GEOMETRY OF ARITHMETIC EXPRESSIONS: I. BASIC CONCEPTS AND UNSOLVED PROBLEMS (DRAFT)

Mingli Yuan
AI Lab
ColorfulClouds Tech.
Beijing, 100083
`mingli.yuan@gmail.com`

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ABSTRACT

TODO

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Contents

1 Introduction

Can arithmetic expressions form a geometric space? In this paper, we present several examples of arithmetic expression spaces and examine their properties.

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2 Basic concepts

2.1 Arithmetic expression

In order to define arithmetic expressions involving real numbers $\mathbb{R}$ in a rigorous way, we need to use a sophisticated type theory. However, in order to keep things simple and maintain clarity, we will start by using only production rules, but with certain semantic restrictions. We will also begin with rational numbers $\mathbb{Q}$ to avoid the difficulties inside real numbers $\mathbb{R}$.

Definition 2.1. *An arithmetic expression a over $\mathbb{Q}$ is a structure given by the following production rules:*

$$
\begin{aligned}
a &\longleftarrow x \\
a &\longleftarrow (a + a) \\
a &\longleftarrow (a - a) \\
a &\longleftarrow (a \times a) \\
a &\longleftarrow (a \div a)
\end{aligned}
\tag{1}
$$

where $x \in \mathbb{Q}$, and we denote this as $a \in \mathbb{E}\left[\mathbb{Q}\right]$.

During the production process, we can obtain both a string representation and a tree representation of arithmetic expression a, where the two representations are equivalent. For instance, the string representation of a might be:

$$
(((((1 \times 2) \times 2) - 1) \times (2 + 1)) - 6)
\tag{2}
$$

and the parsed syntax tree is depicted in Figure 1.

Figure 1: a tree representation of an arithmetic expression

If we interpret the target as a string and the building processes in production rule (1) as string building, we get the *string representation*. On the other hand, if the target is a tree, tree building leads to the *tree representation*. We can easily obtain the string representation of a from its tree representation by performing a pre-order traversal.

The concept of a *sub-expression* can also be derived from the concept of a subtree. The branch nodes are all labeled with operators: $+, -, \times, \div$. The leaf nodes are all labeled with numbers.

Evaluation ν is a partial function that operates on arithmetic expression $a \in \mathbb{E}\left[\mathbb{Q}\right]$. It is undefined only if division by zero occurs during the recursive evaluation process.

We can define evaluation $\nu(a)$ of a recursively as follows:

- Constant leaf: for any $x \in \mathbb{Q}$, $\nu(x) = x$.
- Compositional node by $+$: For any $(a + b)$, $\nu((a + b)) = \nu(a) + \nu(b)$.
- Compositional node by $-$: For any $(a - b)$, $\nu((a - b)) = \nu(a) - \nu(b)$.
- Compositional node by $\times$: For any $(a \times b)$, $\nu((a \times b)) = \nu(a)\nu(b)$.
- Compositional node by $\div$: For any $(a \div b)$, if $\nu(b) \neq 0$, then $\nu((a \div b)) = \nu(a)/\nu(b)$.

We say that an arithmetic expression a is *evaluable* if $\nu(a)$ is defined. In the rest of this article, we will only consider evaluable arithmetic expressions unless stated otherwise.

Given an arithmetic expression a, whatever evaluable or not, we can obtain its tree representation. If a node l is a leaf node, its corresponding subexpression s is a number, so we consider it to be already "evaluated". If a node b is a branch node, its corresponding subexpression s is an expression, and we can apply ν to it to obtain a number $\nu(s)$. During the recursive evaluation process, starting from the leaves and moving towards the root, the subexpressions are evaluated one after another. However, the order of evaluations is generally not unique.

Definition 2.2. *The evaluation order of an arithmetic expression a is an ordering of branch nodes in the tree representation of a such that every node (sub-expression) is evaluated before its parent.*

For example, the possible evaluation orders of the arithmetic expression in Figure 1 are:

- $1 \times 2 \to \underline{2}; \underline{2} \times 2 \to \underline{4}; \underline{4} - 1 \to \underline{3}; 2 + 1 \to \underline{3}; \underline{3} \times \underline{3} \to \underline{9}; \underline{9} - 6 \to 3$
- $1 \times 2 \to \underline{2}; \underline{2} \times 2 \to \underline{4}; 2 + 1 \to \underline{3}; \underline{4} - 1 \to \underline{3}; \underline{3} \times \underline{3} \to \underline{9}; \underline{9} - 6 \to 3$
- $1 \times 2 \to \underline{2}; 2 + 1 \to \underline{3}; \underline{2} \times 2 \to \underline{4}; \underline{4} - 1 \to \underline{3}; \underline{3} \times \underline{3} \to \underline{9}; \underline{9} - 6 \to 3$
- $2 + 1 \to \underline{3}; 1 \times 2 \to \underline{2}; \underline{2} \times 2 \to \underline{4}; \underline{4} - 1 \to \underline{3}; \underline{3} \times \underline{3} \to \underline{9}; \underline{9} - 6 \to 3$

The underlined numbers are the numbers that are evaluated during the evaluation process.

Below are examples of expressions that have a unique evaluation order. These include right-expanded, left-expanded, and combinations of them, as shown in Figure 2 and Figure 3.

Figure 2: right-expanded and left-expanded expressions

Figure 3: combinations of right-expanded and left-expanded expressions

The evaluation order of an arithmetic expression is related to the topological order of its tree representation, but they are not the same. The topological order of a tree is an ordering of nodes such that every node is visited before its parent[2]. However, we are only interested in the ordering of branch nodes, as leaf nodes have already been evaluated and can be ignored. Additionally, the topological order goes from parent to children, while the evaluation order goes from children to parent.

Definition 2.3. *A threadlike expression is an arithmetic expression that all the left nodes in its tree representation are leaf nodes.*

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So a threadlike expression is right-expanded and its evaluation order is unique. One example of threadlike expressions is shown on the left side of Figure 2.

Threadlike expressions are significant here because they are analogous to the concept of paths in homotopy theory in geometry. In a more general context, certain special types of threadlike expressions are also interesting: for example, *alternating threadlike expressions* are expressions in which the additional and multiplicative operators appear in an alternating manner. In the field of computing, a hardware component called *multiplier-accumulator* (MAC) unit has been implemented [5], which is a special case of an alternating threadlike expression. As a result, some numerical algorithms based on MAC units have been studied [3].

2.2 A scalar field and a mesh grid

Consider the upper half plane $\{\mathcal{H} : (x, y)|y > 0\}$ equipped with an inner product and metrics defined as follows:

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} a_x & a_y \end{bmatrix} \begin{bmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2 \ln^2 2} \end{bmatrix} \begin{bmatrix} b_x \\ b_y \end{bmatrix}$$

and

$$ds^2 = \frac{1}{y^2}(dx^2 + \frac{dy^2}{\ln^2 2})$$

We consider a scalar field satisfying

$$A = -\frac{x}{y} \tag{3}$$

We call this field an *assignment*.

Proper assignments allow us to establish a connection between paths in homotopy and threadlike arithmetic expressions, and to incorporate function theory into the study of arithmetic expression geometry.

Figure 4: An addition-multiplication grid by generators with $\mu = 1$ and $\lambda = \ln 2$

We can draw a grid on the scalar field A and underlying upper half plane $\mathcal{H}$ as shown in Figure 4. The blue lines encode a $+1$ relationship, the green lines encode a $\times 2$ relationship, and they are line families that are perpendicular to each other. The length of the line segments between two neighboring crossing points are unit length(calculations in

lemma 8.1). The red value at the crossing points is the value of the scalar field A at that point. Based on the relationships encoded by the lines, we can encode threadlike arithmetic expressions, which will be introduced in the subsection 2.3.

