

# Computer Labs: The PC Keyboard

## 2º MIEIC

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# Contents

## Lab 3 Overview

## PC Keyboard Operation: Data Input

# Lab 3: The PC's Keyboard - Part 1

- ▶ Write functions:

```
int kbd_test_scan(unsigned short assembly)
int kbd_test_poll()
```

that require programming the PC's keyboard controller

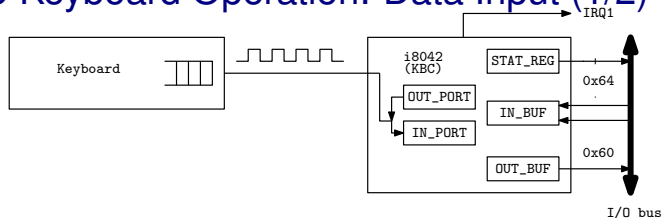
- ▶ These functions are not the kind of functions that you can reuse later in your project
  - ▶ The idea is that you design the lower level functions (with the final project in mind).
  - ▶ Reusable code should go on a different files from non-reusable code.
- ▶ What's new?
  - ▶ Program the KBC controller (i8042)
  - ▶ In part 2:
    - ▶ Mix C with assembly programming
    - ▶ Handle interrupts from more than one device

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Lab 3 Overview

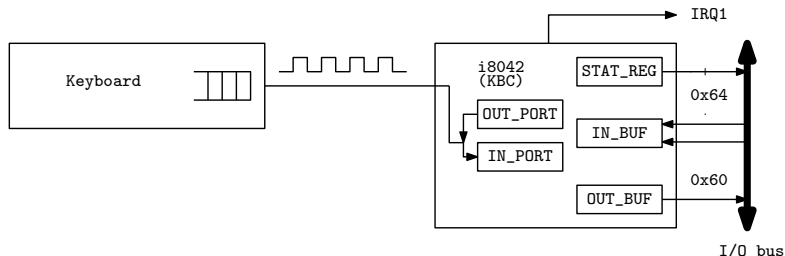
PC Keyboard Operation: Data Input

# PC Keyboard Operation: Data Input (1/2)



- ▶ The keyboard has its own controller chip (not shown): the controller@KBD (C@KBD)
- ▶ When a key is pressed the C@KBD generates a **scancode (make code)** and puts it in a buffer for sending to the PC
  - ▶ **Usually, a scancode is one byte long**
- ▶ The same happens when a key is released
  - ▶ Usually, the scancode when a key is released (**break code**) is the make code of that key with the MSB set to 1
- ▶ The communication between the C@KBD and the PC is via a serial line
  - ▶ I.e. the bits in a byte are sent one after the other over a pair of wires

## PC Keyboard Operation: Data Input (2/2)



- ▶ On the PC side this communication is managed by the keyboard controller (KBC)
  - ▶ In modern PCs, the KBC is integrated in the motherboard chipset
- ▶ When **OUT\_BUF** is empty:
  1. The KBC signals that via the serial bus
  2. The C@KBD sends the byte at the head of its buffer to the KBC
  3. The KBC puts it in the **OUT\_BUF**
  4. The KBC generates an interrupt by raising **IRQ1**

## Lab 3: kbd\_test\_scan (1/2)

**What** Prints the scancodes, both the **makecode** and the **breakcode**, read from the KBC

- ▶ Should terminate when it reads the **breakcode** of the ESC key:  
0x81
- ▶ The first byte of two byte scancodes is usually 0xE0
  - ▶ This applies to both make and break codes

**How** Need to subscribe the KBC interrupts

- ▶ Upon an interrupt, read the scancode from the OUT\_BUF

**Note** There is no need to configure the KBC

- ▶ It is already initialized by Minix

**Issue** Minix already has an IH installed

- ▶ Must be disabled to prevent it from reading the OUT\_BUF before your handler does it

**Solution** Use not only the IRQ\_REENABLE but also the IRQ\_EXCLUSIVE policy in `sys_irqsetpolicy()`, i.e. use `IRQ_REENABLE | IRQ_EXCLUSIVE`

## Lab 3: kbd\_test\_scan (2/2)

KBC interrupt subscription in exclusive mode;

`driver_receive()` loop (similar to that of lab 2)

Interrupt handler reads the bytes from the KBC's `OUT_BUF`

- ▶ Should read only **one byte per interrupt**
  - ▶ The communication between the keyboard and the KBC is too slow
- ▶ Later, you may think about including the code that maps the scancodes to a character code
  - ▶ IH in Minix are usually out of the critical path
    - ▶ They are executed with interrupts enabled and after issuing the EOI command to the PIC
  - ▶ In many systems this may not be appropriate. For example, in Linux most DD break interrupt handling in two:
    - Top half which is in the critical path, and therefore does minimal processing
    - Bottom half which is not in the critical path, and therefore may do additional processing
- ▶ Should not print the scancodes (not reusable)



## Minix 3 Notes: `driver_receive()` is not Polling

`driver_receive()` is a blocking call. If the process's "IPC queue" is empty:

- ▶ The OS will move it to the WAIT state
- ▶ The state will be changed to READY, only when a message (or notification) is sent to the process

```
5: while( 1 ) { /* You may want to use a different condition
6:     /* Get a request message. */
7:     if ( driver_receive(ANY, &msg, &ipc_status) != 0 ) {
8:         printf("driver_receive failed with: %d", r);
9:         continue;
10:    }
11:    if (is_ipc_notify(ipc_status)) { /* received notificat
12:        switch (_ENDPOINT_P(msg.m_source)) {
13:            case HARDWARE: /* hardware interrupt notification
14:                if (msg.NOTIFY_ARG & irq_set) { /* subscribed
15:                    ... /* process it */
16:                }
17:                break;
18:            default:
19:                break; /* no other notifications expected: do
20:        }
```

# Further Reading

- ▶ IBM's Functional Specification of the [8042 Keyboard Controller](#) (IBM PC Technical Reference Manual)
- ▶ [W83C42 Data Sheet](#), Data sheet of an 8042-compatible KBC
- ▶ Andries Brouwer's [The AT keyboard controller](#), Ch. 11 of [Keyboard scancodes](#)
- ▶ Andries Brouwer's [Keyboard commands](#), Ch. 12 of [Keyboard scancodes](#)