```
In[68]:= (*シミュレーション結果を可視化する*)
     AppendTo[$Path,
     |追加割当て | 検索ディレクトリのデフォルトリスト
       //home/motchy/Dropbox/home/individual/motchy/data/hobby/computer/programming/
         languages/Mathematica/lib/"];
     Import["motchyMath`"]
     インポート
     filePath = SystemDialogInput["FileOpen", ".json"]
               色選択ダイアログで選ばれた色を返す
     json = Import[filePath, "RawJSON"];
           【インポート
     Nagent = json["N"];
     T = json["T"];
     Print[
     出力表示
      "environment = ", json["environment name"], "\n",
      "prior name = ", json["prior name"], "\n",
      "graph name = ", json["graph name"], "\n",
      "K : ", json["K"], "\n",
      "N : ", Nagent, "\n",
      数值
      "T : ", json["T"], "\n",
      "Tc: ", json["Tc"], "\n",
      "rep : ", json["repetition number"]
     ]
     list = {Labeled[json["regret"]["loner"], "loner"],
            ラベル付き
        Labeled[json["regret"]["system average"], "system average"]};
        ラベル付き
     For[i = 1, i ≤ Nagent, ++i, AppendTo[list,
       Labeled[json["regret"][ToString[i]], "agent "<> ToString[i]]]]
                                                         文字列にする
       ラベル付き
                               文字列にする
     \texttt{ListLinePlot[list, PlotRange} \rightarrow \texttt{All, AxesLabel} \rightarrow \{\texttt{"t", "Regret"}\}, \texttt{ImageSize} \rightarrow \texttt{Large]}
     折れ線グラフ(点を繋いで… プロット範囲
                                  すべてし軸のラベル
                                                                      画像サイズ
     Print["R(sysAvg,T) = ", json["regret"]["system average"][[T]],
      ", R(loner,T) = ", json["regret"]["loner"][[T]]]
     Print["R(sysAvg,T)/R(loner,T) = ",
     出力表示
      json["regret"]["system average"][[T]] / json["regret"]["loner"][[T]]]
out[70]= /home/motchy/Dropbox/home/individual/motchy/data/univ/lab/open/B4/research/
       graduation-thesis/github/Workspace/Distributed-Thompson-sampling/simulation/
       algorithms/Type2/results/K5_uniform_prior_T10k.json
```

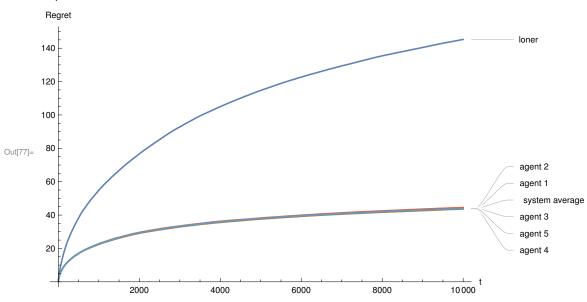
environment = env1 prior name = prior1 graph name = K5

K : 10 N : 5

T : 10000

Tc : 1

rep : 100



R(sysAvg,T) = 44.0134, R(loner,T) = 145.258

R(sysAvg,T)/R(loner,T) = 0.303001