The addition-multiplication grid is also scale-invariant under the transformation

$$\begin{cases} x' = \alpha x \\ y' = \alpha y \end{cases}$$

where $\alpha = 2^k, k \in \mathbb{Z}$.

We can image if we make the grid finer and finer, the grid will become a continuous space. This leads to a rigorous treatment of arithmetic expressions as a geometric space in section 8.

2.3 Encoding threadlike expressions on the addition-multiplication grid

If we interpret the horizontal blue lines as $+1$ and the vertical green lines as $\times 2$ in Figure 4, we can encode threadlike expressions on the addition-multiplication grid. For example, in Figure 5 we encode $\big(((1 \times 4) - 1) \times 2) - 3\big)$ as the bold black lines.
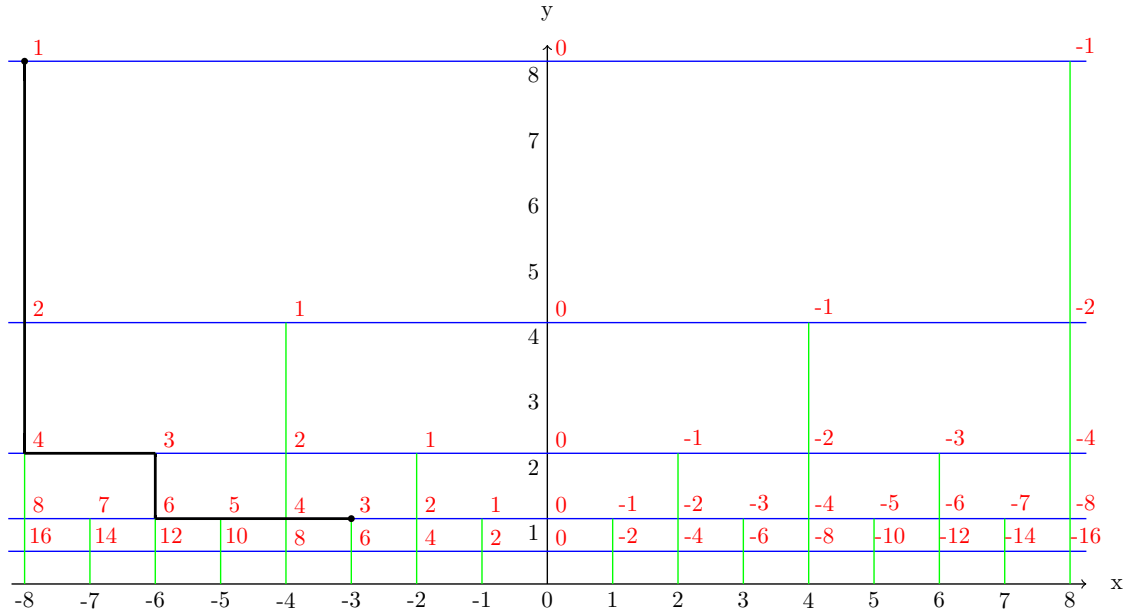
Figure 5: encoding threadlike expression

The zigzag lines in Figure 5 can be divided into four parts:

- the vertical line from 1 to 4: encoded as multiplication by 4
- the horizontal line from 4 to 3: encoded as subtraction by 1
- the vertical line from 3 to 6: encoded as multiplication by 2
- the horizontal line from 6 to 3: encoded as subtraction by 3

2.4 From a scalar field to a space of threadlike expressions

As shown in Figure 6, we have the following paths and expressions:

- the black path: $((1 \times 8) - 5) = 3$
- the purple path: $((1 - \frac{5}{8}) \times 8) = 3$

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- the brown path: $(((((((1 - \frac{1}{8}) \times 2) - \frac{1}{2}) \times 2) - 1) \times 2) = 3$
- the orange path: infinite many addition-multiplication terms accumulated together, a special kind of integration

Figure 6: different encodings and their canonical form

All of the paths in Figure 6 have the same source 1 and same target 3. We will discuss a canonical form for these paths.

It is easy to see that the expressions can be transformed into each other by using the multiplication distributive law and by combining and decomposing terms.

Conversion form brown path to black path

$$3 = ((((((1 - \frac{1}{8}) \times 2) - \frac{1}{2}) \times 2) - 1) \times 2) \tag{4}$$

$$= 1 \times 8 - \frac{1}{8} \times 8 - \frac{1}{2} \times 4 - 1 \times 2 \tag{5}$$

$$= ((1 \times 8) - 5) \tag{6}$$

Conversion form brown path to purple path

$$3 = ((((((1 - \frac{1}{8}) \times 2) - \frac{1}{2}) \times 2) - 1) \times 2) \tag{7}$$

$$= (1 - \frac{1}{8}) \times 8 - \frac{1}{2} \times 4 - 1 \times 2 \tag{8}$$

$$= (1 - \frac{1}{8}) \times 8 - \frac{1}{4} \times 8 - \frac{1}{4} \times 8 \tag{9}$$

$$= (1 - \frac{1}{8} - \frac{1}{4} - \frac{1}{4}) \times 8 \tag{10}$$

$$= ((1 - \frac{5}{8}) \times 8) \tag{11}$$

Therefore, we can define the black and purple paths in Figure 6 as a pair of canonical paths, which represent all threadlike expressions connecting the source 1 and the target 3.

Once we have such canonical paths, we can determine the canonical form of the whole space relative to an arbitrary source point O and any other target point P. This allows us to define the space as a space of threadlike expressions.

2.5 Currying and path notation

Currying is a basic technique in functional programming[6], which is used to transform a function with multiple arguments into a sequence of functions with one argument. By currying a threadlike arithmetic expression, we can obtain a sequence of functions that operate on an operand, which is the leftmost leaf node.

We introduce the following notation for currying a threadlike arithmetic expression:

- initial operand: the leftmost leaf node
- operator: $\oplus_y : x \mapsto x + y$
- operator: $\ominus_y : x \mapsto x - y$
- operator: $\otimes_y : x \mapsto x \cdot e^y$
- operator: $\oslash_y : x \mapsto x \cdot e^{-y}$

For example, the threadlike arithmetic expression $(((((1 \times 2) \times 2) + 1) \times 3) + 6)$ can be curried as

$$\oplus_6(\otimes_{\ln 3}(\oplus_1(\otimes_{\ln 2}(\otimes_{\ln 2}(1)))))$$

Suppose we have a series of operators $a_1, a_2, \cdots a_{n-1}, a_n$, we introduce a *path notation*.

$$xa_1a_2\cdots a_{n-1}a_n := a\_n(a_{n-1}(\cdots a_2(a_1(x))\cdots))$$

So, the above example can be written as

$$1 \otimes_{\ln 2} \otimes_{\ln 2} \oplus_1 \otimes_{\ln 3}\oplus_6$$

If a path begins with a number, we refer to it as a *bounded path*. If it does not, we refer to it as a *free path*, similar to the concept of vectors from the origin versus vectors at arbitrary points. a bounded path results in a number, while a free path results in a function.

Now we will verify that the operators within a path are associative.

Lemma 2.1. *The operators within a path are associative, i.e. we have*

$$a[bc] = [ab]c$$

Proof. We use normal typeface to express the path notation, and bold typeface to express the function notation.

For a free path, follow the definition, we have

$$a[bc] = [bc](\mathbf{a}) = \mathbf{c}(\mathbf{b}(\mathbf{a}))$$
$$[ab]c = \mathbf{c}([ab]) = \mathbf{c}(\mathbf{b}(\mathbf{a}))$$

hence, we have
$$a[bc] = [ab]c$$
is hold for a free path.

For a bounded path, we have
$$xa[bc] = [bc](\mathbf{a}(x)) = \mathbf{c}(\mathbf{b}(\mathbf{a}(x)))$$
$$x[ab]c = \mathbf{c}([ab](x)) = \mathbf{c}(\mathbf{b}(\mathbf{a}(x)))$$

hence, we have
$$a[bc] = [ab]c$$
is hold for a bounded path.

