# Arduino Programming Cheat Sheet eps32

# Structure & Flow

```
Basic Program Structure
void setup() {
 // Runs once when sketch starts
void loop() {
 // Runs repeatedly
Control Structures
if (x < 5) { ... } else { ... }
while (x < 5) \{ \dots \}
for (int i = 0; i < 10; i++) { ... }
break; // Exit a loop immediately
continue; // Go to next iteration
switch (var) {
 case 1:
    • • •
   break;
 case 2:
    • • •
   break;
 default:
    • • •
          // x must match return type
           // For void return type
return;
Function Definitions
<ret. type> <name>(<params>) { ... }
e.g. int double(int x) {return x*2;}
```

# Operators

```
General Operators
= assignment
+ add - subtract
* multiply / divide
% modulo
== equal to != not equal to
< less than > greater than
<= less than or equal to
>= greater than or equal to
&& and | or
```

#### Compound Operators

not

```
++ increment
-- decrement
+= compound addition
-= compound subtraction
*= compound multiplication
/= compound division
&= compound bitwise and
```

= compound bitwise or

#### Bitwise Operators

&	bitwise and		bitwise or
^	bitwise xor	~	bitwise not
<b>&lt;&lt;</b>	shift left	>>	shift right

#### Pointer Access

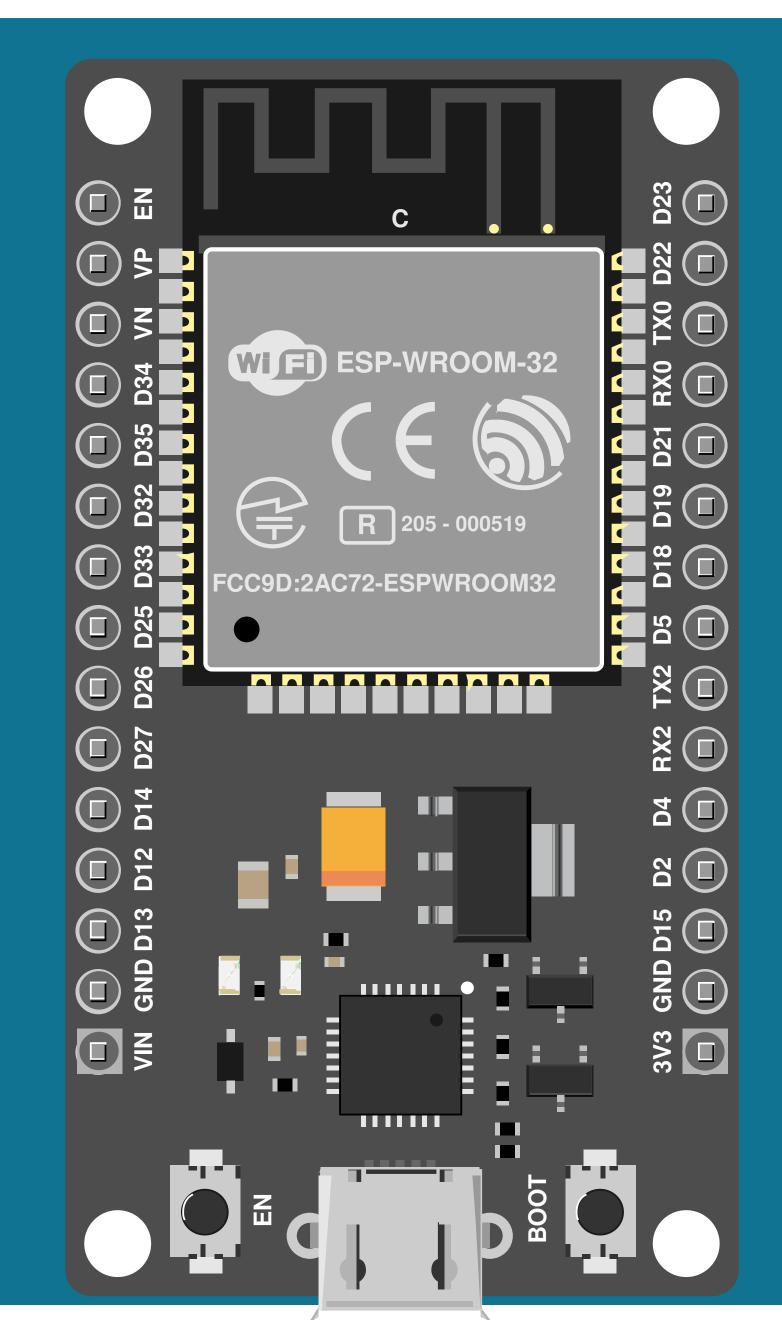
- & reference: get a pointer
- \* dereference: follow a pointer

