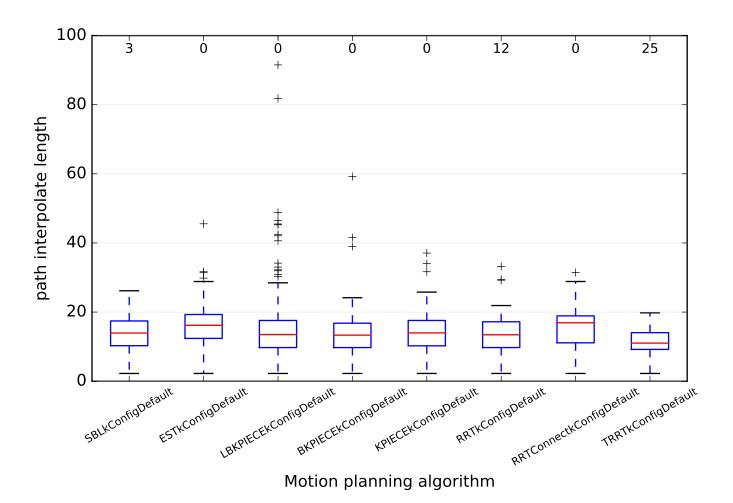
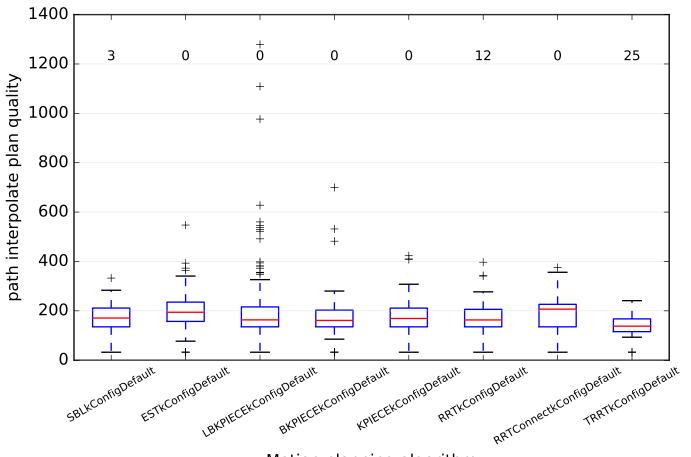
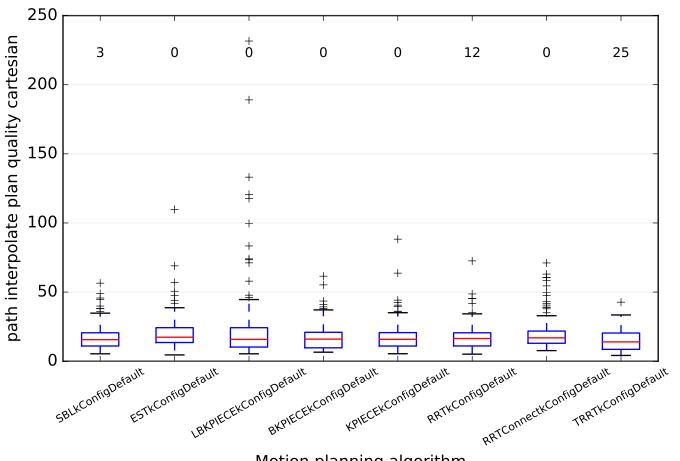


