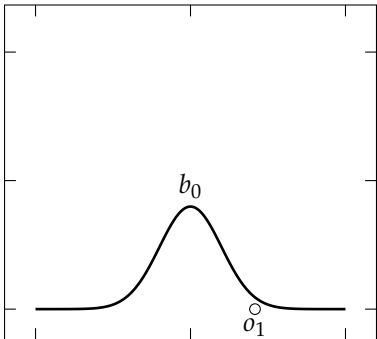


observation

likelihood



state s