



About MSA
MSA Technical
ORC

Jarntimarra
Marsupial
MARS-OZ

SAFMARS
Mars Skin
How you can help

Jason Hoogland
tech@marssociety.org.au

Goals

Broad public outreach

Local activities

National initiatives

“ Make Mars more real for more people” , engage media

Increase membership, grow movement

Advocacy and policy development

Strengthen local public support for Mars exploration

Lobby for a significant Australian role in Mars exploration

Private activity

Technical programme

Grow and facilitate Australian Mars science and engineering community

Position Australians for roles in multi-billion dollar international human

Mars programme

**Where' s our
national space
programme?!?!**



Goals



Mars Society (US)

Founded August 1997

Boulder, Colorado

International

50 countries

5,000 members

Rank	Country	Population - 2001		Membership	
		Total	Growth	Total	Per Million
1	Iceland	281,000	0.67	5	17.79
2	Bermuda	60,000		1	16.67
3	United States	285,926,000	0.89	3430	12.00
4	Canada	31,015,000	0.8	341	10.99
5	Australia	19,339,000	0.99	61	3.15
6	New Zealand	3,808,000	0.73	12	3.15
7	United Kingdom	59,541,000	0.18	177	2.97
8	Malta	392,000	0.4	1	2.55
9	Luxembourg	443,000	1.2	1	2.26
10	Switzerland	7,170,000	-0.06	14	1.95

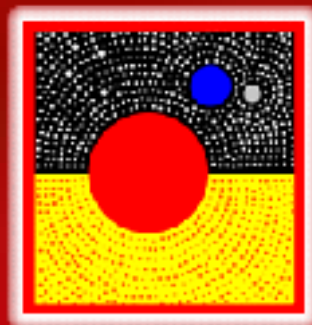


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Operation Red Centre

Establish Australian node of four-base global network

Devon Island, Utah, Iceland, Australia

Year-round field operations

Operations research using mock-up hardware
from other MSA technical projects

Multi-year, i.e. ORC02, ORC03 etc

Dual role – both important

Primarily mission operations research

Secondarily public awareness raising

Goals

Foster and facilitate Australian and
international Mars mission R&D

Make a local contribution to international
mission planning

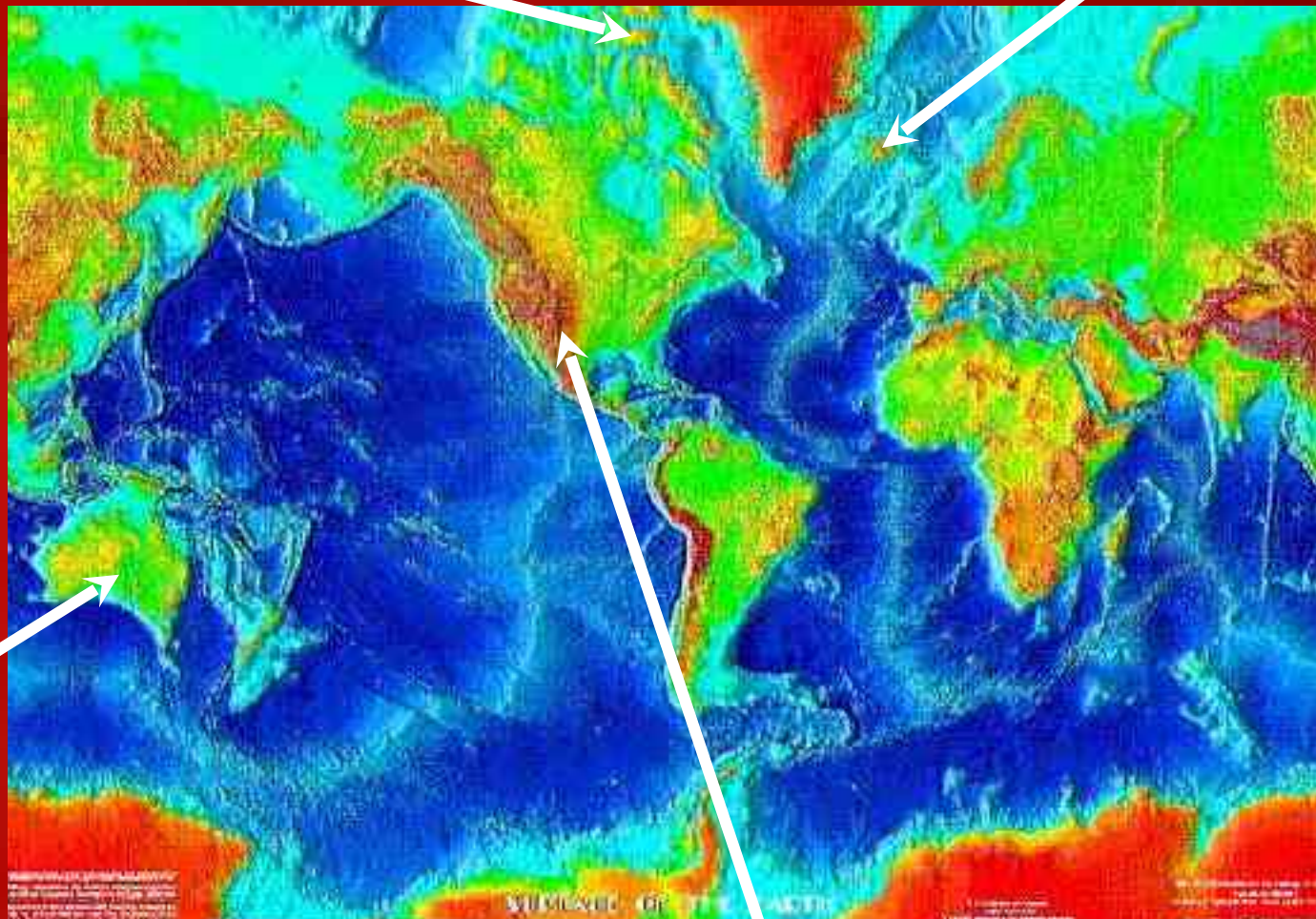
Position Australia for a role in future
international human missions



