Iterative tweaks of theRRTConnect_{wrapped} motion-planning algorithm parameter set
associated to the quality of the resulting plan,
ontext: scene "scene_ground_with_boxes", query "RANDOM_pose46", countdown T =20s, acceptanc

Last parameter set tweak
(and call to
RRTConnect_{wrapped})

range

| 3.5 | 4 | 4.5 | 5 | 5.5 | 6 | 6.5 |