

Mass Spring Simulation Analysis

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0.0.1 Prepared by:

Name	ID
Maha Abdel Aziz Farid	1920060
Manar Mohamed Rashad	18270084
Mostafa Kamal Mostafa Kamel	1920045
Wael Ismail Aboulezz	202001595

1 Evaluation Method

- In this analysis we will be using files we generated from running the three provided test on each of our integrators
- We logged the values of x, y and z for every particle at every step in the simulation. Each test was run for exactly 240 seconds
- The resulting files are quite large (over 700 Mbs). Therefore we will be binning the data every .25 seconds and averaging the x, y and z values for each particle
- We will use the values obtained from our RK5 implementation as a benchmark to compare against
- While evaluating a test, the distance between each particle and its corresponding particle in the RK5 simulation is going to be calculated.
- Finally we will average the distances between corresponding particles in every bin to calculate a single error value

1.1 Step One: Processing the Data

1.1.1 Below is a function we defined to bin the data from every test

```
[1]: import pandas as pd
import numpy as np

def cut_and_agg(path):
    df = pd.read_csv(path)
    df['bin'] = pd.cut(df.timestamp, [i for i in np.arange(0, 240.25, 0.25)])
    df = df.groupby(['bin', 'particle_no']).agg({
        'x': ['mean'],
```

```

        'y':['mean'],
        'z':['mean']})
df.columns = ['x', 'y', 'z']
return df.reset_index()

```

1.1.2 We will call the function iteratively on each test to process the data

```

[2]: from glob import glob

files = [file.split("/")[1] for file in glob('/*.csv')]

[3]: from tqdm import tqdm

with tqdm(total=len(files)) as pbar:
    for file in files:
        pbar.update(1)
        exec(f"{file.split('.')[0].replace('-', '_')} = cut_and_agg('{file}')"

```

```
100%|      | 12/12 [00:11<00:00, 1.00it/s]
```

1.1.3 This is a sample of a test after processing

We can see the values of x, y and z for every particle in every bin

```

[4]: adaptiverk4_test1

[4]:
      bin  particle_no      x      y  z
0  (0.0, 0.25]         0 -4.000000e+00  4.000000  0
1  (0.0, 0.25]         1 -3.000000e+00  3.997849  0
2  (0.0, 0.25]         2 -2.000000e+00  3.997846  0
3  (0.0, 0.25]         3 -1.000000e+00  3.997846  0
4  (0.0, 0.25]         4 -3.934142e-08  3.997846  0
...
61435  (239.75, 240.0]    59 -9.645117e-01 -4.901520  0
61436  (239.75, 240.0]    60  6.901909e-02 -4.896824  0
61437  (239.75, 240.0]    61  1.081908e+00 -4.703116  0
61438  (239.75, 240.0]    62  2.048756e+00 -4.390729  0
61439  (239.75, 240.0]    63  2.994457e+00 -4.058700  0

[61440 rows x 5 columns]

```

1.2 Step Two: Calculating Errors

1.2.1 Below is a function we defined to calculate the distance between each particle and its corresponding particle from the RK5 test.

For every bin we have n number of particles, we will start by obtaining the distance between each respective particle and its peer in the corresponding RK5 test in the same bin. Next we will average the distances for every bin to obtain a measurement for the error

```
[5]: def calc_error(df1, df2):  
    df1_copy = df1.copy()  
    df2_copy = df2.copy()  
    df2_copy.columns = [str(i)+"2" for i in df2_copy.columns]  
    df = pd.concat([df1_copy, df2_copy], axis=1)  
    df['error'] = df.apply(lambda row: np.linalg.norm(np.array([row.x, row.y,   
→row.z])-np.array([row.x2, row.y2, row.z2])), axis=1)  
    df = df.groupby('bin').agg({  
        "error": "mean"}).reset_index()  
    df = df[['bin', 'error']]  
    return df
```

1.2.2 We will call this function for every test using an integrator other than RK5 and compare with respect to the same test using RK5

```
[6]: error_dfs = []  
  
files_excluding_rk5 = list(filter(lambda file: 'rk5' not in file, files))  
  
with tqdm(total=len(files_excluding_rk5)) as pbar:  
    for file in files_excluding_rk5:  
        pbar.update(1)  
        exec(f"{file.split('.')[0].replace('-', '_')} + '_error' =   
→calc_error({file.split('.')[0].replace('-', '_')}, {'rk5_' + file.split('.  
→') [0].split('-')[1]})")  
        error_dfs.append(eval(f"{file.split('.')[0].replace('-', '_')} +   
→'_error'"))
```