Motion planning algorithm

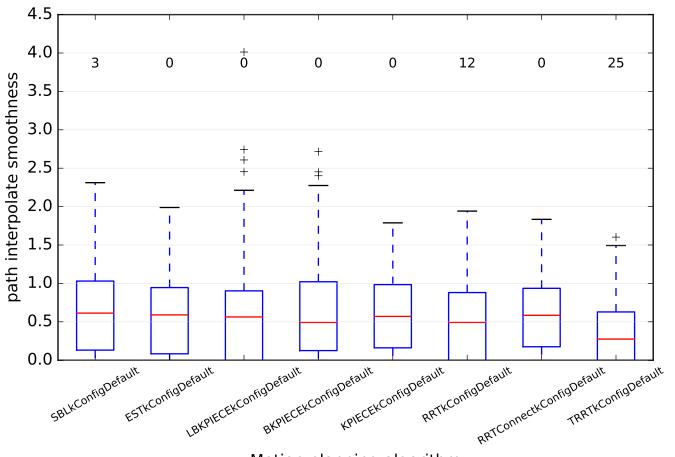




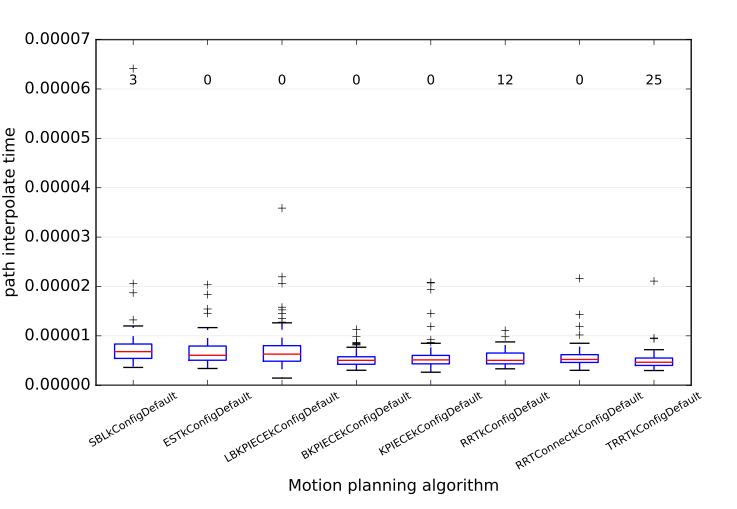
Motion planning algorithm

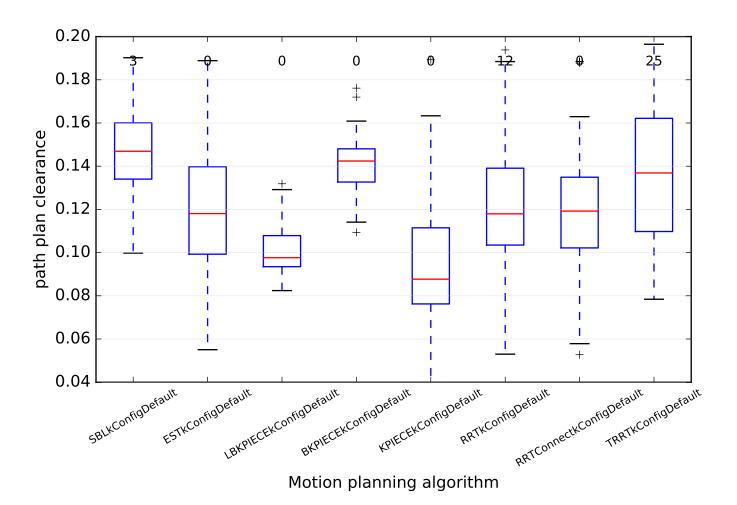


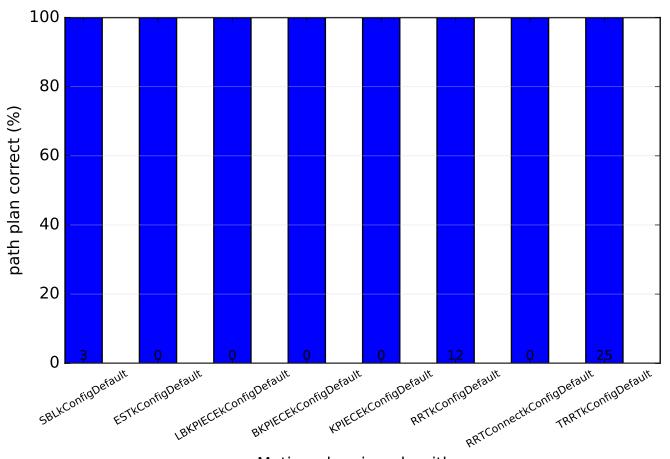
Motion planning algorithm



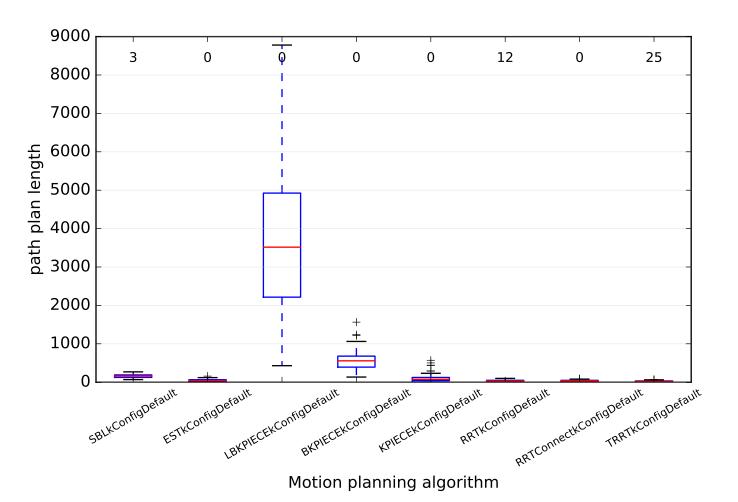
Motion planning algorithm