$\square$

Definition 2.4. *The concatenation of paths $p_1 \cdot p_2$ is defined as the composite of functions:*

$$p_1 \cdot p_2 := p_2 \circ p_1$$

When a sequence of paths is concatenated, and only the first path can be bounded. If the first path is bounded, the concatenated result is a bounded path. Otherwise, the concatenated result is a free path.

2.6 Alternating threadlike expressions

Now we can define alternating threadlike expressions, which were mentioned in Section 2.1, using the path notion.

$$\alpha = a_1 b_1 a_2 b_2 \cdots a_l b_l, a_i = \otimes_{\lambda_i}, b_i = \oplus_{\mu_i}, \lambda_i, \mu_i \in \mathbb{R} \tag{12}$$

where $\oplus$ and $\otimes$ denote addition and multiplication, respectively, and the expression is a zigzag of alternating addition and multiplication operations. α is a free path, and we can bind a number to it.

Since 0 is the identity element for addition and 1 is the identity element for multiplication, it is straightforward to see that any arithmetic expression can be converted into an alternating threadlike expression by introducing more 0 and 1 into the original expression. So alternating threadlike expression is a kind of canonical form.

We can derive a formula for perturbations in alternating threadlike expressions.

Let us define the left-to-right accumulated sum of λ_i as $\check{\lambda}_i$, such that:

$$\check{\lambda}_i = \sum_{j=1}^{i} \lambda_j, \check{\lambda}_0 = 0 \tag{13}$$

Then we also have right-to-left accumulated sum of λ_i

$$\hat{\lambda}_i = \check{\lambda}_l - \check{\lambda}_{l-i}, \hat{\lambda}_0 = 0 \tag{14}$$

Expanding equation (12) using the distributive law and the above notion at point μ_0, we obtain:

$$\alpha(\mu_0) = e^{\lambda_l}(\cdots(e^{\lambda_2}(e^{\lambda_1}\mu_0 + \mu_1) + \mu_2)\cdots) + \mu_l \tag{15}$$

$$= e^{\hat{\lambda}_l}\mu_0 + e^{\hat{\lambda}_{l-1}}\mu_1 + e^{\hat{\lambda}_{l-2}}\mu_2 + \cdots + e^{\hat{\lambda}_1}\mu_{l-1} + e^{\hat{\lambda}_0}\mu_l \tag{16}$$

Next, at the starting point μ_0, we introduce a perturbation $\tilde{\mu}_0 = e^{\eta_0}\mu_0 + \epsilon_0$, where η_0 and ϵ_0 are the disturbance terms added by the summation and multiplication operations, respectively. Then, we have:

$$\alpha(\tilde{\mu}_0) = e^{\hat{\lambda}_l}(\tilde{\mu}_0) + e^{\hat{\lambda}_{l-1}}\mu_1 + e^{\hat{\lambda}_{l-2}}\mu_2 + \cdots + e^{\hat{\lambda}_1}\mu_{l-1} + e^{\hat{\lambda}_0}\mu_l \tag{17}$$

$$= \alpha(\mu_0) + e^{\hat{\lambda}_l}(\tilde{\mu}_0 - \mu_0) \tag{18}$$

As a result, purely from an arithmetic perspective, without the need for limits, we can derive the following meaningful ratio:

$$\frac{\alpha(\tilde{\mu}_0) - \alpha(\mu_0)}{\tilde{\mu}_0 - \mu_0} = e^{\hat{\lambda}_l} = e^{\check{\lambda}_l} \tag{19}$$

Now we extend this relationship from the starting point μ_0 to the entire process, we define the recursive formula

$$w_i = e^{\lambda_i} w_{i-1} + \mu_i, w_0 = 0$$

and then we have

$$\frac{\tilde{w}_i - w_i}{\tilde{\mu}_0 - \mu_0} = e^{\check{\lambda}_i}, i \in \{1, ..., l\} \tag{20}$$

So, we have

$$\tilde{w}_i - w_i = e^{\check{\lambda}_i}(\tilde{\mu}_0 - \mu_0)$$

and hence

$$\tilde{w}_i - w_i = e^{\lambda_i}(\tilde{w}_{i-1} - w_{i-1}) \tag{21}$$

That means the perturbation along the path is controlled by the multiplication terms of e^{λ_i}.

2.7 Generated structure, commutator and arithmetic torsion

In order to study mesh grids like the one described in subsection 2.2, we need to investigate the algebraic structure of the threadlike arithmetic expressions that are generated.

For real number $\mathbb{R}$ and elements $\mu, \lambda \in \mathbb{R}$, we consider all the arithmetical expressions that are freely generated from

- initial operand: 0
- operator: $\oplus_\mu : x \mapsto x + \mu$
- operator: $\ominus_\mu : x \mapsto x - \mu$
- operator: $\otimes_\lambda : x \mapsto x \cdot e^\lambda$
- operator: $\oslash_\lambda : x \mapsto x \cdot e^{-\lambda}$

We denote these expressions as $E(\mu, \lambda)$, where μ is the additional generator and e^λ is the multiplicative generator. In cases where the context is clear, we may omit μ and λ from the index. Our goal is not to study only a single $E(\mu, \lambda)$, but rather to use a family of $E(\mu, \lambda)$ to approach a continuous space.

Since $\oplus_\mu$ and $\ominus_\mu$ are mutually inverse operations, it follows that $\otimes_\lambda$ and $\oslash_\lambda$ are also mutually inverse. This means that $E(\mu, \lambda)$ forms a group. An intriguing observation is that the commutator of this group is not equal to identity generally, especially the commutator of the generators.

$$x \oplus_\mu \otimes_\lambda \ominus_\mu \oslash_\lambda - x = \mu(1 - e^{-\lambda}) \tag{22}$$
$$x \otimes_\lambda \oplus_\mu \oslash_\lambda \ominus_\mu - x = -\mu(1 - e^{-\lambda}) \tag{23}$$

Or equivlently, we define below error τ:

$$\tau = x \otimes_\lambda \oplus_\mu - x \oplus_\mu \otimes_\lambda = \mu(1 - e^\lambda) \tag{24}$$

These errors are constant, indicating a type of torsion in the generated group. And torsion τ is specifically referred to as the arithmetic torsion.

We will reveal that τ is related to the curvature of the surface in later sections.

2.8 Problems on equality, singularity, symmetries

From the perspective of computer science, it is useful to consider different levels of equality within freely generated structures.

- Literal equality: the finest level of equality, judged by the string representation of the expression
- Syntactical equality: equality under certain syntactical rules
  - When inverse operators exist, it forms a group
  - When the commutative and distributive laws exist, it can be considered an algebra
- Semantic equality: the coarsest level of equality, judged by the evaluation of the expression

Literal equality is the strictest level of equality, and two different threadlike expressions are considered equal only if their string representations are exactly the same. This level of equality may be too strict, as it may not be compatible with the evaluation of the expression. However, under literal equality, the generated structure is the most rich and provides the base textures that can be woven into a space.

Semantic equality is the least strict level of equality, and two different threadlike expressions are considered equal if they evaluate to the same number. This level of equality provides the total symmetrical resources of the space.

We can think of literal equality as the bottom and semantic equality as the top of a lattice, with syntactical equality being a compromise between the two extremes.

To end this introduction part of the paper, we present several problems and speculations that drives our research. These important problems arise from distance between syntactical and semantic structures.

Foundational problem: A careful reader may have noticed that the definition 2.1 is based on rational numbers $\mathbb{Q}$. Why can't we use real numbers $\mathbb{R}$ instead? The answer is that syntactically valid expressions may not be semantically valid. Dividing by zero can lead to invalid expressions, and the evaluation of the expression cannot be defined in this situation. Therefore, in real numbers, an expression may be syntactically valid but semantically not valid, and there is no algorithm that can decide whether an expression is semantically valid or not. How can we bridge this gap and provide a continuous geometry space? We will attempt to partially solve this problem in some special cases in section 8.

