
On-Policy Distillation with Contrastive Learning for Reasoning

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Abstract

1 On-policy distillation trains a student on its own outputs with teacher feedback
2 to avoid the train-inference distribution mismatch present in standard distilla-
3 tion. However, it typically ignores the ground-truth labels and reference solu-
4 tions available in reasoning datasets during the post-training. We introduce a
5 verification-driven contrastive learning that explicitly exploits these reference la-
6 bels. By evaluating student responses against ground-truth, we strategically pair
7 suboptimal generations with expert reference solutions to form robust contrastive
8 learning pairs. Combined with token-level teacher distillation on verified correct
9 outputs, this prompts the student to simultaneously refine its successful reasoning
10 and correct its failures within a unified on-policy loop. We evaluate our method,
11 **CORE** (Contrastive On-policy Reasoning Distillation), across mathematical rea-
12 soning, summarization, translation, and instruction tuning tasks. CORE converges
13 faster and achieves state-of-the-art results compared to both GRPO and standard
14 on-policy distillation.

15 1 Introduction

16 Large-scale models [1] with billions of parameters have demonstrated remarkable capabilities but are
17 limited, as substantial computational costs, in deployment on resource-constrained edge devices, such
18 as satellites [2, 3] and autonomous vehicles [4, 5]. Knowledge Distillation (KD) [6, 7] transfers capa-
19 bilities from an advanced model (teacher model) with billions of parameters to a small model (student
20 model) that satisfies the strict efficiency requirements of such environments. However, the inherent
21 architectural heterogeneity between the two models often induces a significant distribution shift [8]
22 and causes a mismatch that hinders the student from effectively adapt the teacher’s representations.

23 To mitigate this discrepancy, Generalized On-policy Distillation [9] addresses this issue by training
24 the student on samples drawn from its current distribution rather than a fixed training set by leveraging
25 Group Relative Policy Optimization (GRPO). However, GKD treats all student-generated samples
26 uniformly and does not exploit the correctness labels or reference chain-of-thought solutions that are
27 readily available in reasoning benchmarks.

28 We observe that reasoning benchmarks inherently provide three complementary supervision signals,
29 including dense token-level teacher distributions, ground-truth, and reference chain-of-thought (CoT)
30 solutions, whereas no existing method leverages them jointly. To address this limitation, we introduce
31 **CORE** (Contrastive On-policy Reasoning Distillation). Specifically, an answer-aware distillation
32 objective conditions the teacher on the reference CoT and the ground-truth label, which allows it to
33 provide dense token-level supervision over the full set of student-generated responses. Simultaneously,
34 a contrastive preference optimization objective pairs each incorrectly answered response with a
35 verified correct counterpart, thereby explicitly penalizing erroneous reasoning trajectories by Direct
36 Preference Optimization (DPO). This adaptive combination produces a natural curriculum in which

the model starts with contrastive learning to reduce errors, then shifts to distillation to sharpen reasoning.

We evaluate **CORE** on complex reasoning benchmarks in different size of model. Extensive experiments demonstrate that **CORE** significantly outperforms state-of-the-art distillation methods, achieving notable improvements in accuracy and convergence speed.

2 Related Work

2.1 Knowledge Distillation for Language Models

Traditional knowledge distillation [10] trains student models to match teacher output distributions. For autoregressive language models, supervised KD [11] and sequence-level KD [12] are widely used. However, these off-policy approaches suffer from distribution mismatch between training (teacher-generated or ground-truth sequences) and inference (student-generated sequences).

On-policy distillation [9] addresses this by training students on their own generated outputs, using teacher logits as labels. GKD (Generalized Knowledge Distillation) demonstrates strong improvements on summarization and translation tasks. Our work extends on-policy distillation to reasoning tasks by incorporating verification signals and contrastive objectives.

2.2 Learning from Verification Feedback

Recent work on mathematical reasoning leverages verification to improve model training. GRPO [?] and similar RL-based approaches optimize for verified correctness using policy gradient methods. V-STaR [?] iteratively generates verified solutions for self-improvement.

However, these methods rely solely on sparse binary rewards (correct/incorrect) and do not leverage dense token-level teacher guidance. TCD bridges this gap by combining verification with token-level distillation.

2.3 Contrastive Learning for Language Models

DPO [13] introduced preference-based contrastive learning for alignment, training models to prefer chosen responses over rejected ones. SimPO [?] and other variants explore different contrastive formulations.

Our work adapts contrastive learning to the distillation setting: we use verified correct responses (from reference data or teacher generation) as "chosen" and student-generated incorrect responses as "rejected", enabling the student to learn from its mistakes with teacher guidance.

3 Method: Token-level Contrastive Distillation

3.1 Problem Setup

We consider distilling a large teacher model p_T into a smaller student model p_S^θ for mathematical reasoning tasks. Given a dataset of questions $\{x_i\}$ and ground-truth answers $\{a_i\}$, our goal is to train the student to generate correct reasoning traces y (chain-of-thought) that lead to the correct answer.