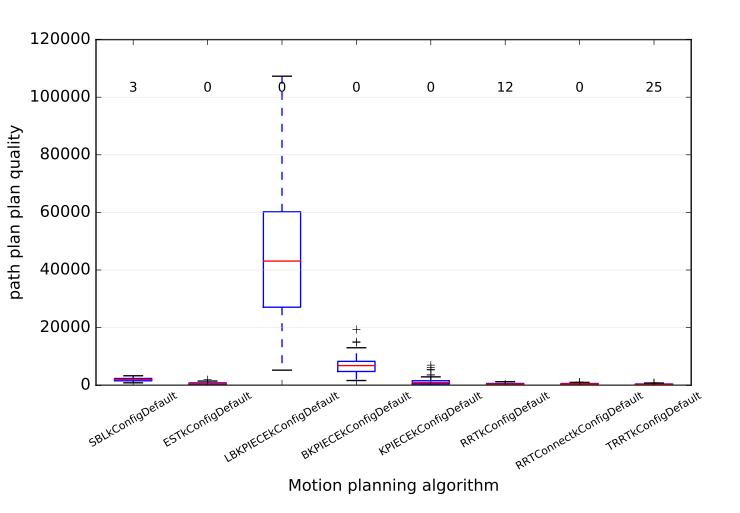


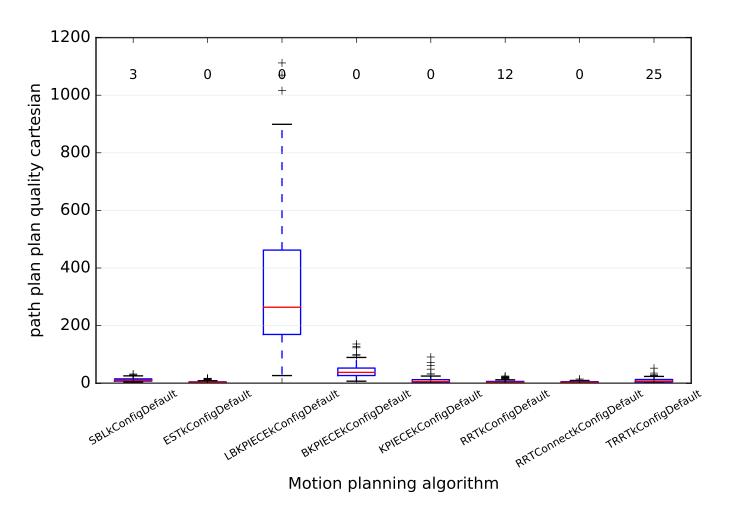


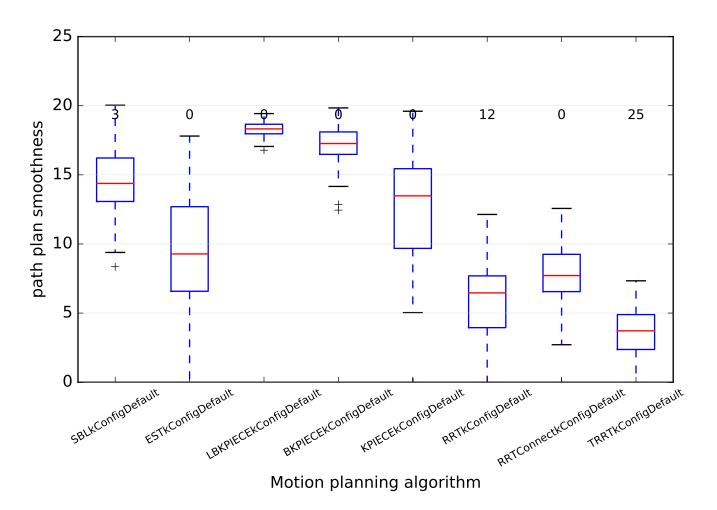


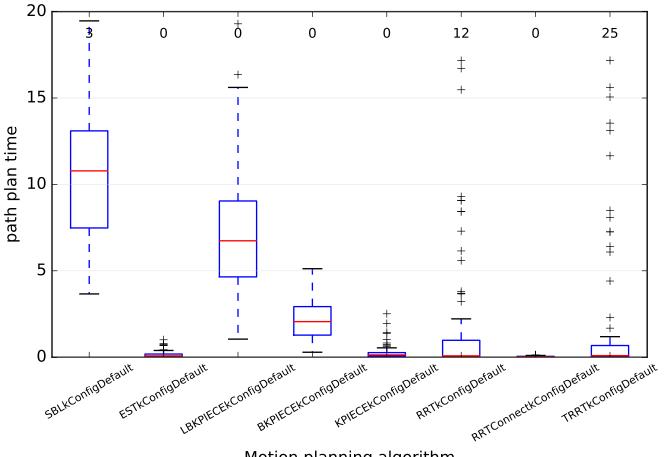
Motion planning algorithm



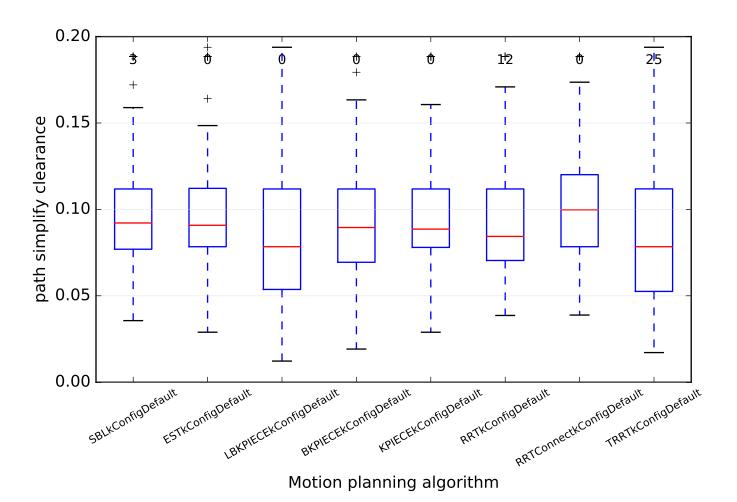


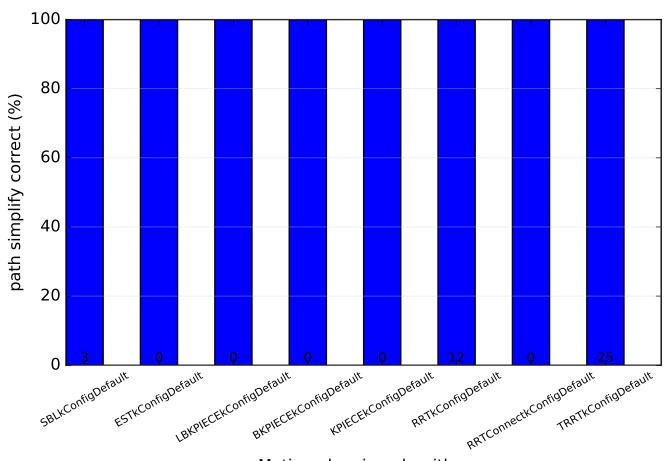




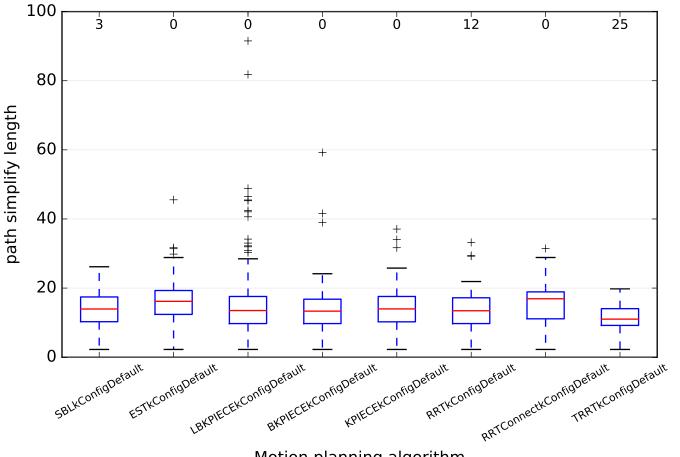


