apply force on each other, the  $3^{\rm rd}$  law states that  $\vec{F}_{12} = -\vec{F}_{21}$ . That is, these two forces are equal in magnitude, but opposite in directions. Hence,  $|\vec{F}_{12}| = |\vec{F}_{21}|$ . These are called 'Action' and 'Reaction' forces.
- ► For every 'Action' (i.e. applied force), there exists a 'Reaction' (i.e. opposite force) such that their vector sum is always zero.
- Note that because of the the  $3^{\rm rd}$  law, we are able walk on the surface. When we try to walk, we apply a force backward (the 'Action'), and as a result a force by the floor is applied on us forward (the 'reaction'), and we move forward.

# **Problem # 5.11:**

A 2.0 kg particle moving along the x-axis is acted on by a force. Because the force, it's position as a function of time changes as

$$x(t) = 3.0 \,\mathrm{m} + (4.0 \,\mathrm{m/s})t + ct^2 - (2.0 \,\mathrm{m/s}^3)t^3$$

where c is a constant, and x is in meters and t is in seconds. At  $t=3.0\,\mathrm{sec}$ , the force has a magnitude of  $36.0\,\mathrm{N}$ , and is in the negative direction of the axis. Find the constant c.

**Solution:** At  $t = 3.0 \, \text{sec}$ , the force is  $\vec{F} = -36 \, \text{N} \, \hat{i}$ . Now, the acceleration at time  $t = 3.0 \, \text{sec}$  is

$$a = \frac{d^2x}{dt^2}\Big|_{t=3} = (2c - 12t)_{t=3} = 2c - 36 \,\mathrm{m/s^2}$$
.

Therefore, by the  $2^{\rm nd}$  law, we find at time  $t=3.0\,{\rm sec}$  that  $\vec{F}=m\vec{a}$ , and we get,

$$-36 = 2.0(2c - 36)$$
  $\therefore$   $c = 9.0 \,\mathrm{m/s^2}$ .



### **Problem # 5.5:**

An asteroid of mass  $m=120\,\mathrm{kg}$  is guided by three forces:  $\vec{F}_1=(32\,\mathrm{N}\,,\,30^\circ)$ ,  $\vec{F}_2=(55\,\mathrm{N}\,,\,0^\circ)$  and  $\vec{F}_3=(41\,\mathrm{N}\,,\,-60^\circ)$ . Find the acceleration in (i) unit vector notation and in (ii) polar form.

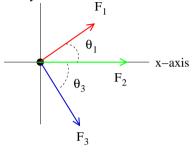
**Solution:**By Newton's  $2^{\rm nd}$  law, we can write:  $\sum \vec{F} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3 = m\vec{a}$ . In Unit vector notation, we write,

$$\vec{a} = \frac{1}{m} \left[ (F_{1x} + F_{2x} + F_{3x}) \hat{i} + (F_{1y} + F_{2y} + F_{3y}) \hat{j} \right] ,$$

$$= \frac{1}{m} \left[ (F_1 \cos \theta_1 + F_2 \cos \theta_2 + F_3 \cos \theta_3) \hat{i} + (F_1 \sin \theta_1 + F_2 \sin \theta_2 + F_3 \sin \theta_3) \hat{j} \right] ,$$

$$= \frac{1}{120} \left[ (32 \cos 30^\circ + 55 \cos 0^\circ + 41 \cos 300^\circ) \hat{i} + (32 \sin 30^\circ + 55 \sin 0^\circ + 41 \sin 300^\circ) \hat{j} \right] \text{m/s}^2 ,$$

$$\therefore \vec{a} = (0.86 \hat{i} - 0.16 \hat{j}) \text{m/s}^2 = (0.87 \text{m/s}^2, 349^\circ) .$$



v-axis