100% | 9/9 [00:39<00:00, 4.43s/it]

1.2.3 Below we will see a sample output from these calculations

notice how the output is a single quantifiable error value for each respective bin

```
[7]: adaptiverk4_test1_error
```

```
[7]:
```

	bin	error
0	(0.0, 0.25]	0.000009
1	(0.25, 0.5]	0.000235
2	(0.5, 0.75]	0.001773
3	(0.75, 1.0]	0.004181
4	(1.0, 1.25]	0.007746
..
955	(238.75, 239.0]	0.000488
956	(239.0, 239.25]	0.000280
957	(239.25, 239.5]	0.000088
958	(239.5, 239.75]	0.000171
959	(239.75, 240.0]	0.000383

[960 rows x 2 columns]

1.3 Step Three: Plotting Our Findings

We will iteratively plot the results of the process explained above to represent our evaluations. In these plots, the y axis represents the error value while the x axis represents time. Notice how the error fluctuates in a number of these tests, this is due to the tests incorporating a reciprocal-type movement.

```
[8]: import seaborn as sns
import matplotlib.pyplot as plt
from IPython.display import display, Markdown

sns.set(rc={'figure.figsize':(30,11)}, font_scale=2.5)

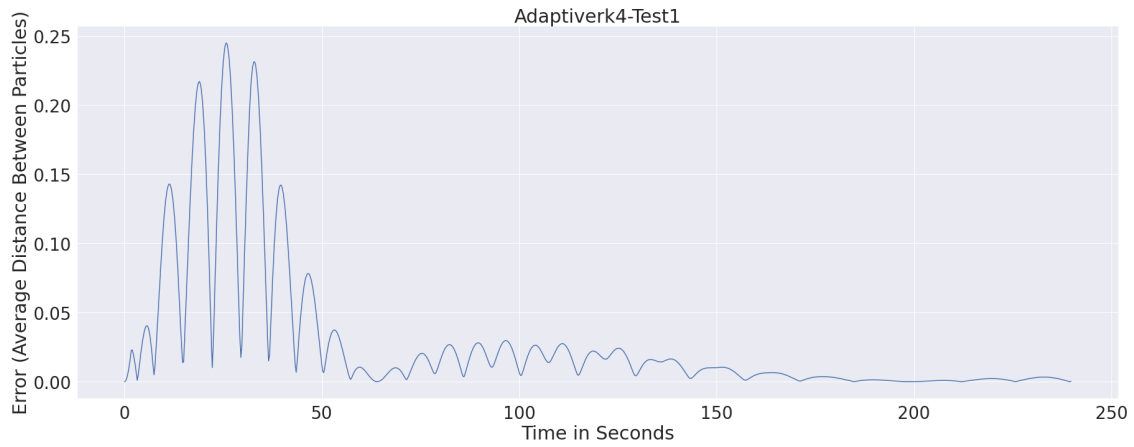
display(Markdown("\pagebreak"))

for ix, df, name in zip(range(len(error_dfs)), error_dfs, files_excluding_rk5):
    test_name = f"{' '.join([s.title() for s in name.split('.')[:-1]])}"
    display(Markdown(f"### {test_name[:-1].split('-')[0].upper()} {test_name[:-1].split('-')[1].title()} {test_name[-1]} Results"))
    df[test_name] = df['error']
    display(df.describe()[[test_name]].transpose())
    df['time'] = df.apply(lambda row: int(row.name)*0.25, axis=1)
    try:
        combined_df = pd.concat([combined_df, df.describe()[[test_name]].
→transpose()])
    except:
        combined_df = df.describe()[[test_name]].transpose()
    ax = sns.lineplot(data=df, x='time', y='error')
    ax.set(xlabel='Time in Seconds', ylabel='Error (Average Distance Between_
→Particles)', title=test_name)
    plt.show()
```

```
if ix % 2 != 0:  
    display(Markdown("\pagebreak"))
```