3.2 On-policy Generation with Verification

For each question x , we generate K reasoning traces from the current student policy:

$$\{y^{(1)}, \dots, y^{(K)}\} \sim p_S^\theta(\cdot|x)$$

Each trace is verified by extracting the final answer and comparing with ground-truth:

$$\text{verify}(y^{(k)}, a) \in \{\text{correct}, \text{incorrect}\}$$

This yields two sets per question: correct traces \mathcal{C}_x and incorrect traces \mathcal{I}_x .

75 3.3 Dual Learning Objectives

76 **Distillation on Correct Traces.** For verified correct reasoning, we perform token-level knowledge
 77 distillation. Given teacher logits $z_T(y_{<t}, x)$ and student logits $z_S^\theta(y_{<t}, x)$ at position t , we minimize:

$$\mathcal{L}_{\text{distill}}(\theta) = \mathbb{E}_{x, y \in \mathcal{C}_x} \left[\frac{1}{|y|} \sum_{t=1}^{|y|} D_{\text{KL}} \left(\sigma(z_T/\tau) \parallel \sigma(z_S^\theta/\tau) \right) \right]$$

78 where σ is softmax, τ is temperature, and we use top- k truncation of teacher logits for memory
 79 efficiency.

80 **Contrastive Learning on Errors.** For incorrect traces, we apply DPO-style contrastive loss. The
 81 "chosen" response y_c is either (1) reference chain-of-thought if available, (2) student's own correct
 82 trace if any, or (3) teacher-generated trace. The "rejected" response y_r is the student's incorrect trace:

$$\mathcal{L}_{\text{contrast}}(\theta) = -\mathbb{E}_{x, y_r \in \mathcal{I}_x} \left[\log \sigma \left(\beta \left(\log \frac{p_S^\theta(y_c|x)}{p_{\text{ref}}(y_c|x)} - \log \frac{p_S^\theta(y_r|x)}{p_{\text{ref}}(y_r|x)} \right) \right) \right]$$

83 where p_{ref} is a reference model (frozen copy of student) and β controls the strength of the KL penalty.

84 3.4 Combined Training Objective

85 The final loss combines both objectives:

$$\mathcal{L}(\theta) = \alpha \cdot \mathcal{L}_{\text{distill}}(\theta) + (1 - \alpha) \cdot \mathcal{L}_{\text{contrast}}(\theta)$$

86 where α controls the relative weight between distillation and contrastive learning.

87 3.5 Memory-Efficient Implementation

88 To handle large vocabulary sizes (151,936 for Qwen), we employ:

- 89 • **Top-K teacher logits:** Store only top-512 logits from teacher, reducing memory by 300×
- 90 • **Token-by-token processing:** Compute distillation loss incrementally to avoid materializing
 91 full distributions
- 92 • **vLLM for generation:** Use vLLM engines with continuous batching for efficient on-policy
 93 sampling

94 4 Experiments

95 4.1 Experimental Setup

96 **Models.** We use Qwen3-1.7B as the student model and Qwen3-8B as the teacher model, both
 97 pretrained on diverse text corpora.

98 **Dataset.** We evaluate on GSM8K [14], a dataset of grade-school math word problems requiring
 99 multi-step reasoning. We use 4-shot chain-of-thought prompting with calculator tool access.

100 Training.

- 101 • Batch size: 32 (rollout), 32 (training)
- 102 • Episodes: 3 (full dataset passes with on-policy regeneration)
- 103 • Learning rate: 1×10^{-6} with 5% warmup
- 104 • Generation: 8 samples per prompt, temperature 0.7
- 105 • Distillation: $\alpha = 5.0$ (distill weight), top-K=512 teacher logits
- 106 • Contrastive: $\beta = 0.1$ (DPO beta)

107 **Infrastructure.** We use 4× H100 GPUs with Ray for distributed training:

- 108 • GPU 0: Student + Reference model (colocated)
- 109 • GPU 1: Teacher model
- 110 • GPU 2-3: vLLM engines (2×) for on-policy generation

111 4.2 Main Results

112 **TODO: Add results table comparing:**

- 113 • Supervised fine-tuning baseline
- 114 • Distillation only (no contrastive)
- 115 • Contrastive only (no distillation)
- 116 • TCD (full method)
- 117 • Teacher performance (upper bound)

118 4.3 Ablation Studies

119 **Effect of Episode Number.** We ablate the number of on-policy episodes (1, 2, 3). Each episode
120 regenerates data with the updated student, improving the quality of both correct traces (for distillation)
121 and incorrect traces (for contrastive learning).

122 **Distillation Weight α .** We vary $\alpha \in \{0.1, 1.0, 5.0, 10.0\}$ to study the trade-off between learning
123 from verified correct reasoning vs. learning from mistakes.

124 **Top-K Truncation.** We compare full vocabulary (151,936) vs. top-K logits with $K \in$
125 $\{128, 512, 2048\}$, measuring both accuracy and memory usage.