**Global
Network**

**Devon Island
F-MARS 2000**

Iceland



**Australia
MARS-Oz
2002**

**Southern Utah
MDRS 2001**



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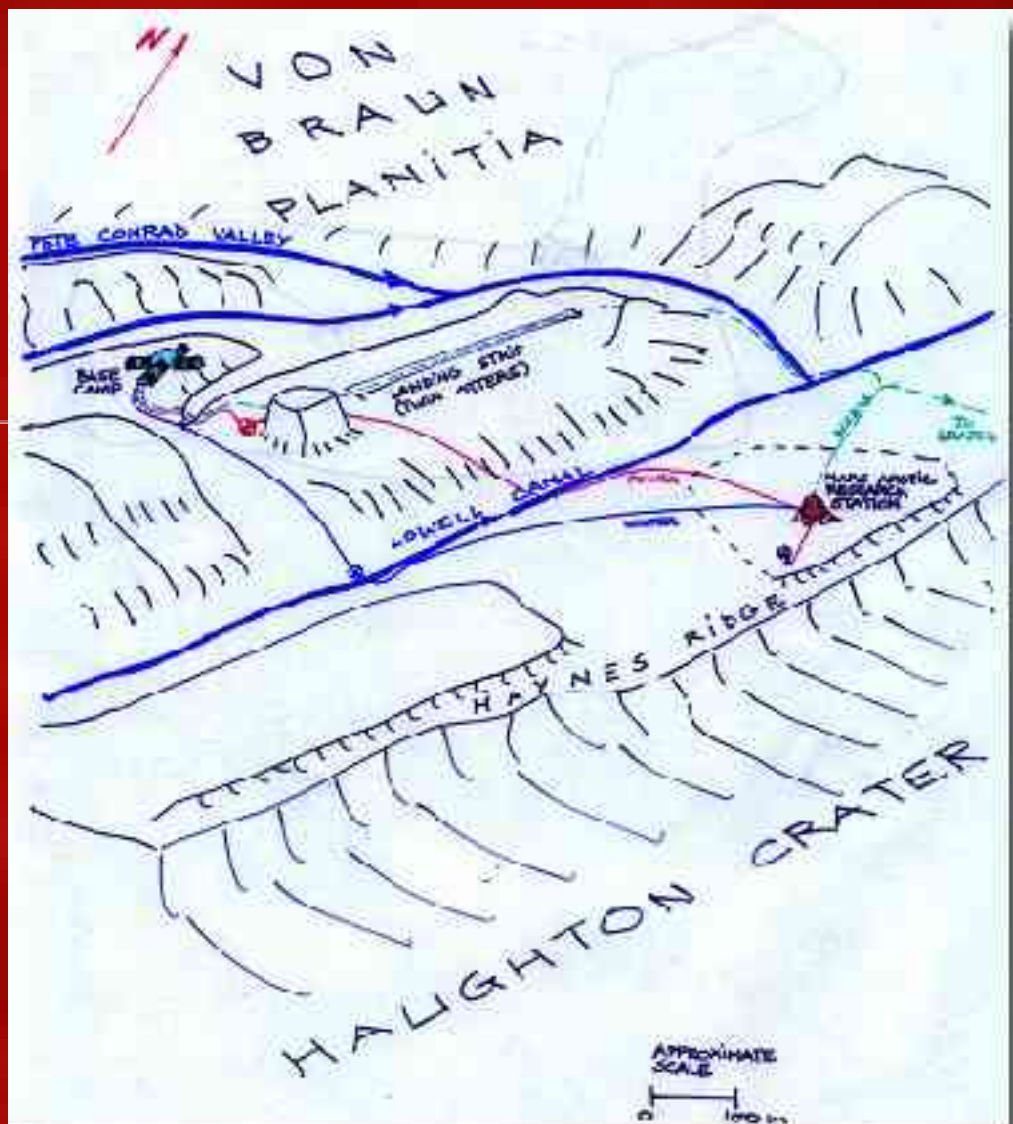


