

2(b)

```
In [1]: 1 #import library function
        2 import numpy as np
        3 from skimage import io
        4 import matplotlib.pyplot as plt
```

Vector Representation of Filter

```
In [2]: 1 # Given filter F
        2 F = np.array([1, 1, 1, 0, 0, 0, -1, -1, -1])
        3 # Flatten the filter
        4 F_flat = F.flatten()
```

Vector Representation of the Neighborhood Patch

```
In [3]: 1 # Given image I' which is maintaining zero-padding
        2 image_patch = np.array([
        3     [0, 0, 0, 0, 0],
        4     [0, 7, 4, 1, 0],
        5     [0, 8, 5, 2, 0],
        6     [0, 9, 6, 3, 0],
        7     [0, 0, 0, 0, 0]
        8 ])
        9
```

```
In [4]: 1 # Initialize a matrix to store correlation results
        2 correlation_matrix = np.zeros((3, 3))
```

Calculate correlation for every valid position

Extract the neighborhood patch at position (i, j)

Flatten the neighborhood patch and calculate the dot product

```
In [5]: 1 for i in range(1, 4):
        2     for j in range(1, 4):
        3
        4         neighborhood_patch = image_patch[i - 1:i + 2, j - 1:j + 2]
        5         correlation_matrix[i - 1, j - 1] = np.dot(F_flat, neighborhood_
        6
        7     # Print the correlation matrix
        8     print("Correlation matrix:")
        9     print(correlation_matrix)
```

```
Correlation matrix:
[[-13. -15.  -7.]
 [ -4.  -6.  -4.]
 [ 13.  15.   7.]]
```

Test code using the provided image and the filters.

In [6]:

```

1  def correlation_filter_image_dot_product(F, I):
2      # implement zero-padding to maintain correct sizes
3      padded_I = np.pad(I, ((1, 1), (1, 1)), mode='constant', constant_val=0)
4
5      # reshape filter F to a column vector
6      f = F.flatten()
7
8      # extract patches from the image using array slicing
9      patches = np.lib.stride_tricks.sliding_window_view(padded_I, (3, 3))
10
11     # reshape patches to 1D arrays
12     patches_1d = patches.reshape(-1, 9)
13
14     # computing G(i,j) for all patches using dot product
15     G = np.dot(patches_1d, f)
16
17     # reshape G to the original image shape
18     G = G.reshape(I.shape)
19
20
21     return G
22
23 # Load the image
24 image_path = 'parrot.png'
25 image = io.imread(image_path)
26
27 # Define filters
28 a = np.array([[0, 0, 0], [0, 1, 0], [0, 0, 0]])
29 b = np.array([[1, 0, 0], [0, 0, 0], [0, 0, 0]])
30 c = np.array([[1, 1, 1], [0, 0, 0], [-1, -1, -1]])
31 d = np.array([[-1, 0, 1], [-1, 0, 1], [-1, 0, 1]])
32 e = (1/16) * np.array([[1, 2, 1], [2, 4, 2], [1, 2, 1]])
33 f = (1/9) * np.array([[1, 1, 1], [1, 1, 1], [1, 1, 1]])
34
35 # Filter a
36 result_a = correlation_filter_image_dot_product(a, image)
37 # Filter b
38 result_b = correlation_filter_image_dot_product(b, image)
39 # Filter c
40 result_c = correlation_filter_image_dot_product(c, image)
41 # Filter d
42 result_d = correlation_filter_image_dot_product(d, image)
43 # Filter e
44 result_e = correlation_filter_image_dot_product(e, image)
45 # Filter f
46 result_f = correlation_filter_image_dot_product(f, image)
47 # Display original image and the results for all filters
48
49 plt.figure(figsize=(40, 30))
50 plt.subplot(3, 3, 1)
51 plt.imshow(image, cmap='gray')
52 plt.title('Original Image', fontsize = 40)
53
54 plt.subplot(3, 3, 2)
55 plt.imshow(result_a, cmap='gray')
56 plt.title('Filter (a) - No change', fontsize = 40)
57
58 plt.subplot(3, 3, 3)
59 plt.imshow(result_b, cmap='gray')
60 plt.title('Filter (b) - Shift', fontsize = 40)
61

```

```

62 plt.subplot(3, 3, 4)
63 plt.imshow(result_c, cmap='gray')
64 plt.title('Filter (c) - Horizontal Edge', fontsize = 40)
65
66 plt.subplot(3, 3, 5)
67 plt.imshow(result_d, cmap='gray')
68 plt.title('Filter (d) - Vertical Edge', fontsize = 40)
69
70 plt.subplot(3, 3, 6)
71 plt.imshow(result_e, cmap='gray')
72 plt.title('Filter (e) - Gaussian Smoothing', fontsize = 40)
73
74 plt.subplot(3, 3, 7)
75 plt.imshow(result_f, cmap='gray')
76 plt.title('Filter (f) - Average Moving', fontsize = 40)
77
78 plt.show()

```

Original Image



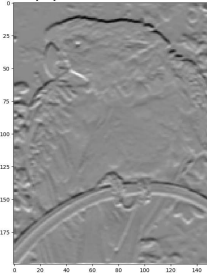
Filter (a) - No change



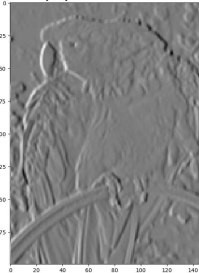
Filter (b) - Shift



Filter (c) - Horizontal Edge



Filter (d) - Vertical Edge



Filter (e) - Gaussian Smoothing



Filter (f) - Average Moving

