Title

Subtitle

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Collaboration









Vision

Save CPU time by using a **Neural Network** to simulate the **HGCAL**.

Use Graph Neural Networks ('GNNs') to deal with sparsity and irregular geometry

Design Decisions

- > Stay as close as possible to the detector geometry ⇒ Node ≡ Cell
- > Q1: When is the neighborhood between the cells constructed?
 - 'Post simulation' step: construct the neighborhood for each event (in CMSSW)
 - simulation always matches geometry

VS.

- Preprocessing step: read neighborhood from lookup table
 - faster ←
- > Q2: How do we continue after the simulation?

Simulation and Machine Learning Frameworks

Integration: Simulate in CMSSW, use the integrated ML software stack.

Directly integrated in the production process

Decoupling: Simulate in CMSSW, continue with standard ML software stack.

- Lean development environment
- > Faster development cycle
- Easier onboarding
- Access to HPC clusters w/o CMS software available
- Cutting edge software versions
- ⇒ Preferred solution for this case

The integrated ML tool chain in CMSSW is also widely used in CMS!

Loading the dataset

- Read simulated hits from ROOT file
 - Most tools cannot handle data of variable dimension
 - uproot → awkward arrays
- Convert simulated hits to graphs
 - Select the active cells from the extracted geometry
 - Extract the cell properties, construct the neighborhood information
 - CPU intensive ⇒ parallel processing
- Batch the graphs (torch_geometric [1])
- Move to GPU

Custom dataloader based on

torch.multiprocessing[2]

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- Batch the graphs (torch_geometric [1])
- (De)Serialize files (from) to disc (torch.save)
- Move to GPU

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torch.multiprocessing[2]

Thank you!

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Bibliography I

- [1] Mini-batches. URL: https://pytorchgeometric.readthedocs.io/en/latest/notes/introduction.html#minibatches.
- [2] Multiprocessing package. URL: https://pytorch.org/docs/stable/multiprocessing.html.