First HMP field work
in 1997

F-MARS assembled
in 2000 with airdrops

Devon
Island

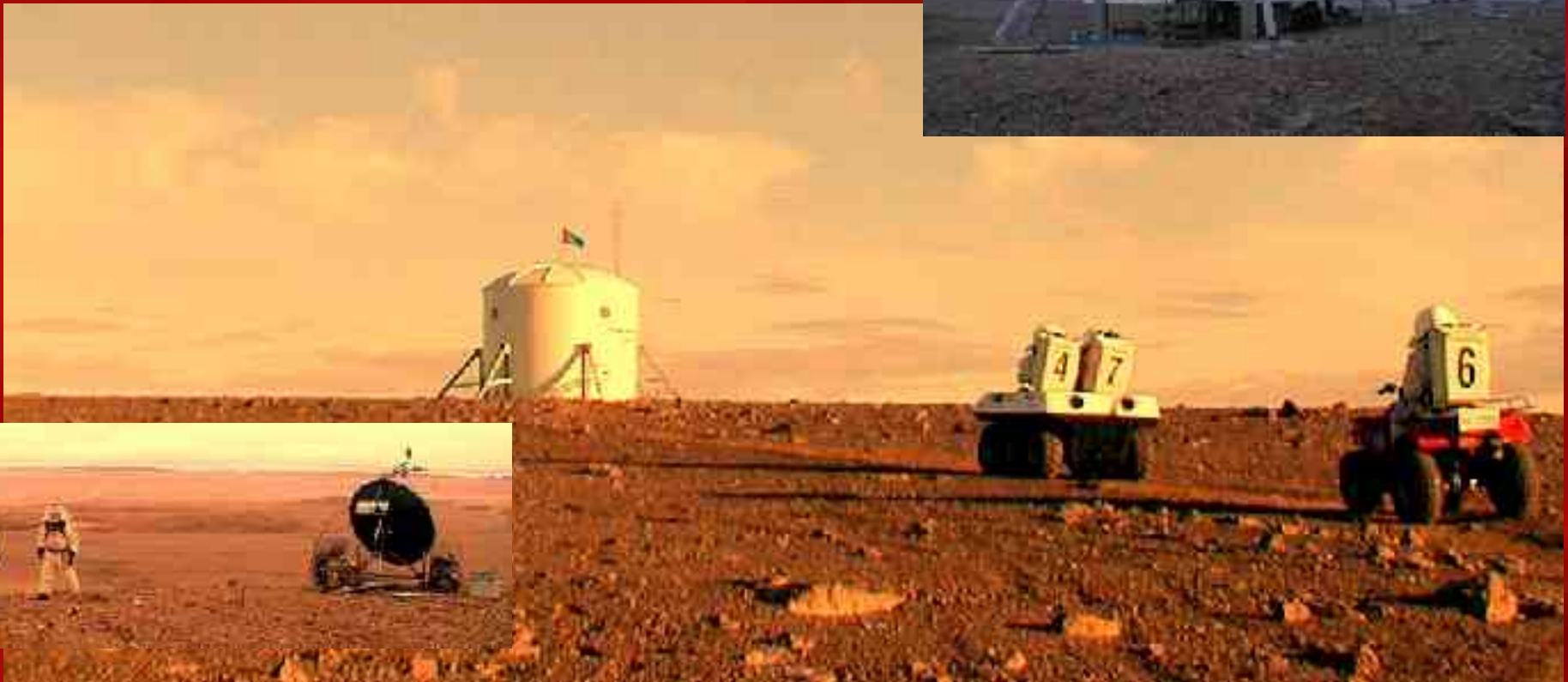
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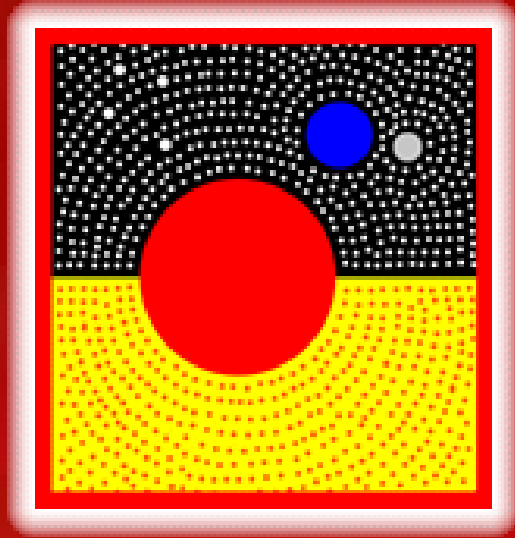