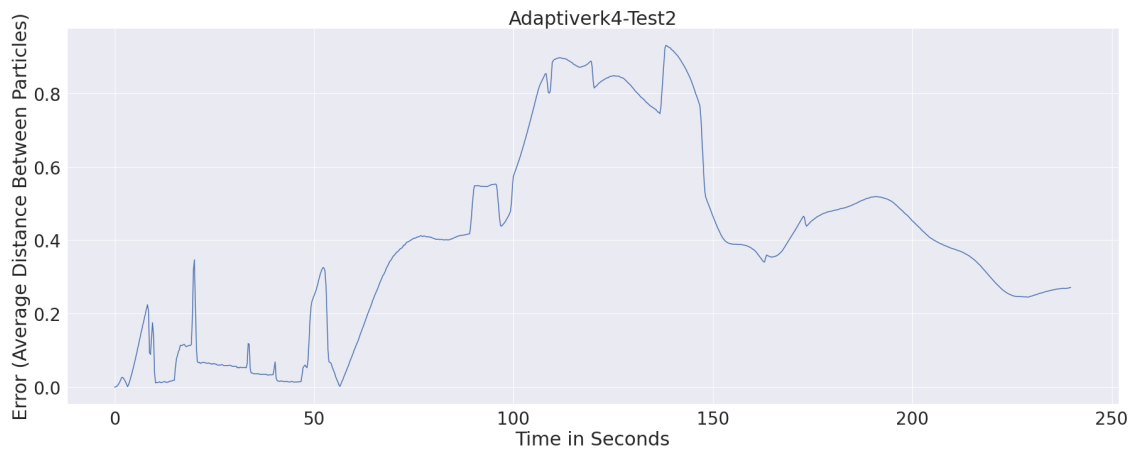
1.3.1 ADAPTIVERK4 Test 1 Results

	count	mean	std	min	25%	50%	\
Adaptiverk4-Test1	960.0	0.02784	0.04949	0.000002	0.002213	0.00992	
		75%	max				
Adaptiverk4-Test1	0.023642	0.245071					



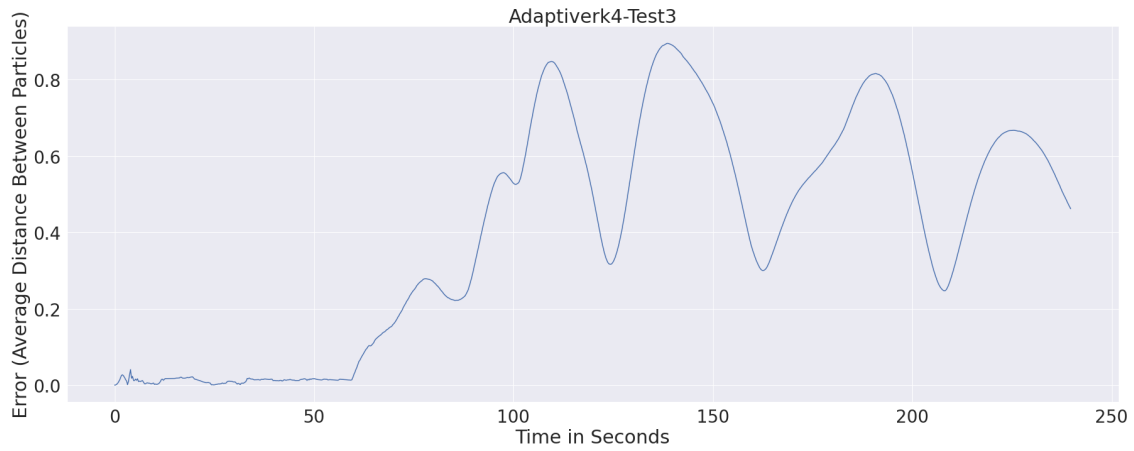
1.3.2 ADAPTIVERK4 Test 2 Results

	count	mean	std	min	25%	50%	\
Adaptiverk4-Test2	960.0	0.39711	0.263574	0.00001	0.227298	0.390569	
		75%	max				
Adaptiverk4-Test2	0.512692	0.930646					