Motion planning algorithm

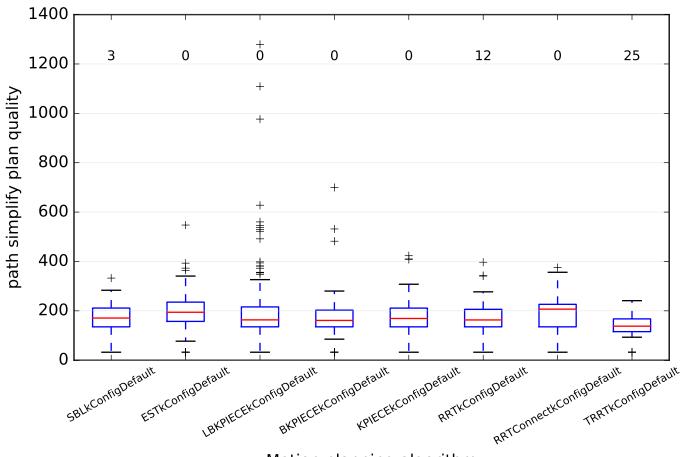




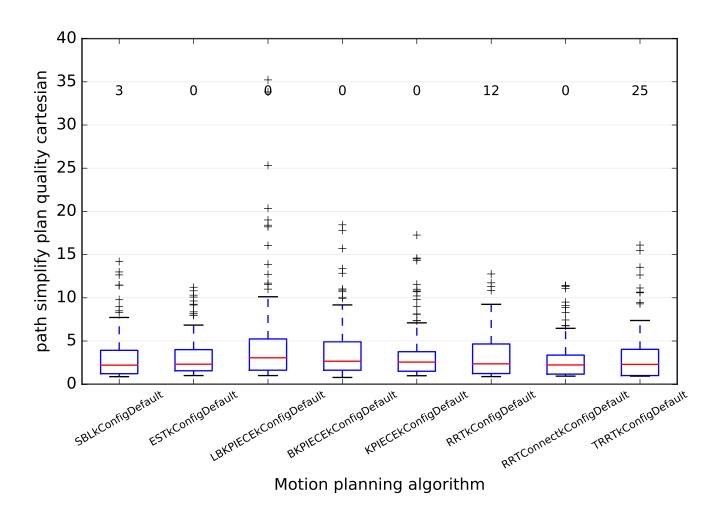
Motion planning algorithm

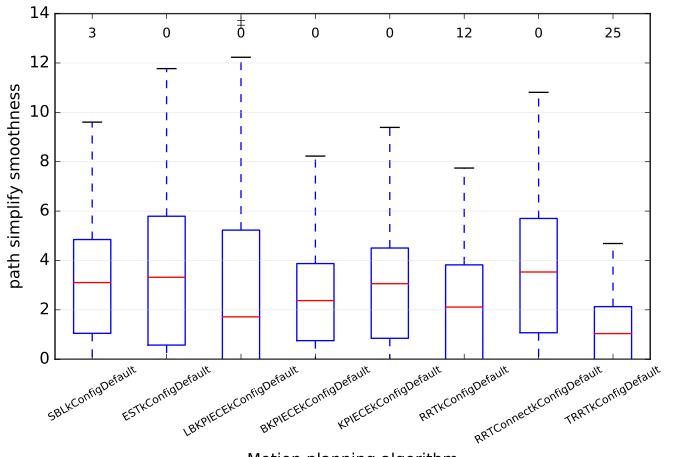


Motion planning algorithm

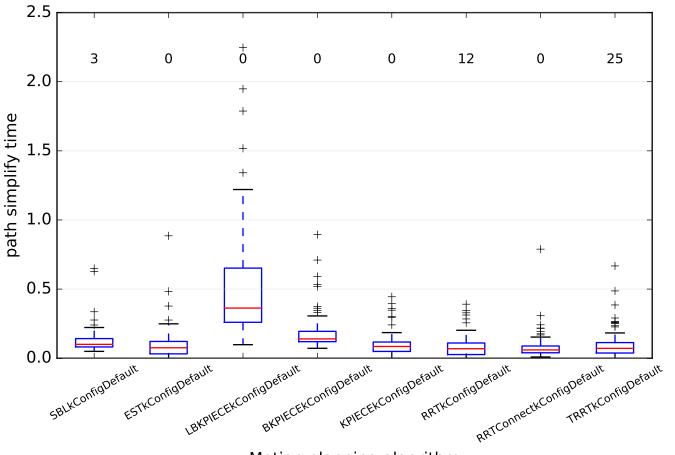


Motion planning algorithm

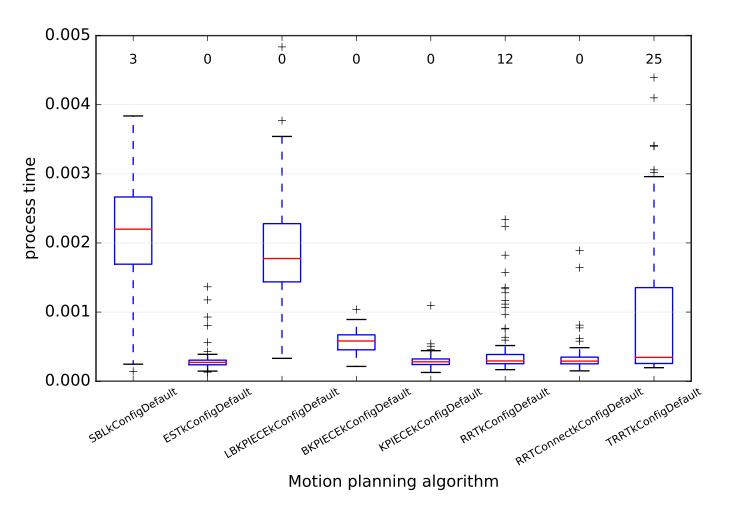


