Template Matching in Image Processing

Abdelrahman Atif

December 18, 2024

1 Introduction

Template matching is a technique in image processing used to find a specific template or pattern in a larger image. The process involves comparing a template image to portions of a target image to find the regions that match the template.

Given an image I and a template T, the goal is to find locations in I where T is most similar. Template matching is often used in applications such as object detection, face recognition, and barcode reading.

2 Template Matching Process

Template matching can be described as follows:

- 1. Convert both the template and the input image to grayscale (if not already in grayscale).
- 2. Slide the template over the input image and compare the region of the image currently under the template with the template.
- 3. For each position, compute a similarity score (e.g., correlation, sum of squared differences).
- 4. The position with the highest (or lowest) score corresponds to the location where the template best matches the image.

3 Methods for Template Matching

There are several different methods to compute the similarity between the template and the image region. These methods include:

- $\bullet \ \, \mathtt{cv2.TM}_{C}COEFF_NORMED(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCorrelationCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficient)\mathtt{cv2.TM}_\mathtt{SQDIFF_NORMED}(NormalizedCoefficien$
- cv2.TM_CCOEFF (Correlation Coefficient)
- cv2.TM_SQDIFF (Squared Difference)

3.1 Normalized Cross-Correlation

One commonly used method is cv2.TM_CCOEFF_NORMED, which normalizes the correlation coefficient between the template and the image region. The result will be a score between -1 and 1, where a value close to 1 indicates a high degree of similarity.

3.2 Squared Difference

Display the result

Another method is cv2.TM_SQDIFF, which calculates the squared difference between the template and the image region. The result will be a value between 0 and infinity, where a lower value indicates a better match.

4 Implementation in Python

The following Python code demonstrates how to implement template matching using OpenCV.

```
import cv2
import numpy as np
import matplotlib.pyplot as plt
# Load the main image and the template image
main_image = cv2.imread('main_image.jpg', cv2.IMREAD_COLOR)
template = cv2.imread('template_image.jpg', cv2.IMREAD_COLOR)
# Convert both images to grayscale
gray_main_image = cv2.cvtColor(main_image, cv2.COLOR_BGR2GRAY)
gray_template = cv2.cvtColor(template, cv2.COLOR_BGR2GRAY)
# Apply template matching using cv2.TM_CCOEFF_NORMED
result = cv2.matchTemplate(gray_main_image, gray_template, cv2.TM_CCOEFF_NORMED)
# Get the location of the best match (highest value)
min_val, max_val, min_loc, max_loc = cv2.minMaxLoc(result)
# Top-left corner of the matched area
top_left = max_loc
# Bottom-right corner
bottom_right = (top_left[0] + template.shape[1], top_left[1] + template.shape[0]
# Draw a rectangle around the matched area
cv2.rectangle(main_image, top_left, bottom_right, (0, 255, 0), 2)
```

```
 plt.imshow(cv2.cvtColor(main\_image, cv2.COLOR_BGR2RGB)) \ \# \ Convert \ BGR \ to \ RGB \ fo \ plt.title('Template-Matching-Result') \\ plt.show()
```

5 Explanation of Code

- cv2.imread(): Loads the main image and the template image.
- cv2.cvtColor(): Converts both the main image and the template to grayscale to simplify processing.
- cv2.matchTemplate(): Performs the template matching, using the cv2.TM_CCOEFF_NORMED method in this case.
- cv2.minMaxLoc(): Finds the location of the best match in the result image (the location with the highest correlation score).
- cv2.rectangle(): Draws a rectangle around the matched area in the main image.
- matplotlib.pyplot.imshow(): Displays the result with the matching region highlighted.

6 Conclusion

Template matching is a simple yet powerful technique for locating patterns in images. OpenCV provides a variety of methods to perform template matching, each suitable for different applications. The example provided uses normalized cross-correlation (cv2.TM_CCOEFF_NORMED) to locate a template within a larger image, but other methods like squared difference can also be used depending on the specific problem at hand.