



# Diagnostics in Probabilistic Program Verification

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Philipp Schröer, **Darion Haase**, Joost-Pieter Katoen  
RWTH Aachen University

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# Formally Justified Diagnostics for Verification

## What if verification fails?

- What is the issue?
- Which statement(s) are the 'cause'?



```
23  method DutchFlag(a: array<Color>)
24    requires a != null modifies a
25    ensures forall i,j :: 0 <= i < j < a.Length ==> Ordered(a[i], a[j])
26    ensures multiset(a[..]) == old(multiset(a[..]))
27  {
28    var r, w, b := 0, 0, a.Length;
29    while w != b
30      invariant 0 <= r <= w <= b <= a.Length;
31      invariant forall i :: 0 <= i < r ==> a[i] == Red
32      invariant multiset(a[..]) == old(multiset(a[..]))
33    { match a[w]
34      case Red =>
35        a[r], a[w] := a[w], a[r];
36        r, w := r + 1, w + 1;
37      case White =>
38        w := w + 1;
39      case Blue =>
40        b := b - 1;
41        a[w], a[b] := a[b], a[w];
42    }
43 }
```

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- ▷ Improve the *verification loop*: attempt verification, failure, targeted refine.
- ▷ Good diagnostics are key for formal verification.

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## The Three Pillars of Caesar:

- (1) **Probabilistic** programs with  $\mathbb{R}_{\geq 0}^\infty$ -valued specifications,
- (2) **Quantitative verification statements** to encode a range of proof rules,
- (3) **Duality**: reasoning about lower/upper bounds of expected values (`assert` and `coassert`, ...).

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▷ How to generalize error reporting/diagnostics to the probabilistic setting?

# Slicing for Error Reporting

```
1  x := flip<1/2>
2  assert x ≥ 0
3  assert x = 1
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Idea: Errors are caused by presence of statements that create unfulfillable proof obligations.

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Idea: Errors are caused by presence of statements that create unfulfillable proof obligations.

Error localization. Error-witnessing Slice:

Subprogram  $S'$  of program  $S$  such that:

- (1)  $S'$  has a counter-example, and
- (2)  $\forall \sigma. \sigma$  is a counter-example in  $S' \implies \sigma$  is a counter-example in  $S$

▷ Report an error at the remaining assertion(s).

## Contributions

- Theory for diagnostics, suitable for *classical and probabilistic programs*:
  - (1) **Error Localization** by **error-witnessing slices** (slice has error  $\Rightarrow$  original has same error),

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  - (3) **Hints** by **verification-preserving slices** (tailoring program to specification).
- Defined for *quantitative intermediate verification language* (IVL).
- Specialized diagnostics for proof rules (induction, procedure calls).
- Slicing engine *Brutus* implemented in *Caesar*.

## Induction Proof Rule – Encoding

Reason about loops by finding a suitable loop *invariant*  $I$ :

```
// pre:  $X$ 
while  $b$  invariant  $I$  {
     $C$ 
}
// post:  $Y$ 
```



```
// pre:  $X$ 
assert  $I$ ;
havoc variables;
validate;
assume  $I$ ;
if  $b$  {
     $C$ ;
    assert  $I$ ;
    assume false
} else {}
// post:  $Y$ 
```

## Induction Proof Rule – From Slices to Error Localization

Minimal error-witnessing slice  $S'$  removing from {①, ②}:

```
// pre: X
① assert I;
    havoc variables;
    validate;
    assume I;
    if b {
        C;
    }
② assert I;
    assume false
} else {}
// post: Y
```

# Induction Proof Rule – From Slices to Error Localization

Minimal error-witnessing slice  $S'$  removing from  $\{ \textcircled{1}, \textcircled{2} \}$ :