F-MARS

**Commissioning 2000
First real field ops, 6
weeks in 2001**





Project Jarntimarra

Field expeditions and sorties

Into remote areas of continental Australia

Provides field experience for ORC

Database (JNT-DB)

ver1A available at website

Expand Australian localities, then extend worldwide

Become a primary source of information for international workers

Goals

Assemble an online database of worldwide analogue sites for scientific and operations research

Identify potential sites for ORC

Grow and facilitate an Australian Mars mission

R&D community, encourage international researchers to work here



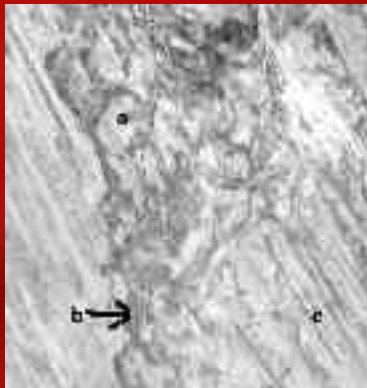
JNT-1





Hale
River
flood
channel

JNT-1



Sturt Stony Desert



Henbury
Craters



“ Presidential pan ” from the Imager for Mars
Pathfinder (IMP) in Ares Valles





JNT-1

Who (includes)

**Dr Jonathan Clarke,
geologist ANU, Expedition
Leader and lead scientist**

**Dr Graham Mann,
roboticist Murdoch Uni and
lead engineer**

**Dr Carol Stoker, NASA
Ames**

**Dr Larry Lemke, NASA
Ames**

**Dr Vic Gostin, geologist
Uni of Adelaide**

**Prof Malcolm Walter,
Director, Australian Centre
for Astrobiology**

What

Visual reconnaissance

Photography

Consultation with locals

**Sampling of hot artesian
bores along Birdsville Track
– identify new extremophiles**

**3 day workshop at Arkaroola
to discuss MSA technical
programme**

**Journal paper on Australian
Mars analogue sites**

**Shortlisting of ORC sites
based on expedition report**





Project Marsupial

Family of mobility vehicles

Mobility critical for 18 month exploration of Mars landing areas

Impetus from international competition

First vehicle

Human Operations Prototype - HOP

Preliminary design complete

Base chassis acquired

Goals

Provide a key platform for field operations research and for development of niche hardware systems (e.g. sensors)

