

## Embedded Software Developer

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## Education

## Software Engineering MAsc.

McMaster University

Sep. 2020 – Dec. 2023

*Hamilton, ON*

## **Mechatronics Engineering & Management B.Eng.**

McMaster University

Sep. 2014 – Apr. 2020

*Hamilton, ON*

## Experience

## Application Engineer

## Indie Semiconductor

Jan. 2023 – Present

Toronto, ON

- › Designed and developed customized software and hardware solutions to meet customer requirements
- › Implemented features within image sensor drivers of a camera vision processor SoC
- › Developed tools for extracting, parsing and verification of embedded data from a video stream
- › Created host-side tools for communicating with the camera vision processor SoC via I<sup>2</sup>C
- › Conducted functional safety and timing analyses to ensure industry standards compliance

## Graduate Research Assistant

McMaster Automotive Resource Centre

May 2020 – Dec. 2022

*Hamilton, ON*

- › Collaborated with NXP Semiconductor and an automotive OEM to migrate a motor control application to a centralized architecture
- › Developed firmware for pre-production hardware (NXP S32S & S32K3) configuring peripherals, clock trees and pin multiplexing
- › Implemented time synchronization using Time Sensitive Networking (TSN) over Automotive Ethernet
- › Utilized Lauterbach TRACE32 with JTAG debugging and ETM tracing for hardware and software testing and troubleshooting
- › Conducted signal verification and timing analysis for networking and motor control applications

## Embedded Systems Specialist

NEUDOSE Satellite Team

Oct. 2018 – Aug. 2020

*Hamilton, ON*

- › Worked on a project funded by the Canadian Space Agency (CSA) to build and launch a satellite
- › Developed CAN drivers for the satellite's On-Board Computer (STM32) to support a network stack (CSP)
- › Contributed to the development of the On-Board Computer's FreeRTOS based flight software in C/C++
- › Designed a Printed Circuit Board using Altium Designer to serve as a prototype for testing flight software

## Research Assistant

McMaster Centre for Software Certification

May 2017 – Apr. 2020

*Hamilton, ON*

- › Developed a model-based Pacemaker, following Boston Scientific's Pacemaker System Specification, using MATLAB Simulink on an embedded target NXP FRDM-K64F.
- › Implemented UART communication in MATLAB Simulink to configure and monitor the Pacemaker in real-time using a Python graphical user interface (GUI).
- › Created an automated hardware testing and verification process, including Arm Mbed based firmware in C++ and Python scripts for communication over UART.

## Projects

### RETINA (Realtime Indoor Navigation Assistant)

May 2020

- > A navigation system to assist people with visual impairment navigate buildings utilizing Ultra-Wide Band (UWB) technology with sub-meter precision
- > Implemented BLE communication between the mobile app and Decawave DW1000 UWB transceivers to retrieve the user's real-time position and heading
- > Integrated the mobile app with OpenStreetMap API for indoor maps as well as Nominatim for reverse geocoding and Valhalla for route generation

### Booky

Jan. 2018

- > A Cross-Platform mobile app (iOS & Android) that allows the user to search for books by using a picture of the book built using Google flutter
- > Used Google Cloud services for image search as well retrieving information about the book of interest

### Sumobot Challenge

Mar. 2018

- > Selected the components and built the electrical circuitry for the Sumobot
- > Developed a C++ arduino project for motor control as well sensor sampling (line detection, ultrasound)

## Publications

### Two Simulink Models with Requirements for a Simple Controller of a Pacemaker Device

Sep. 2022

- > Accepted at the 9th International Workshop on Applied Verification of Continuous and Hybrid Systems

## Skills

**Languages** C, Python, C++, ARM Assembly, JavaScript, Java, Dart, Verilog, SQL

**Tools** CMake, Ninja, GDB, OpenOCD, Git, Docker, SVN

**Software** MATLAB, Simulink, Altium Designer, Lauterbach TRACE32, STM32CubeMX

**Hardware** ARM Cortex-M (STM32, NXP S32K3), ARM Cortex-R (NXP S32S24), PowerPC (NXP MPC5777C), FPGA

**Communication** CAN, Automotive Ethernet (TSN), UART, SPI, I<sup>2</sup>C, MQTT, UDP, TCP/IP