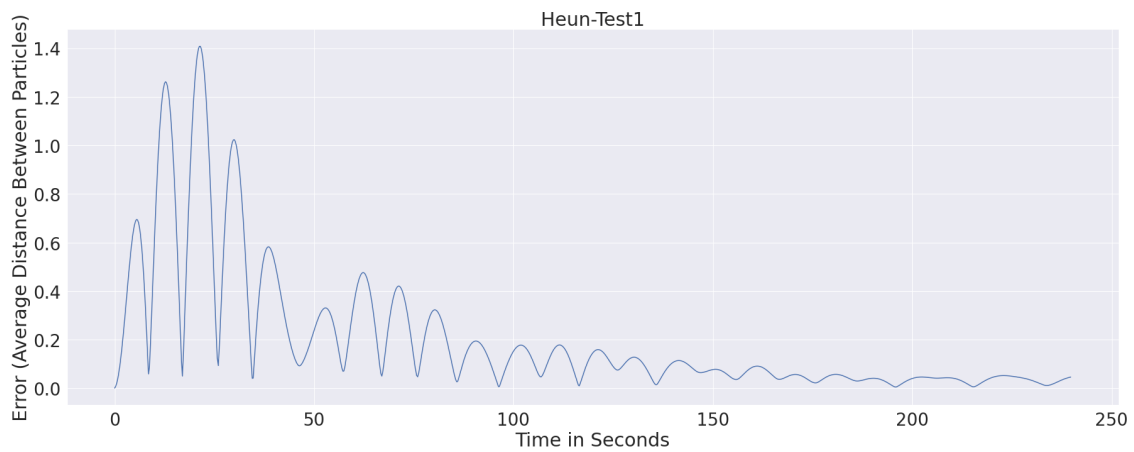
1.3.3 ADAPTIVERK4 Test 3 Results

	count	mean	std	min	25%	50%	\
Adaptiverk4-Test3	960.0	0.398567	0.29205	0.00001	0.031993	0.429513	
		75%	max				
Adaptiverk4-Test3	0.646001	0.895372					



1.3.4 HEUN Test 1 Results

	count	mean	std	min	25%	50%	75%	\
Heun-Test1	960.0	0.200569	0.272599	0.000979	0.043249	0.089809	0.226279	
		max						
Heun-Test1	1.407952							



1.3.5 HEUN Test 2 Results

	count	mean	std	min	25%	50%	75%	\
Heun-Test2	960.0	1.601195	0.542275	0.000985	1.331452	1.550308	1.871948	