Test particular functional designs for mobility vehicles, contribute to future designs

Investigate crew-crew, crew-machine and machine-machine interactions and produce

research papers

MICHIGAN MARS ROVER TEAM



Mars Society Rover Initiative

Other groups

University of Michigan led
Everest

University of Toronto led ARES



ARES
Analog Rover Experimental System

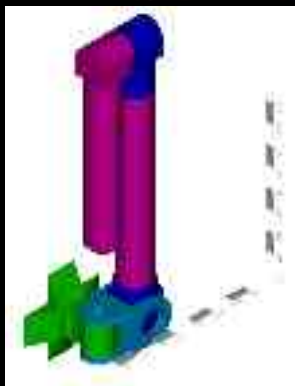
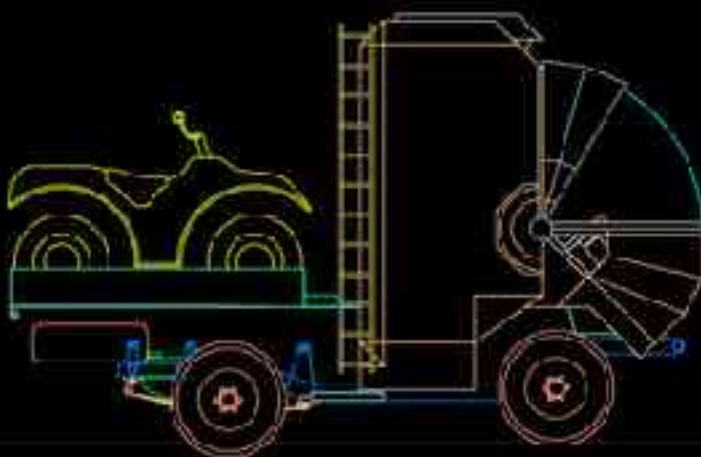
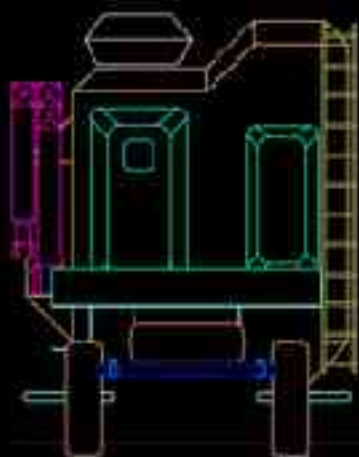
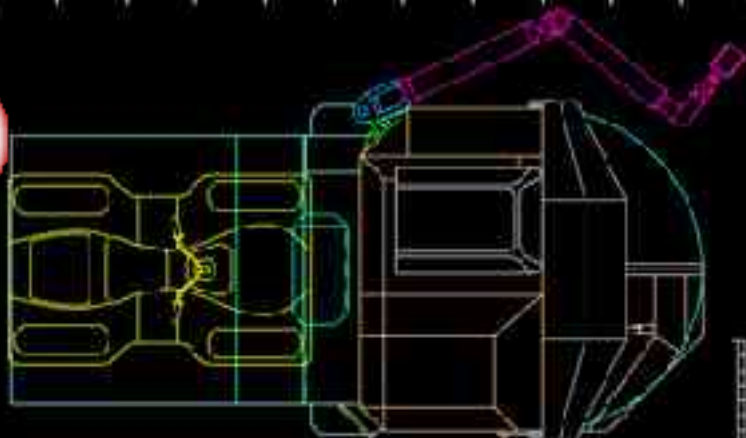


