Iterative tweaks of theTRRTkConfigDefault motion-planning algorithm parameter set associated to the quality of the resulting plan,

context: scene "scene_ground_with_boxes", query "RANDOM_pose23", countdown T =2.001s, accepta

Last parameter set tweak
(and call to
TRRTkConfigDefault)

frountier_NodeRatio

...stant

...er_threshold

range

goal_bias

0.1

1

15

20

0.0

.5