



ITEM NO.	PART NUMBER	QTY.
1	skeleton	1
2	servo 25kg*sm	12
3	shoulder (limbC)	4
4	Hip_right (LimbA)	2
5	transmission arm	4
6	feet (limbB)	2
7	25T servo arm	4
8	ISO 7046-1 - M3 x 20 - Z - 20C	15
9	battery pack	1
10	to close the battery pack	1
11	hip_servo_restrainer	4
12	shoulder_servo_holder	8
13	ISO 7046-1 - M3 x 16 - Z - 16C	30
14	Hip_left(limbA)	2
15	Feet_left(LimbB)	2
16	2shoulder_hold	2
17	608 - 2RS	4

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Nr.	Page	Docum. Nr.	Signature
Performed			
Supervisor			
Checked by			
Servo actuated quadruped robot mechanical design			
RTU IEEI			