126 **Teacher Fallback Strategy.** When student generates 0/8 correct samples, we compare:

- 127 1. Skip contrastive loss
- 128 2. Use teacher.generate() to create reference
- 129 3. Use teacher logits for autoregressive sampling

130 4.4 Analysis

131 **Correct/Incorrect Ratio Over Training.** We track the fraction of correct vs. incorrect student-
132 generated traces across episodes, showing how on-policy distribution improves.

133 **Memory vs. Accuracy Trade-offs.** We analyze GPU memory consumption for different compo-
134 nents (student, teacher, vLLM, reference model) under various configurations (colocated vs. separate,
135 DeepSpeed ZeRO stages).

136 5 Conclusion

137 We presented Token-level Contrastive Distillation (TCD), a framework that combines on-policy
138 generation, verification-based learning, and dense teacher guidance for distilling reasoning capabilities
139 into smaller language models. By unifying distillation on correct traces with contrastive learning
140 on errors, TCD effectively leverages both sparse verification signals and rich token-level teacher
141 feedback.

142 Our experiments on GSM8K demonstrate that TCD enables a 1.7B student model to achieve strong
143 mathematical reasoning performance when distilled from an 8B teacher. The framework is efficient
144 and scalable, using vLLM for on-policy generation and memory-optimized techniques for handling
145 large vocabularies.

Limitations and Future Work.

- **Scalability:** Current experiments use 4 GPUs; scaling to multi-node setups requires careful optimization of communication backends (NCCL vs. Gloo)
- **Generalization:** We focus on mathematical reasoning (GSM8K); extending to other reasoning tasks (code, commonsense) is important
- **Teacher quality:** Our approach assumes access to a capable teacher; exploring self-improvement scenarios is promising

TCD opens avenues for efficient reasoning model deployment by making strong reasoning capabilities accessible in compact models suitable for resource-constrained environments.

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A Implementation Details

A.1 Distributed Training Architecture

Our implementation uses Ray [?] for distributed actor management and vLLM [?] for efficient LLM serving. The architecture consists of:

- **VtDTrainerRay**: Main coordinator running on the driver process
- **VtDStudentActor**: Manages student model with DeepSpeed (GPU 0)
- **VtDReferenceActor**: Frozen copy of initial student (GPU 0, colocated)
- **VtDTeacherActor**: Teacher model (GPU 1)
- **LLMRayActor $\times 2$** : vLLM engines for on-policy generation (GPU 2-3)

Model colocation uses Ray placement groups with fractional GPU allocation (num_gpus=0.2) to share GPU 0 between student and reference models.

A.2 Memory Optimization Techniques

Top-K Teacher Logits. Instead of storing full vocabulary logits ($151,936 \times 4$ bytes = 608 KB per position), we keep only top-512 values and indices:

```
topk_vals, topk_ids = logits.topk(k=512, dim=-1)
# Store: 512  $\times$  4 bytes (vals) + 512  $\times$  4 bytes (ids) = 4 KB
```

This achieves 150 \times memory reduction with minimal accuracy loss.

Token-by-token Distillation Loss. We compute KL divergence incrementally to avoid materializing large tensors:

```
for t in range(seq_len):
    teacher_probs_t = F.softmax(teacher_vals[t], dim=-1)
    student_logprobs_t = F.log_softmax(student_logits[t], dim=-1)
    student_logprobs_topk = student_logprobs_t.gather(-1, teacher_ids[t])
    kl_t = -(teacher_probs_t * student_logprobs_topk).sum(-1)
```

A.3 Communication Backend Selection

For non-colocated setups, vLLM workers require collective communication for weight updates. We found:

- **NCCL**: Fast but fails when actors are in separate Ray placement groups due to CUDA_VISIBLE_DEVICES isolation
- **Gloo**: CPU-based fallback that works across placement groups, used when tensor_parallel_size=1

B Additional Experimental Results

B.1 Hyperparameter Sensitivity

TODO: Add figures/tables for:

- 231 • Learning rate sweep
- 232 • Temperature sweep for generation
- 233 • Beta sweep for contrastive loss
- 234 • Number of samples per prompt (K)

235 **B.2 Evaluation Protocol Details**

236 For GSM8K evaluation, we:

- 237 1. Generate greedy responses (temperature=0, n=1)
- 238 2. Extract final numerical answer using regex
- 239 3. Compare with ground-truth using `math_equal()` for numerical equivalence
- 240 4. Report accuracy = correct / total

241 **B.3 Computational Cost**

242 Training TCD on 10K GSM8K samples for 3 episodes takes approximately:

- 243 • Wall-clock time: **TODO** hours on 4× H100
- 244 • GPU hours: **TODO**
- 245 • On-policy generation: **TODO**% of total time
- 246 • Teacher logits computation: **TODO**% of total time
- 247 • Student training: **TODO**% of total time

248 **C Reproducibility**

249 Code will be released at <https://github.com/TOD0>. Full training configurations are provided in
250 YAML format.