Singular point problem: We have a very strong intuition that semantically invalid expressions lead to singular points. The way we discussed in complex analysis may be borrowed here: essential singularities and poles.

Symmetry and classification problem: We conjecture that the equality lattice may not only play a role in the construction of a space, but also determine the symmetry of that space. We can imagine that, at certain levels of the lattice, we weave syntactically generated substructures into points to form a space, and the weaving process uses up some symmetrical resources, leaving the rest to form a symmetry on the space. The structure within the total symmetry may provide us with a systematic way of constructing spaces, and allow us to classify spaces based on their symmetries.

3 Flow equation and related notion study

3.1 Flow equation

Consider an infinitesimal generating process on a Riemannian surface M using two generators: one for an additional action μ and the other for a multiplicative action e^λ. These two generators are perpendicular. This generation process produces an assignment $A : M \to R$ over the surface.

For any point with an assignment a_0, if we consider a movement of distance ϵ in a direction with angle θ over a time period of δ, we can establish the following:

$$a_\delta = (a_0 + \mu\epsilon\cos\theta)e^{\lambda\epsilon\sin\theta}$$

or

$$a_\delta = a_0 e^{\lambda\epsilon\sin\theta} + \mu\epsilon\cos\theta$$

Both formula can be simplified to the same result:

$$a_\delta = a_0 + \epsilon(a_0\lambda\sin\theta + \mu\cos\theta)$$

Then, we have the following equation:

$$\frac{1}{\delta}(a_\delta - a_0) = \frac{\epsilon}{\delta}(\mu\cos\theta + x_0\lambda\sin\theta)$$

When both δ and ϵ are towards zero, we get da/dt, and hence

$$\frac{da}{dt} = u(\mu\cos\theta + a\lambda\sin\theta)$$

Or, we can change it to another form

$$\frac{da}{ds} = \mu\cos\theta + a\lambda\sin\theta \tag{25}$$

We name this equation (25) as the flow equation.

The left side of this equation is governed by the distance structure, while the right side is governed by the angle structure. This leads to below theorem.

Theorem 3.1. *Isometries keep the flow equation*(25)

Proof. An isometry keeps both the distance structure and the angle structure, so it keeps the flow equation. □

We can also get a direct formal solution of the flow equation (25)(details in Appendix A).

$$a = (a_0 + \frac{\mu}{\lambda}\cot\theta)e^{\lambda s\sin\theta} - \frac{\mu}{\lambda}\cot\theta \tag{26}$$

While the validity of this solution is still uncertain because we have not assumed any constraints on the local coordinate system, it is still a useful starting point for further investigation. For example, we can use this solution to derive (details in Appendix B) the relationship between assignments at different vertices in a cell of a mesh grid.

Assuming the assignment at the center point of a cell is a_0, we move in different directions and obtain the following assignments:

- $\theta = 0$: $a_s = a_0 + \mu s$
- $\theta = \frac{\pi}{2}$: $a_s = a_0 e^{\lambda s}$
- $\theta = \pi$: $a_s = a_0 - \mu s$

- $\theta = \frac{3\pi}{2}$: $a_s = a_0 e^{-\lambda s}$

This result is straightforward, but it demonstrates that the infinitesimal generating process is consistent with the discrete mesh grid.

3.2   The contour-gradient form of flow equation

It is easy to derive the contour equation in the local coordinate

$$\mu \cos\theta_c + a\lambda \sin\theta_c = 0 \tag{27}$$

then we have

$$\theta_c = -\arctan\frac{\mu}{a\lambda} \tag{28}$$

the contour and the gradient are perpendicular to each other

$$\theta_g = \pm\frac{\pi}{2} - \arctan\frac{\mu}{a\lambda} \tag{29}$$

then along θ_g we have

$$\frac{da}{ds} = \mu\cos(\pm\frac{\pi}{2} - \arctan\frac{\mu}{a\lambda}) + a\lambda\sin(\pm\frac{\pi}{2} - \arctan\frac{\mu}{a\lambda}) \tag{30}$$

$$\frac{da}{ds} = \pm\sqrt{\mu^2 + \lambda^2 a^2} \tag{31}$$

By introducing the right-hand rotation angle ϕ along the gradient direction, we can establish a local polar coordinate system based on the gradient and contour lines. Then the growth rate of a along the angle ϕ is

$$\frac{da}{ds} = \mu\cos(\frac{\pi}{2} - \arctan\frac{\mu}{a\lambda} + \phi) + a\lambda\sin(\frac{\pi}{2} - \arctan\frac{\mu}{a\lambda} + \phi) \tag{32}$$

And the simplified equation is

$$\frac{da}{ds} = \sqrt{\mu^2 + a^2\lambda^2}\cos\phi \tag{33}$$

or

$$\frac{da_\phi}{ds_\phi} = \sqrt{\mu^2 + a^2\lambda^2}\cos\phi \tag{34}$$

if we want to emphasize the path is along the angle ϕ.

The equation (33) is the flow equation in the contour-gradient coordinate system.

Equation (33) is solvable, and we get the relation between a and s:

$$\tanh(\lambda s\cos\phi - c) = \frac{\lambda a}{\sqrt{\mu^2 + \lambda^2 a^2}} \tag{35}$$

we can further simplify the equation to

$$a = \pm\frac{\mu}{\lambda}\sinh(\lambda s\cos\phi - c) \tag{36}$$

Under the initial condition $a = a_0$ when $s = 0$, we can get the following equation:

$$a = \frac{\mu}{\lambda} \sinh(\lambda s \cos \phi + \operatorname{arcsinh} \frac{a_0 \lambda}{\mu}) \tag{37}$$

or

$$a = -\frac{\mu}{\lambda} \sinh(\lambda s \cos \phi - \operatorname{arcsinh} \frac{a_0 \lambda}{\mu}) \tag{38}$$

In this coordinate system, the additional line and the multiplicative line are:

$$\phi = \arccos \frac{\mu}{\sqrt{\mu^2 + a^2 \lambda^2}} \tag{39}$$

$$\phi = \arcsin \frac{\mu}{\sqrt{\mu^2 + a^2 \lambda^2}} \tag{40}$$

3.3 Flow and function

In this section, we aim to present novel insight into functions. Namely, the treatment of functions as flows will be discussed.

Definition 3.1. *Given a function k on the real domain R, we can introduce a mapping l on the arithmetic expression space H such that the following diagram commutes.*

$$
\begin{array}{ccc}
H & \xrightarrow{\quad l \quad} & H \\
{\scriptstyle \nu}\downarrow & & \downarrow{\scriptstyle \nu} \\
R & \xrightarrow{\quad k \quad} & R
\end{array}
$$

where ν is the evaluation function of the expression. Then we call the mapping l is the promotion of the function k, or function k is the projection of the mapping l.

Giving the arithmetic expression space H, now we introduce the standard definition of flow by one-parameter group.

Definition 3.2. *a continuous group homomorphism*

Giving a function f on R, the arithmetic expression space H, we introduce a flow T on H.

Giving an arithmetic expression space as definition at the beginning of the section2.2, we will show examples of flows as functions.