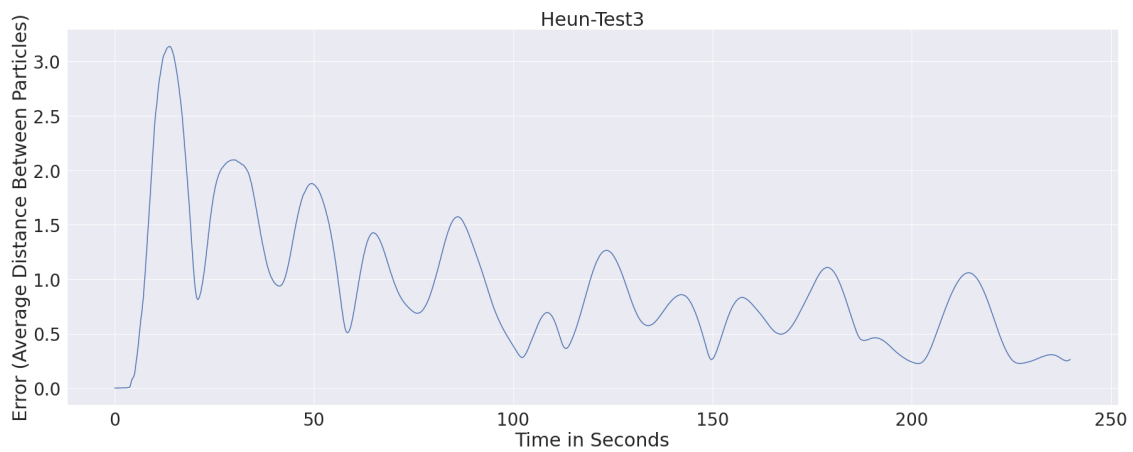
max
Heun-Test2 2.801356



1.3.6 HEUN Test 3 Results

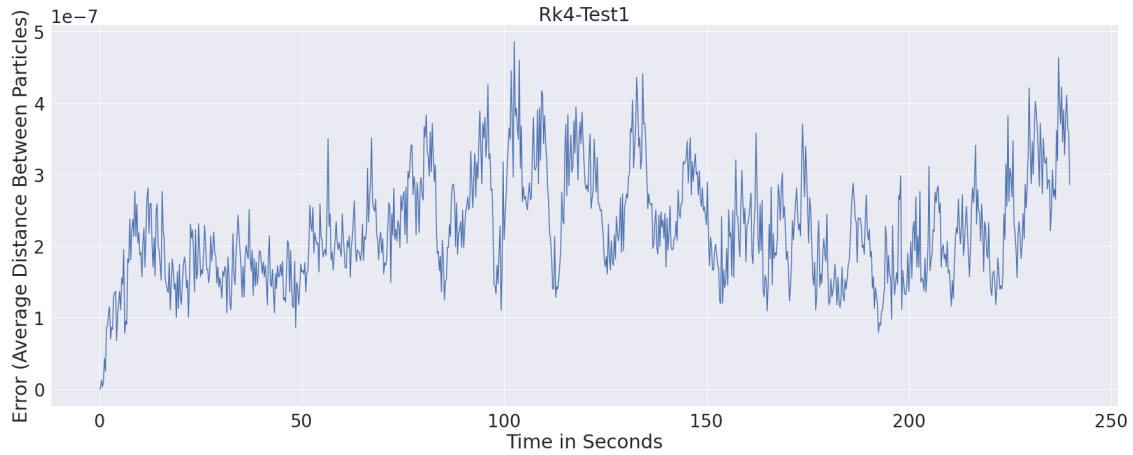
	count	mean	std	min	25%	50%	75%	\
Heun-Test3	960.0	0.911553	0.597761	0.000126	0.495348	0.787156	1.154473	

max
Heun-Test3 3.137841



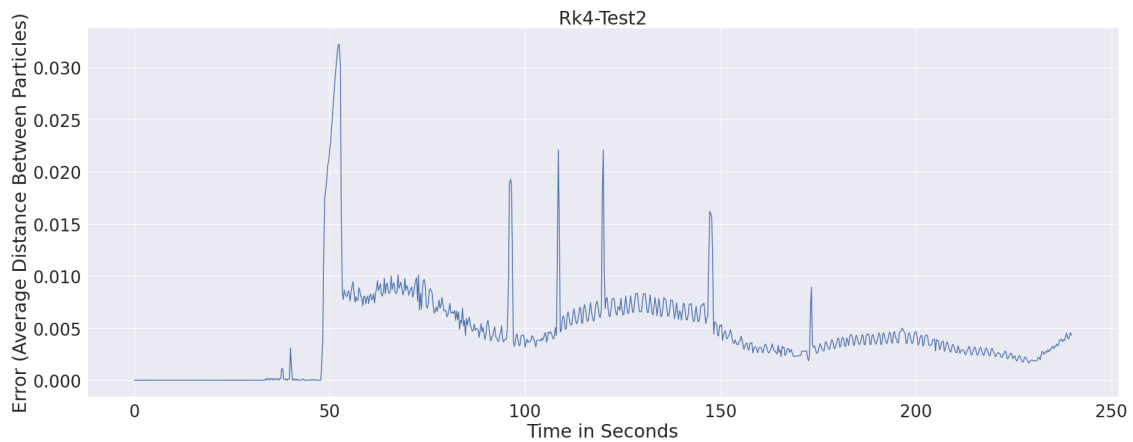
1.3.7 RK4 Test 1 Results

	count	mean	std	min	25%	\
Rk4-Test1	960.0	2.237405e-07	7.584915e-08	4.380328e-11	1.684821e-07	
		50%	75%	max		
Rk4-Test1	2.132327e-07	2.704770e-07	4.854779e-07			



