

**SPRINTS RTOS COURSE**  
**Designing a real-time system**  
**Task Report**

**Prepared By :**

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**•Task: Design a healthcare system using RTOS with the following requirements:**

- A touch LCD as input that can control the system and give commands. Every LCD command is represented in 4 bytes. LCD is connected to the micro-controller through UART with speed 9600 bps [Bit per second]. (Reading 4 bytes and processing the command takes 2 ms)
- Blood pressure sensor with new data every 25ms. (Reading the sensor and processing its data takes 3 ms)
- Heart beat detector with new data every 100ms. (Reading the sensor and processing its data takes 1.5 ms)
- Temperature sensor with new data every 10ms. (Reading the sensor and processing its data takes 2.5 ms)
- Alert siren. (Activate or Deactivate the siren takes 1 ms)Tasks

[1] Decide how many tasks are needed?

→ 5 tasks

[2] Decide task parameters (periodicity - Deadline)

Task<sub>1</sub> (LCD-Reading-Command)

Execution time = 2ms

periodicity = 10ms

Task<sub>2</sub> (Blood-pressure-sensor-reading)

Execution time = 3ms

periodicity = 25ms

Task<sub>3</sub> (Heart-Beat-Sensor-Reading)

Execution time = 1.5ms

periodicity = 100ms

Task<sub>4</sub> (Temperature-sensor-Reading)

Execution time = 2.5ms

periodicity = 10ms

Task<sub>5</sub> (Alert-siren)

Execution time = 1ms

periodicity = 10ms

③ Decide system tick rate

$$\begin{aligned}\rightarrow \text{tick rate} &= \text{total of all execution time of all tasks} \\ &= 2 + 3 + 1.5 + 2.5 + 1 = \underline{10 \text{ ms}}\end{aligned}$$

④ Calculate Hyperperiod

$$\begin{aligned}\rightarrow \text{Hyperperiod} &= \text{least common multiplier of all tasks} \\ &= \underline{100 \text{ ms}}\end{aligned}$$

⑤ Calculate cpu load

$$\text{Cpu load} = \sum \frac{\text{execution time of each task}}{\text{period of task}}$$

$$= \frac{2}{10} + \frac{3}{25} + \frac{1.5}{100} + \frac{2.5}{10} + \frac{1}{10} = 0.685 = 68.5 \%$$

$\rightarrow$  Cpu load is not high, so we can add features in system

6] Draw the timeline manually and analyze the system schedulability:



→ All tasks do not miss their deadline  
So, system is guaranteed schedulable

# Model The System Using Simso :

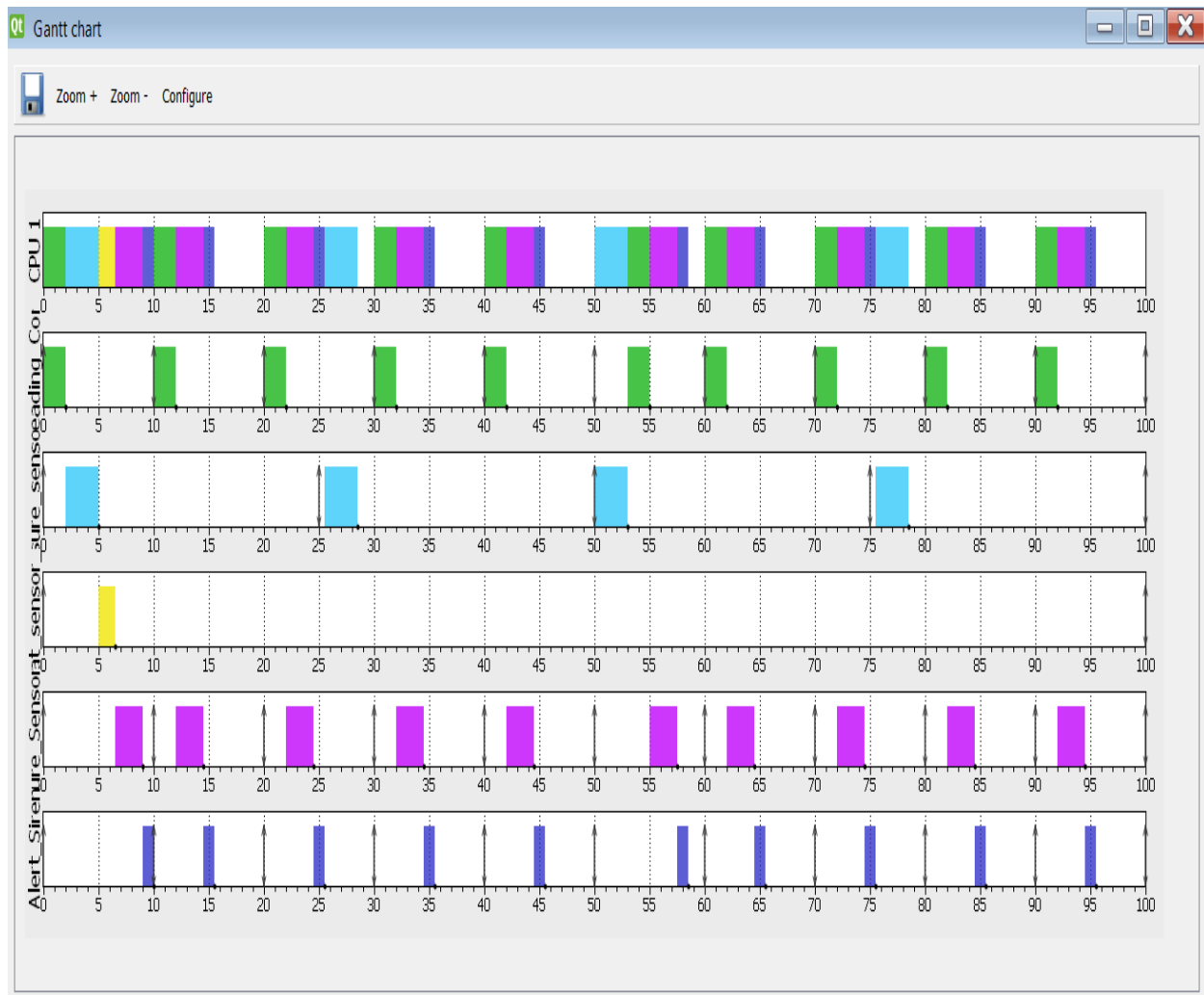
## 1- Tasks List

Qt Model data										
General		Scheduler		Processors		Tasks				
id	Name	Task type	Abort on miss	Act. Date (ms)	Period (ms)	List of Act. dates (ms)	Deadline (ms)	WCET (ms)	Followed by	priority
1	LCD_Reading_Command	Periodic	<input checked="" type="checkbox"/> Yes	0	10	-	10	2.0	▼ 0	0
2	Bloodpressure_sensor_Reading	Periodic	<input checked="" type="checkbox"/> Yes	0	25	-	25	3	▼ 0	0
3	heartbeat_sensor_Reading	Periodic	<input checked="" type="checkbox"/> Yes	0	100	-	100	1.5	▼ 0	0
4	Temperature_Sensor_Reading	Periodic	<input checked="" type="checkbox"/> Yes	0	10	-	10	2.5	▼ 0	0
5	Alert_Siren	Periodic	<input checked="" type="checkbox"/> Yes	0	10	-	10	1	▼ 0	0

## Cpu Load

Qt Results			
General		Logs	Tasks
Observation Window:			
from 0.00 to 100.00 ms		Configure...	
	Total load	Payload	System load
CPU 1	0.6850	0.6850	0.0000
Average	0.6850	0.6850	0.0000

# Gantt Chart



**My Calculations Match Simso Analysis Computation and  
System Is Guaranteed Schedulable.**