3.3.1 Example 1: the flow of sine

Form the flow equation (25) we have

$$\frac{da}{ds} = \cos \theta + a \sin \theta$$

$$\frac{da}{dt} = (\cos \theta + a \sin \theta) \frac{ds}{dt}$$

And along the variation of t, we have $a(t) = \sin t$, so we have

$$\cos t = (\cos \theta + \sin t \sin \theta) \frac{ds}{dt}$$

$$\frac{ds}{dt} = \frac{\cos t}{\cos \theta + \sin t \sin \theta}$$

$$s = \csc\theta \ln(\cos\theta + \sin t \sin\theta) + C$$

$$e^{(s-C)\sin\theta} = \cos\theta + \sin t \sin\theta$$

Notice that $a(t) = \sin t$ and $a = -\frac{x}{y}$, we have

$$e^{(s-C)\sin\theta} = \cos\theta + \sin t \sin\theta$$

3.3.2 Example 2: Brachistochrone curve

The brachistochrone curve is the curve between two points that minimizes the time taken by a frictionless bead sliding along a wire. We assume the wire is a curve $\eta = f(\delta)$, and the bead starts at $(0,0)$ and ends at (Δ, H) as time t goes from 0 to T.

3.4 The existence theorems

There are two important existence theorems related to the flow equation (25).

The first existence theorem states that if we have a 2D Riemannian manifold M, then there exists a function a on M that satisfies the flow equation (25). This theorem is proved in a later section, and we will not go into the details of the proof here.

Theorem 3.2. *Given a 2D Riemannian manifold M, there exists a function a on M satisfying the flow equation* (25).

The second existence theorem is also crucial. It says that if we have a smooth surface S and a function a on S, then we can find a metric g on S that makes a satisfy the flow equation (25). We morph the metric g to make a satisfy the flow equation (25), this technique will be touched back and forth in the following sections.

Theorem 3.3. *(By Le Zhang) Given an oriented 2D Riemannian manifold S, and a function a over S, there exists a metric g on S that makes a satisfying the flow equation* (25).

Proof. The proof consists of two main steps. First, we demonstrate the existence of a metric g on S that allows a to satisfy the flow equation (25) in a local coordinate system. Then, we show that this local metric can be extended to a global metric on S.

Part 1: Local Perspective

Consider a point p on the surface S, and there is a neighborhood U around p. In this area, we can find a local isothermal coordinate system in which the metric takes the form:

$$ds^2 = e^{2\rho}(du^2 + dv^2),$$

where u and v are the coordinates of U, and ρ is a function of u, v in U. The gradient of a in this local isothermal coordinate system is expressed as:

$$\nabla a = \frac{\partial a}{\partial u}du + \frac{\partial a}{\partial v}dv.$$

Using the definition of the directional derivative, we obtain:

$$\frac{da_\psi}{ds_\psi} = ||\nabla a|| \cos\psi,$$

where $||\nabla a||$ is the norm of ∇a, and ψ is the angle between ∇a and the direction of movement.

Now, considering the flow equation 34 in the gradient-contour coordinate system, we have:

$$\frac{da_\phi}{ds_\phi} = \sqrt{\mu^2 + a^2\lambda^2}\cos\phi.$$

Note that $||\nabla a||$ is fixed for the given function a and the local coordinate system, and $\sqrt{\mu^2 + a^2\lambda^2}$ is also fixed for the given function a. We can scale $e^{2\rho}$ with a linear factor κ to make $||\nabla a||$ match the fixed value of $\sqrt{\mu^2 + a^2\lambda^2}$, thus we have a morphing process controlled by κ that

$$ds^2 = \kappa e^{2\rho}(du^2 + dv^2) \tag{41}$$

$$= e^{2\rho + \ln\kappa}(du^2 + dv^2). \tag{42}$$

Under the morphing ratio κ, we have:

$$||\nabla_\kappa a|| = \kappa^{-1}||\nabla a||, \tag{43}$$

and when κ is set to the value of:

$$||\nabla_\kappa a|| = \sqrt{\mu^2 + a^2\lambda^2},$$

the flow equation (25) is satisfied in the local coordinate system.

The morphing ratio κ is calculated as follows:

$$\kappa = \frac{||\nabla a||}{\sqrt{\mu^2 + a^2\lambda^2}}. \tag{44}$$

Part 2: Global Perspective

$\square$

3.5 Notion study

The flow equation (25) is taken in a local polar coordinate system,

$$\frac{da}{ds} = \mu\cos\theta + a\lambda\sin\theta$$

If we take $dx = \cos\theta ds$ and $dy = \sin\theta ds$, we can rewrite it as

$$da = \mu dx + a\lambda dy$$

$$a + da = (a + \mu dx)e^{\lambda dy}$$

$$a + da = (a + \mu dx)e^{\lambda dy}$$

$$\lfloor a \rfloor = \lceil \lfloor A \rfloor \rceil$$

4   The first kind arithmetic expression space $\mathfrak{K}_1$

In this section, we will present two analytic examples due to Le that are equivalent and belong to the class of spaces called the first kind arithmetic expression space $\mathfrak{K}_1$.

4.1   Example space I

Consider the upper half plane $\mathcal{H} : (x, y) \mid y > 0$ equipped with an inner product and metrics defined as follows:

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} a_x & a_y \end{bmatrix} \begin{bmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2} \end{bmatrix} [b_x \ b_y]$$

and

$$ds^2 = \frac{1}{y^2}(dx^2 + dy^2)$$

We also consider an assignment function A defined on $\mathcal{H}$ as follows[1]:

$$A = -\frac{x}{y} \tag{45}$$

Theorem 4.1. [2] *For the assignment A defined by above formula, A satisfy the flow equation*(25)

Proof.

$$da = d(-\frac{x}{y}) = \frac{xdy - ydx}{y^2} = -\frac{dx + ady}{y}$$

and

$$ds = \frac{\sqrt{dx^2 + dy^2}}{y}$$

then

$$\frac{da}{ds} = -\frac{dx + ady}{y}\frac{y}{\sqrt{dx^2 + dy^2}} = -\frac{dx + ady}{\sqrt{dx^2 + dy^2}}$$

Considering that the local coordinate is given by $(-1, 0)$ and $(0, -1)$ under the right-hand rule, we have:

$$\cos\theta = \frac{\begin{bmatrix} dx & dy \end{bmatrix} \begin{bmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2} \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}}{\sqrt{\begin{bmatrix} dx & dy \end{bmatrix} \begin{bmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2} \end{bmatrix} \begin{bmatrix} dx \\ dy \end{bmatrix}}\sqrt{\begin{bmatrix} -1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2} \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}}}$$

hence

$$\cos\theta = \frac{-dx}{\sqrt{dx^2 + dy^2}}$$

and similarly

---

[1]This analytic example is provided by Le Zhang, and the geometry interpretation is given by Mingli Yuan
[2]The proof is originally by Le Zhang, and modified by Mingli Yuan

$$\sin \theta = \frac{-dy}{\sqrt{dx^2 + dy^2}}$$

then

$$\frac{da}{ds} = \cos \theta + a \sin \theta$$

$\square$

We can verify A is an eigenfunction of the Laplacian

$$\Delta A = -y^2 \left(\frac{\partial^2}{\partial x^2} A + \frac{\partial^2}{\partial y^2} A \right) = y^2 \left(\frac{1}{\partial y} \left(\frac{1}{\partial y} \frac{x}{y} \right) \right) = 2A$$

4.2 A horocycle-based coordinate system

First, we introduce the horocycle-based coordinate system for hyperbolic surfaces. It is a global coordinate system given by two orthogonal sets of circles: one set consists of horocycles that share the same ideal point, while the other consists of geodesics that are perpendicular to the first set.

On the Poincaré disc $\mathcal{P}$, the blue horocycles are tangible at the ideal point Ω, forming the first set of circles. The green lines are geodesics that form the second set. The coordinates of point P are given by the lengths of OQ and QP, where point O is the origin and the length is measured using the metric of the hyperbolic surface.