HOP Preliminary work





HOP Preliminary Design

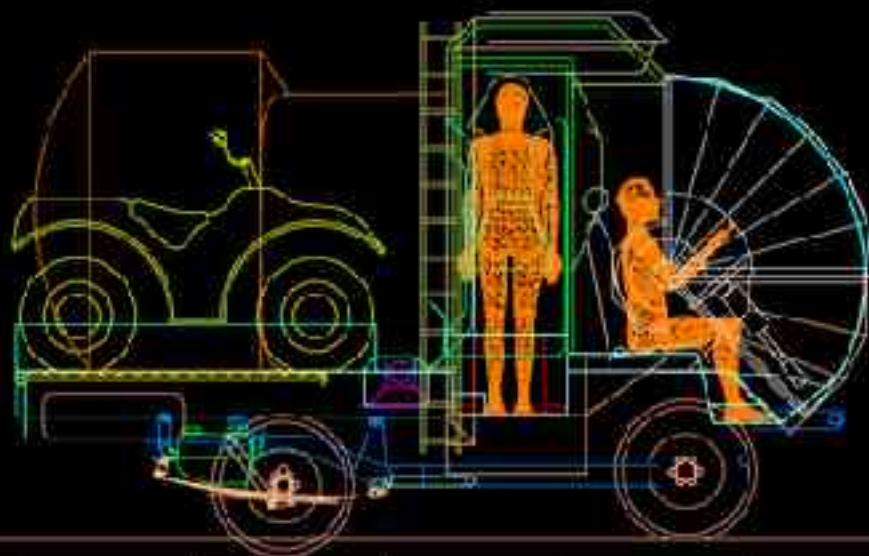
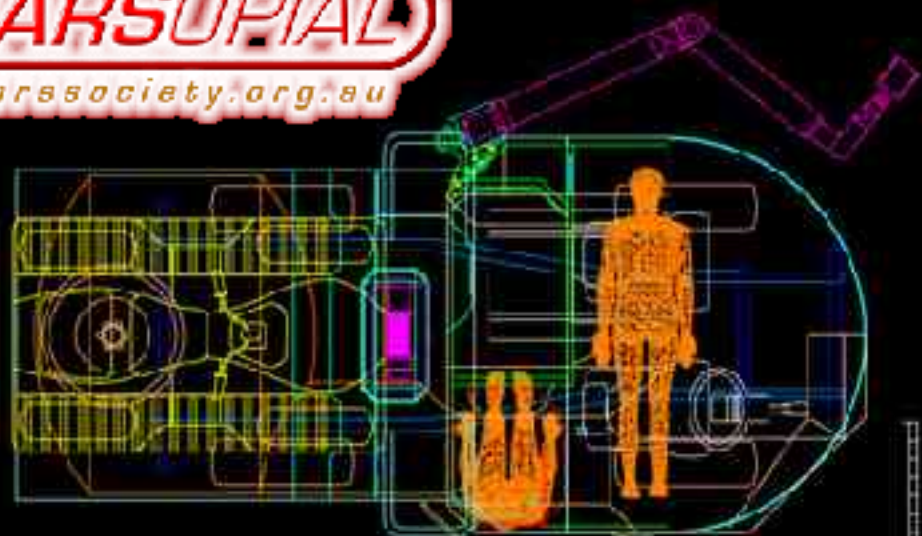


100 mm units

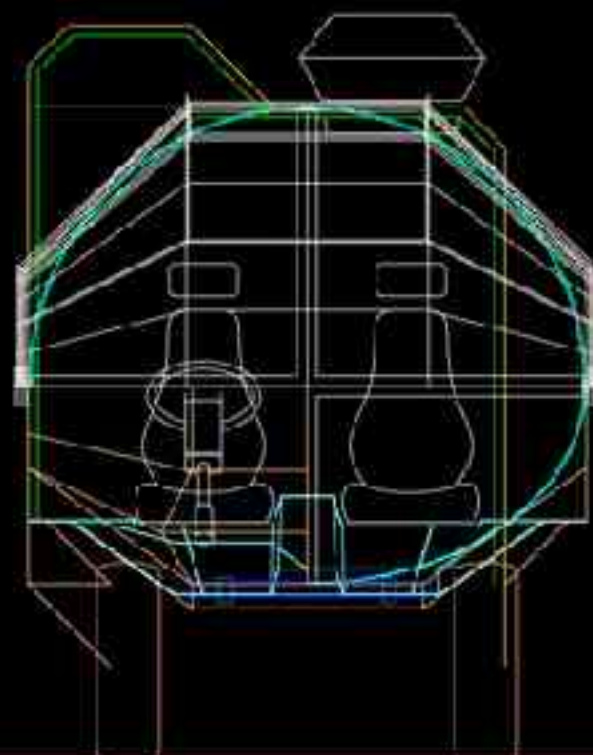
Project Marsupial - HEP Utility			
General Arrangement - Hidden Line			
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DESIGNED BY	APPROVED BY	APPROVAL DATE	
JDH			
FILED BY	FILED BY	FILED DATE	
0010M0	ACA02000		
NOTES: 1. Comments to tech@marsociety.org.au			
 Mars Society Australia Inc.		© MSA, Inc. 2001 All dimensions in millimeters unless specified	

MARSUPIAL

marssociety.org.au



100 mm units



Project Marsupial - HUP Utility

General Arrangement

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Mars Society
Australia Inc.