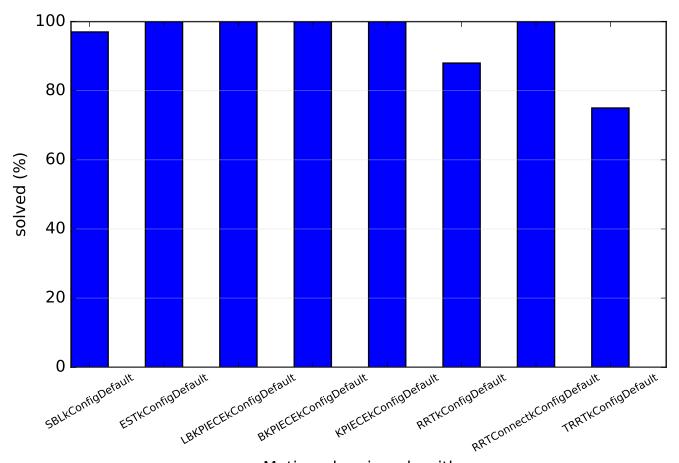


Motion planning algorithm

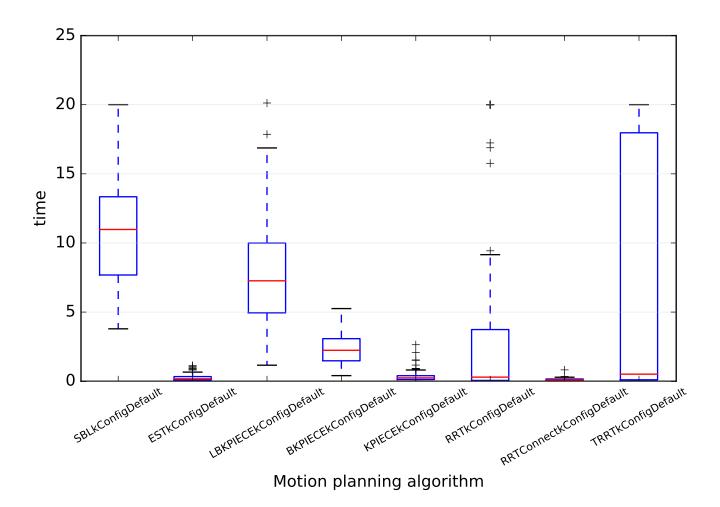


Motion planning algorithm





Motion planning algorithm



Experiment "Pose easy 1" Number of averaged runs: 10 Time limit per run: 20 seconds Memory limit per run: -1 MB Experiment "Pose hard 0" Time limit per run: 20 seconds

Number of averaged runs: 10

Memory limit per run: -1 MB

Experiment "Pose medium 0" Number of averaged runs: 10 Time limit per run: 20 seconds

Memory limit per run: -1 MB Experiment "Pose easy 0"

Number of averaged runs: 10 Time limit per run: 20 seconds Memory limit per run: -1 MB

Experiment "Pose medium 2"