The coordinates of P are (u, v), where the sign of the length is determined by the following rules:

- u: if P is on the same side of Ω, then u is positive; otherwise, u is negative
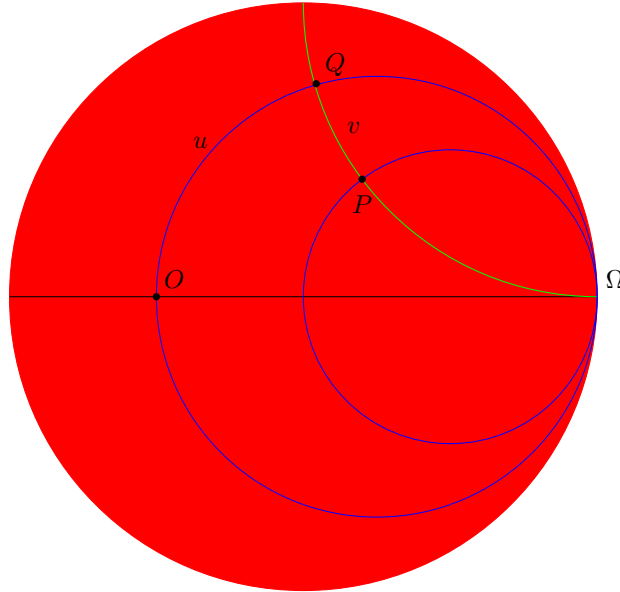- v: the sign of the length should satisfy the right-hand rule

Figure 7: A horocycle-based coordinate system

We can equip it with an inner product

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} a_u & a_v \end{bmatrix} \begin{bmatrix} e^{-2v} & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} b_u \\ b_v \end{bmatrix}$$

and the metrics

$$ds^2 = e^{-2v}du^2 + dv^2$$

Laplacian is given by[1]

$$\Delta = e^{2v}\frac{\partial^2}{\partial u^2} + \frac{\partial^2}{\partial v^2} - \frac{\partial}{\partial v}$$

4.3 Example space II

Giving the Poincaré disc $\mathcal{P}$ equipped with the above horocycle-based coordinate system, we consider an assignment function A defined on $\mathcal{P}$ as follows[3]:

$$A = ue^{-v} \tag{46}$$

Theorem 4.2. *For the assignment A defined by above formula, A satisfy the flow equation*(25)
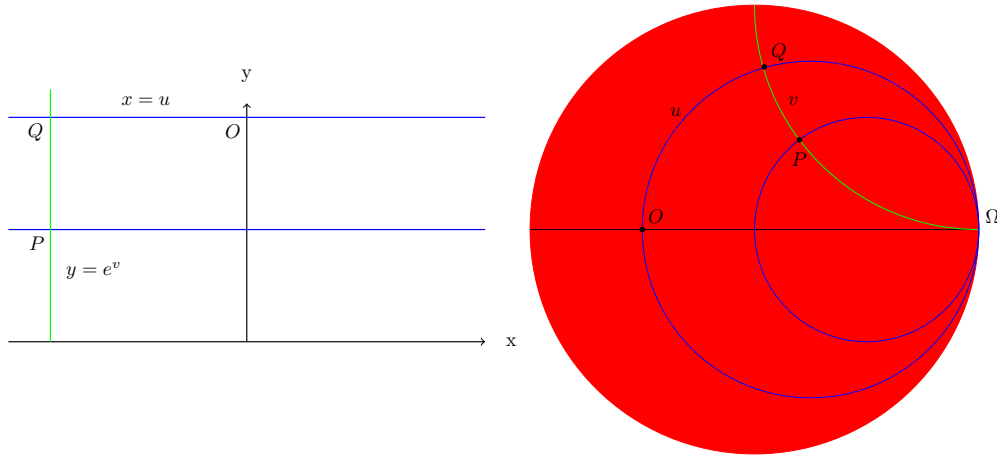

Figure 8: Mapping between two examples

Proof. If we introduce complex in the upper half plane model in last section 4.1

$$z = x + yi$$

and setup a Möbius transform between the upper half plane and current horocycle-based coordinate system:

$$z \mapsto \frac{z-i}{z+i}$$

This transform maps each horizontal lines in $\mathcal{H}$ into the horocycles sharing the same ideal point $\Omega = 1$ in $\mathcal{P}$, also it maps each vertical geodesics in $\mathcal{H}$ into geodesics in $\mathcal{P}$ which are perpendicular to the above horocycles.

And rewrite the Möbius transform in the target coordinate, we get:

$$\begin{cases} x = u \\ y = e^v \end{cases}$$

This lead to

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[3]This analytic example is provided by Le Zhang, and the geometry interpretation is given by Mingli Yuan

$$A = -\frac{x}{y} = ue^{-v}$$

And because of theorem 3.1 and Möbius transform is conformal, we can conclude that $A = ue^{-v}$ obey flow equation.

$\square$

We can verify A is also an eigenfunction of the Laplacian

$$\Delta A = e^{2v}\frac{\partial^2(ue^{-v})}{\partial u^2} + \frac{\partial^2(ue^{-v})}{\partial v^2} - \frac{\partial(ue^{-v})}{\partial v} = 2A$$

From the above proof, we can see that the two assignment function A arose from the same geometry setting, they are equivalent to each other.

4.4 Generator independence

Considering the upper half plane $\mathcal{B}$:

$$\{\mathcal{B} : (x,y)|y > 0\}$$

equipped with an inner product and metrics as follows:

$$\mathbf{a} \cdot \mathbf{b} = \begin{bmatrix} a_x & a_y \end{bmatrix} \begin{bmatrix} \frac{1}{\mu^2 y^2} & 0 \\ 0 & \frac{1}{\lambda^2 y^2} \end{bmatrix} \begin{bmatrix} b_x \\ b_y \end{bmatrix}$$

$$ds^2 = \frac{1}{y^2}\left(\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}\right)$$

Whatever the choice of μ and λ, the assignment is given by

$$A = -\frac{x}{y} \tag{47}$$

We can verify A satisfying the flow equation(25), and also it is generator independent.

Theorem 4.3. *The above A satisfying the flow equation*(25)

Proof.

$$da = d(-\frac{x}{y}) = \frac{xdy - ydx}{y^2} = -\frac{dx + ady}{y}$$

Notice that

$$ds = \frac{1}{y}\sqrt{\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}}$$

then

$$\frac{da}{ds} = -\frac{dx + ady}{y}\frac{y}{\sqrt{\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}}} = \frac{dx + ady}{\sqrt{\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}}}$$

Consider the local coordinate system given by $(-1, 0)$ and $(0, -1)$ according to the right-hand rule, we have

$$\cos\theta = \frac{\begin{bmatrix} dx & dy \end{bmatrix} \begin{bmatrix} \frac{1}{\mu^2 y^2} & 0 \\ 0 & \frac{1}{\lambda^2 y^2} \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}}{\sqrt{\begin{bmatrix} dx & dy \end{bmatrix} \begin{bmatrix} \frac{1}{\mu^2 y^2} & 0 \\ 0 & \frac{1}{\lambda^2 y^2} \end{bmatrix} \begin{bmatrix} dx \\ dy \end{bmatrix}}\sqrt{\begin{bmatrix} -1 & 0 \end{bmatrix} \begin{bmatrix} \frac{1}{\mu^2 y^2} & 0 \\ 0 & \frac{1}{\lambda^2 y^2} \end{bmatrix} \begin{bmatrix} -1 \\ 0 \end{bmatrix}}}$$

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Therefore we have

$$\cos\theta = \frac{-\frac{dx}{\mu}}{\sqrt{\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}}}$$

Similarly

$$\sin\theta = \frac{-\frac{dy}{\lambda}}{\sqrt{\frac{dx^2}{\mu^2} + \frac{dy^2}{\lambda^2}}}$$

Hence we have

$$\frac{da}{ds} = \mu\cos\theta + a\lambda\sin\theta$$

$\square$

4.5   Related problems

Eigenfunction problem: TODO.

Eigenfunction and classification problem: TODO.

