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Mostafa Khaled Sa
import numpy as np
import cv2
from google.colab.patches import cv2_imshow
photo=cv2.imread('/content/WhatsApp Image 2023-04-12 at 14.16.20.jpg')
def avrage_3X3(old):
           image=cv2.copyMakeBorder(old,1,1,1,1,cv2.BORDER_REFLECT)
           templetm=np.ones([3,3])
           new_avg=np.zeros([row,col,chh])
           for ch in range(chh):
                 for r in range(row):
                      for c in range(col):
new\_avg[(r,c,ch)] = int((image[(r,c,ch)]*templetm[0][0]+image[(r+1,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r+2,c,ch)]*templetm[1][0]+image[(r
empletm[2][0] + image[(r,c+1,ch)]*templetm[0][1] + image[(r,c+2,ch)]*templetm[0][2] + image[(r+1,c+1,ch)]*templetm[0][2] + image[(r+1,ch)]*templetm[0][2] +
mpletm[1][1]+image[(r+1,c+2,ch)]*templetm[1][2]+image[(r+2,c+1,ch)]*templetm[2][1]+image[(r+2,c+2,ch)]
*templetm[2][2])/9)
           new_avg=np.uint8(new_avg)
           return new_avg
X=avrage_3X3(photo)
photo2=cv2.imread('/content/Screenshot 2023-04-13 165318.png')
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photo3=cv2.imread('/content/1_XAgKINgc2c2gNa2nV3zbNQ.png')

cv2 imshow(photo2)

cv2_imshow(photo3)

def unsharpingdetection(old):

image avrage=avrage 3X3(old)

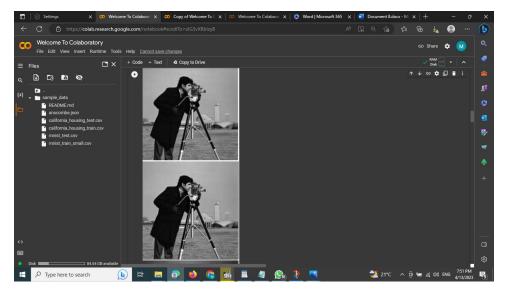
image avrage=photo2-image avrage

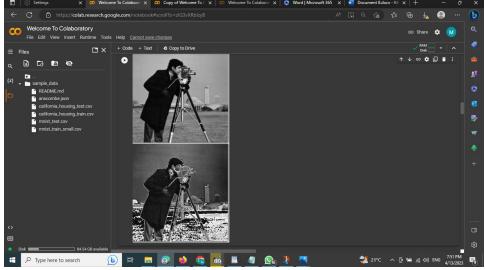
cv2 imshow(image avrage)

image_avrage=image_avrage+photo2

cv2 imshow(image avrage)

unsharpingdetection(photo2)





```
import numpy as np
import cv2
from google.colab.patches import cv2_imshow
pho=cv2.imread('/content/railway-hdr-1361893.jpg')
def Guassian_function(image,sigma):
  N = int(3.7*sigma-0.5)
  mask_size = 2*N+1
  image = cv2.copyMakeBorder(image, N, N, N, N, cv2.BORDER_REFLECT)
  t = round(mask_size/2)
  x= range(-t, t)
  filter = np.zeros([mask_size, mask_size], dtype=float)
  coef=(1/(2*np.pi*(sigma**2)))
  for i in range(mask_size):
    for j in range(mask_size):
      power=-((x[i]**2)+(x[j]**2))/(2*(sigma**2))
      temp=float(coef*np.exp(power))
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return filter, N
def Smoothing_with_weighted_Filter( old,sigma ):
  new = np.zeros([r1, c1, ch1])
  old=cv2.copyMakeBorder(old, N, N, N,N, cv2.BORDER_REFLECT)
  for chh in range(0, ch):
    for i in range(N, r - N):
      for j in range(N, c - N):
         temp = old[i - N:i + N + 1, j - N:j + N + 1, chh]
         new[i - N, j - N, chh] = value
  return (new)
# ggg=Guassian_function(pho,2)
f=Smoothing_with_weighted_Filter(pho,.5)
```

```
cv2_imshow(f)
photo2=cv2.imread('/content/Screenshot 2023-04-13 165318.png')
# photo3=cv2.imread('/content/1_XAgKINgc2c2gNa2nV3zbNQ.png')
cv2_imshow(photo2)
# cv2_imshow(photo3)

def unsharpingdetection(old):
    image_avrage=Smoothing_with_weighted_Filter(old,.5)
    image_avrage=photo2-image_avrage
    cv2_imshow(image_avrage)
    image_avrage=image_avrage+photo2
    cv2_imshow(image_avrage)
```

unsharpingdetection(photo2)