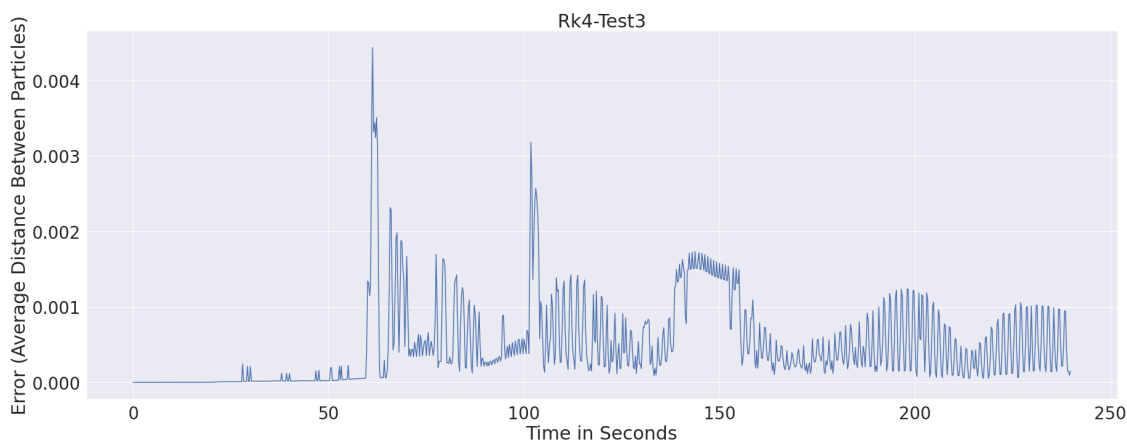
1.3.8 RK4 Test 2 Results

	count	mean	std	min	25%	50%	\
Rk4-Test2	960.0	0.004505	0.004253	1.585681e-10	0.002367	0.003809	
		75%	max				
Rk4-Test2	0.006436	0.032198					



1.3.9 RK4 Test 3 Results

	count	mean	std	min	25%	50%	\
Rk4-Test3	960.0	0.000498	0.000562	4.409171e-11	0.000068	0.000322	
		75%	max				
Rk4-Test3	0.000676	0.004435					



[9]: combined_df

	count	mean	std	min	\
Adaptiverk4-Test1	960.0	2.783975e-02	4.949013e-02	2.418725e-06	
Adaptiverk4-Test2	960.0	3.971101e-01	2.635744e-01	1.010462e-05	
Adaptiverk4-Test3	960.0	3.985668e-01	2.920495e-01	1.017311e-05	
Heun-Test1	960.0	2.005688e-01	2.725990e-01	9.792633e-04	
Heun-Test2	960.0	1.601195e+00	5.422747e-01	9.853182e-04	
Heun-Test3	960.0	9.115530e-01	5.977611e-01	1.256250e-04	
Rk4-Test1	960.0	2.237405e-07	7.584915e-08	4.380328e-11	
Rk4-Test2	960.0	4.504559e-03	4.253269e-03	1.585681e-10	
Rk4-Test3	960.0	4.977654e-04	5.618401e-04	4.409171e-11	

	25%	50%	75%	max
Adaptiverk4-Test1	2.213080e-03	9.919838e-03	2.364151e-02	2.450708e-01
Adaptiverk4-Test2	2.272984e-01	3.905686e-01	5.126916e-01	9.306464e-01
Adaptiverk4-Test3	3.199258e-02	4.295131e-01	6.460005e-01	8.953724e-01
Heun-Test1	4.324898e-02	8.980912e-02	2.262794e-01	1.407952e+00
Heun-Test2	1.331452e+00	1.550308e+00	1.871948e+00	2.801356e+00
Heun-Test3	4.953476e-01	7.871555e-01	1.154473e+00	3.137841e+00
Rk4-Test1	1.684821e-07	2.132327e-07	2.704770e-07	4.854779e-07
Rk4-Test2	2.366723e-03	3.808852e-03	6.436079e-03	3.219823e-02
Rk4-Test3	6.828317e-05	3.222026e-04	6.759377e-04	4.435306e-03

2 Discussion of Benchmarks

Compared to RK5 the best performing method is RK4, followed by adaptive rk4, and lastly Heun's method.

We would expect adaptive RK4 to perform better than RK4 but the reason why it doesn't in this simulation is that during the adaptive RK4 simulation, the "m_CollisionRootFinding" is triggered in multiple iterations causing the simulation to default to Euler's integration during that iteration