# Variables, Arrays, and Data

```
Data Types
                                       Numeric Constants
               true false
                                       123
                                                    decimal
bool
               -128 - 127, 'a' '$' etc. 0b01111011 binary
char
unsigned char
                                                  octal - base 8
                  0 - 255
                                        0x7B
                                                    hexadecimal - base 16
byte
             -32768 - 32767
                                        123U
                                                    force unsigned
int
                  0 - 65535
                                        123L
                                                    force long
unsigned int
                  0 - 65535
                                        123UL
                                                    force unsigned long
word
                                        123.0
        -2147483648 - 2147483647
                                                    force floating point
long
                                        1.23e6
                                                    1.23*10^6 = 1230000
unsigned long
                 0 - 4294967295
       -3.4028e+38 - 3.4028e+38
float
                                        Qualifiers
        currently same as float
double
                                        static
                                                    persists between calls
void
         return type: no return value
                                        volatile
                                                    in RAM (nice for ISR)
                                                    read-only
                                        const
Strings
                                        PROGMEM
                                                    in flash
char str1[8] =
  {'A','r','d','u','i','n','o','\0'};
                                       Arrays
  // Includes \0 null termination
                                       byte myPins[] = \{2, 4, 8, 3, 6\};
char str2[8] =
                                       int myInts[6]; // Array of 6 ints
  {'A','r','d','u','i','n','o'};
                                       myInts[0] = 42; // Assigning first
  // Compiler adds null termination
                                                         // index of myInts
char str3[] = "Arduino";
                                       myInts[6] = 12;
                                                        // ERROR! Indexes
char str4[8] = "Arduino";
                                                         // are 0 though 5
```

### Built-in Functions

```
Pin Input/Output
                                     Math
Digital I/O - pins 0-13 A0-A5
                                     min(x, y)
                                                  max(x, y)
                                                               abs(x)
  pinMode(pin,
                                                               tan(rad)
                                     sin (rad)
                                                  cos (rad)
    { INPUT | OUTPUT | INPUT_PULLUP } )
                                                  pow(base, exponent)
                                     \mathbf{sqrt}(\mathbf{x})
  int digitalRead(pin)
                                     constrain(x, minval, maxval)
  digitalWrite(pin, {HIGH LOW})
                                     map(val, fromL, fromH, toL, toH)
Analog In - pins A0-A5
                                     Random Numbers
  int analogRead(pin)
                                      randomSeed (seed) // long or int
  analogReference (
                                     long random (max) // 0 to max-1
    {DEFAULT | INTERNAL | EXTERNAL } )
                                      long random(min, max)
PWM Out - pins 3 5 6 9 10 11
                                     Bits and Bytes
  analogWrite(pin, value) // 0-255
                                     lowByte(x)
                                                    highByte(x)
                                     bitRead(x, bitn)
Advanced I/O
                                      bitWrite(x, bitn, bit)
tone(pin, freq_Hz, [duration_msec])
                                      bitSet(x, bitn)
noTone (pin)
                                     bitClear(x, bitn)
shiftOut (dataPin, clockPin,
                                     bit (bitn) // bitn: 0=LSB 7=MSB
   {MSBFIRST | LSBFIRST }, value)
shiftIn (dataPin, clockPin,
                                     Type Conversions
  {MSBFIRST | LSBFIRST } )
                                     char (val)
                                                      byte(val)
unsigned long pulseIn (pin,
                                     int (val)
                                                      word(val)
  {HIGH LOW}, [timeout_usec])
                                                      float (val)
                                     long(val)
Time
                                     External Interrupts
unsigned long millis()
  // Overflows at 50 days
                                      attachInterrupt (interrupt, func,
                                       {LOW | CHANGE | RISING | FALLING } )
unsigned long micros()
                                      detachInterrupt (interrupt)
  // Overflows at 70 minutes
                                     interrupts()
delay (msec)
delayMicroseconds (usec)
                                     noInterrupts()
```



## Libraries

Serial - comm. with PC or via RX/TX

begin (long speed) // Up to 115200

```
end()
int available() // #bytes availabl
             // -1 if none availabl
int read()
             // Read w/o removing
int peek()
flush()
               println (data)
print (data)
write(byte)
               write(char * string)
write(byte * data, size)
SerialEvent() // Called if data rd
SoftwareSerial.h - comm. on any pin
SoftwareSerial (rxPin, txPin)
begin (long speed) // Up to 115200
              // Only 1 can listen
listen()
isListening() // at a time.
read, peek, print, println, write
  // Equivalent to Serial library
EEPROM.h - access non-volatile memor
byte read (addr)
write (addr, byte)
EEPROM[index] // Access as array
Servo.h - control servo motors
attach(pin, [min_usec, max_usec])
write(angle) // 0 to 180
writeMicroseconds (uS)
   // 1000-2000; 1500 is midpoint
int read() // 0 to 180
bool attached()
detach()
Wire.h - I<sup>2</sup>C communication
begin()
           // Join a master
begin (addr) // Join a slave @ addr
requestFrom(address, count)
beginTransmission(addr) // Step 1
send (byte)
                        // Step 2
send(char * string)
send(byte * data, size)
endTransmission()
                        // Step 3
int available() // #bytes available
byte receive() // Get next byte
onReceive (handler)
onRequest (handler)
```



by Fred-Olav version: 2024-04-24

source: https://github.com/liffiton/Arduino-Cheat-Sheet/

Adapted from: Mark Liffiton

- Original: Gavin Smith
- SVG version: Frederic Dufourg
- Arduino board drawing: Fritzing.org