

Arduino Programming Cheat Sheet eps32

Structure & Flow

```
Basic Program Structure
void setup() {
  // Runs once when sketch starts
}
void loop() {
  // Runs repeatedly
}

Control Structures
if (x < 5) { ... } else { ... }
while (x < 5) { ... }
for (int i = 0; i < 10; i++) { ... }
break; // Exit a loop immediately
continue; // Go to next iteration
switch (var) {
  case 1:
    ...
    break;
  case 2:
    ...
    break;
  default:
    ...
}
return x; // x must match return type
return; // For void return type

Function Definitions
<ret. type> <name>(<params>) { ... }
e.g. int double(int x) {return x*2;}
```

Operators

```
General Operators
= assignment
+ add - subtract
* multiply / divide
% modulo
== equal to != not equal to
< less than > greater than
<= less than or equal to
>= greater than or equal to
&& and || or
! not

Compound Operators
++ increment
-- decrement
+= compound addition
-= compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
|= compound bitwise or

Bitwise Operators
& bitwise and | bitwise or
^ bitwise xor ~ bitwise not
<< shift left >> shift right

Pointer Access
& reference: get a pointer
* dereference: follow a pointer
```

Built-in Functions

```
Pin Input/Output
Digital I/O - pins 0-13 A0-A5
pinMode(pin, {INPUT|OUTPUT|INPUT_PULLUP})
int digitalRead(pin)
digitalWrite(pin, {HIGH|LOW})

Analog In - pins A0-A5
int analogRead(pin)
analogReference({DEFAULT|INTERNAL|EXTERNAL})

PWM Out - pins 3 5 6 9 10 11
analogWrite(pin, value) // 0-255

Advanced I/O
tone(pin, freq_Hz, [duration_msec])
noTone(pin)
shiftOut(dataPin, clockPin, {MSBFIRST|LSBFIRST}, value)
shiftIn(dataPin, clockPin, {MSBFIRST|LSBFIRST})
unsigned long pulseIn(pin, {HIGH|LOW}, [timeout_usec])

Time
unsigned long millis() // Overflows at 50 days
unsigned long micros() // Overflows at 70 minutes
delay(msec)
delayMicroseconds(usec)

Math
min(x, y) max(x, y) abs(x)
sin(rad) cos(rad) tan(rad)
sqrt(x) pow(base, exponent)
constrain(x, minval, maxval)
map(val, fromL, fromH, toL, toH)

Random Numbers
randomSeed(seed) // long or int
long random(max) // 0 to max-1
long random(min, max)

Bits and Bytes
lowByte(x) highByte(x)
bitRead(x, bitn)
bitWrite(x, bitn, bit)
bitSet(x, bitn)
bitClear(x, bitn)
bit(bitn) // bitn: 0=LSB 7=MSB

Type Conversions
char(val) byte(val)
int(val) word(val)
long(val) float(val)

External Interrupts
attachInterrupt(interrupt, func, {LOW|CHANGE|RISING|FALLING})
detachInterrupt(interrupt)
interrupts()
noInterrupts()
```

Libraries

```
Serial - comm. with PC or via RX/TX
begin(long speed) // Up to 115200
end()
int available() // #bytes available
int read() // -1 if none available
int peek() // Read w/o removing
flush()
print(data) println(data)
write(byte) write(char * string)
write(byte * data, size)
SerialEvent() // Called if data ready

SoftwareSerial.h - comm. on any pin
SoftwareSerial(rxPin, txPin)
begin(long speed) // Up to 115200
listen() // Only 1 can listen
isListening() // at a time.
read, peek, print, println, write
// Equivalent to Serial library

EEPROM.h - access non-volatile memory
byte read(addr)
write(addr, byte)
EEPROM[index] // Access as array

Servo.h - control servo motors
attach(pin, [min_usec, max_usec])
write(angle) // 0 to 180
writeMicroseconds(uS)
// 1000-2000; 1500 is midpoint
int read() // 0 to 180
bool attached()
detach()
```

