# FANUC Robot CR-35iA



### **FEATURES**

FANUC Robot CR-35iA is a 35 kg payload collaborative robot that can work without safety fences.

#### **Collaborative** Operation

- This robot and a human operator can work together within a shared workspace without safety fences.
- This robot can work in cooperation with a human operator. (example: heavy workpiece transfer, parts assembling)
- With Hand Guidance(option), intuitive operation and easy teaching are possible.

### Safety Function

- This robot stops safely when it touches a human operator.
- Safe and gentle looking green soft cover reduces an impact force and prevents a human operator from being pinched.
- CR-35iA is certified to meet the requirements of international standard ISO 10218-1.

### Intelligence and High Reliability

- Latest intelligent functions such as iRVision (Integrated vision) are available.
- This robot is designed with the same high reliability as conventional robots.

# **Application Example**



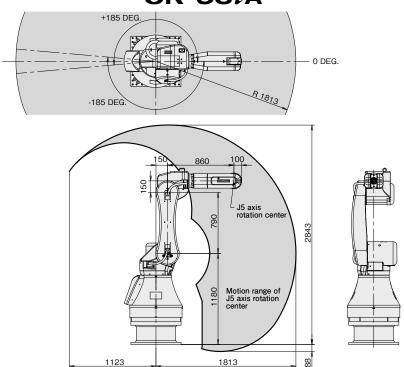
Parts assembly by collaborative operation



Workpiece transfer with Hand Guidance

# Operating space

# CR-351A



# **Specifications**

| ilcations                       |                        |  |  |
|---------------------------------|------------------------|--|--|
| Model                           |                        |  | CR-35 <i>i</i> A   |
| Type                            |                        | Articulated Type   |  |
| Controlled axes                 |                        | 6 axes (J1, J2, J3, J4, J5, J6)                              |  |
| Reach                           |                        | 1813 mm  |  |
| Installation                    |                        | Floor  |  |
| Motion range                    | J1 axis rotation       | 340° / 370   | O°(Option) 5.93 rad / 6.46 rad(Option)   |
|                                 | J2 axis rotation       |  | 165° 2.88 rad  |
|                                 | J3 axis rotation       |  | 258° 4.50 rad  |
|                                 | J4 axis wrist rotation | 400° 6.98 rad  |  |
|                                 | J5 axis wrist swing    | 220° 3.84 rad  |  |
|                                 | J6 axis wrist rotation |  | 900° 15.71 rad   |
| Max. load capacity at wrist     |                        | 35 kg  |  |
| Max. load capacity on J3 casing |                        | 2 kg   |  |
| Maximum speed (Note 1, Note 2)  |                        | 750 mm/s   |  |
| Allowable load moment at wrist  | J4 axis                | 110 N⋅m  |  |
|                                 | J5 axis                | 110 N⋅m  |  |
|                                 | J6 axis                | 60 N·m   |  |
| Allowable load inertia at wrist | J4 axis                | 4.00 kg⋅m²   |  |
|                                 | J5 axis                | 4.00 kg⋅m²   |  |
|                                 | J6 axis                | 1.50 kg⋅m²   |  |
| Drive method                    |                        | Electric servo drive by AC servo motor                       |  |
| Repeatability (Note 3)          |                        | ±0.03 mm   |  |
| Mass (Note 4)                   |                        | 990 kg   |  |
| Installation environment        |                        | Ambient temperature Ambient humidity  Vibration acceleration | <ul> <li>: 0 to 45°C</li> <li>: Normally 75 %RH or less (No dew nor frost allowed)<br/>Short time (within one month) Max.95%RH</li> <li>: 4.9 m/s² (0.5G) or less</li> </ul> |

Note 1) In case of short distance motion, the speed may not reach the maximum value stated.

Note 2) It is necessary to set a motion speed according to risk assessment of system.

Note 3) Compliant with ISO9283.

Note 4) Without controller.

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