```
// pre: X
① assert I;
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    validate;
    assume I;
    if b {
        C;
    }
② assert I;
    assume false
} else {}
// post: Y
```

$\textcircled{1} \in S' \implies \text{Pre does not entail invariant.}$   
 $\exists \sigma. X(\sigma) \not\Rightarrow I(\sigma).$

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①  $\in S' \implies$  Pre does not entail invariant.  
 $\exists \sigma. X(\sigma) \not\Rightarrow I(\sigma).$

②  $\in S' \implies$  Invariant not inductive.  
 $\exists \sigma. \sigma \models b \text{ and } \sigma \not\models \{I\} C \{I\}.$

# Induction Proof Rule – From Slices to Error Localization

Minimal error-witnessing slice  $S'$  removing from  $\{ \textcircled{1}, \textcircled{2} \}$ :

	// pre: $X$	
①	<b>assert <math>I</math>;</b>	$\textcircled{1} \in S' \implies \text{Pre does not entail invariant.}$
	<b>havoc variables;</b>	$\exists \sigma. X(\sigma) \not\Rightarrow I(\sigma).$
	<b>validate;</b>	
	<b>assume <math>I</math>;</b>	
	<b>if <math>b</math> {</b>	
	$C;$	
②	<b>assert <math>I</math>;</b>	$\textcircled{2} \in S' \implies \text{Invariant not inductive.}$
	<b>assume false</b>	$\exists \sigma. \sigma \models b \text{ and } \sigma \not\models \{ I \} C \{ I \}.$
	<b>} else {}</b>	
	// post: $Y$	$\textcircled{1}, \textcircled{2} \notin S' \implies \text{Invariant does not entail post.}$
		$\exists \sigma. \sigma \not\models b \text{ and } I(\sigma) \not\Rightarrow Y(\sigma).$

## Assert-like (Reductive) Statements:

- Boolean intuition: can only *reduce the number of verifying paths*.
- Probabilistic: expected value of  $X$  after executing  $S \leq X$ .
- in Caesar: e.g. **assert**, **coassume**, **validate**, **havoc**.

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## From Reductive Statements to Error-Witnessing Slice:

Erase reductive statements from  $S$  to obtain  $S'$ . Then,

$S'$  has an error  $\implies S'$  is an error-witnessing slice of  $S$ .

Recall error-witnessing slice  $S'$  of  $S$ : (1)  $S'$  has an error; and (2) errors in  $S'$  are also in  $S$ .

Certificates. **Verification-witnessing Slice:**

Subprogram  $S'$  of program  $S$  such that:

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## Assume-like (Extensive) Statements:

- Boolean intuition: can only *reduce the number of erroring paths*.
- Erase extensive statements from  $S$  to obtain verification-witnessing slice  $S'$ .

# Reporting Certificates & Hints

## Certificates. Verification-witnessing Slice:

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## Assume-like (Extensive) Statements:

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## Hints. Verification-preserving Slice:

Subprogram  $S'$  of program  $S$  such that:

$S$  verifies  $\Rightarrow S'$  verifies.

- ▷ Remove statements while preserving the specification.

## Induction Proof Rule – From Slices to Hints

Verification-witnessing slice  $S'$  removing from  $\{\textcircled{I}, \textcircled{II}\}$ :

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// pre:  $X$ 
assert  $I$ ;
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① assume  $I$ ;            $\textcircled{I} \notin S' \implies$  Assuming the invariant is not necessary.
    if  $b$  {
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$\models \{X\} \text{ while } b \text{ invariant true } \{C\} \{Y\}$

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havoc variables;
validate;
① assume  $I$ ;          ①  $\notin S' \Rightarrow$  Assuming the invariant is not necessary.
if  $b$  {
     $C$ ;
    assert  $I$ ;
② assume false          ②  $\notin S' \Rightarrow$  While loop could be an if statement.
} else {}
// post:  $Y$ 
```

$\models \{X\} \text{ while } b \text{ invariant true } \{C\} \{Y\}$

$\models \{X\} \text{ if } b \{C\} \text{ else } \{\} \{Y\}$

Verification-preserving slices tailor the program to the specification:

```
assume  $x_{in} \geq 0$ ;  
x :=  $x_{in}$ ;  
if  $x < 0$  {  
    x :=  $-x$   
} else { };  
assert  $x = |x_{in}|$ 
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# Implementation

Given program  $S$  and sliceable statements  $S_1, \dots, S_n$ ,

1. Pre-processing: Transform  $S_i \rightsquigarrow \text{if } \text{enabled}_{S_i} \{S_i\} \text{ else } \{\}$

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1. Pre-processing: Transform  $S_i \rightsquigarrow \text{if } enabled_{S_i} \{S_i\} \text{ else } \{\}$
2. Solving for slices:
  - Erroring slices: Solve SMT query

$$\exists enabled_{S_1}, \dots, enabled_{S_n}. (\exists \sigma \in \text{States}. \text{vp}[\![S]\!](\top)(\sigma) \neq \top) .$$

▷ We support *first* counter-example and *globally optimal* by size (binary search).

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- ▷ We support *first* counter-example and *globally optimal* by size (binary search).
  - **Verifying slices:** Solve SMT query
- $$\exists \text{enabled}_{S_1}, \dots, \text{enabled}_{S_n}. (\forall \sigma \in \text{States}. \text{vp}[\![S]\!](\top)(\sigma) = \top) .$$
- ▷ Quantifier alternation makes this more difficult.
  - ▷ Using *unsat cores*, also support locally/globally optimal slices (minimum UNSAT subset search).

## Discussion & Evaluation

We tested our slicer *Brutus* on 46 benchmarks (probabilistic and Boolean), mostly quantifier-free.

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### Erroring slices:

- Error localization is done like in Boogie/Dafny (*first* counter-example)
  - Boogie's error localization is based on inconsistent models<sup>1</sup>
  - Caesar tries to keep SMT problem quantifier-free if possible
- Minimization is cheap and helps ( $\leq +20$  ms, from  $\leq 2$  ms for 80% of benchmarks)

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### Verifying slices:

- UNSAT core is cheap, often suboptimal. Minimization more expensive but helps.
- Dafny's *verification coverage report* reports statements necessary for verification  
⇒ corresponds to *verification-witnessing slices*?

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- Relation to existing slicing approaches.
- Formal proofs.



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Thu 10:45 - 11:10 @ POPL: “Verifying Almost-Sure Termination for Randomized Distributed Algorithms” by Enea et al., using Caesar!