5 Fundamental domains in $\mathfrak{K}_1$

In this section, we delve into an investigation of the fundamental domain within the space $\mathfrak{K}_1$. Our focus encompasses an examination of the discrete symmetry group and an exploration into the methodologies by which symmetry can be achieved through flow.

5.1 Fundamental domain in $\mathfrak{K}_1$

5.2 Discrete symmetry of $\mathfrak{K}_1$ and its flow realization

6 On order-4 apeirogonal tiling

6.1 Construction of order-4 apeirogonal tiling

6.2 Coloring and compatible coordinate

7 The second and third kind of arithmetic expression space $\mathfrak{K}_2$ and $\mathfrak{K}_3$

8 Topological arithmetic expression space

8.1 The construction of the grid G_0

To construct the grid described in subsection **??** and Figure 4, we will use the number theory decomposition introduced by Victor Pambuccian in [4] and Celia Schacht in [7].

$$n = \tau(n)\omega(n)$$

where $\tau(n)$ is a power of 2 and $\omega(n)$ is an odd.

We can see directly from the Figure 4 that the grid is constructed by the following rules:

- horizantal lines (blue, additional lines) satisfying $y = 2^k, k \in \mathbb{Z}$
- vertical lines (green, multiplicative lines) satisfying
  - the value of x satisfying $x = \frac{m}{2^l}, l \in \mathbb{Z}^+, m \in \mathbb{Z}$
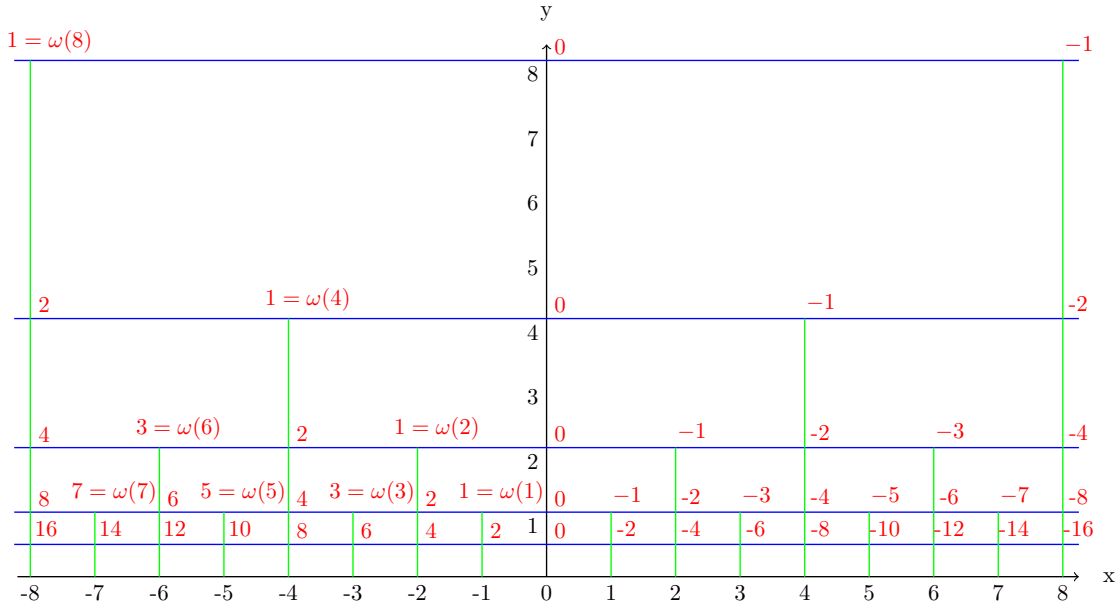 - the assignment begin from $\omega(-m)$ and increase exponentially by power 2.

Figure 9: ω gives the assignment at the start points of vertical lines in G_0

The horizontal lines and the vertical lines divide the whole space into a mesh grid $G_0 = (V_0, E_0, F_0)$, where V_0 is the set of crossing points, E_0 is the set of edges (segments in the horizontal and vertical lines, it should be noted that only the vertical lines are geodesics, while the horizontal lines are horocycles) connecting the crossing points, and F_0 is the set of cut cells. This mesh grid is generated by the additional generator 1 and the multiplicative generator 2, and V_0, E_0, and F_0 are all countable sets.

We illustrate the construction schema of G_0 in Figure 10.

We notice that G_0 is very regular, in fact, all edges are equidistant.

Lemma 8.1. *All edges in G_0 are equidistant.*

Proof. Following the construction schema in Figure 10, we can calculate the length of segments are all equidistant.

Length of AC and BD:

$$\int ds = \int\limits_{2^k}^{2^{k+1}} \frac{1}{y \ln 2} dy = \frac{1}{\ln 2} \left(\ln 2^{k+1} - \ln 2^k \right) = 1$$
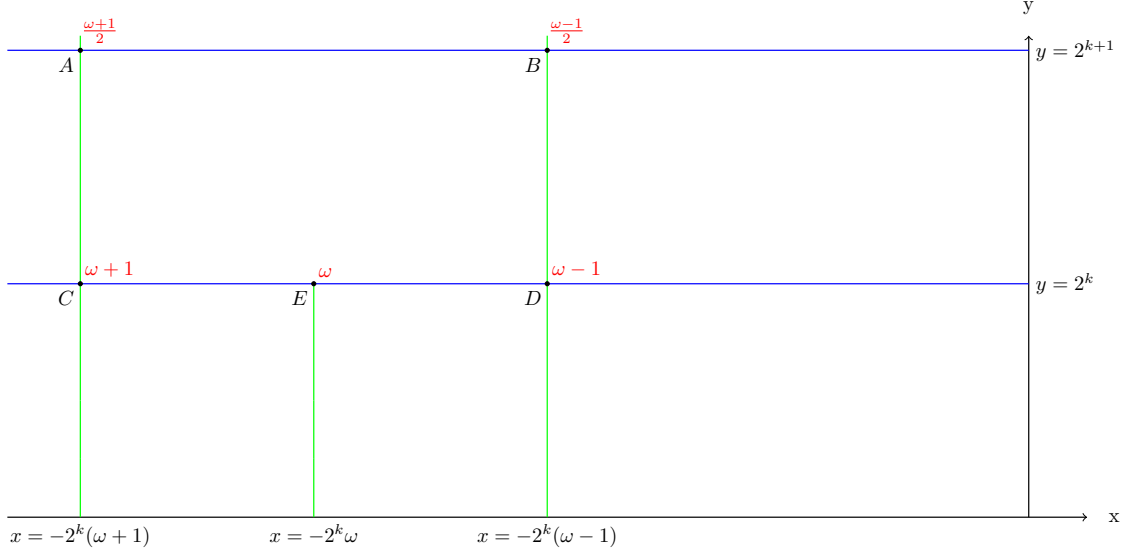
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Figure 10: the construction schema of G_0

Length of AB:

$$\int ds = \int_{-2^k(\omega+1)}^{-2^k(\omega-1)} \frac{1}{2^{k+1}}dx = \frac{1}{2^{k+1}}\left(2^{k+1}\right) = 1$$

Length of CE:

$$\int ds = \int_{-2^k(\omega+1)}^{-2^k\omega} \frac{1}{2^k}dx = \frac{1}{2^k}\left(2^k\right) = 1$$

Length of ED:

$$\int ds = \int_{-2^k\omega}^{-2^k(\omega-1)} \frac{1}{2^k}dx = \frac{1}{2^k}\left(2^k\right) = 1$$

□

8.2 The construction of the grid G_1

We can similarly construct the grid G_1 using the additional generator $\frac{1}{2}$ and the multiplicative generator $\sqrt{2}$, the grid G_2 using the additional generator $\frac{1}{4}$ and the multiplicative generator $\sqrt[4]{2}$, and so on. And each time the cell of the mesh grid is divided into smaller cells and the end points of the vertical lines move upward.

