

# Mostafa Ayesh

Embedded Software Developer

✉ [mostafaayesh@outlook.com](mailto:mostafaayesh@outlook.com)

in [/mostafaayesh](#)

🐙 [/MostafaAyesh](#)

🌐 [mostafaayesh.com](http://mostafaayesh.com)

## Education

### Software Engineering MAsc.

McMaster University

Sep. 2020 – May. 2024

Hamilton, ON

### Mechatronics Engineering & Management B.Eng.

McMaster University

Sep. 2014 – Apr. 2020

Hamilton, ON

## Experience

### Application Engineer

Indie Semiconductor

Jan. 2023 – Present

Toronto, ON

- › Tailored software and hardware solutions to fulfill specific customer needs
- › Implemented image sensor drivers to support new image sensors
- › Developed tools for extraction, parsing, and verification of embedded data from video streams
- › Engineered host-side tools to facilitate communication with the camera video processor SoC through I<sup>2</sup>C
- › Conducted comprehensive functional safety and timing analyses, ensuring adherence to industry standards and regulatory requirements

### Graduate Research Assistant

McMaster Automotive Resource Centre

May 2020 – Dec. 2022

Hamilton, ON

- › Collaborated with NXP Semiconductor and an automotive OEM to migrate motor control application to a centralized architecture
- › Designed firmware for pre-production hardware (NXP S32S & S32K3), configuring peripherals, clock trees, and pin multiplexing
- › Implemented time synchronization using Time Sensitive Networking (TSN) over Automotive Ethernet
- › Utilized Lauterbach TRACE32 with JTAG debugging and ETM tracing for hardware and software testing and troubleshooting
- › Performed signal verification and timing analysis for networking and motor control applications

### Embedded Systems Specialist

NEUDOSE Satellite Team

Oct. 2018 – Aug. 2020

Hamilton, ON

- › Worked on a project funded by the Canadian Space Agency (CSA) to build and launch a satellite
- › Developed STM32-based CAN drivers for satellite On-Board Computer with (CSP) network stack support
- › Contributed to the development of FreeRTOS-based flight software for the On-Board Computer in C/C++
- › Created a prototype Printed Circuit Board using Altium Designer for flight software testing purposes

### Research Assistant

McMaster Centre for Software Certification

May 2017 – Apr. 2020

Hamilton, ON

- › Developed model-based Pacemaker following Boston Scientific specs using MATLAB Simulink on NXP FRDM-K64F
- › Implemented real-time Pacemaker configuration and monitoring through UART in MATLAB Simulink with a Python GUI
- › Automated hardware testing with Arm Mbed firmware (C++) and Python scripts utilizing UART communication

## Projects

### RETINA (Realtime Indoor Navigation Assistant)

May 2020

- > A navigation system to assist people with visual impairment navigate buildings utilizing Ultra-Wide Band (UWB) technology with sub-meter precision
- > Implemented BLE communication between the mobile app and Decawave DW1000 UWB transceivers to retrieve the user's real-time position and heading
- > Integrated the mobile app with OpenStreetMap API for indoor maps as well as Nominatim for reverse geocoding and Valhalla for route generation

### Booky

Jan. 2018

- > A Cross-Platform mobile app (iOS & Android) that allows the user to search for books by using a picture of the book built using Google flutter
- > Used Google Cloud services for image search as well retrieving information about the book of interest

### Sumobot Challenge

Mar. 2018

- > Selected the components and built the electrical circuitry for the Sumobot
- > Developed a C++ arduino project for motor control as well sensor sampling (line detection, ultrasound)

## Publications

### Two Simulink Models with Requirements for a Simple Controller of a Pacemaker Device

Sep. 2022

- > Accepted at the 9th International Workshop on Applied Verification of Continuous and Hybrid Systems

## Skills

**Languages** C, Python, C++, ARM Assembly, JavaScript, Java, Dart, Verilog, SQL

**Tools** CMake, Ninja, GDB, OpenOCD, Git, Docker, SVN

**Software** MATLAB, Simulink, Altium Designer, Lauterbach TRACE32, STM32CubeMX

**Hardware** ARM Cortex-M (STM32, NXP S32K3), ARM Cortex-R (NXP S32S24), PowerPC (NXP MPC5777C), FPGA

**Communication** CAN, Automotive Ethernet (TSN), UART, SPI, I<sup>2</sup>C, MQTT, UDP, TCP/IP