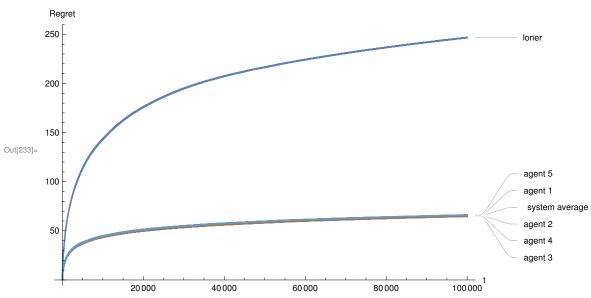
```
In[224]:= (*シミュレーション結果を可視化する*)
     AppendTo[$Path,
     |追加割当て | 検索ディレクトリのデフォルトリスト
       //home/motchy/Dropbox/home/individual/motchy/data/hobby/computer/programming/
         languages/Mathematica/lib/"];
     Import["motchyMath`"]
     インポート
     filePath = SystemDialogInput["FileOpen", ".json"]
               色選択ダイアログで選ばれた色を返す
     json = Import[filePath, "RawJSON"];
           【インポート
     Nagent = json["N"];
     T = json["T"];
     Print[
     出力表示
      "environment = ", json["environment name"], "\n",
      "prior name = ", json["prior name"], "\n",
      "graph name = ", json["graph name"], "\n",
      "K : ", json["K"], "\n",
      "N : ", Nagent, "\n",
       数值
      "T : ", json["T"], "\n",
      "rep : ", json["repetition number"]
     list = {Labeled[json["regret"]["loner"], "loner"],
        Labeled[json["regret"]["system average"], "system average"]);
        ラベル付き
     For[i = 1, i ≤ Nagent, ++i, AppendTo[list,
     繰返し評価
                              追加割当て
       Labeled[json["regret"][ToString[i]], "agent "<> ToString[i]]]]
                              文字列にする
                                                      文字列にする
     ListLinePlot[list, PlotRange → All, AxesLabel → {"t", "Regret"}, ImageSize → Large]
     上折れ線グラフ(点を繋いで… プロット範囲 すべて 軸のラベル
                                                                   画像サイズ
     Print["R(sysAvg,T) = ", json["regret"]["system average"][[T]],
     出力表示
      ", R(loner,T) = ", json["regret"]["loner"][[T]]]
     Print["R(sysAvg,T)/R(loner,T) = ",
     出力表示
      json["regret"]["system average"][[T]] / json["regret"]["loner"][[T]]
Out[226]= /home/motchy/Dropbox/home/individual/motchy/data/univ/lab/open/B4/research/
       graduation-thesis/github/Workspace/Distributed-Thompson-sampling/simulation/
       algorithms/Type1/results/K5_-3diagLines_uniform-prior_T100k.json
```

environment = env1 prior name = prior1 graph name = K5_-3diagLines

K : 10 N : 5

T : 100000

rep : 100



R(sysAvg,T) = 65.4508, R(loner,T) = 246.688

R(sysAvg,T)/R(loner,T) = 0.265318