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FILED	FILED	FILED	FILED
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ACADEMIC	ACADEMIC	ACADEMIC	ACADEMIC
NOTE	NOTE	NOTE	NOTE
1. Comments to tech@marssociety.org.au			

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All dimensions in millimeters unless specified

Mars Australian Research Station

Semi-mobile, multiple sites over several years

Basic unit supplemented with subsystems (i.e. solar power, bio-regeneration etc.)

Options

Possibility of obtaining US\$150,000 unit from The Mars Society (US), similar to F-MARS, MDRS

Alternate plans considered for custom local design and fabrication

Goals

Centerpiece, MSA mission operations research

Available for international and local workers to undertake wide range of research activities

Platform for R&D of niche mission technologies in partnership with local organisations

Make Mars more real for more people, space-tourism potential



Project MARS-Oz



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Mars
Direct
Design



Top floor living
quarters

Station
exterior



Bottom floor work
area, EVA airlock
and storm shelter



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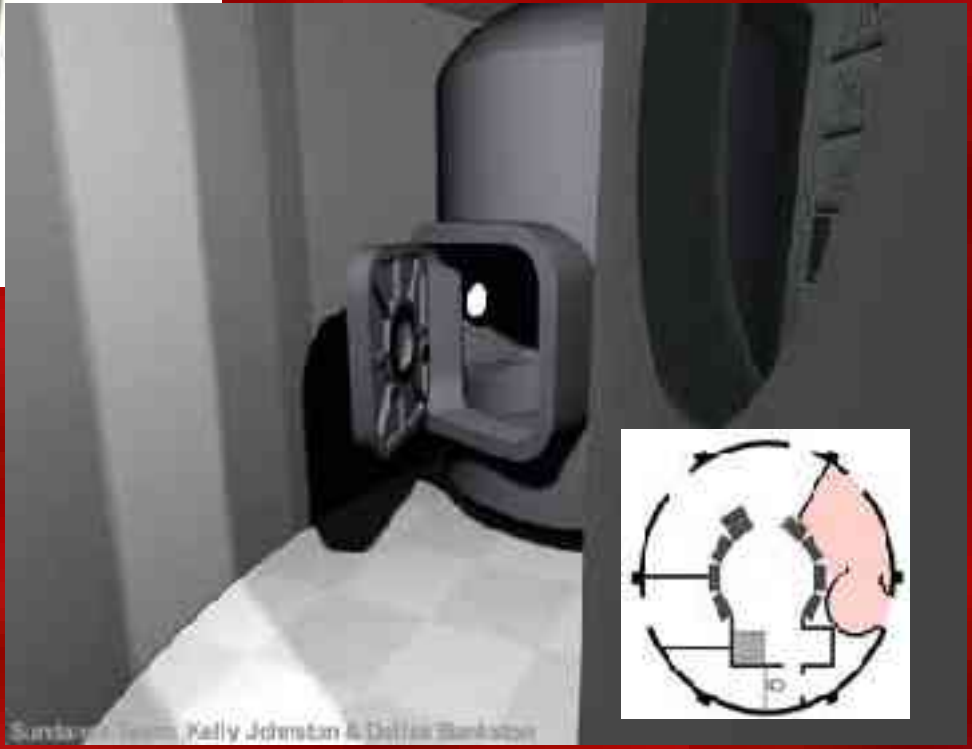
Mars
Direct
Design



BUnCC – Basic
Unified Crew
Compartment

Other design
features

Single
airlock



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**MDRS
mock-up**



**MDRS at
Kennedy Space
Centre**



**Egress door
simulating airlock**



Bottom floor lab



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