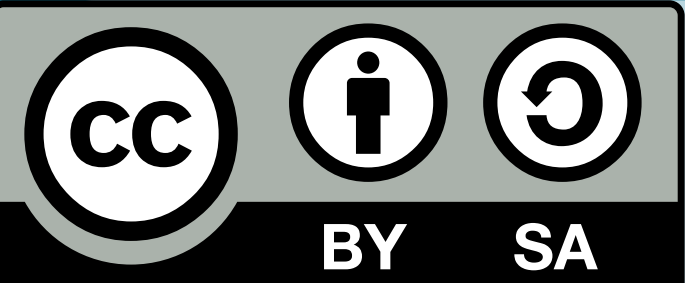
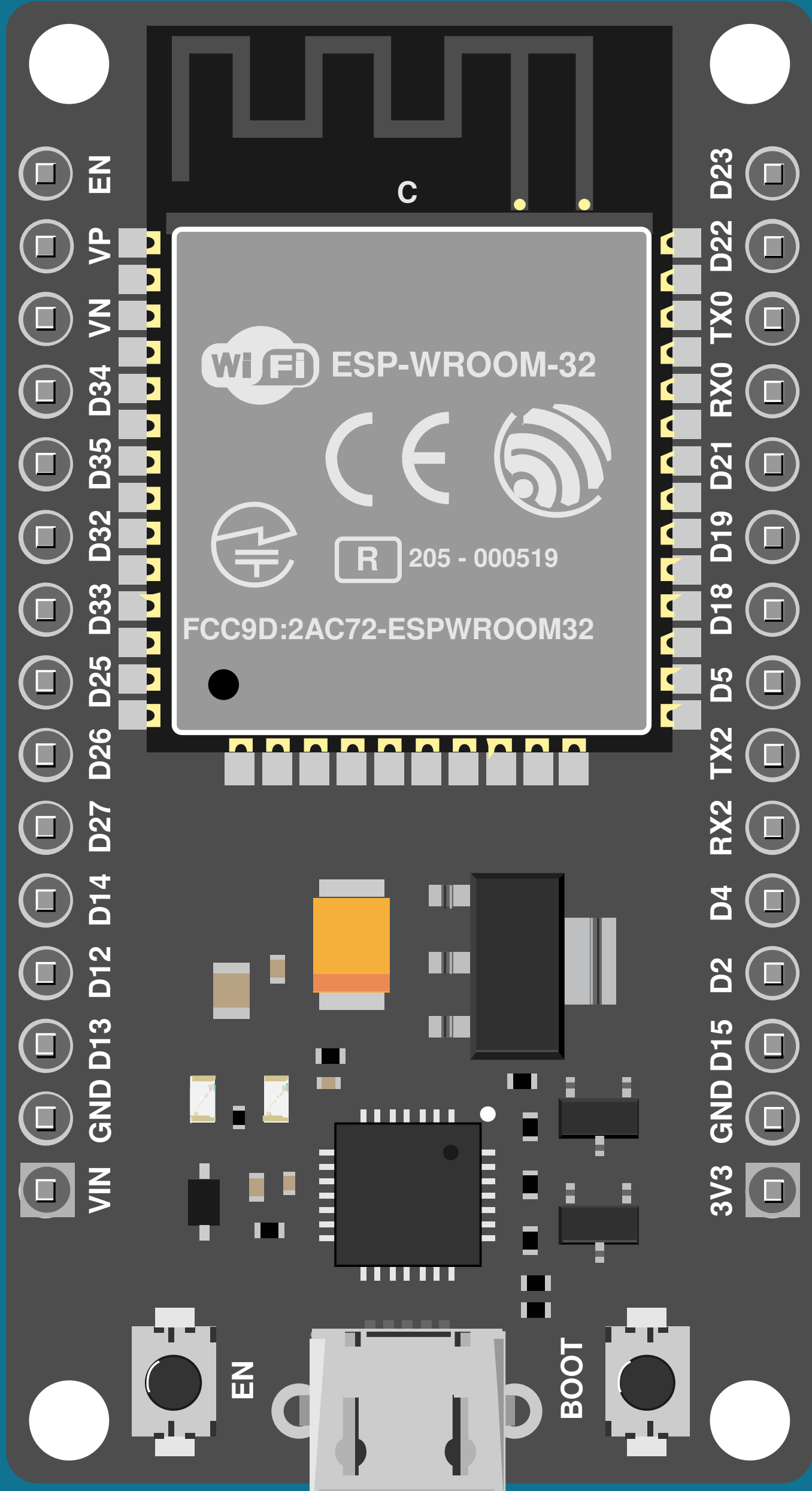
Variables, Arrays, and Data

```
Data Types
bool true | false
char -128 - 127, 'a' '$' etc.
unsigned char 0 - 255
byte 0 - 255
int -32768 - 32767
unsigned int 0 - 65535
word 0 - 65535
long -2147483648 - 2147483647
unsigned long 0 - 4294967295
float -3.4028e+38 - 3.4028e+38
double currently same as float
void return type: no return value

Numeric Constants
123 decimal
0b01111011 binary
0173 octal - base 8
0x7B hexadecimal - base 16
123U force unsigned
123L force long
123UL force unsigned long
123.0 force floating point
1.23e6 1.23*10^6 = 1230000

Qualifiers
static persists between calls
volatile in RAM (nice for ISR)
const read-only
PROGMEM in flash

Arrays
byte myPins[] = {2, 4, 8, 3, 6};
int myInts[6]; // Array of 6 ints
myInts[0] = 42; // Assigning first
// index of myInts
myInts[6] = 12; // ERROR! Indexes
// are 0 though 5
```



by Fred-Olav
version: 2024-04-24

source: <https://github.com/liffiton/Arduino-Cheat-Sheet/>
Adapted from: Mark Liffiton
- Original: Gavin Smith
- SVG version: Frederic Dufourg
- Arduino board drawing: Fritzing.org