Hooke's Law and the Simple Harmonic Motion

OBJECTIVE:

- 1. To determine the spring constant by studying the simple harmonic motion of an oscillating mass.
- 2. To determine the mass of the spring.

APPARATUS:

Stand with a clamp, a set of slotted masses, meter stick, geometry box, stop watch, digital balance.

THEORY:

Hooke's Law

A spring with a varying amounts of force applied is proportional to its displacement. This proportionality constant is called the spring constant, *k*, and the entire relation is referred to as Hooke's Law:

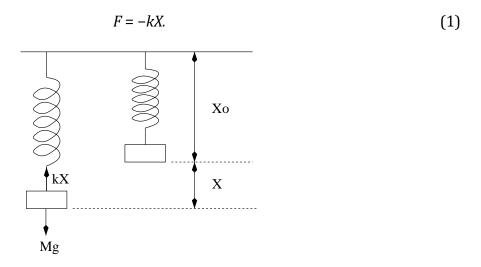


Figure 1: Hooke's Law Setup.

The minus sign is only used to describe the "restoring" force. This force opposes the applied force on the spring and tries to return the spring to equilibrium. In figure 1, X_0 is the length of the spring with the mass holder hanging at rest at the equilibrium point. The displacement, X, is measured relative to the equilibrium point. Hooke's Law becomes invalid only when the elastic limit of the spring is surpassed.

When a mass of an ideal or friction free spring is displaced its oscillation is known as simple harmonic motion. If this motion is graphed it would look sine-like with its amplitude remaining

constant. Taking Hooke's Law into account with Newton's Second Law we get F = -kX = Ma and then rewrite as

$$a + (k/M)X = 0. (2)$$

This is the equation for simple harmonic motion. The corresponding position (i.e. the solution) as a function of time is

$$X = A\cos(\omega t + \phi), \tag{3}$$

where $\omega = \sqrt{k/M}$. Since ω is the angular frequency, we have $\omega = 2\pi f = 2\pi/T$. Therefore the period,

T, can be written as follows

$$T = 2\pi/\omega = 2\pi\sqrt{\frac{M}{k}} \tag{4}$$

The mass M in equation-(4) is equal to the mass added including the holder M_a plus a contribution from the mass of the spring (m), that is, $M = M_a + m$). In this experiment, the dependence of period upon the mass is investigated. It can be shown that m equals 1/3 of the spring mass M_s .

PROCEDURE:

1. The apparatus should look similar to Figure-2.

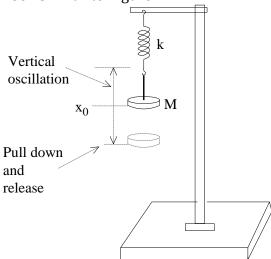


Figure 2: The Experimental Setup

2. Start with enough mass on the holder to separate the coils of the spring. The initial mass should be about 0.150 kg.

- 3. Pull down the mass holder by a relatively small amount and then release it do not apply any external forces. The mass should be oscillating straight up and down. If not, stop it and try again until you get vertical oscillation.
- 4. With the digital stop watch count the time for 20 cycles for each mass added three times and then take the average. Note: All of your time values should have to the same first two digits otherwise your experimental setup might have some flaws. Record your results in Table 1.
- 5. To gather the best results one has to be very careful and consistent. The base of the apparatus should be firmly held and not allowed to move. Any motion of the apparatus outside the spring and the holder will increase the error in your results.
- 6. Construct a graph of <u>Period</u>² <u>vs. Mass Added</u>. The scale on the x axis should start at zero.

Calculations:

- 1. Measure the actual mass of the spring (M_s) by using the digital balance and record it under the table-2.
- 2. Rewriting from Eq.(4) by using $M = M_a + m$, we obtain,

$$T^2 = \left(\frac{4\pi^2}{k}\right) M_a + \frac{4\pi^2 m}{k}$$

So T^2 vs. M_a graph is straight line with

$$\text{Slope} = \frac{4\pi^2}{k} \qquad \text{and} \qquad \text{Intercept} = \quad \frac{4\pi^2 m}{k}.$$

- 3. From the graph, find the slope of the best fit line. Use the slope to calculate the spring constant *k* and record Table-3.
- 4. From the graph, find the *y*-intercept, and use this and the spring constant just computed in the previous step to calculate *m* which is the contribution of the mass of the spring and record Table-2.
- 5. Compute the spring mass from the data in the previous steps and then compute the percent error.

Lab Report

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Instructor's comments:

Table 1. Period Dependence on Mass

Mass Added to Holder (kg)	Time for 20 Oscillations (sec)	Time Period (T) (sec)	Average Time Period (T_{av}) (sec)	Time Period ² (T ²) (sec ²)
0.150				
0.200				
0.250				
0.300				
0.350				
0.400				

Table 2. Calculation spring constant and mass

Mass of spring by digital balance, M_s	kg
Slope of the best fit line	
y-intercept of the graph	
Spring constant, k	N/m
Mass contribution from the spring, <i>m</i>	kg
Experimental value of Mass of the spring, $M_{s,exp}$	kg
Percent error in the mass of spring	

QUESTIONS:

1. What would be value of the *y*-intercept if the spring were a ideal massless spring? Explain.

2. How does your calculated and measured values of the spring mass compare? What might be source of the differences (if any)

3.	How the value of the spring constant compare with value found in a previous experiment?					

Prelab:

1. An object oscillates from a massless vertical spring with a frequency of 4.00 Hz. Hanging at rest from this spring, how much would the object stretch the spring?

2. A 100 grams hanging from a spring oscillates vertically with time period T = 1.5sec on the surface of earth. On the moon surface what would be the time period (same spring and same mass). The value of g on moon surface is 1/6-th times on earth.