Proposal

蔡昀達

王碩陽

Outline

- Motivation
- Air dispersion model
- Scenario
- Problem formulation
- Comparison
- Expected result
- Reference

Motivation

- Fukushima Daiichi nuclear disaster
 - Tōhoku earthquake and tsunami on 11 March
 2011
 - Radioactive material has been released from the Fukushima containment vessels.
 - Nuclear power plant has been destroyed, the power supply is constraint.
 - The radiation particle data (ex. iodine-131)
 distribution must to be report immediately to help
 the government determine the resident in which
 region should be migrated to the safety region.



Distribution of radioactive material

Satellite image of the nuclear power explosion



Human health care

- Daily amount of the radiation absorbed by human body is limited
- More real time of radiate active particles' report and more detailed distribution map can help people to avoid from the impact of radiation

Wireless Sensor Network

- With the low cost wireless sensor, we could spread the sensor node broadly and construct a higher resolution map, which could help us get more useful information to make decision.
- Resource issue(ex. low power supply) can always exist in this kind of application.

The correlation between data

- With consideration of correlation between data, we may reserve the radio resource but achieve the same requirement of data accuracy.
- We can design a scheduling mechanism to choose a set of sensor with lower correlation to prevent the redundancy in data acquisition.

Air dispersion model

 The Ermak solution, describe the heavy particles behavior.

$$c(x, y, z) = \frac{Q}{4\pi u r} \exp\left(-\frac{y^2}{4r}\right) \exp\left(-\frac{w_{set}(z - H)}{2K} - \frac{w_{set}^2 r}{4K^2}\right)$$

$$\times \left[\exp\left(-\frac{(z - H)^2}{4r}\right) + \exp\left(-\frac{(z + H)^2}{4r}\right) - \frac{2w_0\sqrt{\pi r}}{K} \exp\left(\frac{w_0(z + H)}{K} + \frac{w_0^2 r}{K^2}\right) erfc\left(\frac{z + H}{2\sqrt{r}} + \frac{w_0\sqrt{r}}{K}\right)\right]$$

Scenario

- We choose single source and is located at (0, X, H), cluster head is located at (0,0,0)
- The wind direction and speed is fixed.
- The emission rate is a Gaussian random process.

Problem formulation

 Given the requirement of MSE, we can calculate the entropy H.

$$H \geq \frac{1}{2} \log_2 \left(\frac{\left| \Sigma_{v} \right|}{\left(MSE \right)^N} \right)$$

 Then, if the accuracy must meet the requirement, the total entropy is constraint.
 And we want to minimize the total transmission time.

$$\min_{S \subseteq V} \sum_{t_i \in S} t_i , t_i = \frac{H(x_i)}{w \log_2 \left(1 + \frac{G_i P_i}{W N_0}\right)}$$
subject to $h(x_s) \ge \frac{1}{2} \log_2 \left(\frac{\left|\Sigma_v\right|}{\left(MSE\right)^N}\right)$

$$\Rightarrow h(x_s) = \frac{1}{2} \log_2 \left[\left(2\pi e\right)^{|S|} \det\left(\Sigma_s\right)\right] - \left|S\left|\log \Delta\right|$$

$$= \frac{1}{2} \log_2 \left[\left(\frac{2\pi e}{\Delta^2}\right) \det\left(\Sigma_s\right)\right] \ge \frac{1}{2} \log_2 \left(\frac{\left|\Sigma_v\right|}{\left(MSE\right)^N}\right)$$

 Given the simulate value as the known, we can find the minimized MSE theoretically.

$$\min_{S \subseteq V} \sum_{t_i \in S} t_i, \quad t_i = \frac{H(x_i)}{w \log_2 \left(1 + \frac{G_i P_i}{W N_0}\right)}$$

Subject to

Estimate value - exact value

Estimate value on discard sensors

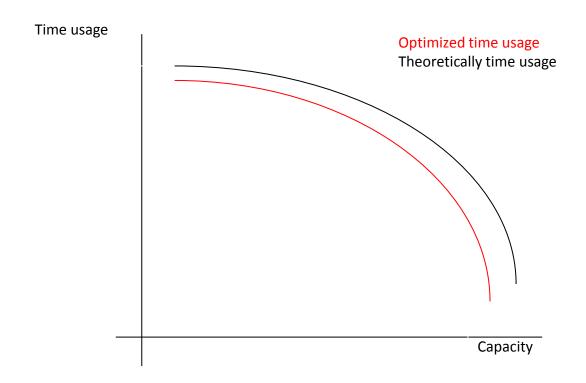
 $= Q \times \text{remain terms of } Ermak \text{ solution}$

Q can be estimated by the chosen sensors

Comparison

- If we do not consider the correlation between the sensors, in order to meet the same requirement of the data accuracy all the sensors need to report their data.
- We can the compare the time usage between these two kind of mechanism.

Expected result



- Reference
- [1] http://fukushima-radioactivity.jp/
- [2] http://people.math.sfu.ca/~stockie/atmos/