8.3 The construction of the grid G_2

8.4 The grid mesh is dense

It is easy to see that there is a chain of inclusion relations:

$$V_0 \subset V_1 \subset V_2 \subset \cdots V_i \subset \cdots$$

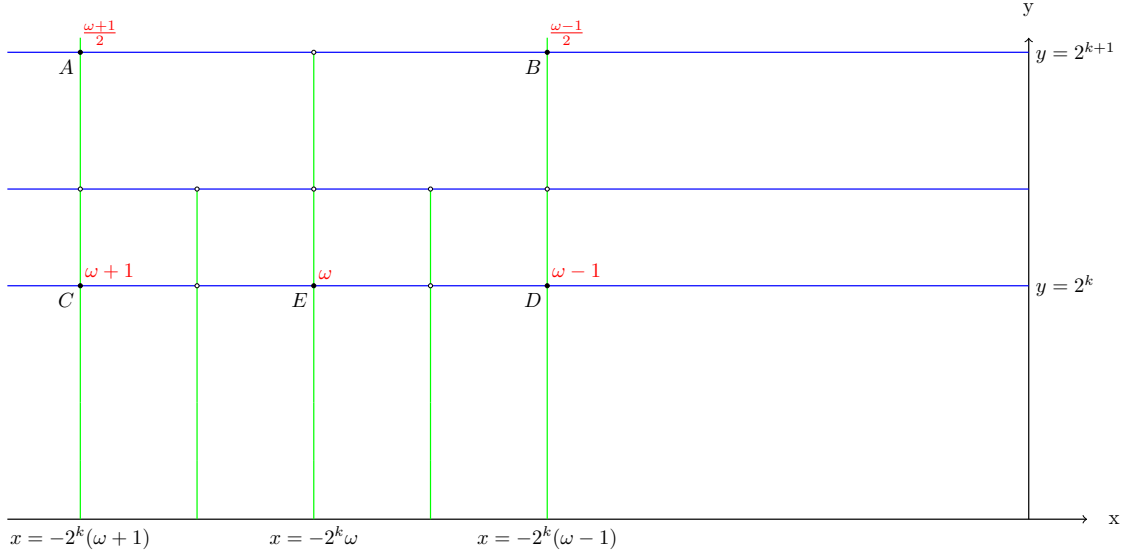Suppose $V = \bigcup_{i=1}^{\infty} V_i$, we have below lemma

Figure 11: the construction schema of G_1

Lemma 8.2. *V is a countable dense set.*

Proof. Because V_i is countable, and the union is over a countable index set, so V is countable.

We can prove it is dense by contradiction. Suppose V is not a dense set. Then there is a point p in the space neither belongs to V nor is a limit point of V.

TODO...

$\square$

8.5 Completeness and topology

8.6 As a special integral

9 From arithmetic torsion to curvature

from homotopy to homology

- 0-form: assignment a
- 1-form: path elements
- 2-form: area elements

Poincare duality on the meshgrid

But what is the point from arithmetic expressions?

10 Tube structure, complexification and fibration

11 General discussion

11.1 On integral theory

11.2 On limitation and boundary

11.3 On representation of function

11.4 Questions related with complexity?

12 A glossary of unsolved problems

12.1 Foundation questions

12.2 Classification problem

12.3 Eigenfunction problem

12.4 Tube structure

12.5 Singular points and divergent series

12.6 Function and a new calculus?

12.7 Category of function theories?

12.8 Computation geometry

12.9 Logic geometry

12.9.1 irrationality of $\sqrt{17}$

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A   A direct formal solution of the flow equation

We can also get a direct formal solution of the flow equation ((25)) step by step:

$$\frac{da}{\mu\cos\theta + a\lambda\sin\theta} = ds$$

$$\frac{1}{\lambda\sin\theta}\frac{d(\mu\cos\theta + a\lambda\sin\theta)}{\mu\cos\theta + a\lambda\sin\theta} = ds$$

$$\frac{1}{\lambda\sin\theta}ln(\mu\cos\theta + a\lambda\sin\theta) = s + C$$

$$\mu\cos\theta + a\lambda\sin\theta = e^{\lambda s\sin\theta}e^{C\lambda\sin\theta}$$

Considering the initial condition

$$\mu\cos\theta + a_0\lambda\sin\theta = e^{C\lambda\sin\theta}$$

We have

$$\mu\cos\theta + a\lambda\sin\theta = e^{\lambda s\sin\theta}(\mu\cos\theta + a_0\lambda\sin\theta)$$

$$a = \frac{\mu\cos\theta + a_0\lambda\sin\theta}{\lambda\sin\theta}e^{\lambda s\sin\theta} - \frac{\mu}{\lambda}\cot\theta$$

$$a = (a_0 + \frac{\mu}{\lambda}\cot\theta)e^{\lambda s\sin\theta} - \frac{\mu}{\lambda}\cot\theta$$

$$a = a_0 e^{\lambda s\sin\theta} + \frac{\mu}{\lambda}(e^{\lambda s\sin\theta} - 1)\cot\theta \tag{48}$$

$$a = a_0 e^{\lambda s\sin\theta} + \frac{\mu}{\lambda}(e^{\lambda s\sin\theta} - 1)\cot\theta \tag{49}$$

B Conformance between infinitesimal generating process and discrete mesh grid

In order to verify the conformance, we expand the formula (49) in the following way:

$$a = a_0 e^{\lambda s \sin \theta} + \frac{\mu}{\lambda}[1 + \lambda s \sin \theta + \frac{1}{2!}(\lambda s \sin \theta)^2 + \frac{1}{3!}(\lambda s \sin \theta)^3 + \cdots - 1] \cot \theta \tag{50}$$

$$a = a_0 e^{\lambda s \sin \theta} + \mu s \cos \theta + \frac{\mu}{\lambda} \sin \theta \cos \theta (\frac{\lambda^2 s^2}{2!} + \frac{\lambda^3 s^3}{3!} \sin \theta + \frac{\lambda^4 s^4}{4!} \sin^2 \theta + \cdots) \tag{51}$$

$$a = a_0 e^{\lambda s \sin \theta} + \mu s \cos \theta + \frac{\mu}{2\lambda} \sin 2\theta (\frac{\lambda^2 s^2}{2!} + \frac{\lambda^3 s^3}{3!} \sin \theta + \frac{\lambda^4 s^4}{4!} \sin^2 \theta + \cdots) \tag{52}$$

$$a = a_0 e^{\lambda s \sin \theta} + \mu s \cos \theta + \frac{\mu}{2\lambda} \Psi(s) \sin 2\theta \tag{53}$$

When $\theta = \frac{k\pi}{2}, k = 0, 1, 2, 3 \cdots, s = 0, 1, 2, 3 \cdots$, we have

$$a = a_0 e^{\lambda s \sin \theta} + \mu s \cos \theta \tag{54}$$

Especially, we have

$$a = a_0 + \mu s, s = 0, 1, 2, 3 \cdots, k = 0, 1, 2, 3 \cdots, \theta = 2k\pi \tag{55}$$

$$a = x_0 e^{\lambda s}, s = 0, 1, 2, 3 \cdots, k = 0, 1, 2, 3 \cdots, \theta = 2k\pi + \frac{\pi}{2} \tag{56}$$

$$a = a_0 - \mu s, s = 0, 1, 2, 3 \cdots, k = 0, 1, 2, 3 \cdots, \theta = 2k\pi + \pi \tag{57}$$

$$a = a_0 e^{-\lambda s}, s = 0, 1, 2, 3 \cdots, k = 0, 1, 2, 3 \cdots, \theta = 2k\pi + \frac{3\pi}{2} \tag{58}$$

which gives the conformance.

C   Arithmetic expression, combinators and transformation over trees

C.1   LISP and combinators

C.2   Applicative and concatenative

C.3   Donaghey transformation